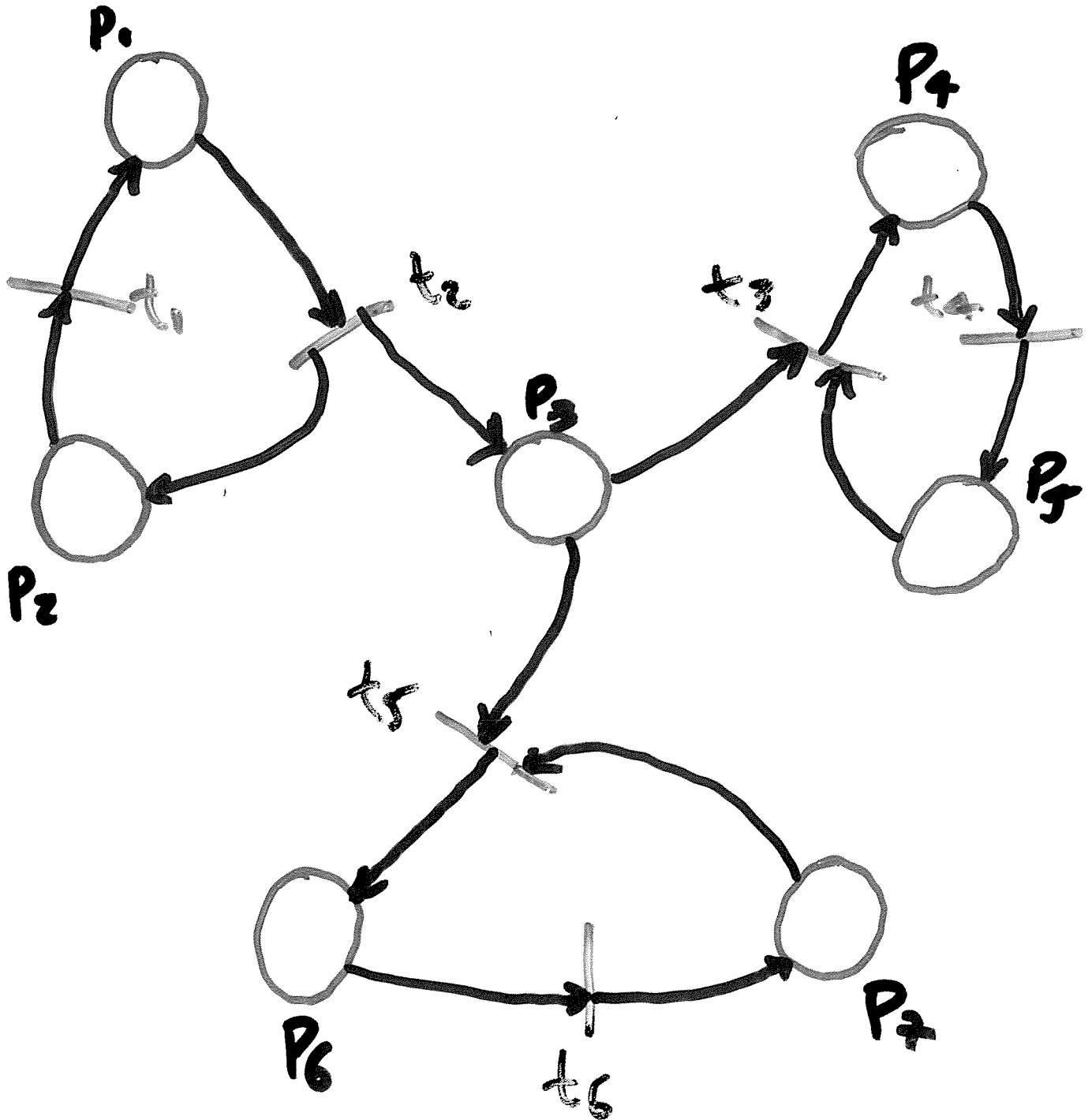


# PETRI NETS

- A formal model of information flow.
- Used for modeling systems of parallel or concurrent activities.
- Created by Carl A. Petri in 1962.
- Graphs with two types of nodes: places and transitions.

