# The Traditional Graphics Pipeline



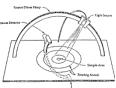
#### Last Time?

- · Participating Media
- · Measuring BRDFs
- 3D Digitizing & Scattering
- · BSSRDFs
  - Monte Carlo Simulation
  - Dipole Approximation









#### Today

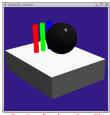
- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline
- Clipping
- Rasterization/Scan Conversion

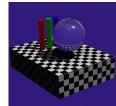
# Ray Casting / Tracing

- · Advantages?
  - Smooth variation of normal, exact silhouettes
  - Generality: can render anything that can be intersected with a ray
  - Atomic operation, allows recursion
- · Disadvantages?
  - Time complexity (N objects, R pixels)
  - Usually too slow for interactive applications
  - Hard to implement in hardware (lacks computation coherence, must fit entire scene in memory)

#### How Do We Render Interactively?

• Use graphics hardware (the graphics pipeline), via OpenGL, MesaGL, or DirectX





Graphics Pipeline (OpenGL

• Most global effects available in ray tracing will be sacrificed, but some can be approximated

# Ray Casting vs. Rendering Pipeline

Ray Casting
For each pixel
For each object

Send pixels into the scene Discretize first

"Inverse-Mapping" approach

For each gied on the screen
go through the depole to

Rendering Pipeline
For each triangle
For each pixel

Project scene to the pixels Discretize last

"Forward-Mapping" approach to Computer Graphies

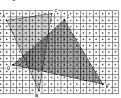
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#### Scan Conversion (Rendering Pipeline)

- Given a primitive's vertices & the illumination at each vertex:
- Figure out which pixels to "turn on" to render the primitive
- Interpolate the illumination values to "fill in" the primitive
- At each pixel, keep track of the closest primitive (z-buffer)





#### Limitations of Scan Conversion

- · Restricted to scan-convertible primitives
  - Must "polygonize" all objects
- · Faceting, shading artifacts
- Effective resolution is hardware dependent
- No handling of shadows, reflection, transparency
- Problem of overdraw (high depth complexity)
- What if there are many more triangles than pixels?







# Ray Casting vs. Rendering Pipeline

#### Ray Casting

#### For each pixel

- For each object
  Whole scene must be in
- memory

  Depth complexity:
  w/spatial acceleration data
  structures no computation
  needed for hidden parts
- Atomic computation
- More general, more flexible
   Primitives, lighting effects, adaptive antialiasing

# Rendering Pipeline For each triangle

#### or each triangle For each pixel

- Primitives processed one at a time
- Coherence: geometric
- transforms for vertices only

  Early stages involve analytic
- processing
   Computation increases with
  - depth of the pipeline

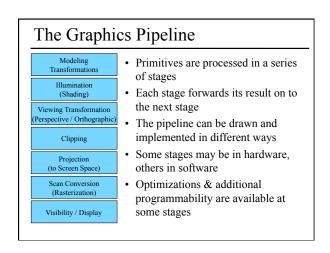
     Good bandwidth/computation ratio
- Sampling occurs late in the pipeline
- Minimal state required

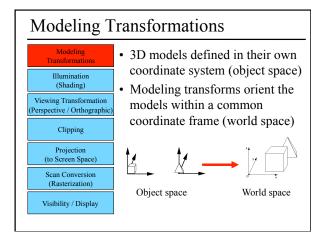
## Questions?

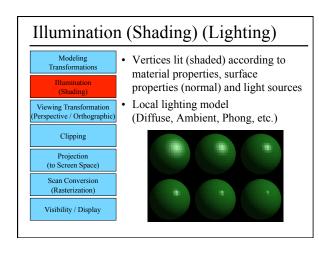
# Today

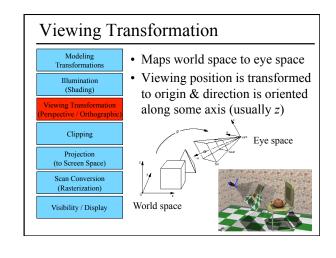
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- Clipping
- · Rasterization/Scan Conversion

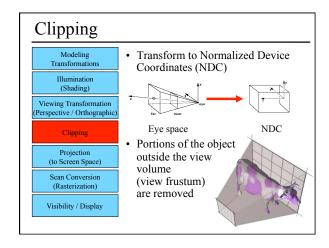
#### The Graphics Pipeline Modeling Description of all object, surface, and Illumination light source geometry and transformations (Shading) Lighting model: Computational description of object and light properties, interaction (reflection) Viewing Transformation (Perspective / Orthographic Synthetic Viewpoint (or Camera): Eye position and viewing frustum Clipping Raster Viewport: Pixel grid onto which image plane is mapped Projection Scan Conversion Colors/Intensities suitable for framebuffer display Visibility / Display (For example, 24-bit RGB value at each pixel)

