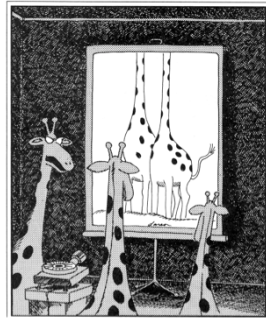


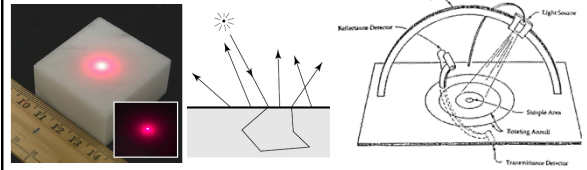
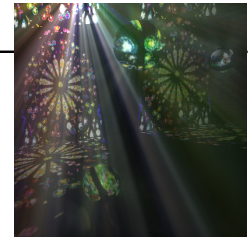
The Traditional Graphics Pipeline



"Oh, lovely — just the hundredth time you've managed to cut everyone's head off."

Last Time?

- Participating Media
- Measuring BRDFs
- 3D Digitizing & Scattering
- BSSRDFs
 - Monte Carlo Simulation
 - Dipole Approximation



Today

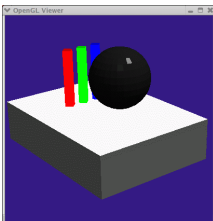
- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline
- Clipping
- Rasterization/Scan Conversion

Ray Casting / Tracing

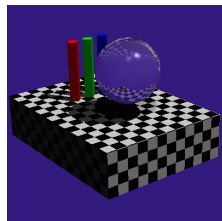
- Advantages?
 - Smooth variation of normal, exact silhouettes
 - Generality: can render anything that can be intersected with a ray
 - Atomic operation, allows recursion
- Disadvantages?
 - Time complexity (N objects, R pixels)
 - Usually too slow for interactive applications
 - Hard to implement in hardware (lacks computation coherence, must fit entire scene in memory)

How Do We Render Interactively?

- Use graphics hardware (the graphics pipeline), via OpenGL, MesaGL, or DirectX



Graphics Pipeline (OpenGL)



Ray Tracing

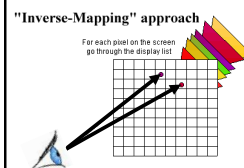
- Most global effects available in ray tracing will be sacrificed, but some can be approximated

Ray Casting vs. Rendering Pipeline

Ray Casting

For each pixel
For each object

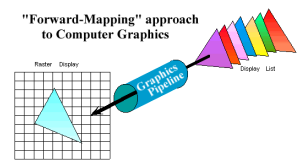
Send pixels into the scene
Discretize first



Rendering Pipeline

For each triangle
For each pixel

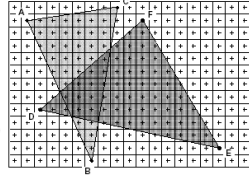
Project scene to the pixels
Discretize last



Scan Conversion (Rendering Pipeline)

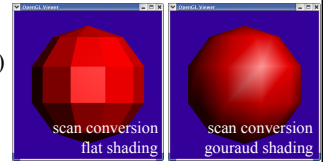
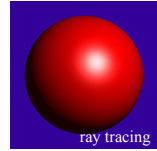
- Given a primitive's vertices & the illumination at each vertex:
- Figure out which pixels to "turn on" to render the primitive
- Interpolate the illumination values to "fill in" the primitive
- At each pixel, keep track of the closest primitive (z-buffer)

```
glBegin(GL_TRIANGLES)
glNormal3f(...);
glVertex3f(...);
glVertex3f(...);
glVertex3f(...);
glEnd();
```



Limitations of Scan Conversion

- Restricted to scan-convertible primitives
 - Must "polygonize" all objects
- Faceting, shading artifacts
- Effective resolution is hardware dependent
- No handling of shadows, reflection, transparency
- Problem of overdraw (high depth complexity)
- What if there are many more triangles than pixels?



