

CSCI-1200 Data Structures — Fall 2021

Lecture 23 – Hash Tables, Part 2

Review from Lecture 22 & Lab 12

- “the single most important data structure known to mankind”
- Hash Tables, Hash Functions, and Collision Resolution
- Performance of: Hash Tables vs. Binary Search Trees
- Collision resolution: separate chaining
- Using a hash table to implement a set/map
 - Iterators, find, insert, and erase

Today’s Lecture

- Using STL’s `for_each`
- Something weird & cool in C++... Function Objects, a.k.a. *Functors*
- Hash Tables, part II
 - STL’s `unordered_set` (and `unordered_map`)
 - Hash functions as functors/function objects (or non-type template parameters, or function pointers)
 - Collision resolution: separate chaining vs. open addressing

23.1 Using STL’s `for_each`

- First, here’s a tiny helper function:

```
void float_print (float f) {
    std::cout << f << std::endl;
}
```

- Let’s make an STL vector of floats:

```
std::vector<float> my_data;
my_data.push_back(3.14);
my_data.push_back(1.41);
my_data.push_back(6.02);
my_data.push_back(2.71);
```

- Now we can write a loop to print out all the data in our vector:

```
std::vector<float>::iterator itr;
for (itr = my_data.begin(); itr != my_data.end(); itr++) {
    float_print(*itr);
}
```

- Alternatively we can use it with STL’s `for_each` function to visit and print each element:

```
std::for_each(my_data.begin(), my_data.end(), float_print);
```

Wow! That’s a lot less to type. Can I stop using regular `for` and `while` loops altogether?

- We can actually also do the same thing without creating & explicitly naming the `float_print` function. We create an *anonymous function* using *lambda*:

```
std::for_each(my_data.begin(), my_data.end(), [](float f){ std::cout << f << std::endl; });
```

Lambda is new to the C++ language (part of C++11). But lambda is a core piece of many classic, older programming languages including Lisp and Scheme. Python lambdas and Perl anonymous subroutines are similar. (In fact lambda dates back to the 1930’s, before the first computers were built!) You’ll learn more about lambda more in later courses like CSCI 4430 Programming Languages!

23.2 Function Objects, a.k.a. *Functors*

- In addition to the basic mathematical operators + - * / < > , another operator we can overload for our C++ classes is the *function call operator*.

Why do we want to do this? This allows instances or objects of our class, to be used like functions. It's weird but powerful.

- Here's the basic syntax. Any specific number of arguments can be used.

```
class my_class_name {
public:
    // ... normal class stuff ...
    my_return_type operator() ( /* my list of args */ );
};
```

23.3 Why are Functors Useful?

- One example is the default 3rd argument for `std::sort`. We know that by default STL's sort routines will use the less than comparison function for the type stored inside the container. How exactly do they do that?
- First let's define another tiny helper function:

```
bool float_less(float x, float y) {
    return x < y;
}
```

- Remember how we can sort the `my_data` vector defined above using our own homemade comparison function for sorting:

```
std::sort(my_data.begin(), my_data.end(), float_less);
```

If we don't specify a 3rd argument:

```
std::sort(my_data.begin(), my_data.end());
```

This is what STL does by default:

```
std::sort(my_data.begin(), my_data.end(), std::less<float>());
```

- What is `std::less`? It's a templated class. Above we have called the default constructor to make an instance of that class. Then, that instance/object can be used like it's a function. Weird!
- How does it do that? `std::less` is a teeny tiny class that just contains the overloaded function call operator.

```
template <class T>
class less {
public:
    bool operator() (const T& x, const T& y) const { return x < y; }
};
```

You can use this instance/object/functor as a function that expects exactly two arguments of type T (in this example `float`) that returns a `bool`. That's exactly what we need for `std::sort`! This ultimately does the same thing as our tiny helper homemade compare function (but for any type T)!

