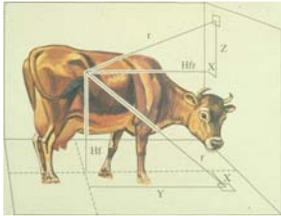


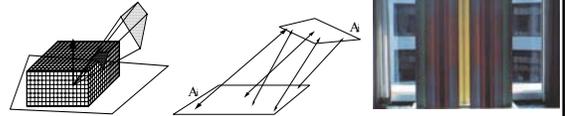
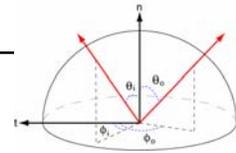
The Rendering Equation & Radiosity II



An early application of radiative heat transfer in stables.

Last Time?

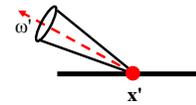
- Local Illumination
 - BRDF
 - Ideal Diffuse Reflectance
 - Ideal Specular Reflectance
 - The Phong Model
- Radiosity Equation/Matrix
- Calculating the Form Factors



Today

- **The Rendering Equation**
- Radiosity Equation/Matrix
- Advanced Radiosity
 - Progressive Radiosity
 - Adaptive Subdivision
 - Discontinuity Meshing
 - Hierarchical Radiosity

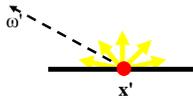
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

$L(x', \omega')$ is the radiance from a point on a surface in a given direction ω'

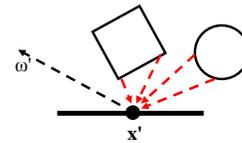
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

$E(x', \omega')$ is the emitted radiance from a point: E is non-zero only if x' is emissive (a light source)

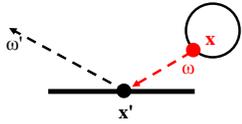
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_r(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

Sum the contribution from all of the other surfaces in the scene

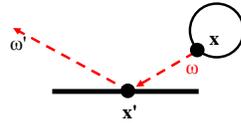
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

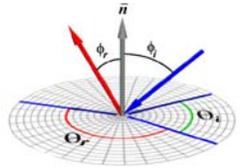
For each x, compute $L(x, \omega)$, the radiance at point x in the direction ω (from x to x')

The Rendering Equation

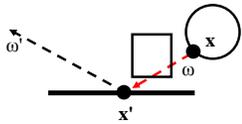


$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

scale the contribution by $\rho_x(\omega, \omega')$, the reflectivity (BRDF) of the surface at x'



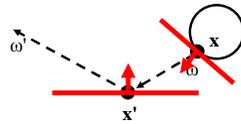
The Rendering Equation



$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

For each x, compute $V(x, x')$, the visibility between x and x': 1 when the surfaces are unobstructed along the direction ω , 0 otherwise

The Rendering Equation

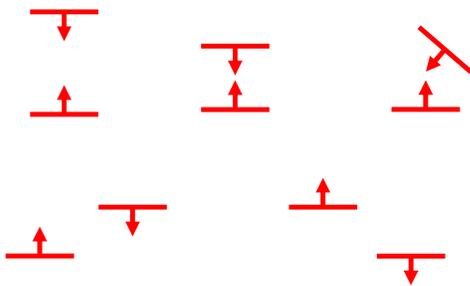


$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

For each x, compute $G(x, x')$, which describes the on the geometric relationship between the two surfaces at x and x'

Intuition about $G(x, x')$?

- Which arrangement of two surfaces will yield the greatest transfer of light energy? Why?



Questions?