# PETRI NETS -- AN EXAMPLE



# PETRI NET STRUCTURE

-- EXAMPLE

$$C = (P, T, I, O)$$

$$P = \{P_1, P_2, P_3, P_4, P_5, P_6, P_7\}$$

$$T = \{t_1, t_2, t_3, t_4, t_5, t_6\}$$

$$I(t_1) = \{P_2\}$$

$$O(t_1) = \{P_1\}$$

$$I(t_2) = \{P_1\}$$

$$O(t_2) = \{P_2, P_3\}$$

$$I(t_3) = \{P_3, P_5\}$$

$$O(t_3) = \{P_4\}$$

$$I(t_4) = \{P_4\}$$

$$O(t_4) = \{P_5\}$$

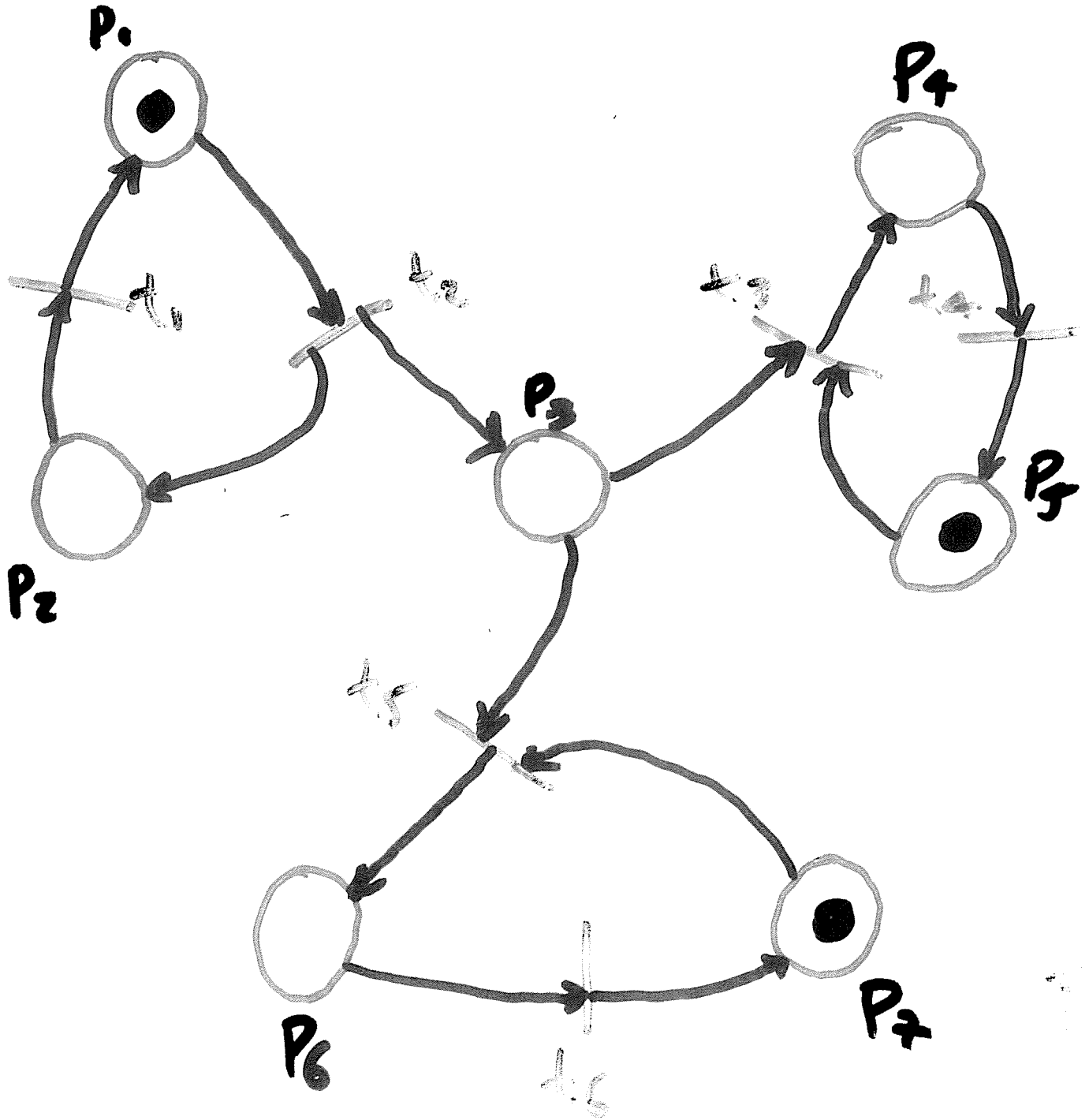
$$I(t_5) = \{P_3, P_7\}$$

$$O(t_5) = \{P_6\}$$

$$I(t_6) = \{P_6\}$$

$$O(t_6) = \{P_7\}$$

# MARKED PETRI NETS -- AN EXAMPLE



$P_1, P_5, P_7$  each has a token.

# PETRI NET COMPUTATION

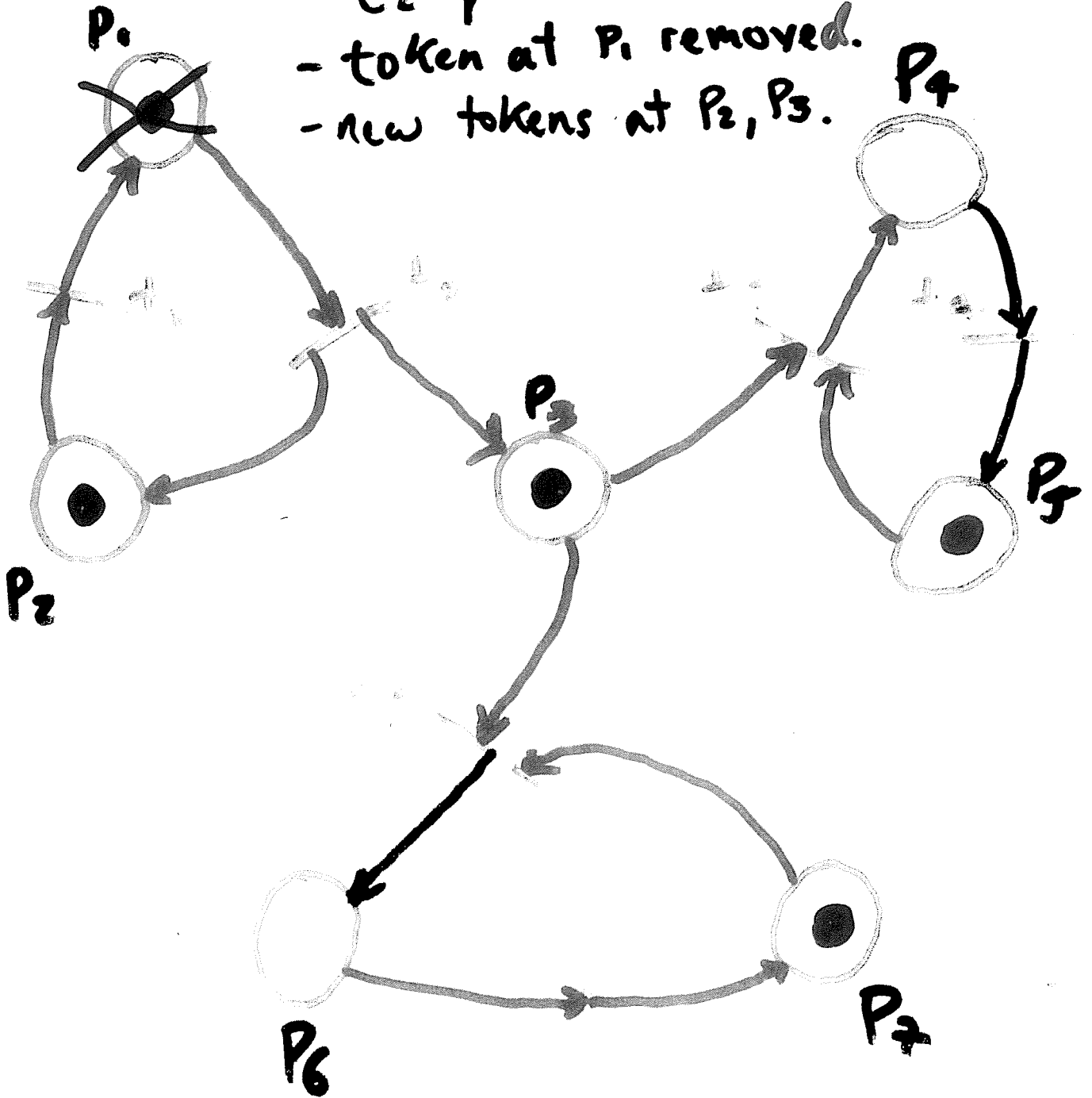
- Tokens are moved by the firing of the transitions of the net.
- A transition must be enabled in order to fire.