Ray Casting vs. Rendering Pipeline

Ray Casting

For each pixel

- For each object
- Whole scene must be in memory
- Depth complexity: w/ spatial acceleration data structures no computation needed for hidden parts
- Atomic computation
- More general, more flexible
 - Primitives, lighting effects, adaptive antialiasing

Rendering Pipeline

For each triangle

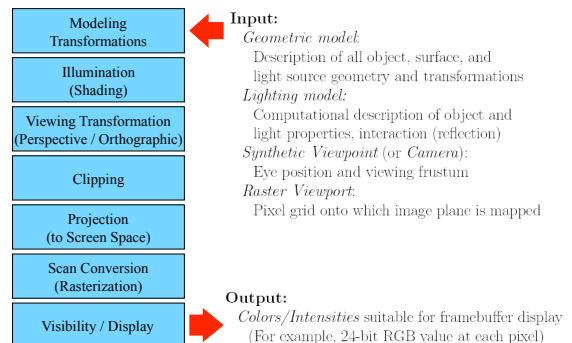
- For each pixel
- Primitives processed one at a time
- Coherence: geometric transforms for vertices only
- Early stages involve analytic processing
- Computation increases with depth of the pipeline
 - Good bandwidth/computation ratio
- Sampling occurs late in the pipeline
- Minimal state required

Questions?

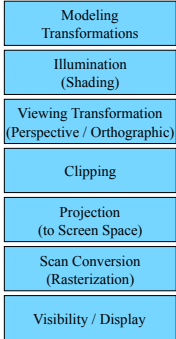
Today

- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline**
- Clipping
- Rasterization/Scan Conversion

The Graphics Pipeline

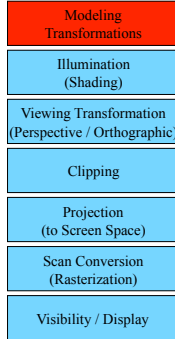


The Graphics Pipeline

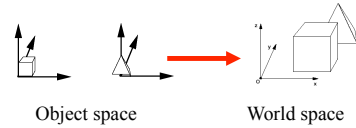


- Primitives are processed in a series of stages
- Each stage forwards its result on to the next stage
- The pipeline can be drawn and implemented in different ways
- Some stages may be in hardware, others in software
- Optimizations & additional programmability are available at some stages

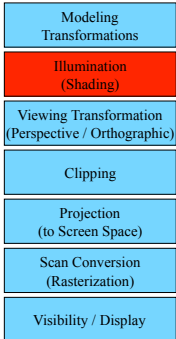
Modeling Transformations



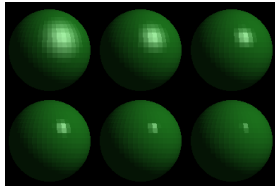
- 3D models defined in their own coordinate system (object space)
- Modeling transforms orient the models within a common coordinate frame (world space)



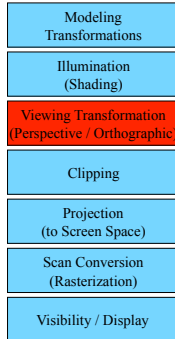
Illumination (Shading) (Lighting)



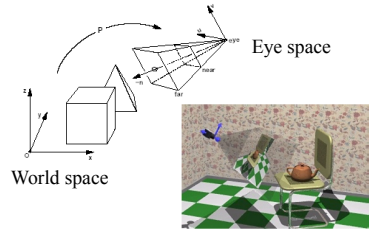
- Vertices lit (shaded) according to material properties, surface properties (normal) and light sources
- Local lighting model (Diffuse, Ambient, Phong, etc.)



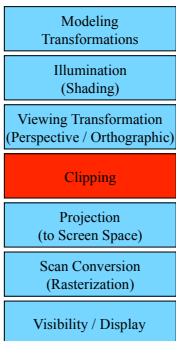
Viewing Transformation



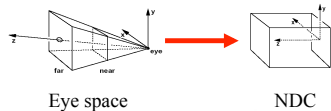
- Maps world space to eye space
- Viewing position is transformed to origin & direction is oriented along some axis (usually z)



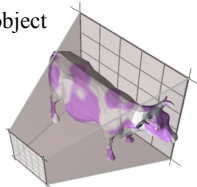
Clipping



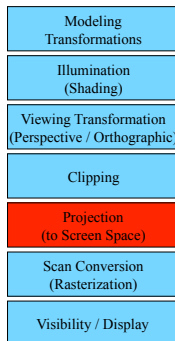
- Transform to Normalized Device Coordinates (NDC)



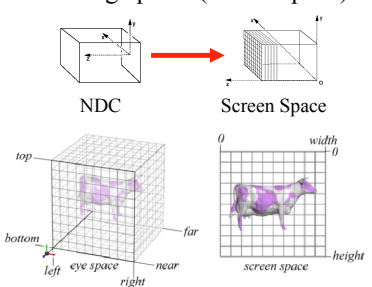
- Portions of the object outside the view volume (view frustum) are removed