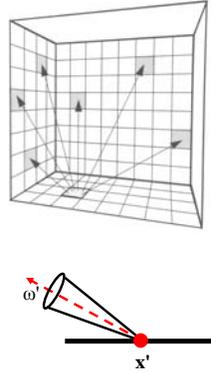
Lightscape <http://www.lightscape.com>

Today

- The Rendering Equation
- Radiosity Equation/Matrix
- Advanced Radiosity
 - Progressive Radiosity
 - Adaptive Subdivision
 - Discontinuity Meshing
 - Hierarchical Radiosity

Radiosity Overview

- Surfaces are assumed to be perfectly Lambertian (diffuse)
 - reflect incident light in all directions with equal intensity
- The scene is divided into a set of small areas, or patches.
- The radiosity, B_i , of patch i is the total rate of energy leaving a surface. The radiosity over a patch is constant.
- Units for radiosity: Watts / steradian * meter²

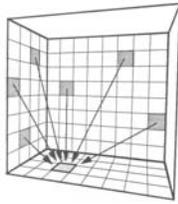


Radiosity Equation

$$L(x', \omega') = E(x', \omega') + \int \rho_x(\omega, \omega') L(x, \omega) G(x, x') V(x, x') dA$$

Radiosity assumption:
perfectly diffuse surfaces (not directional)

$$B_{x'} = E_{x'} + \rho_{x'} \int B_x G(x, x') V(x, x')$$



Continuous Radiosity Equation



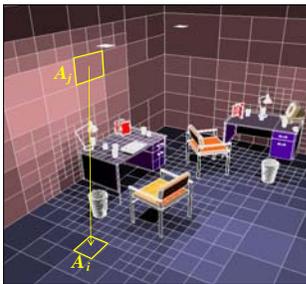
$$B_{x'} = E_{x'} + \rho_{x'} \int \underbrace{G(x, x') V(x, x')}_{\text{form factor}} B_x$$

G: geometry term
V: visibility term

No analytical solution, even for simple configurations

Discrete Radiosity Equation

Discretize the scene into n patches, over which the radiosity is constant



$$B_i = E_i + \rho_i \sum_{j=1}^n F_{ij} B_j$$

- discrete representation
- iterative solution
- costly geometric/visibility calculations

The Radiosity Matrix

$$B_i = E_i + \rho_i \sum_{j=1}^n F_{ij} B_j$$

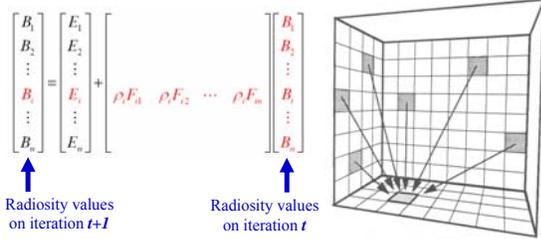
n simultaneous equations with n unknown B_i values can be written in matrix form:

$$\begin{bmatrix} 1 - \rho_1 F_{11} & -\rho_1 F_{12} & \cdots & -\rho_1 F_{1n} \\ -\rho_2 F_{21} & 1 - \rho_2 F_{22} & & \\ \vdots & & \ddots & \\ -\rho_n F_{n1} & \cdots & \cdots & 1 - \rho_n F_{nn} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} E_1 \\ E_2 \\ \vdots \\ E_n \end{bmatrix}$$

A solution yields a single radiosity value B_i for each patch in the environment, a view-independent solution.

Solving the Radiosity Matrix

The radiosity of a single patch i is updated for each iteration by *gathering* radiosities from all other patches:



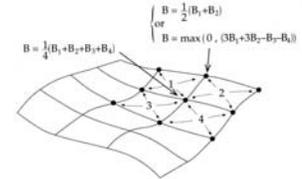
This method is fundamentally a Gauss-Seidel relaxation

Computing Vertex Radiosities

- B_i radiosity values are constant over the extent of a patch.
- How are they mapped to the vertex radiosities (intensities) needed by the renderer?



- Average the radiosities of patches that contribute to the vertex
- Vertices on the edge of a surface are assigned values extrapolation



Questions?