A transition is enabled when all of its input places have a token in them.

- The transition fires by removing tokens from input places & generating tokens in output places.

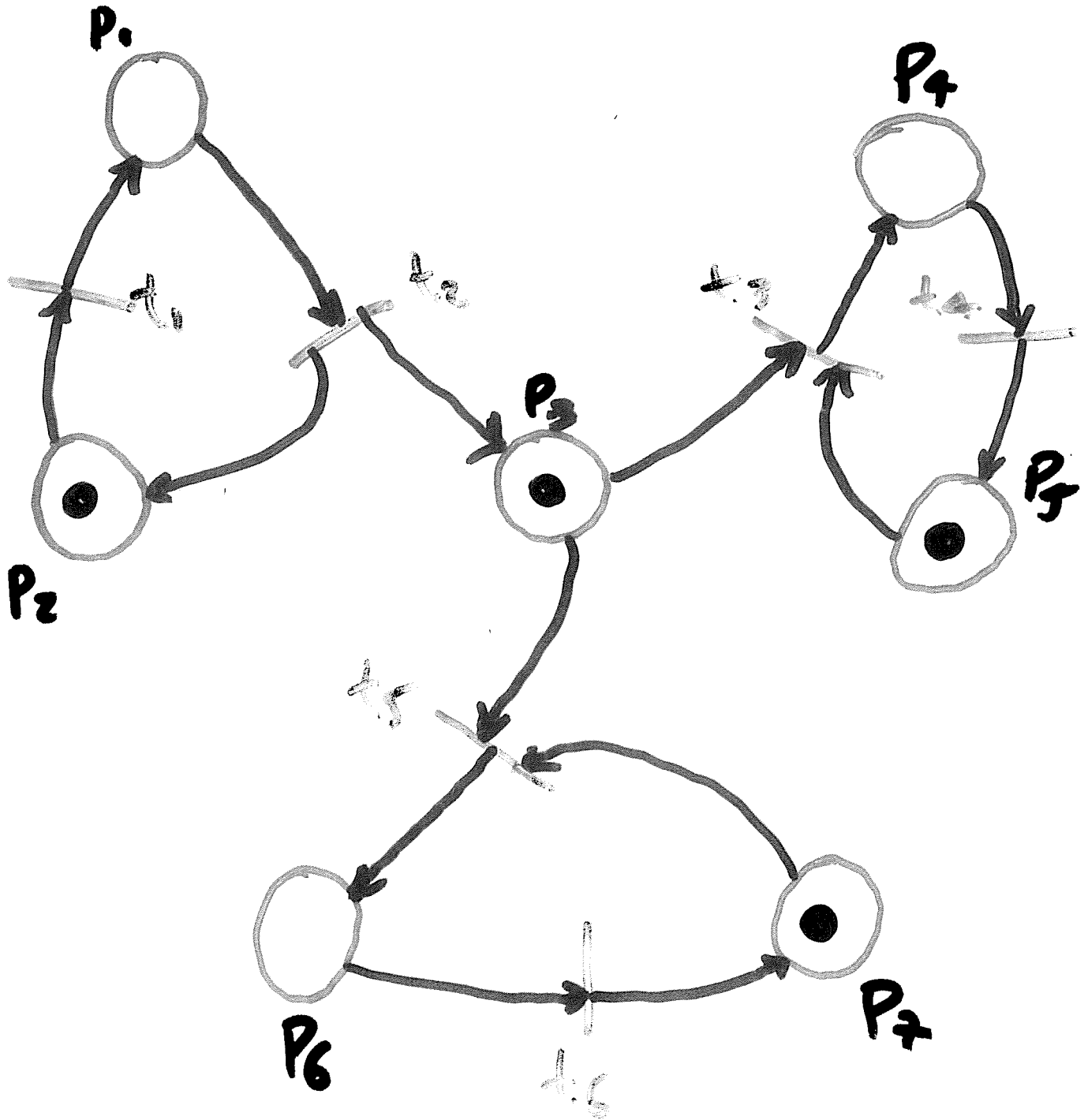
# MARKED PETRI NETS -- AN EXAMPLE COMPUTATION