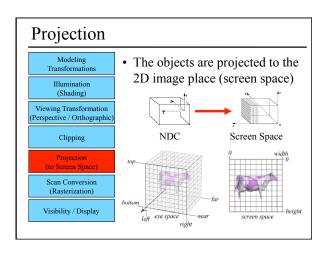


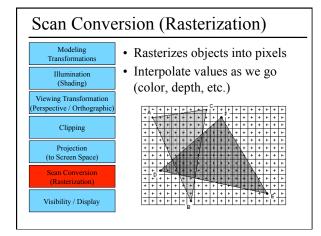


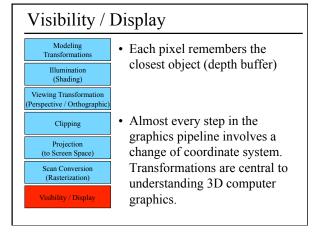




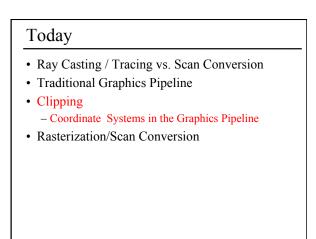


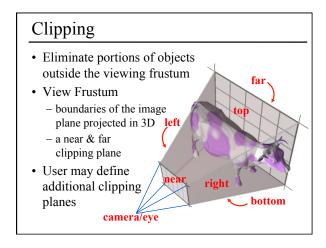


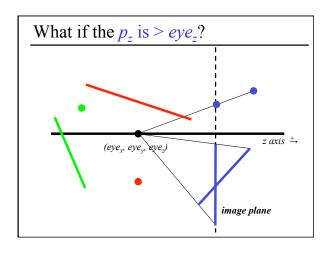


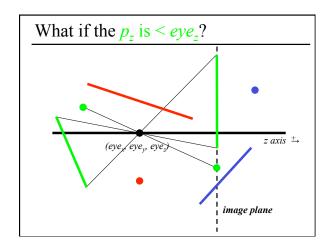


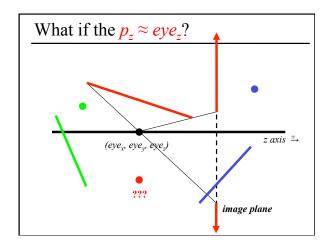
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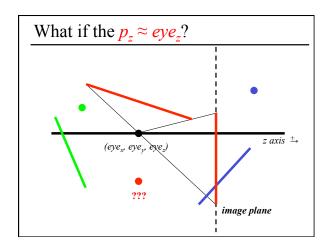


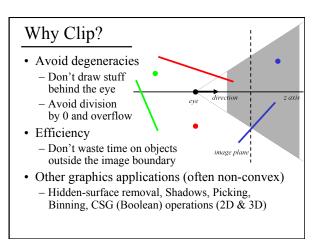


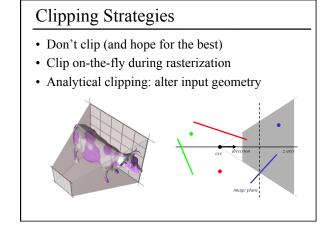


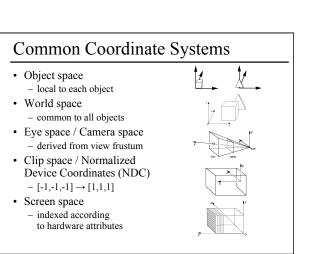


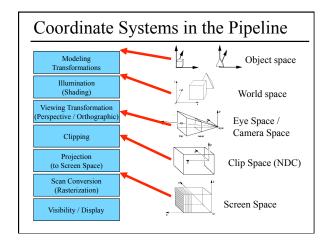


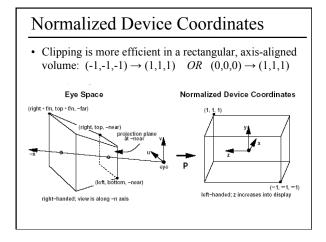


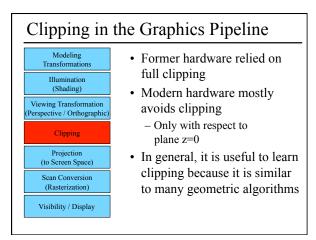


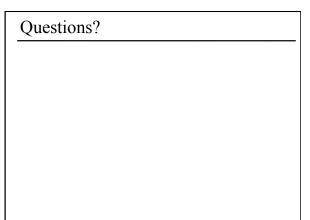










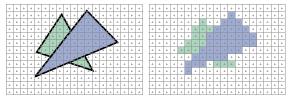


# Today

- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline
- Clipping
- Rasterization/Scan Conversion
  - Line Rasterization
  - Triangle Rasterization