23.4 Another more Complicated Functor Example

- Constructors of function objects can be used to specify *internal data* for the functor that can then be used during computation of the function call operator! For example:

```
class between_values {
private:
    float low, high;
public:
    between_values(float l, float h) : low(l), high(h) {}
    bool operator() (float val) { return low <= val && val <= high; }
};
```

- The range between `low` & `high` is specified when a functor/an instance of this class is created. We might have multiple different instances of the `between_values` functor, each with their own range. Later, when the functor is used, the query value will be passed in as an argument. The function call operator accepts that single argument `val` and compares against the internal data `low` & `high`.
- STL has a `find` function that can be used for vectors to find a specific value (it simply loops over the structure using an iterator in $O(n)$ time).

```
std::vector<int>::iterator itr;
itr = std::find(my_data.begin(), my_data.end(), 3);
if (itr != my_data.end()) {
    std::cout << "Yes, the value 3 is in this container." << endl;
}
```

- STL also has a `find_if` construct that we can use with our `between_values` functor. For example:

```
between_values two_and_four(2,4);

if (std::find_if(my_data.begin(), my_data.end(), two_and_four)
    != my_data.end()) {
    std::cout << "Found a value greater than 2 & less than 4!" << std::endl;
}
```

- Alternatively, we could create the functor without giving it a variable name. And in the use below we also capture the return value to print out the first item in the vector inside this range. Note that it does not print all values in the range.

```
std::vector<float>::iterator itr;
itr = std::find_if(my_data.begin(), my_data.end(), between_values(2,4));
if (itr != my_data.end()) {
    std::cout << "my_data contains " << *itr
                << ", a value greater than 2 & less than 4!" << std::endl;
}
```

“Weird Things we can do in C++” Finished – Now back to Hash Tables!

23.5 Hash Table in STL?

- The Standard Template Library standard and implementation of hash table have been slowly evolving over many years. Unfortunately, the names “hashset” and “hashmap” were spoiled by developers anticipating the STL standard, so to avoid breaking or having name clashes with code using these early implementations...
- STL’s agreed-upon standard for hash tables: `unordered_set` and `unordered_map`
- Depending on your OS/compiler, you may need to add the `-std=c++11` flag to the compile line (or other configuration tweaks) to access these more recent pieces of STL. (And this will certainly continue to evolve in future years!)
- For many types STL has a good default hash function, so in those cases you do not need to provide your own hash function. But sometimes we do want to write our own...

23.6 Writing our own Hash Functions or Hash Functors

- Often the programmer/designer for the program using a hash function has the best understanding of the distribution of data to be stored in the hash function. Thus, they are in the best position to define a custom hash function (if needed) for the data & application.
- Here’s an example of a (generically) good hash function for STL strings:

Note: This implementation comes from <http://www.partow.net/programming/hashfunctions/>

```
unsigned int MyHashFunction(std::string const& key) {
    unsigned int hash = 1315423911;
    for(unsigned int i = 0; i < key.length(); i++)
        hash ^= ((hash << 5) + key[i] + (hash >> 2));
    return hash;
}
```

- Alternately, this same string hash code can be written as a functor – which is just a class wrapper around a function, and the function is implemented as the overloaded function call operator for the class.

```
class MyHashFunctor {
public:
    unsigned int operator() (std::string const& key) const {
        unsigned int hash = 1315423911;
        for(unsigned int i = 0; i < key.length(); i++)
            hash ^= ((hash << 5) + key[i] + (hash >> 2));
        return hash;
    }
};
```

- Once our new type containing the hash function is defined, we can create instances of our hash set object containing `std::string` by specifying the type `MyHashFunctor` as the second template parameter to the declaration of a `ds_hashset`. E.g.,

```
ds_hashset<std::string, MyHashFunctor> my_hashset;
```

23.7 Using STL's Associative Hash Table (Unordered Map)

- Using the default `std::string` hash function.
 - With no specified initial table size.


```
std::unordered_map<std::string, Foo> m;
```
 - Optionally specifying initial (minimum) table size.


```
std::unordered_map<std::string, Foo> m(1000);
```
- Using a home-made `std::string` hash function. Note: We are required to specify the initial table size.
 - Manually specifying the hash function type.


```
std::unordered_map<std::string, Foo, std::function<unsigned int(std::string)>> >
    m(1000, MyHashFunction);
```
 - Using the `decltype` specifier to get the “declared type of an entity”.


```
std::unordered_map<std::string, Foo, decltype(&MyHashFunction)>
    m(1000, MyHashFunction);
```
- Using a home-made `std::string` hash functor or function object.
 - With no specified initial table size.


```
std::unordered_map<std::string, Foo, MyHashFunctor> m;
```
 - Optionally specifying initial (minimum) table size.


```
std::unordered_map<std::string, Foo, MyHashFunctor> m(1000);
```
- Note: In the above examples we're creating an association between two types (STL strings and custom `Foo` object). If you'd like to just create a set (no associated 2nd type), simply switch from `unordered_map` to `unordered_set` and remove the `Foo` from the template type in the examples above.