- $t_2$  fires.
- token at  $P_1$  removed.
- new tokens at  $P_2, P_3$ .



$P_1, P_5, P_7$  each has a token.

# PETRI NETS -- AN EXAMPLE COMPUTATION CONTINUED.



# PETRI NET MARKINGS

A marking  $\mu$  of a Petri net is an assignment of tokens to the places in that net.

The vector  $\mu = (\mu_1, \mu_2, \dots, \mu_n)$  gives for each place in the Petri net, the number of tokens in that place.  $\mu$  can be seen as a function, s.t.  $\mu(P_i) = \mu_i$

## EXAMPLE

$$\mu = (1, 0, 0, 0, 1, 0, 1)$$

Before

$$\mu' = (0, 1, 1, 0, 1, 0, 1)$$

After transition.



# MARKED PETRI NET STRUCTURE

A Petri net  $C = (P, T, I, O)$   
with a marking  $\mu$  becomes  
the marked Petri net

$$M = (P, T, I, O, \mu)$$

Since number of tokens is unbounded,  
there is a denumerable infinite  
number of markings for a Petri net.

# STATE SPACE OF A PETRI NET

For a Petri net  $\mathcal{P}$  with  $n$  places, the state space is the set of all possible markings, i.e.  $\mathbb{N}^n$ .

The next-state function is a partial function  $\delta$ , defined for enabled transitions  $t_j$  in a marking  $\mu$ , s.t.

$$\delta(\mu, t_j) = \mu'$$

where  $\mu'$  is the marking resulting from firing the transition.

# TRANSITION SEQUENCES

- To record a Petri net execution, we use a sequence of markings:

$$(\mu_0^0, \mu_0^1, \mu_0^2, \dots)$$

and a sequence of transitions:

$$(t_{j_0}, t_{j_1}, t_{j_2}, \dots)$$

such that:

$$\delta(\mu^k, t_{j_k}) = \mu^{k+1} \text{ for } k=0,1,2,\dots$$

# EXAMPLE OF TRANSITION SEQUENCE

$(t_2, t_1, t_3, \dots)$

$$\mu^0 = (1, 0, 0, 0, 1, 0, 1)$$

$$\mu^1 = (0, 1, 1, 0, 1, 0, 1)$$

$$\mu^2 = (1, 0, 1, 0, 1, 0, 1)$$

$$\mu^3 = (1, 0, 0, 1, 0, 0, 1)$$

$$j_0 = 2, j_1 = 1, j_2 = 3, \dots$$

$$\delta(\mu^0, t_2) = \mu^1$$

$$\delta(\mu^1, t_1) = \mu^2$$

$$\delta(\mu^2, t_3) = \mu^3$$

and so on.

