

Irradiance Caching & Photon Mapping

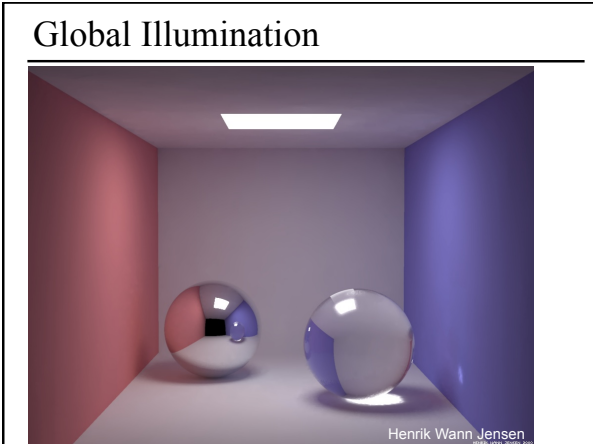
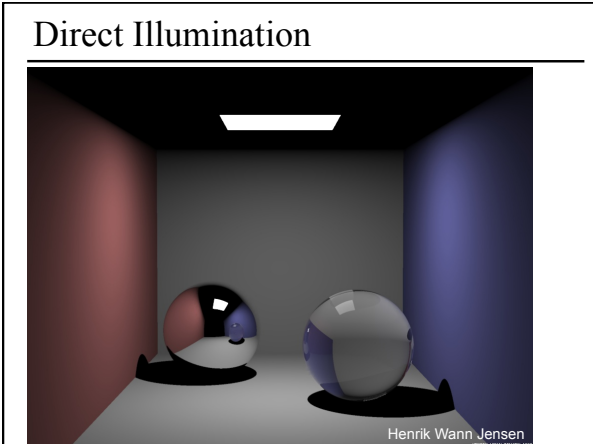
Last Time? $L(x', \omega') = E(x', \omega') + \int_{\rho, (\omega, \omega')} L(x, \omega) G(x, x') V(x, x') dA$

- Rendering Equation
- Monte-Carlo Integration
- Monte Carlo Rendering
- Forward Ray Tracing
- Stratified Sampling

- Today**
- Irradiance Caching
 - Photon Mapping
 - Acceleration Data Structures
 - Ray Grammar

Path Tracing is costly

- Needs tons of rays per pixel

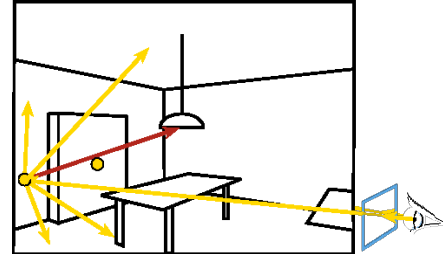


Indirect Illumination: smooth



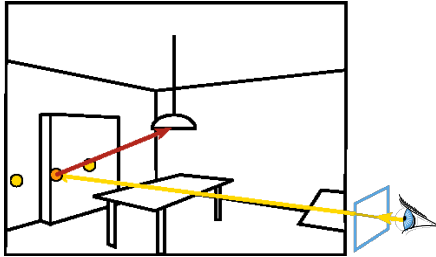
Irradiance Cache

- The indirect illumination is smooth
- Store the indirect illumination

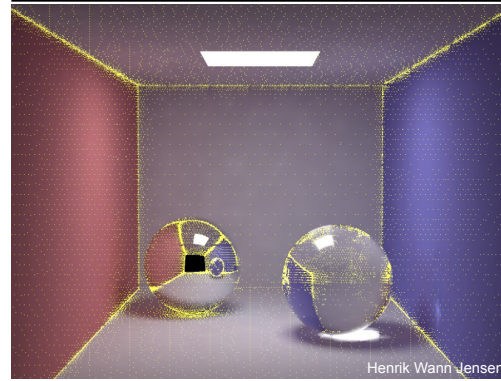


Irradiance Cache

- Interpolate nearby cached values
- But do full calculation for direct lighting

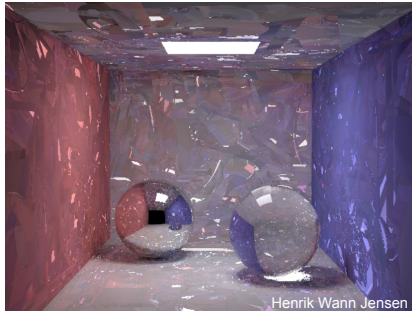


Irradiance Cache



Questions?