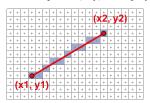
#### 2D Scan Conversion

- Geometric primitives (point, line, polygon, circle, polyhedron, sphere...)
- Primitives are continuous; screen is discrete
- Scan Conversion: algorithms for *efficient* generation of the samples comprising this approximation



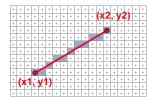
# Scan Converting 2D Line Segments

- Given:
  - Segment endpoints (integers x1, y1; x2, y2)
- Identify:
  - Set of pixels (x, y) to display for segment



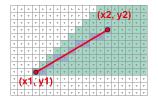
#### Line Rasterization Requirements

- Transform **continuous** primitive into **discrete** samples
- Uniform thickness & brightness
- Continuous appearance
- No gaps
- Accuracy
- Speed



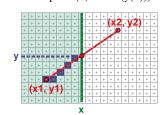
# Algorithm Design Choices

- Assume:
  - m = dy/dx, 0 < m < 1
- Exactly one pixel per column
  - fewer  $\rightarrow$  disconnected, more  $\rightarrow$  too thick



# Naive Line Rasterization Algorithm

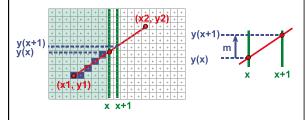
- Simply compute y as a function of x
  - Conceptually: move vertical scan line from x1 to x2
  - What is the expression of y as function of x?
  - Set pixel (x, round (y(x)))



- $y = y1 + \frac{x x1}{x2 x1}(y2 y1)$
- $m = \frac{dy}{dy}$

# Efficiency

- Computing y value is expensive y = y1 + m(x x1)
- Observe: y += m at each x step (m = dy/dx)



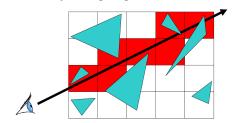
# Bresenham's Algorithm (DDA)

- Select pixel vertically closest to line segment
  - intuitive, efficient, pixel center always within 0.5 vertically
- · Generalize to handle all eight octants using symmetry
- Can be modified to use only integer arithmetic

| + | + | + | + | + | + | + | ø |
|---|---|---|---|---|---|---|---|
| + | + | + | + | + | • | • | + |
| + | + | + | + | 9 | + | + | + |
| + | + | + | 1 | + | + | + | + |
| + | 9 | 4 | + | + | + | + | + |
| 6 | + | + | + | + | + | + | + |

# Line Rasterization & Grid Marching

- Can be used for ray-casting acceleration
- March a ray through a grid

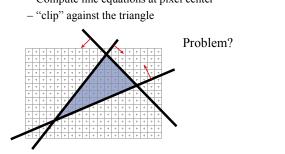


• Collect all grid cells, not just 1 per column (or row)

## Questions?

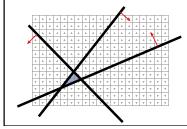
#### Brute force solution for triangles

- For each pixel
  - Compute line equations at pixel center



#### Brute force solution for triangles

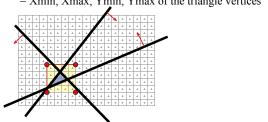
- For each pixel
  - Compute line equations at pixel center
  - "clip" against the triangle



Problem? If the triangle is small, a lot of useless computation

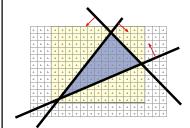
# Brute force solution for triangles

- Improvement: Compute only for the *screen bounding box* of the triangle
- How do we get such a bounding box?
  - Xmin, Xmax, Ymin, Ymax of the triangle vertices



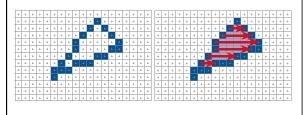
#### Can we do better? Kind of!

- We compute the line equation for many useless pixels
- · What could we do?



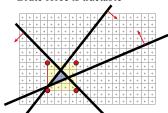
#### Scan-line Rasterization

- Compute the boundary pixels
- Fill the spans
- Interpolate vertex color along the edges & spans!



# But These Days...

- Triangles are usually very small
- Setup costs are becoming more troublesome
- · Clipping is annoying
- Brute force is tractable



#### Modern Rasterization

For every triangle

ComputeProjection

Compute bbox, clip bbox to screen limits

For all pixels in bbox

Compute line equations

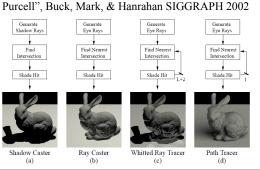
If all line equations>0 //pixel [x,y] in triangle

Framebuffer[x,y]=triangleColor

#### Questions?

# Reading for Today:

 "Ray Tracing on Programmable Graphics Hardware Purcell", Buck, Mark, & Hanrahan SIGGRAPH 2002



# Reading for Tuesday:

• "Shadow Algorithms for Computer Graphics", Frank Crow, SIGGRAPH 1977