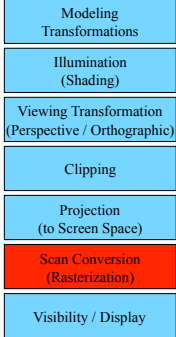
Projection



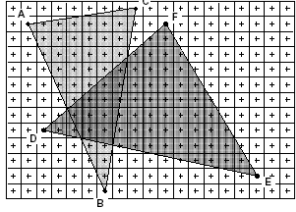
- The objects are projected to the 2D image plane (screen space)



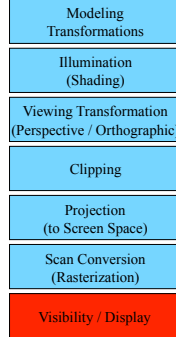
Scan Conversion (Rasterization)



- Rasterizes objects into pixels
- Interpolate values as we go (color, depth, etc.)



Visibility / Display



- Each pixel remembers the closest object (depth buffer)
- Almost every step in the graphics pipeline involves a change of coordinate system. Transformations are central to understanding 3D computer graphics.

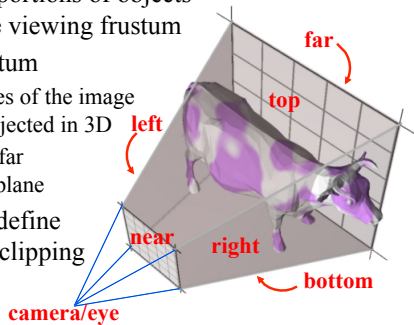
Questions?

Today

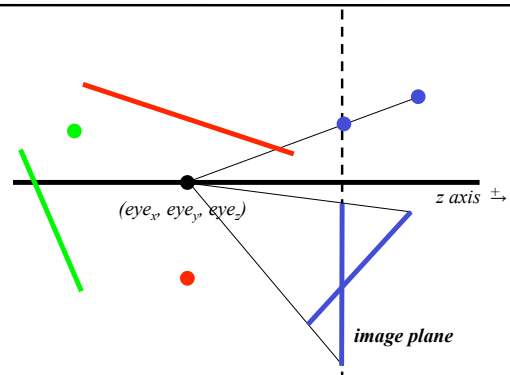
- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline
- Clipping
 - Coordinate Systems in the Graphics Pipeline
- Rasterization/Scan Conversion

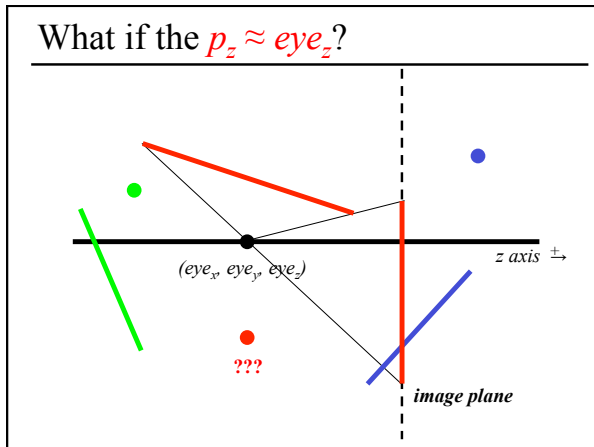
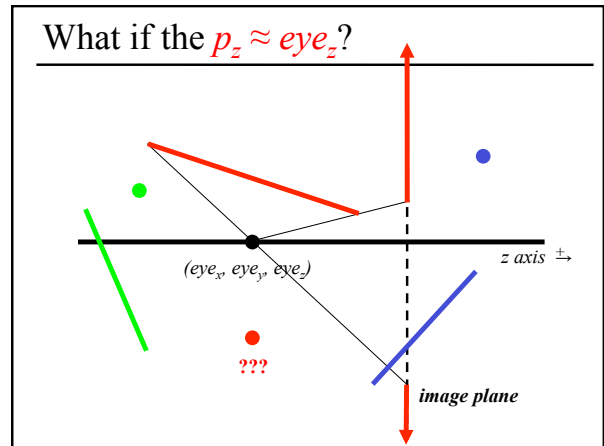
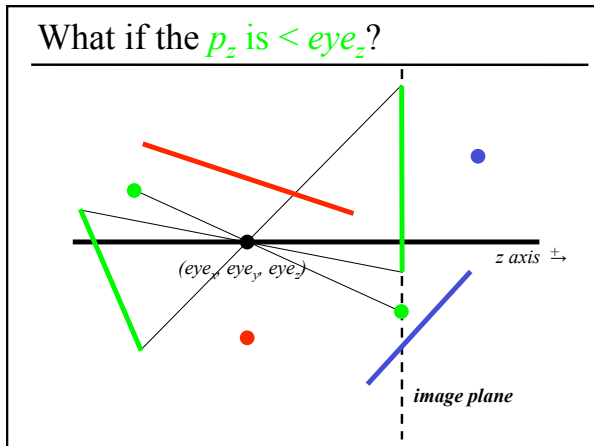
Clipping