- Why do we need “good” random numbers?
 - With a fixed random sequence, we see the structure in the error

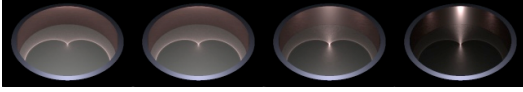


Today

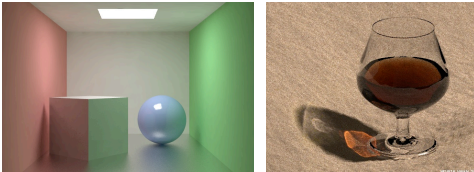
- Irradiance Caching
- **Photon Mapping**
- Acceleration Data Structures
- Ray Grammar

Readings for Today (*pick one*)

- “Rendering Caustics on Non-Lambertian Surfaces”, Henrik Wann Jensen, *Graphics Interface* 1996.

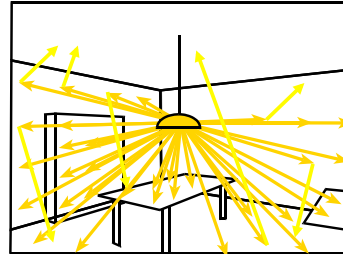


- “Global Illumination using Photon Maps”, Henrik Wann Jensen, *Rendering Techniques* 1996.



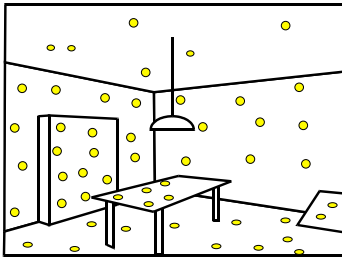
Photon Mapping

- Preprocess: cast rays from light sources – independent of viewpoint



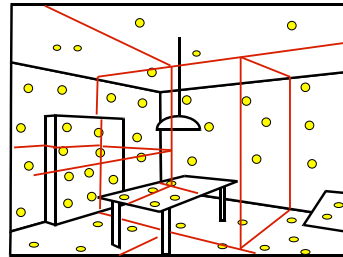
Photon Mapping

- Store photons – position + light power + incoming direction



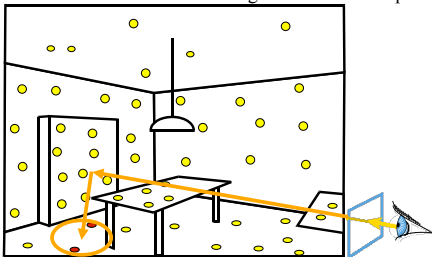
Photon Map

- Efficiently store photons for fast access
- Use hierarchical spatial structure (kd-tree)

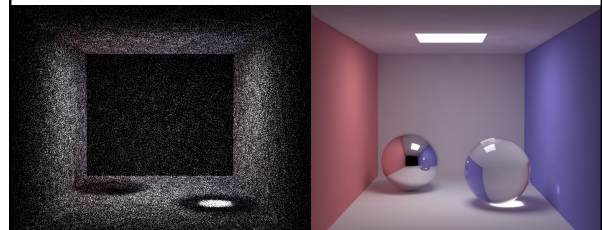


Rendering with Photon Map

- Cast primary rays
- For secondary rays – reconstruct irradiance using k closest photons
- Combine with irradiance caching and other techniques

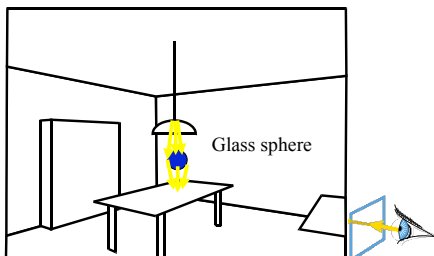


Photon Map Results



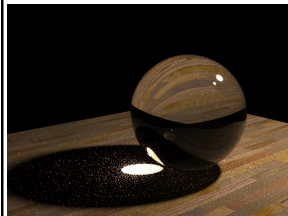
Photon Mapping - Caustics

- Special photon map for specular reflection and refraction

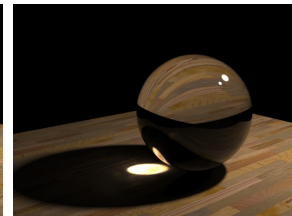


Comparison

Path Tracing
1000 paths/pixel

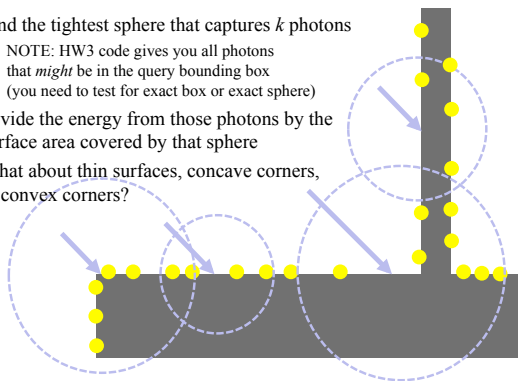


Photon mapping



Closest Photon Details

- Find the tightest sphere that captures k photons
 - NOTE: HW3 code gives you all photons that *might* be in the query bounding box (you need to test for exact box or exact sphere)
- Divide the energy from those photons by the surface area covered by that sphere
- What about thin surfaces, concave corners, & convex corners?