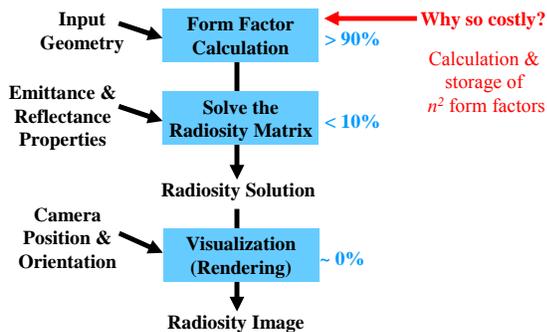


Factory simulation. Program of Computer Graphics, Cornell University. 30,000 patches.

Today

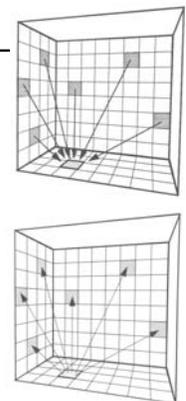
- The Rendering Equation
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Stages in a Radiosity Solution



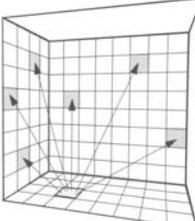
Progressive Refinement

- Goal: Provide frequent and timely updates to the user during computation
- Key Idea: Update the entire image at every iteration, rather than a single patch
- How? Instead of summing the light received by one patch, distribute the radiance of the patch with the most *undistributed radiance*.



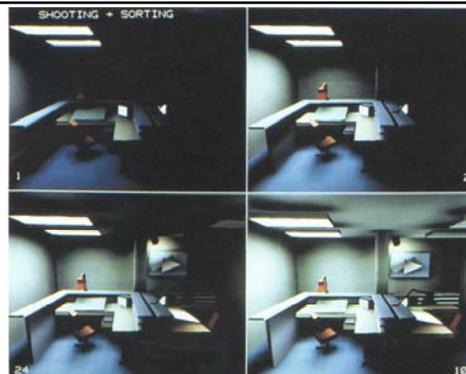
Reordering the Solution for PR

Shooting: the radiosity of all patches is updated for each iteration:

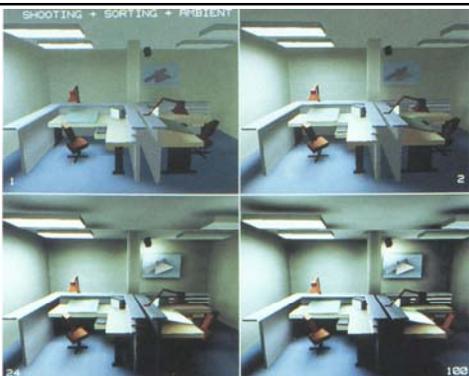
$$\begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} = \begin{bmatrix} B_1 \\ B_2 \\ \vdots \\ B_n \end{bmatrix} + \begin{bmatrix} \dots & \rho_1 F_{1i} & \dots \\ \dots & \rho_2 F_{2i} & \dots \\ \vdots & \vdots & \vdots \\ \dots & \rho_n F_{ni} & \dots \end{bmatrix} \begin{bmatrix} \vdots \\ B_i \\ \vdots \end{bmatrix}$$


This method is fundamentally a Southwell relaxation

Progressive Refinement w/out Ambient Term



Progressive Refinement with Ambient Term



Questions?



Lightscape <http://www.lightscape.com>

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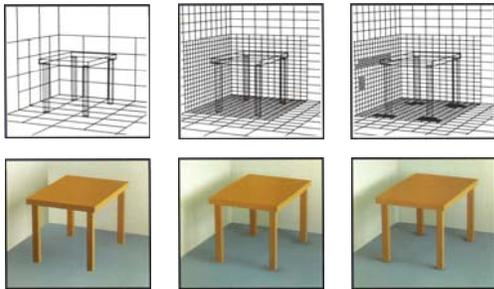
Increasing the Accuracy of the Solution

What's wrong with this picture?



