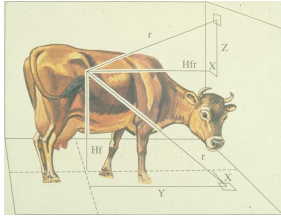


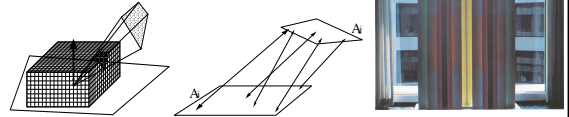
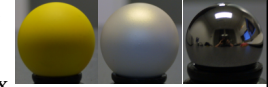
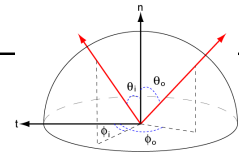
The Rendering Equation & Radiosity II



An early application of radiative heat transfer in stables.

Last Time?

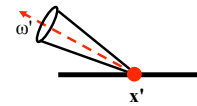
- Local Illumination
 - BRDF
 - Ideal Diffuse Reflectance
 - Ideal Specular Reflectance
 - The Phong Model
- Radiosity Equation/Matrix
- Calculating the Form Factors



Today

- The Rendering Equation
- Radiosity Equation/Matrix
- Advanced Radiosity
 - Progressive Radiosity
 - Adaptive Subdivision
 - Discontinuity Meshing
 - Hierarchical Radiosity

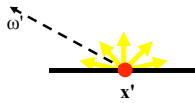
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

$L(x', \omega')$ is the radiance from a point on a surface in a given direction ω'

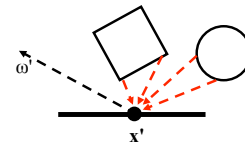
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

$E(x', \omega')$ is the emitted radiance from a point: E is non-zero only if x' is emissive (a light source)

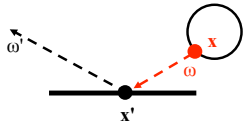
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

Sum the contribution from all of the other surfaces in the scene

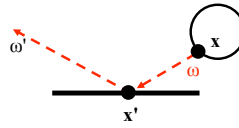
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

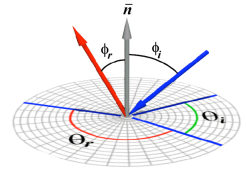
For each x , compute $L(x, \omega)$, the radiance at point x in the direction ω (from x to x')

The Rendering Equation

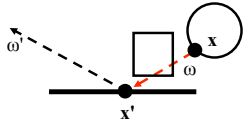


$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

scale the contribution by $\rho_x(\omega, \omega')$, the reflectivity (BRDF) of the surface at x'



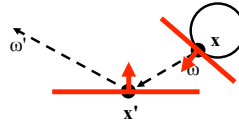
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

For each x , compute $V(x, x')$, the visibility between x and x' :
 1 when the surfaces are unobstructed along the direction ω , 0 otherwise

The Rendering Equation

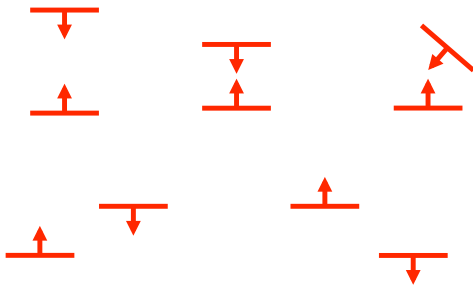


$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

For each x , compute $G(x, x')$, which describes the on the geometric relationship between the two surfaces at x and x'

Intuition about $G(x, x')$?

- Which arrangement of two surfaces will yield the greatest transfer of light energy? Why?



Questions?



Lightscape <http://www.lightscape.com>

Today

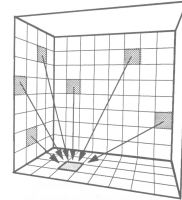
- The Rendering Equation
- Radiosity Equation/Matrix
- Advanced Radiosity
 - Progressive Radiosity
 - Adaptive Subdivision
 - Discontinuity Meshing
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Rendering Equation → Radiosity

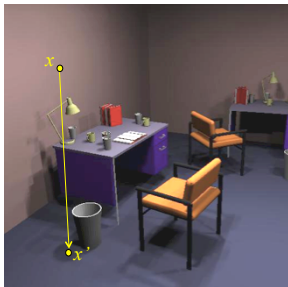
$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

↓ Radiosity assumption:
perfectly diffuse surfaces (not directional)

$$B_{x'} = E_{x'} + \rho_{x'} \int B_x G(x, x') V(x, x')$$



Continuous Radiosity Equation



$$B_{x'} = E_{x'} + \rho_{x'} \int \underbrace{G(x, x') V(x, x')}_{\text{form factor}} B_x$$