# REACHABILITY SET OF A PETRI NET

-  $\mu'$  is immediately reachable

from  $\mu$  if

$$\exists t \in T, \text{ s.t. } \delta(\mu, t) = \mu'$$

(if we can fire some enabled transition in  $\mu$  resulting in  $\mu'$ .)

-  $\mu'$  is reachable from  $\mu$  if it is immediately reachable from  $\mu$  or it is reachable from any marking immediately reachable from  $\mu$ .

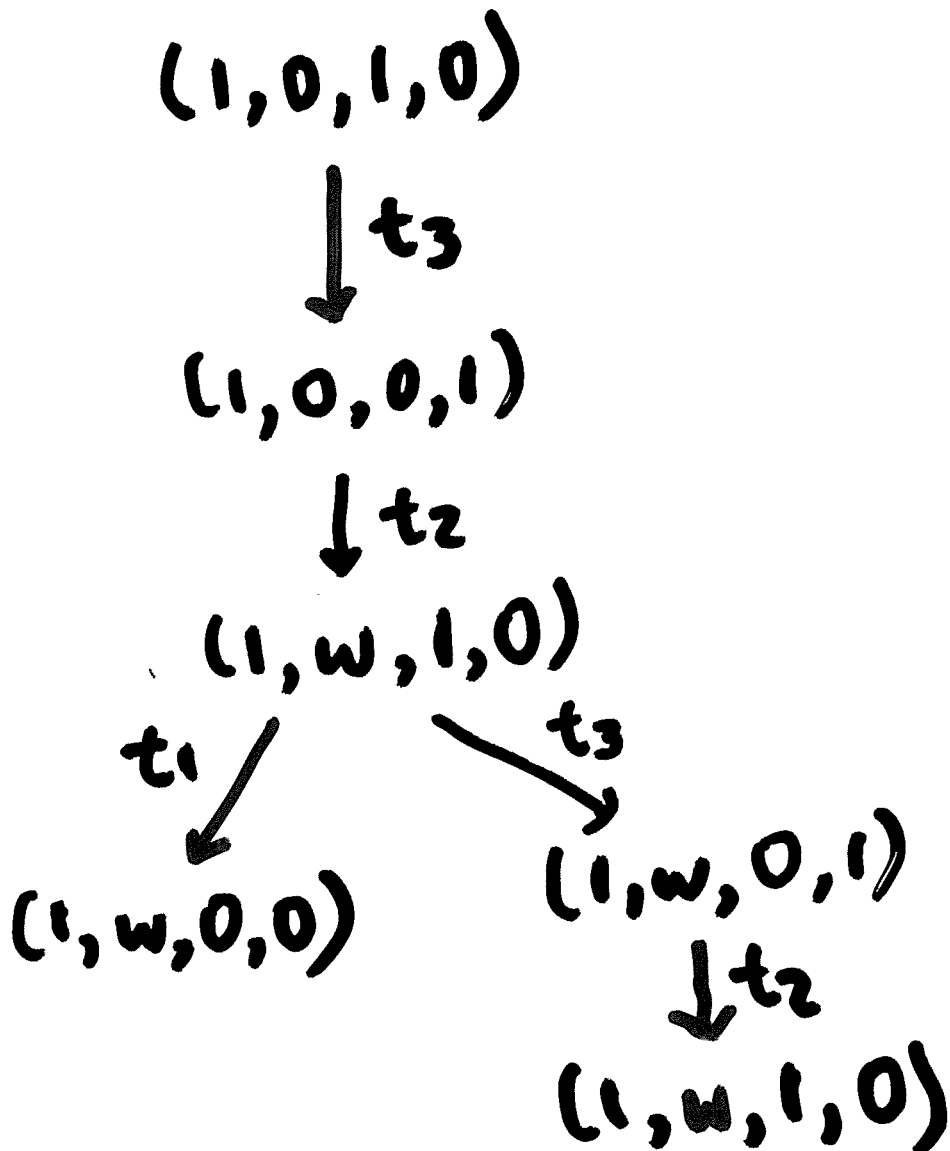
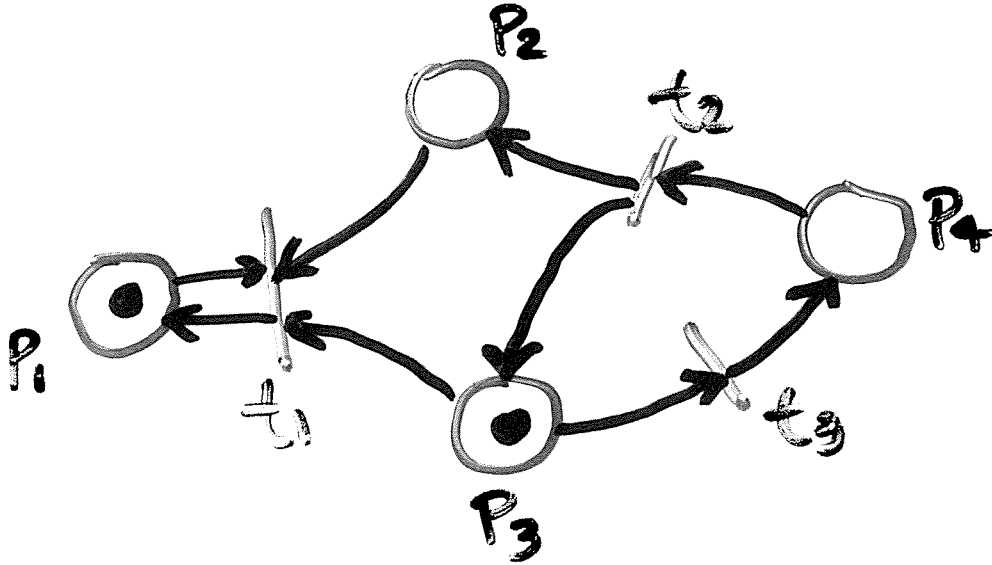
(reflexive transitive closure of immediately reachable)

