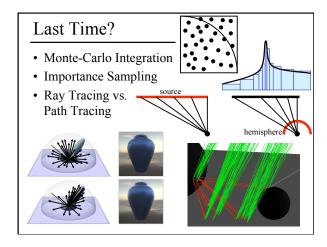
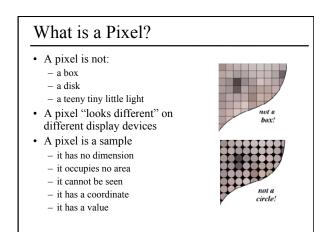
# Sampling, Aliasing, & Mipmaps



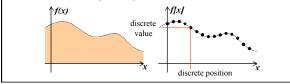
#### Today

- What is a Pixel?
- Examples of Aliasing
- Sampling & Reconstruction
- Filters in Computer Graphics
- Anti-Aliasing for Texture Maps



#### More on Samples

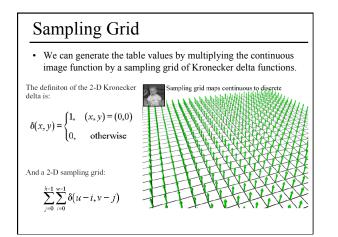
- Most things in the real world are *continuous*, yet everything in a computer is *discrete*
- The process of mapping a continuous function to a discrete one is called *sampling*
- The process of mapping a continuous variable to a discrete one is called *quantization*
- To represent or render an image using a computer, we must both sample and quantize

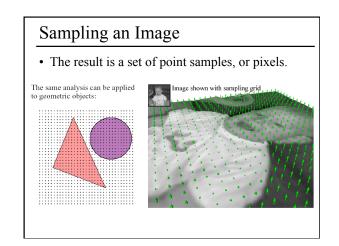


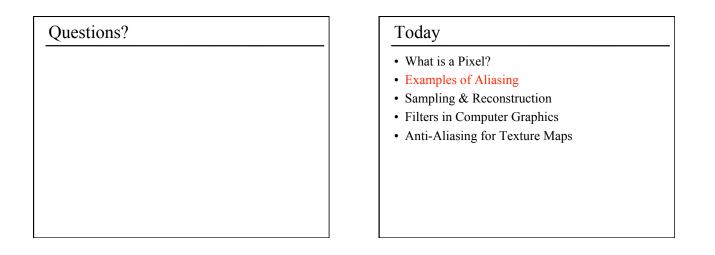
# An Image is a 2D Function

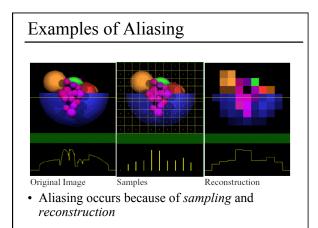
- An *ideal image* is a continuous function I(x,y) of intensities.
- It can be plotted as a height field.
- In general an image cannot be represented as a continuous, analytic function.
  Instead we represent
- images as tabulated functions.How do we fill
- this table?