- Eliminate portions of objects outside the viewing frustum
- View Frustum
 - boundaries of the image plane projected in 3D
 - a near & far clipping plane
- User may define additional clipping planes



What if the p_z is $> eye_z$?





Why Clip?

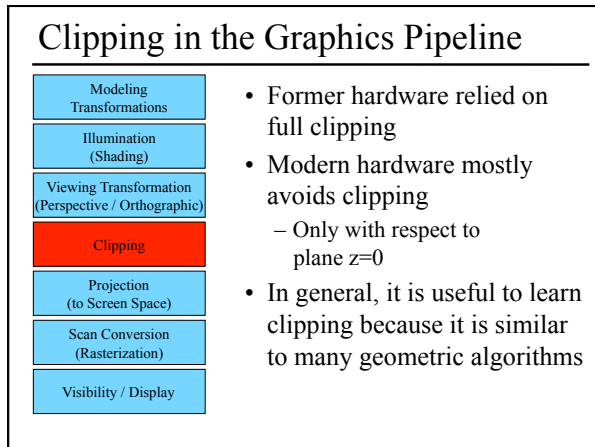
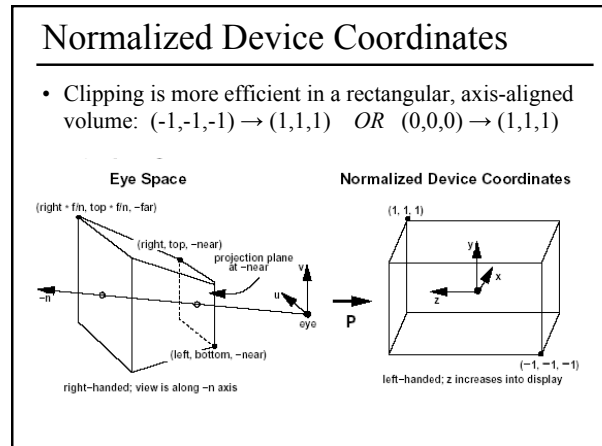
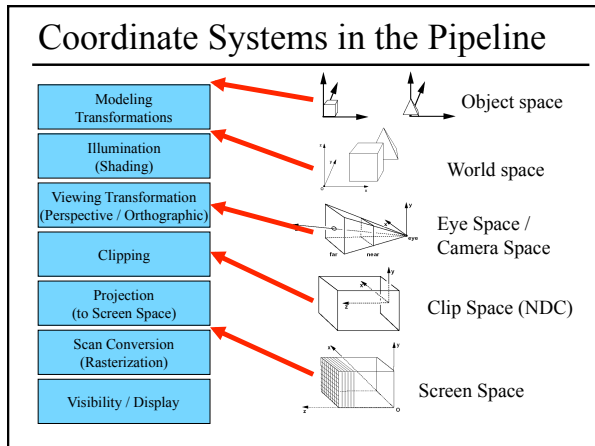
- Avoid degeneracies
 - Don't draw stuff behind the eye
 - Avoid division by 0 and overflow
- Efficiency
 - Don't waste time on objects outside the image boundary
- Other graphics applications (often non-convex)
 - Hidden-surface removal, Shadows, Picking, Binning, CSG (Boolean) operations (2D & 3D)

Clipping Strategies

- Don't clip (and hope for the best)
- Clip on-the-fly during rasterization
- Analytical clipping: alter input geometry