-  $R(\mu)$  is set of all reachable markings. (13)

# REACHABILITY TREE OF PETRI NETS

- Since often reachability set is infinite, the symbol  $\omega$  is used to represent an arbitrarily large number of tokens.
- The reachability tree contains nodes representing markings, and links representing transitions.

# REACHABILITY TREE EXAMPLE



# A SEMAPHORE MODELING EXAMPLE

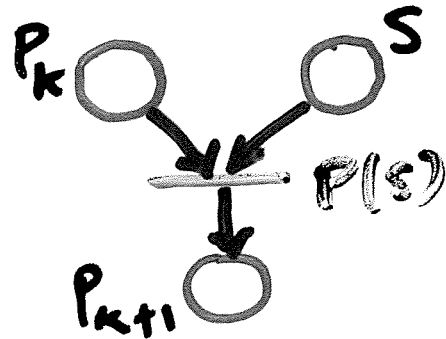
Process 1

P(mutex);  
"Critical Section";  
V(mutex);

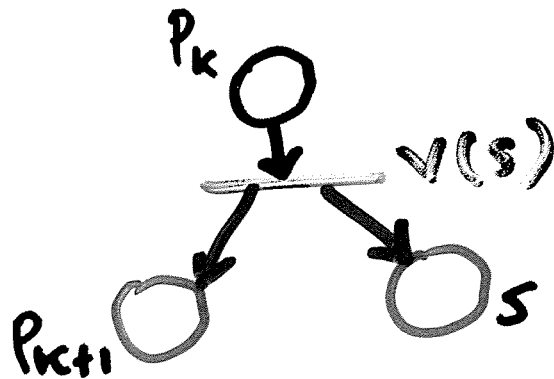
Process 2

P(mutex);  
"Critical Section";  
V(mutex);