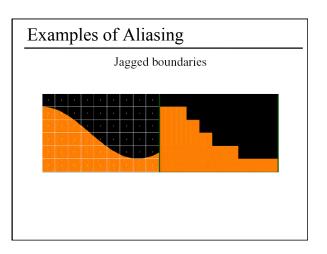


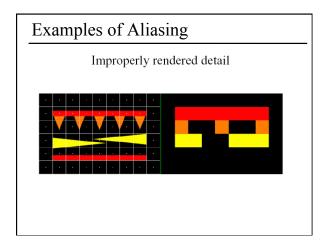


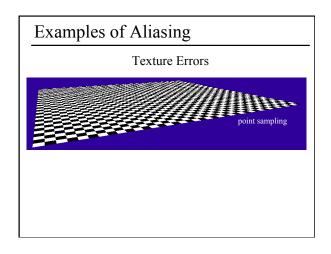


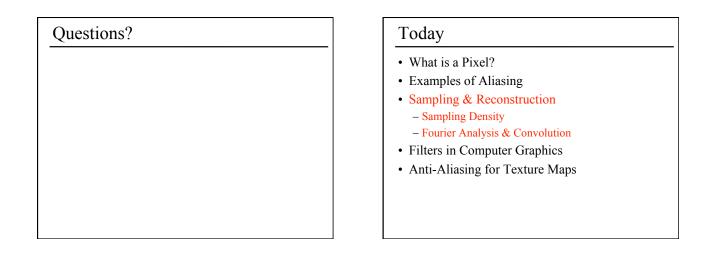






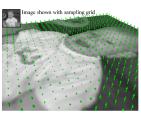


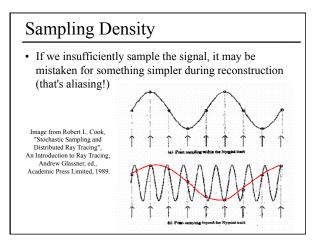


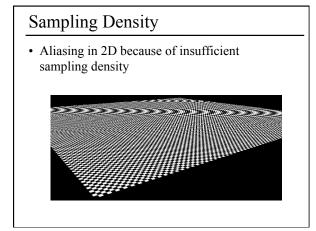


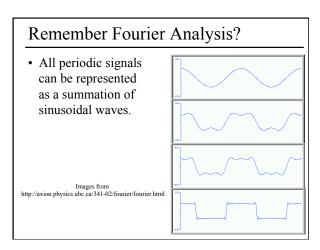
## Sampling Density

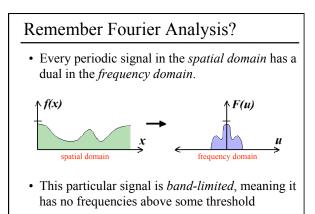
- How densely must we sample an image in order to capture its essence?
- If we under-sample the signal, we won't be able to accurately reconstruct it...

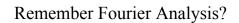






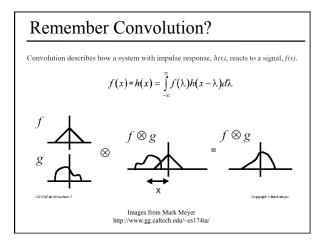


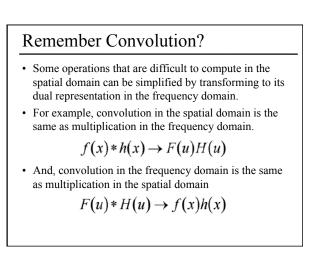


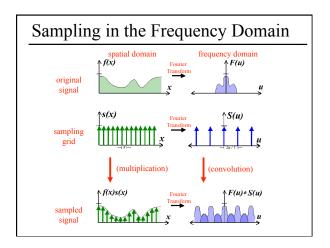


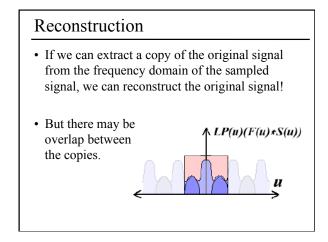
• We can transform from one domain to the other using the Fourier Transform.

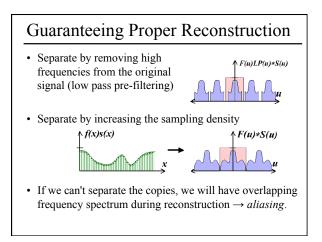
Fourier Transform  $F(u, v) = \iint_{-\infty-\infty}^{\infty} f(x, y) e^{-i2\pi(ux+vy)} dxdy$ Inverse Fourier Transform  $f(x, y) = \iint_{-\infty-\infty}^{\infty} F(u, v) e^{-i2\pi(ux+vy)} dudv$ 











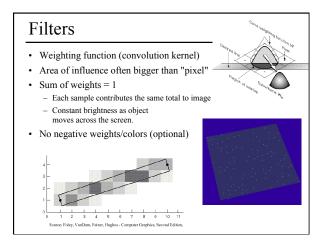
#### Sampling Theorem

• When sampling a signal at discrete intervals, the sampling frequency must be *greater than twice* the highest frequency of the input signal in order to be able to reconstruct the original perfectly from the sampled version (Shannon, Nyquist)

## Questions?

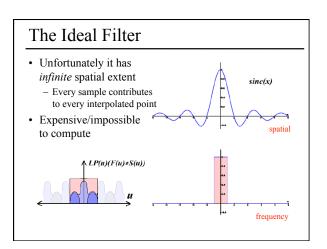
#### Today

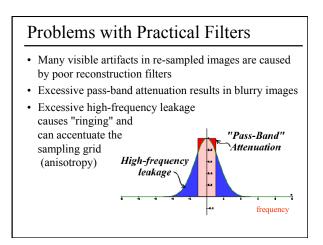
- What is a Pixel?
- Examples of Aliasing
- Sampling & Reconstruction
- Filters in Computer Graphics
  - Ideal, Gaussian, Box, Bilinear, Bicubic
- Anti-Aliasing for Texture Maps

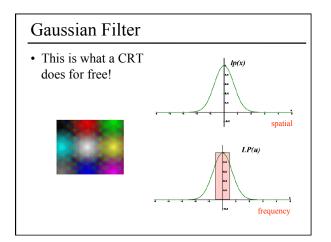


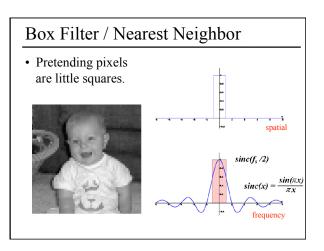
#### Filters

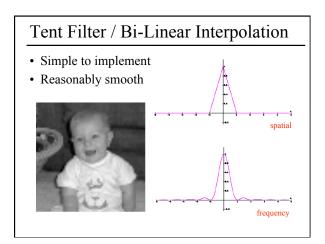
- · Filters are used to
  - reconstruct a continuous signal from a sampled signal (reconstruction filters)
  - band-limit continuous signals to avoid aliasing during sampling (low-pass filters)
- Desired frequency domain properties are the same for both types of filters
- Often, the same filters are used as reconstruction and low-pass filters