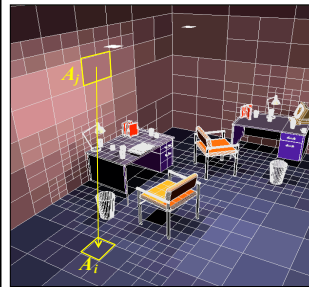
↑
reflectivity

G: geometry term
V: visibility term

No analytical solution,
even for simple configurations

Discrete Radiosity Equation

Discretize the scene into n patches, over which the radiosity is constant



$$B_i = E_i + \rho_i \sum_{j=1}^n F_{ij} B_j$$

↑
form factor

↓
reflectivity

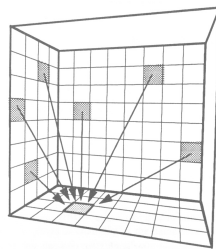
- discrete representation
- iterative solution
- costly geometric/visibility calculations

Solving the Radiosity Matrix

The radiosity of a single patch i is updated for each iteration by gathering radiosities from all other patches:

$$\begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_i \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_i \\ \vdots \\ E_n \end{bmatrix} + \begin{bmatrix} \rho_1 F_{1i} & \rho_2 F_{2i} & \dots & \rho_n F_{ni} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_i \\ \vdots \\ B_n \end{bmatrix}$$

↑ Radiosity values on iteration $t+1$ ↑ Radiosity values on iteration t

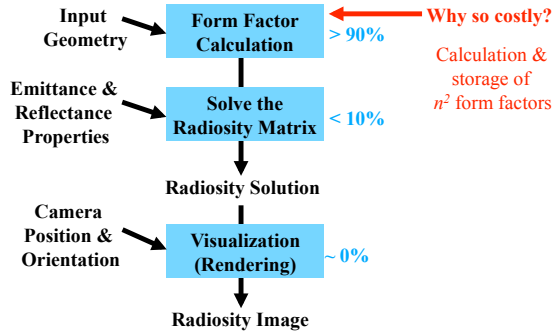


This method is fundamentally a Gauss-Seidel relaxation

Today

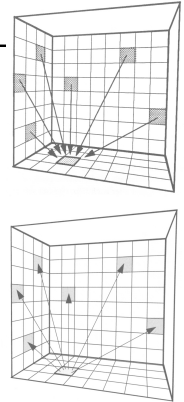
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Stages in a Radiosity Solution



Progressive Refinement

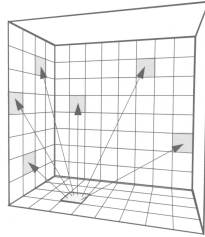
- Goal: Provide frequent and timely updates to the user during computation
- Key Idea: Update the entire image at every iteration, rather than a single patch
- How? Instead of summing the light received by one patch, distribute the radiance of the patch with the most *undistributed radiance*.



Reordering the Solution for PR

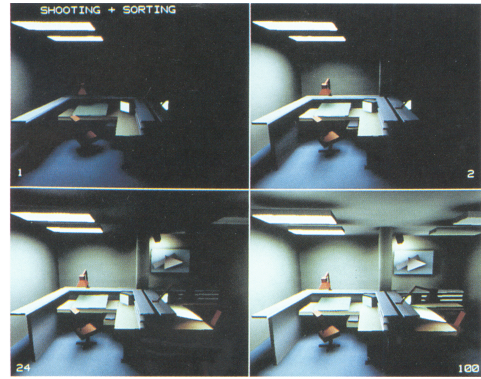
Shooting: the radiosity of all patches is updated for each iteration:

$$\begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} + \begin{bmatrix} \rho_1 F_{11} & \dots & \rho_1 F_{1n} \\ \rho_2 F_{21} & \dots & \rho_2 F_{2n} \\ \vdots & \vdots & \vdots \\ \rho_n F_{n1} & \dots & \rho_n F_{nn} \end{bmatrix} \begin{bmatrix} B_1 \\ \vdots \\ B_n \end{bmatrix}$$

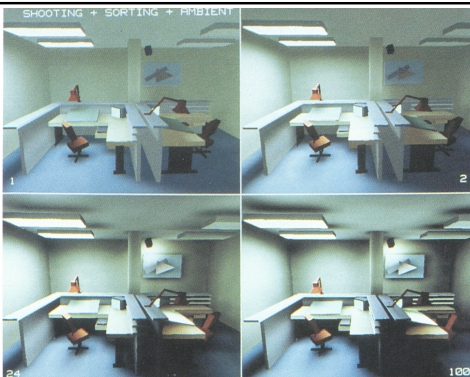


This method is fundamentally a Southwell relaxation

Progressive Refinement w/out Ambient Term



Progressive Refinement with Ambient Term



Questions?