P operation

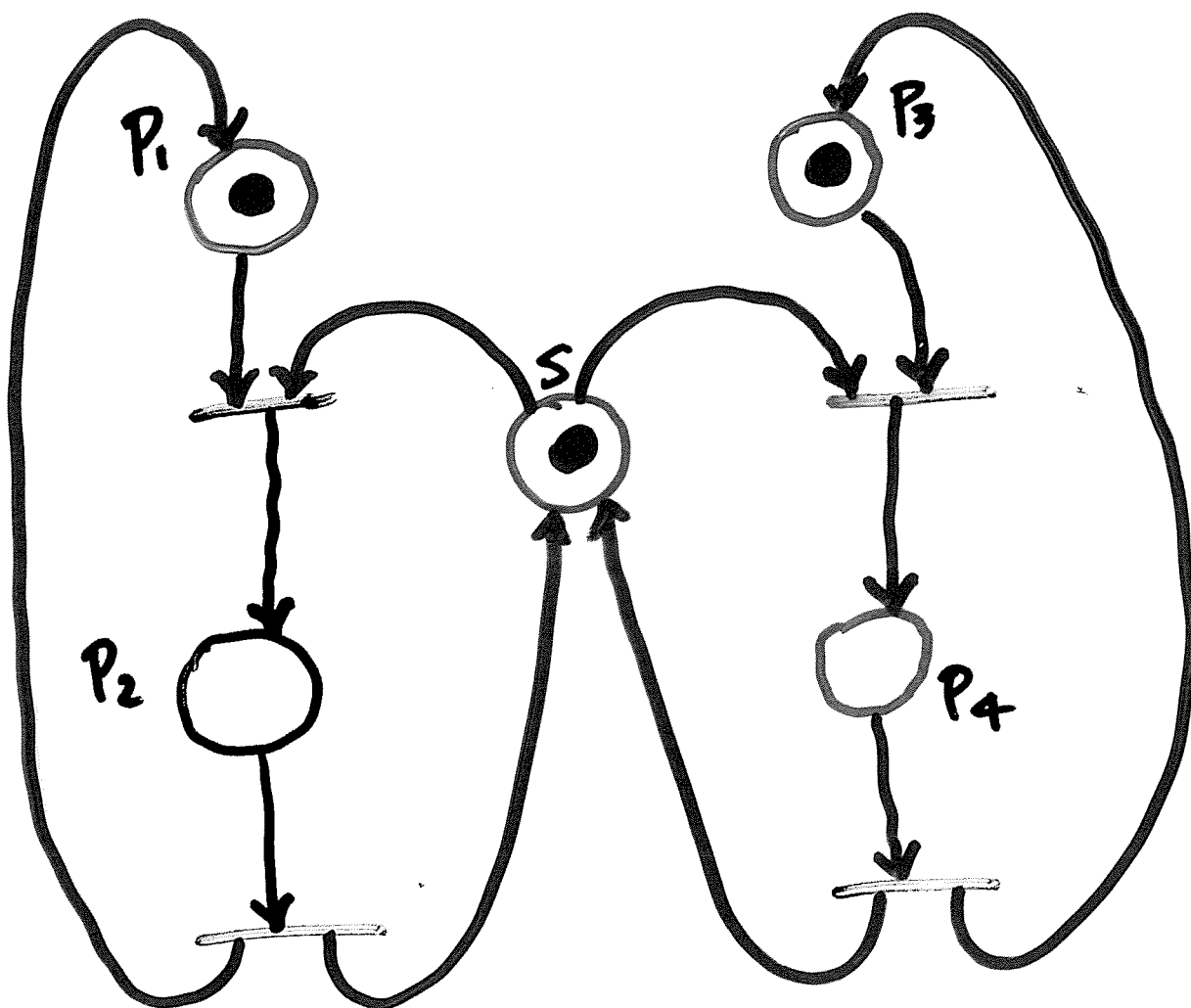


V operation





# MUTUAL EXCLUSION USING A SEMAPHORE



# PETRI NETS AS SYSTEM DESCRIPTIONS

- Atomic (local) states/places conditions P
- Atomic (local) transitions events T

$$P \cap T = \emptyset \quad (\text{disjoint sets})$$

- Distributed (global) state case  
set of conditions holding concurrently
- Distributed (global) transition step  
set of events occurring concurrently
- Transition relation  
specifies how cases are transformed into cases by the occurrence of steps