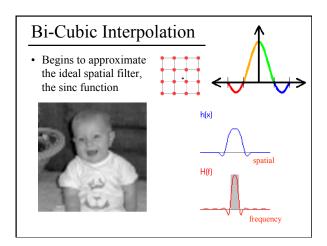


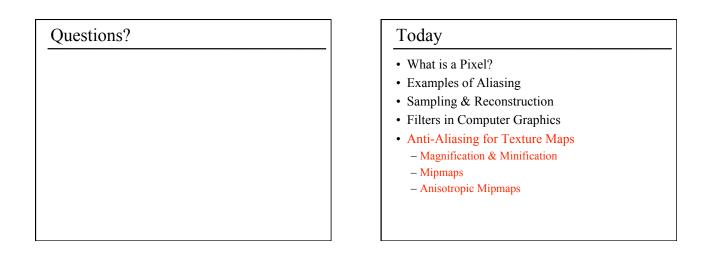


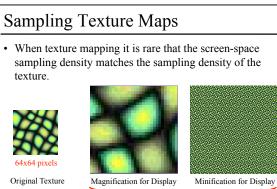








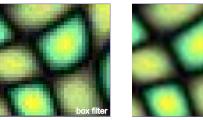


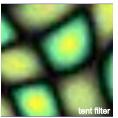


for which we must use a reconstruction filter

## Linear Interpolation

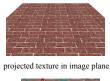
- Tell OpenGL to use a tent filter instead of a box filter.
- · Magnification looks better, but blurry - (texture is under-sampled for this resolution)



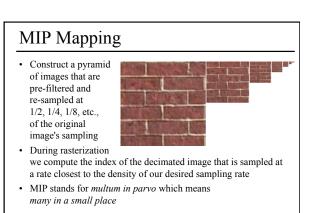


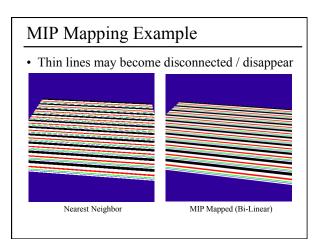
## Spatial Filtering

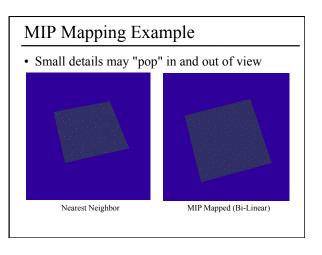
- Remove the high frequencies which cause artifacts in texture minification.
- Compute a spatial integration over the extent of the pixel
- This is equivalent to convolving the texture with a filter kernel centered at the sample (i.e., pixel center)!
- Expensive to do during rasterization, but an approximation it can be precomputed

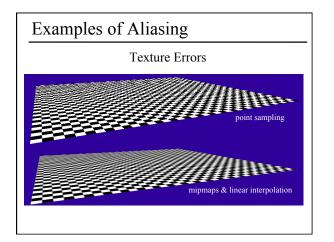


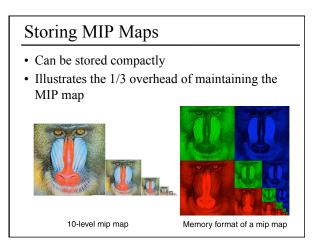


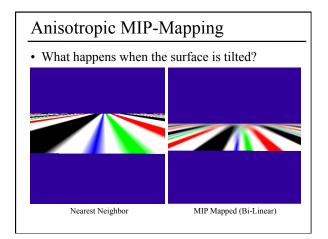


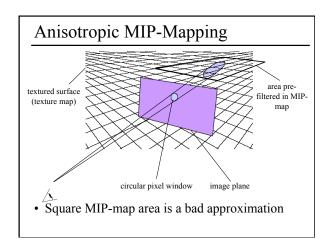


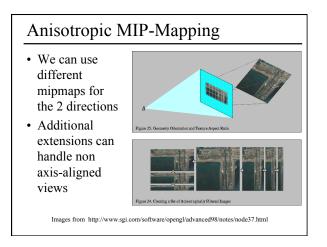


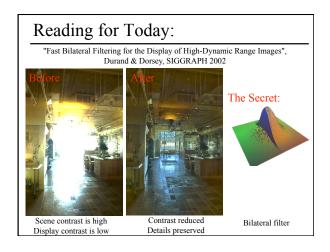












## Reading for Tuesday (4/1):

• *Global Illumination using Photon Maps*, Henrik Wann Jensen, Rendering Techniques 1996



• Post a comment or question on the LMS discussion by 10am on Tuesday 1/29