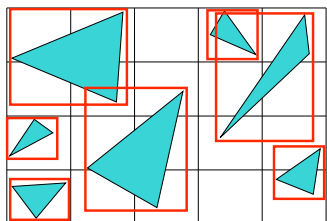


Today

- Irradiance Caching
- Photon Mapping
- Acceleration Data Structures
- Ray Grammar

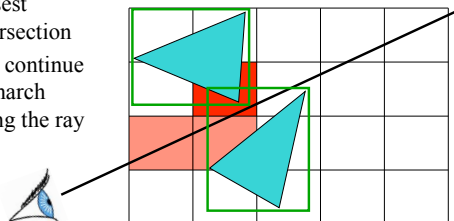
Regular Grid

- Primitives that overlap multiple cells?
- Insert into multiple cells (use pointers)



For Each Cell Along a Ray

- Does the cell contain an intersection?
- Yes: return closest intersection
- No: continue to march along the ray

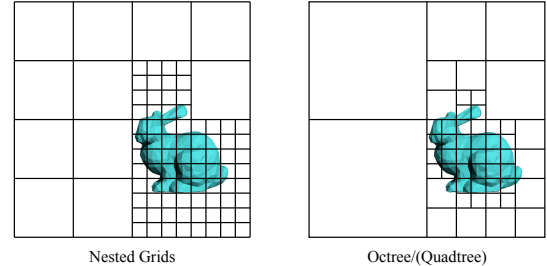


Regular Grid Discussion

- Advantages?
 - easy to construct
 - easy to traverse
- Disadvantages?
 - may be only sparsely filled
 - geometry may still be clumped

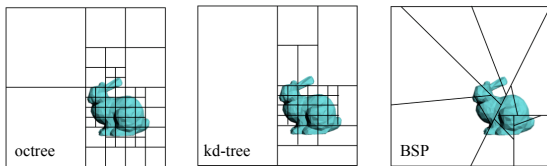
Adaptive Grids

- Subdivide until each cell contains no more than n elements, or maximum depth d is reached



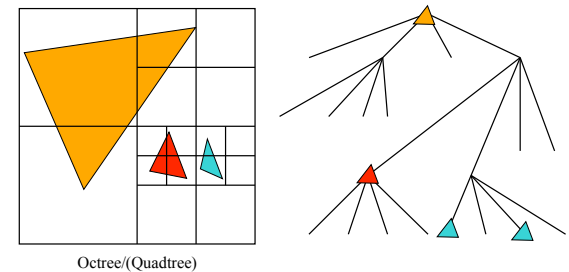
Variations of Adaptive Grids

- **When to split?** When a cell contains “lots” of geometry, but has not yet reached the max tree depth
- **Where to split?**
 - Quadtree/Octree: split *every* dimension in half, always axis aligned
 - kd-tree: choose *one* dimension (often the largest dimension) and split it axis aligned (but not necessarily at the midpoint)
 - Binary Space Partition (BSP): choose a *arbitrary* cut plane
- **Which one is best?** It depends.... Often they are all equally good!



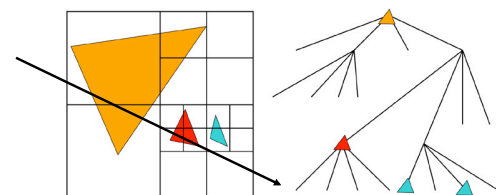
Primitives in an Adaptive Grid

- Can live at intermediate levels, or be pushed to lowest level of grid



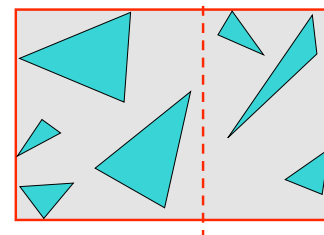
Adaptive Grid Discussion

- Advantages?
 - grid complexity matches geometric density
- Disadvantages?
 - more expensive to traverse (binary tree, lots of pointers)



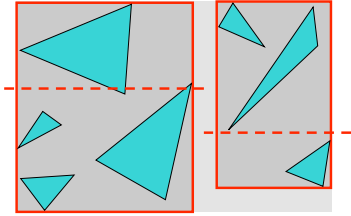
Bounding Volume Hierarchy

- Find bounding box of objects
- Split objects into two groups
- Recurse



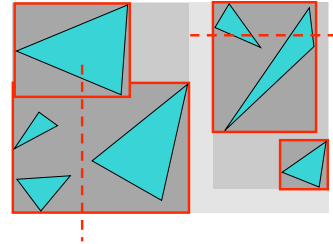
Bounding Volume Hierarchy

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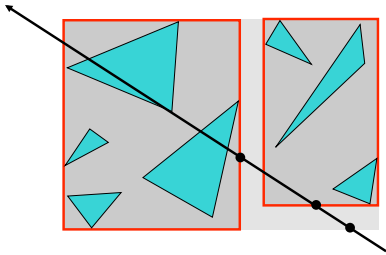
Where to split objects?