Common Coordinate Systems

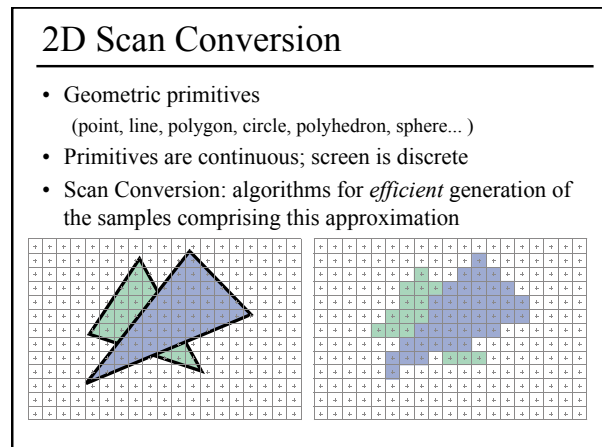
- Object space
 - local to each object
- World space
 - common to all objects
- Eye space / Camera space
 - derived from view frustum
- Clip space / Normalized Device Coordinates (NDC)
 - $[-1,-1,-1] \rightarrow [1,1,1]$
- Screen space
 - indexed according to hardware attributes



Questions?

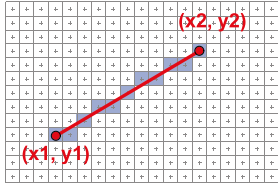
Today

- Ray Casting / Tracing vs. Scan Conversion
- Traditional Graphics Pipeline
- Clipping
- Rasterization/Scan Conversion
 - Line Rasterization
 - Triangle Rasterization



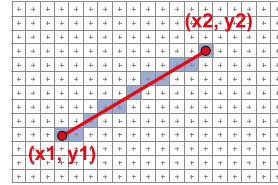
Scan Converting 2D Line Segments

- Given:
 - Segment endpoints (integers $x_1, y_1; x_2, y_2$)
- Identify:
 - Set of pixels (x, y) to display for segment



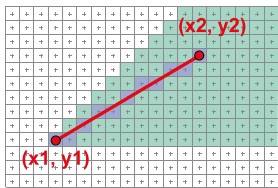
Line Rasterization Requirements

- Transform **continuous** primitive into **discrete** samples
- Uniform thickness & brightness
- Continuous appearance
- No gaps
- Accuracy
- Speed



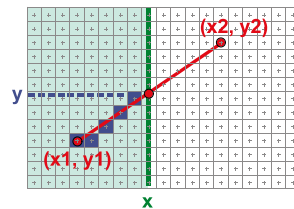
Algorithm Design Choices

- Assume:
 - $m = dy/dx, 0 < m < 1$
- Exactly one pixel per column
 - fewer \rightarrow disconnected, more \rightarrow too thick



Naive Line Rasterization Algorithm

- Simply compute y as a function of x
 - Conceptually: move vertical scan line from x_1 to x_2
 - What is the expression of y as function of x ?
 - Set pixel $(x, \text{round}(y(x)))$



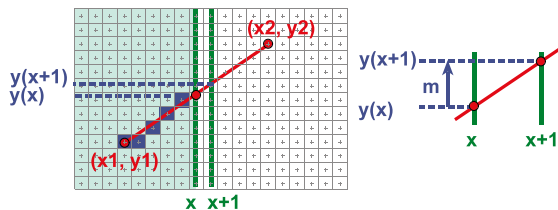
$$y = y_1 + \frac{x - x_1}{x_2 - x_1}(y_2 - y_1)$$

$$= y_1 + m(x - x_1)$$

$$m = \frac{dy}{dx}$$

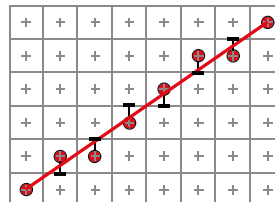
Efficiency

- Computing y value is expensive
 - $y = y_1 + m(x - x_1)$
- Observe: $y += m$ at each x step ($m = dy/dx$)



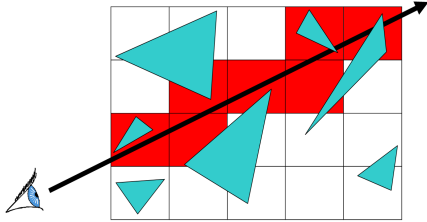
Bresenham's Algorithm (DDA)

- Select pixel vertically closest to line segment
 - intuitive, efficient, pixel center always within 0.5 vertically
- Generalize to handle all eight octants using symmetry
- Can be modified to use only integer arithmetic



Line Rasterization & Grid Marching

- Can be used for ray-casting acceleration
- March a ray through a grid

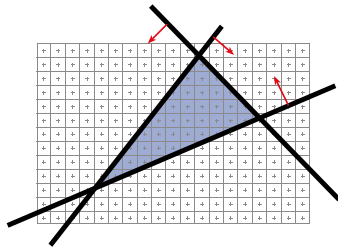


- Collect *all* grid cells, not just 1 per column (or row)

Questions?

