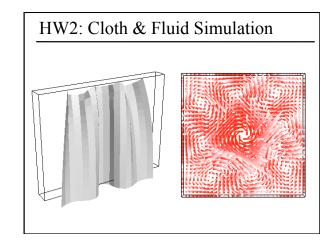
### Navier-Stokes & Flow Simulation

### Spring-Mass Systems Numerical Integration (Euler, Midpoint, Runge-Kutta) Modeling string, hair, & cloth

# Optional Reading for Last Time: • Baraff, Witkin & Kass Untangling Cloth SIGGRAPH 2003

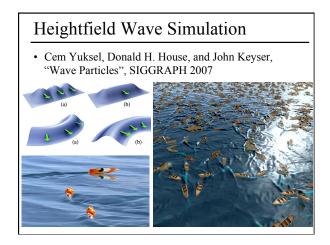


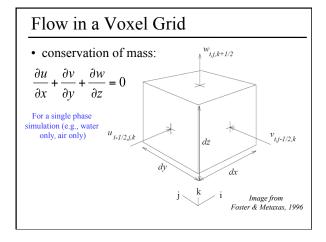
### Today

- Flow Simulations in Computer Graphics
  - water, smoke, viscous fluids
- Navier-Stokes Equations
  - incompressibility, conservation of mass
  - conservation of momentum & energy
- Fluid Representations
- · Basic Algorithm
- Data Representation

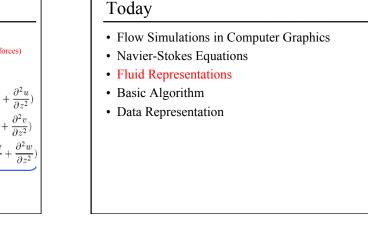
### Flow Simulations in Graphics

- · Random velocity fields
  - with averaging to get simple background motion
- Shallow water equations
  - height field only, can't represent crashing waves, etc.
- Full Navier-Stokes
- note: typically we ignore surface tension and focus on macroscopic behavior





### Navier-Stokes Equations • conservation of momentum: $\frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uv}{\partial y} + \frac{\partial uw}{\partial z} = -\frac{\partial p}{\partial x} + g_x + \nu(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2})$ $\frac{\partial v}{\partial t} + \frac{\partial vu}{\partial x} + \frac{\partial v^2}{\partial y} + \frac{\partial vw}{\partial z} = -\frac{\partial p}{\partial y} + g_y + \nu(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2})$ $\frac{\partial w}{\partial t} + \frac{\partial wu}{\partial x} + \frac{\partial wv}{\partial y} + \frac{\partial w^2}{\partial z} = -\frac{\partial p}{\partial z} + g_z + \nu(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2})$ acceleration Convection: internal movement in a fluid (e.g., caused by variation in density due to a transfer of heat)



# Modeling the Air/Water Surface • Volume-of-fluid tracking • Marker and Cell (MAC) • Smoothed Particle Hydrodynamics (SPH)

Comparing Representations
How do we render the resulting surface?
Are we guaranteed not to lose mass/volume? (is the simulation incompressible?)
How is each affected by the grid resolution and timestep?
Can we guarantee stability?

### Volume-of-fluid-tracking

• Each cell stores a scalar value indicating that cell's "full"-ness

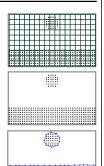




- + preserves volume
- difficult to render
- very dependent on grid resolution

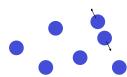
### Marker and Cell (MAC)

- Harlow & Welch, "Numerical calculation of time-dependent viscous incompressible flow of fluid with free surface", *The Physics of Fluids*, 1965.
- Volume marker particles identify location of fluid within the volume
- (Optional) surface marker particles track the detailed shape of the fluid/air boundary
- But... marker particles don't have or represent a mass/volume of fluid
- + rendering
- does not preserve volume
- dependent on grid resolution



### Smoothed Particle Hydrodynamics (SPH)

- Each particle represents a specific mass of fluid
- "Meshless" (no voxel grid)
- Repulsive forces between neighboring particles maintain constant volume



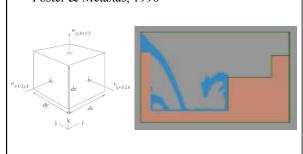
- + no grid resolution concerns (now accuracy depends on number/size of particles)
- + volume is preserved\*
- + render similar to MAC
- much more expensive (particle-particle interactions)