- At midpoint *OR*
- Sort, and put half of the objects on each side *OR*
- Use modeling hierarchy



Intersection with BVH

- Check sub-volume with closer intersection first

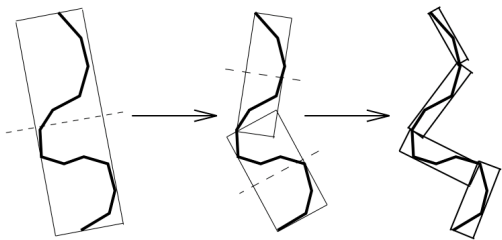


Bounding Volume Hierarchy Discussion

- Advantages
 - easy to construct
 - easy to traverse
 - binary
- Disadvantages
 - may be difficult to choose a good split for a node
 - poor split may result in minimal spatial pruning

Oriented Bounding Box (OBB)

- Generalization of the (axis-aligned) BVH



OBB-Tree: A Hierarchical Structure for Rapid Interference Detection,
Gottschalk, Lin, & Manocha, SIGGRAPH 1996.

Today

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Ray Grammar

- Classify local interaction:

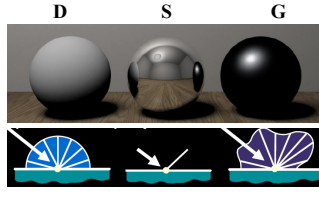
E = eye

L = light

S = perfect specular reflection or refraction

G = glossy scattering

D = diffuse scattering

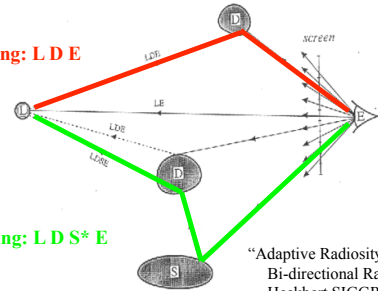


From Dutre et al.'s slides

Classic Ray Casting/Tracing

Ray casting: $L D E$

Ray tracing: $L D S^* E$

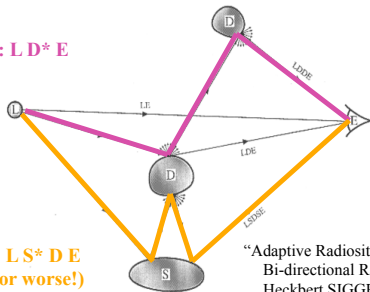


"Adaptive Radiosity Textures for Bi-directional Ray Tracing"
Heckbert SIGGRAPH 1990

Photon Tracing

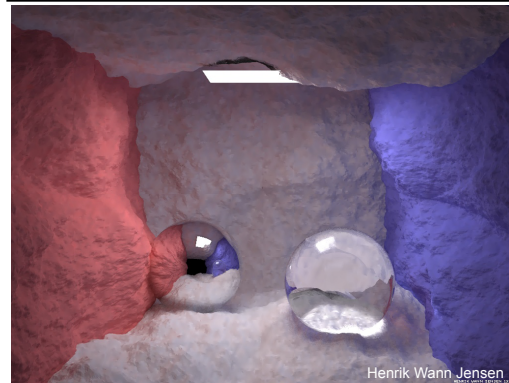
Radiosity: $L D^* E$

Caustics: $L S^* D E$
(or worse!)



"Adaptive Radiosity Textures for Bi-directional Ray Tracing"
Heckbert SIGGRAPH 1990

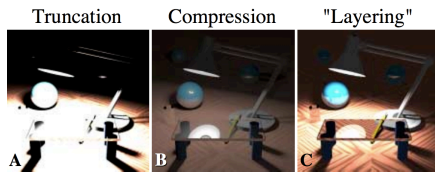
Questions?



Henrik Wann Jensen

Readings for Friday 3/25 (pick one)

"Two Methods for the Display of High Contrast Images",
Tumblin, Hodgins, & Guenter,
ACM Transactions on Graphics 1999



"Fast Bilateral Filtering for the Display of High-Dynamic Range Images",
Durand & Dorsey,
SIGGRAPH 2002