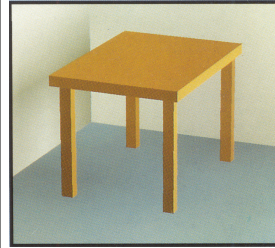
Lightscape <http://www.lightscape.com>

Today

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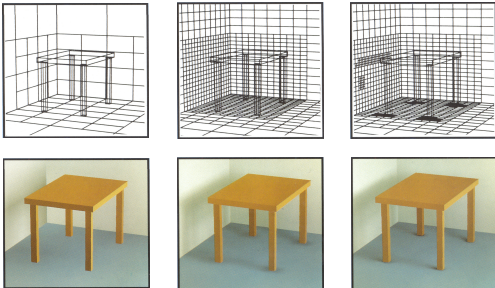
Increasing the Accuracy of the Solution

What's wrong with this picture?



- Image quality is a function of patch size
- Compute a solution on a uniform initial mesh, then refine the mesh in areas that exceed some error tolerance:
 - shadow boundaries
 - other areas with a high radiosity gradient

Adaptive Subdivision of Patches



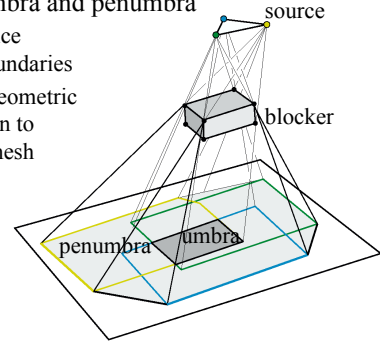
Coarse patch solution
(145 patches)

Improved solution
(1021 subpatches)

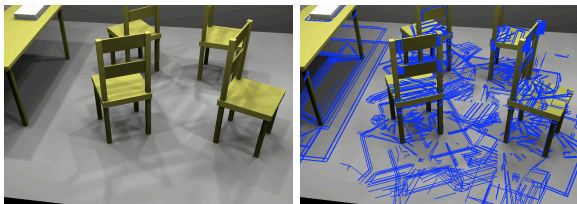
Adaptive subdivision
(1306 subpatches)

Discontinuity Meshing

- Limits of umbra and penumbra
 - Captures nice shadow boundaries
 - Complex geometric computation to construct mesh



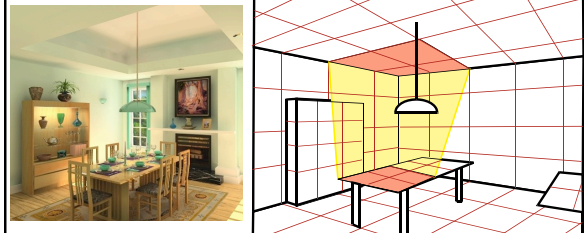
Discontinuity Meshing



“Fast and Accurate Hierarchical Radiosity Using Global Visibility”
Durand, Drettakis, & Puech 1999

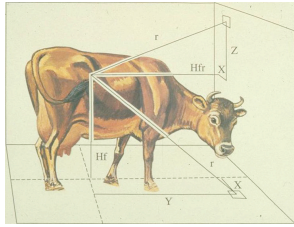
Hierarchical Radiosity

- Group elements when the light exchange is not important
 - Breaks the quadratic complexity
 - Control non trivial, memory cost



Practical Problems with Radiosity

- Meshing
 - memory
 - robustness
- Form factors
 - computation
- Diffuse limitation
 - extension to specular takes too much memory



Cow-cow form factor?

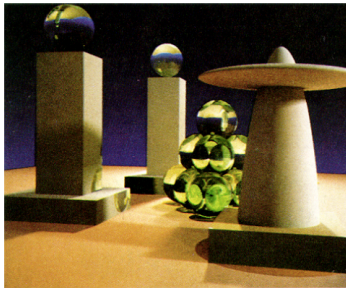
Questions?



Lightscape <http://www.lightscape.com>

Reading for Today:

- “The Rendering Equation”, Kajiya, 1986.



Reading for Today:

- “A Two-Pass Solution to the Rendering Equation: A Synthesis of Ray Tracing and Radiosity Methods”
Wallace, Cohen, & Greenberg, SIGGRAPH 1987



direct illumination (standard raytracing) indirect illumination (standard radiosity) full solution

- *Optional Reading:* “The Rendering Equation”
Kajiya, SIGGRAPH 1986

Readings for Friday 3/6 (pick one):

- “Rendering Fake Soft Shadows with Smoothies”, Chan & Durand, 2003.



- Rendering Lunar Eclipses”, Yapo & Cutler, GI 2009