### Demos • Nice Marker and Cell (MAC) videos at: http://panoramix.ift.uni.wroc.pl/~maq/eng/cfdthesis.php

http://mme.uwaterloo.ca/~fslien/free\_surface/free\_surface.htm

### Reading for Today

• "Realistic Animation of Liquids", Foster & Metaxas, 1996

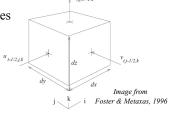


### Today

- Flow Simulations in Computer Graphics
- Navier-Stokes Equations
- Fluid Representations
- Basic Algorithm
- Data Representation

### Each Grid Cell Stores:

- Velocity at the cell faces (offset grid)
- Pressure
- List of particles



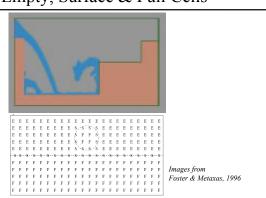
### Initialization

- Choose a voxel resolution
- Choose a particle density
- Create grid & place the particles
- Initialize pressure & velocity of each cell
- Set the viscosity & gravity
- Choose a timestep & go!

### At each Timestep:

- Identify which cells are Empty, Full, or on the Surface
- Compute new velocities
- Adjust the velocities to maintain an incompressible flow
- Move the particles
  - Interpolate the velocities at the faces
- Render the geometry and repeat!

### Empty, Surface & Full Cells



### At each Timestep:

- Identify which cells are Empty, Full, or on the Surface
- Compute new velocities
- Adjust the velocities to maintain an incompressible flow
- Move the particles
  - Interpolate the velocities at the faces
- Render the geometry and repeat!

### Compute New Velocities

$$\begin{split} \tilde{u}_{i+1/2,j,k} &= u_{i+1/2,j,k} + \delta t \{ (1/\delta x) [(u_{i,j,k})^2 - (u_{i+1,j,k})^2] \\ &+ (1/\delta y) [(uv)_{i+1/2,j-1/2,k} - (uv)_{i+1/2,j+1/2,k}] \\ &+ (1/\delta z) [(uw)_{i+1/2,j,k-1/2} - (uw)_{i+1/2,j,k+1/2}] + g_x \\ &+ (1/\delta x) (p_{i,j,k} - p_{i+1,j,k}) + (\nu/\delta x^2) (u_{i+3/2,j,k} \\ &- 2u_{i+1/2,j,k} + u_{i-1/2,j,k}) + (\nu/\delta y^2) (u_{i+1/2,j+1,k} \\ &- 2u_{i+1/2,j,k} + u_{i+1/2,j-1,k}) + (\nu/\delta z^2) (u_{i+1/2,j,k+1} \\ &- 2u_{i+1/2,j,k} + u_{i+1/2,j,k-1}) \}, \end{split}$$

Note: some of these values are the average velocity within the cell rather than the velocity at a cell face

### At each Timestep:

- Identify which cells are Empty, Full, or on the Surface
- Compute new velocities
- Adjust the velocities to maintain an incompressible flow
- Move the particles
  - Interpolate the velocities at the faces
- Render the geometry and repeat!

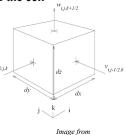
### Adjusting the Velocities

• Calculate the *divergence* of the cell (the extra in/out flow)

• The divergence is used to update the *pressure* within the cell

 Adjust each face velocity uniformly to bring the divergence to zero

• Iterate across the entire grid until divergence is  $< \epsilon$ 

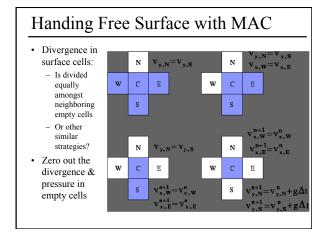


Foster & Metaxas, 199

### 

0 0

divergence



### At each Timestep:

0 0

divergence

• Identify which cells are Empty, Full, or on the Surface

-4 0

divergence

- Compute new velocities
- Adjust the velocities to maintain an incompressible flow
- Move the particles
  - Interpolate the velocities at the faces
- Render the geometry and repeat!

### • In 2D: For each axis, find the 4 closest face velocity samples: $u_1 = A_0 u_0 + A_1 u_1 + A_2 u_2 + A_1 u_3$ $w_k = A_0 w_0 + A_1 w_1 + A_2 w_2 + A_1 w_3$ $w_k = A_0 w_0 + A_1 w_1 + A_2 w_2 + A_1 w_3$ Original image from Foster & Metaxas, 1996• In 3D... find 8 closest face velocities in each dimension

• NOTE: The complete implementation isn't particularly elegant