23.8 How do we Resolve Collisions? METHOD 1: Separate Chaining

NOTE: We used this method in the last lecture & in lab!

- Each table location stores a linked list of keys (and values) hashed to that location. Thus, the hashing function really just selects which list to search or modify.
- This works well when the number of items stored in each list is small, e.g., an average of 1. Other data structures, such as binary search trees, may be used in place of the list, but these have even greater overhead considering the (hopefully, very small) number of items stored per bin.

23.9 How do we Resolve Collisions? METHOD 2: Open Addressing

- Let's eliminate the individual memory allocations and pointer indirection / dereferencing that are necessary for separate chaining. This will improve memory / data access performance.
- We will directly store the data (key/key-value pair) in the the top level vector, and store at most one item per index/location.
- When the chosen table index/location already stores a key (or key-value pair), we will seek a different table location to store the new value (or pair).
- Here are three different open addressing variations to handle a collision during an *insert* operation:
 - *Linear probing*: If i is the chosen hash location then the following sequence of table locations is tested (“probed”) until an empty location is found:

$(i+1)\%N, (i+2)\%N, (i+3)\%N, \dots$

- *Quadratic probing*: If i is the hash location then the following sequence of table locations is tested:

$(i+1)\%N, (i+2^2)\%N, (i+3^2)\%N, (i+4^2)\%N, \dots$

More generally, the j^{th} “probe” of the table is $(i + c_1j + c_2j^2) \bmod N$ where c_1 and c_2 are constants.

- *Secondary hashing*: When a collision occurs a second hash function is applied to compute a new table location. If that location is also full, we go to a third hash function, etc. This is repeated until an empty location is found.

We can generate a sequence/family of hash functions by swapping in a fixed random-like sequence of constant values (e.g., big primes) into the same general function structure.

- For each of these approaches, the *find* operation follows the same sequence of locations as the *insert* operation. The key value is determined to be absent from the table only when an empty location is found.
- When using open addressing to resolve collisions, the *erase* function must mark a location as “formerly occupied”. If a location is instead marked empty (“never occupied”), *find* may fail to return elements that are actually in the table.
- When using open addressing it is critical to monitor *how full* the table is – specifically the counts of “currently occupied”, “formerly occupied”, and “never occupied” locations.

Formerly-occupied locations may (and should) be reused, but only after the *find* search operation has been run to completion (either finding the element or encountering a “never occupied” location) to determine the item is definitely not in the table.

- Hash table performance degrades when the sum of counts of currently and formerly occupied cells is high (e.g., greater than 80%).
- These operations will fail completely if the table is full (no “never occupied” locations remain).
- For performance critical applications, it is helpful to run benchmark tests with real-world data (number of insert/find/erase operations, typical values, specific hash function, actual hardware, etc.) to determine the optimal table size and capacity threshold to balance memory usage and running time.

Determine when to *resize* the table – increase (or decrease) the table size to better fit the number of values currently held in the table. Or only *groom* the data – recreate the table at the current size, and re-insert all values so all *formerly occupied* labels can be cleared.

A maximum allowed hash table load factor as low as 50% or 60% might be appropriate for some applications.

23.10 Collision Resolution: Separate Chaining vs. Open Addressing – Discussion

- Advantages of open addressing over separate chaining:
 - No linked lists! No pointers! It's faster! (Indirect memory accesses are slow!)
- Problems with open addressing:
 - Memory cache performance can be poor when we are jumping around unpredictably in the top level array.
 - Cost of computing new hash values (linear < quadratic < secondary hashing).
 - Capacity and performance must be closely monitored. Expensive re-sizing and grooming may be necessary.
 - Careful testing and parameter tuning is necessary to achieve optimal memory/speed performance.