- Image quality is a function of patch size
- Compute a solution on a uniform initial mesh, then refine the mesh in areas that exceed some error tolerance:
 - shadow boundaries
 - other areas with a high radiosity gradient

Adaptive Subdivision of Patches



Coarse patch solution
(145 patches)

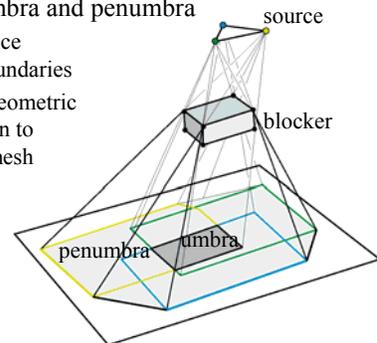
Improved solution
(1021 subpatches)

Adaptive subdivision
(1306 subpatches)

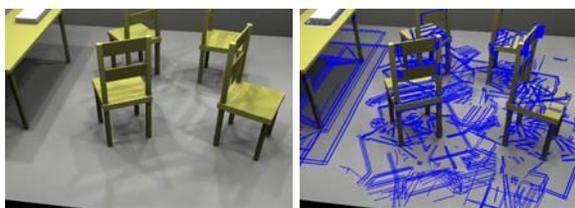
Discontinuity Meshing

- Limits of umbra and penumbra

- Captures nice shadow boundaries
- Complex geometric computation to construct mesh



Discontinuity Meshing

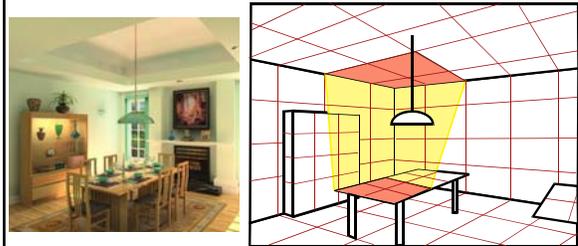


“Fast and Accurate Hierarchical Radiosity Using Global Visibility”
Durand, Drettakis, & Puech 1999

Hierarchical Radiosity

- Group elements when the light exchange is not important

- Breaks the quadratic complexity
- Control non trivial, memory cost



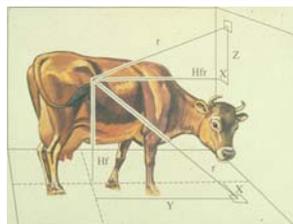
Practical Problems with Radiosity

- Meshing

- memory
- robustness

- Form factors

- computation



Cow-cow form factor?

- Diffuse limitation

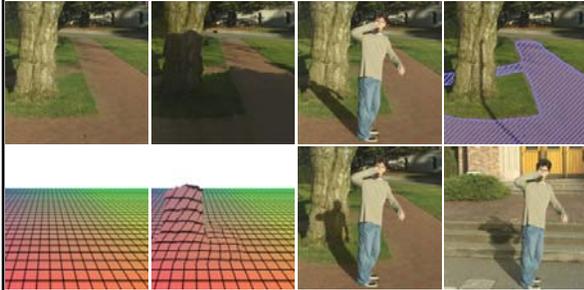
- extension to specular takes too much memory

Questions?



Lightscape <http://www.lightscape.com>

Reading for Today:



Chuang, Goldman, Curless, Salesin, & Szeliski
Shadow Matting and Compositing
SIGGRAPH 2003

Reading for Tuesday 3/20:

Lokovic and Veach
Deep Shadow Maps
SIGGRAPH 2000



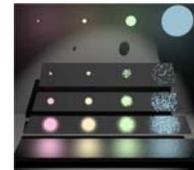
Shadows are important!



Local illumination only

Reading for Friday 3/23:

Veach & Guibas
"Optimally Combining
Sampling Techniques for
Monte Carlo Rendering"
SIGGRAPH 95



Sampling the light source



Sampling the BRDF