Brute force solution for triangles

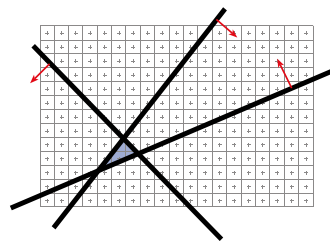
- For each pixel
 - Compute line equations at pixel center
 - “clip” against the triangle



Problem?

Brute force solution for triangles

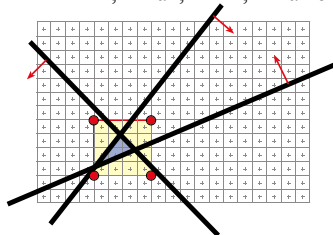
- For each pixel
 - Compute line equations at pixel center
 - “clip” against the triangle



Problem?
If the triangle is small,
a lot of useless
computation

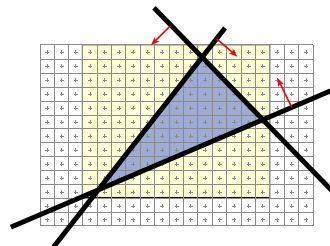
Brute force solution for triangles

- Improvement: Compute only for the *screen bounding box* of the triangle
- How do we get such a bounding box?
 - Xmin, Xmax, Ymin, Ymax of the triangle vertices



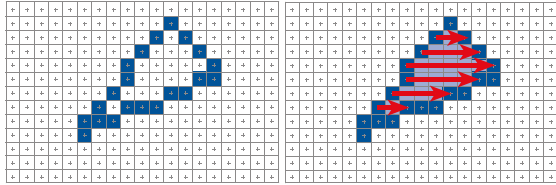
Can we do better? Kind of!

- We compute the line equation for many useless pixels
- What could we do?



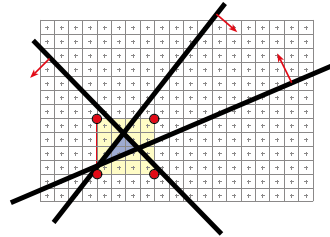
Scan-line Rasterization

- Compute the boundary pixels
- Fill the spans
- Interpolate vertex color along the edges & spans!



But These Days...

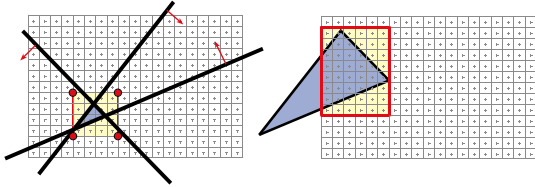
- Triangles are usually very small
- Setup costs are becoming more troublesome
- Clipping is annoying
- Brute force is tractable



Modern Rasterization

```

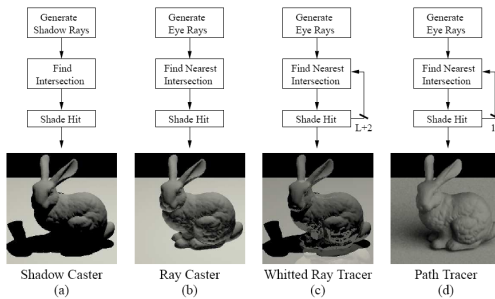
For every triangle
  ComputeProjection
  Compute bbox, clip bbox to screen limits
  For all pixels in bbox
    Compute line equations
    If all line equations > 0 //pixel [x,y] in triangle
      Framebuffer[x,y]=triangleColor
    
```



Questions?

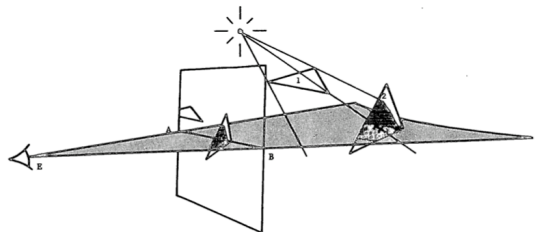
Reading for Friday:

- “Ray Tracing on Programmable Graphics Hardware Purcell”, Buck, Mark, & Hanrahan SIGGRAPH 2002



Reading for Friday: (or before you start HW4)

- “Shadow Algorithms for Computer Graphics”, Frank Crow, SIGGRAPH 1977



Reading for HW4: *(start reading this weekend)*

- “Improving Shadows and Reflections via the Stencil Buffer”, Mark Kilgard, NVIDIA

