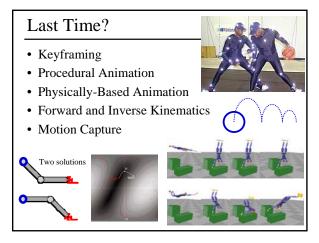
### Rigid Body Dynamics, Fracture, & Deformation

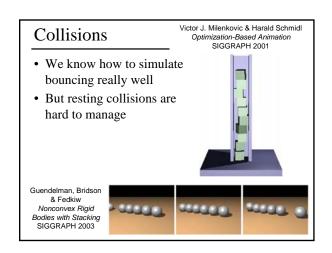


### Today

- Rigid Body Dynamics
- Finite Element Method
- Deformation
- Fracture

# Rigid Body Dynamics Could use particles for all points on the object But rigid body does not deform Few degrees of freedom Vity one particle at the center of mass Compute Net Force & Net Torque Net Force & Net Torque Nice Reference Material: http://www.pixar.com/companyinfo/research/pbm2001/http://www.myphysicslab.com/collision.html

## Physics - Velocity - Acceleration - Angular Momentum Collisions Friction from: Darren Lewis http://www-cs-students.stanford.edu/~dalewis/cs448a/rigidbody.html

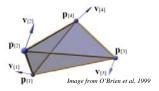


### Today

- Rigid Body Dynamics
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### Simulation of Non-Rigid Objects

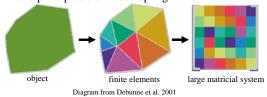
- We modeled string & cloth using mass-spring systems. Can we do the same?
- Yes...
- But a more physically accurate model uses volumetric elements:



### Finite Element Method

- To solve the continuous problem (deformation of all points of the object)
  - Discretize the problem
  - Express the interrelationship
  - Solve a big linear system

· More principled than Mass-Spring



### Strain & Stress

- Stress
  - the internal distribution of forces within a body that balance and react to the loads applied to it
  - normal stress & shear stress
- Strain

http://en.wikipedia.org/wiki/Image:St

- material deformation caused by stress.
- measured by the change in length of a line or by the change in angle between two lines

### Isotropic vs. Anisotropic

- *Isotropic*: is a property which does not depend on the direction.
- Anisotropic: is a proper which is directionally dependent.



### Elastic vs. Plastic

- Elastic Deformation: Once the forces are no longer applied, the object returns to its original shape.
- Plastic Deformation: An object in the plastic deformation range will first have undergone elastic deformation, which is reversible, so the object will return part way to its original shape.

http://en.wikipedia.org/wiki/Image:Stress-strain1.png

### Brittle vs. Ductile

- Brittle: Material deforms by fracturing. Glass is brittle. Rocks are typically brittle at low temperatures and pressures.
- Ductile: Material deforms without breaking. Metals are ductile.
  Many materials show both types of behavior. They may deform in
  a ductile manner if deformed slowly, but fracture if deformed too
  quickly or too much. Rocks are typically ductile at high
  temperatures or pressures.
- Viscous: Materials that deform steadily under stress. Purely viscous materials like liquids deform under even the smallest stress. Rocks may behave like viscous materials under high temperature and pressure.
- Viscoelastic: Combines elastic and viscous behavior. Models of glacio-isostasy frequently assume a viscoelastic earth: the crust flexes elastically and the underlying mantle flows viscously.

### Degenerate Elements

- Degenerate/Ill-conditioned Element: a.k.a. how "equilateral" are the elements?
  - Ratio of volume<sup>2</sup> to surface area<sup>3</sup>
  - Smallest solid angle
  - Ratio of volume to volume of smallest circumscribed sphere





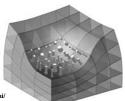


### **Tension & Compression**

- *Tension*: The direction of the force of tension is parallel to the string, away from the object exerting the stretching force.
- Compression: resulting in reduction of volume







### Today

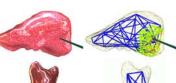
- Rigid Body Dynamics
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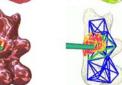
### Level of Detail

• Interactive shape deformation

 Use highresolution model only in areas of extreme deformation

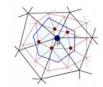


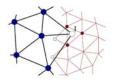




### Multi-Resolution Deformation

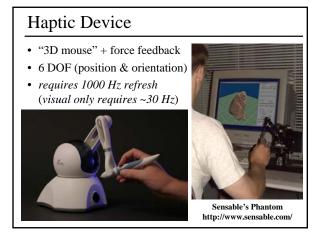
- Use Voronoi diagrams to match parent & child vertices.
- Interpolate values for inactive interface vertices from active parent/child vertices

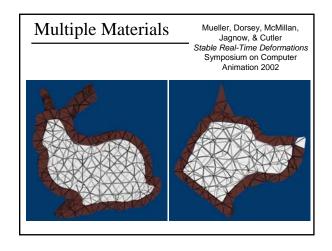




 Need to avoid interference of vibrations between simulations at different resolutions

Debunne et al. "Dynamic Real-Time Deformations using Space & Time Adaptive Sampling", 2001











## Today

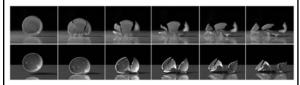
- Rigid Body Dynamics
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### Today

- Rigid Body Dynamics
- Finite Element Method
- Deformation
- Fracture

### Reading for Today:

 James O'Brien & Jessica Hodgins "Graphical Modeling and Animation of Brittle Fracture" SIGGRAPH 1999.



- · Fracture threshhold
- Material properties
- Remeshing
- Parameter tuning
- need connectivity info!

### Fracture Opening Modes

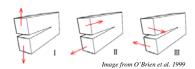
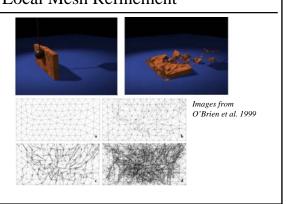
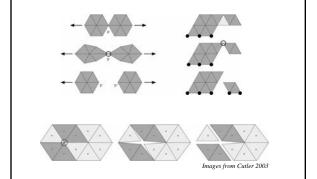


Figure 6: Three loading modes that can be experienced by a crack. Mode I: Opening, Mode II: In-Plane Shear, and Mode III: Out-of-Plane Shear. Adapted from Anderson [1].

### Local Mesh Refinement

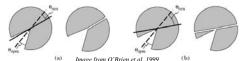


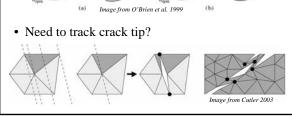
## Managing Fracture Adjacency

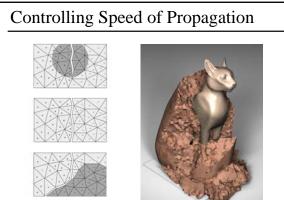


### Fracture Propagation Difficulties

• Need to track direction of fracture propagation?

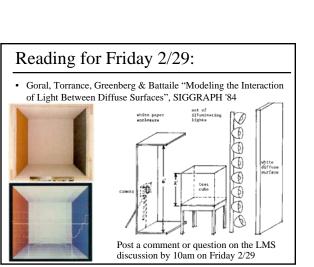






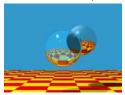
(no remeshing)





### Reading for Friday 2/22:

- "An improved illumination model for shaded display" Turner Whitted, 1980.
- ("Distributed Ray Tracing", Cook, Porter, & Carpenter, SIGGRAPH 1984.)





• Post a comment or question on the LMS discussion by 10am on Friday 2/22