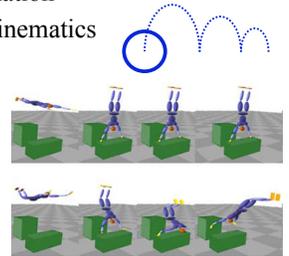
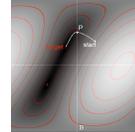
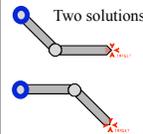


# Rigid Body Dynamics, Fracture, & Deformation

## Last Time?

- Keyframing
- Procedural Animation
- Physically-Based Animation
- Forward and Inverse Kinematics
- Motion Capture



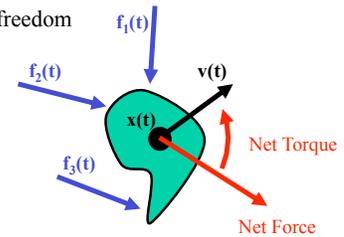
## Today

- Rigid Body Dynamics
- Finite Element Method
- Deformation
- Fracture

## Rigid Body Dynamics

- Could use particles for all points on the object
  - But rigid body does not deform
  - Few degrees of freedom

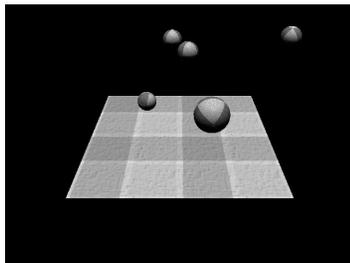
- Use only one particle at the center of mass
- Compute Net Force & Net Torque



Nice Reference Material: <http://www.pixar.com/companyinfo/research/pbm2001/>  
<http://www.myphysicslab.com/collision.html>

## Rigid Body Dynamics

- Physics
  - Velocity
  - Acceleration
  - Angular Momentum
- Collisions
- Friction

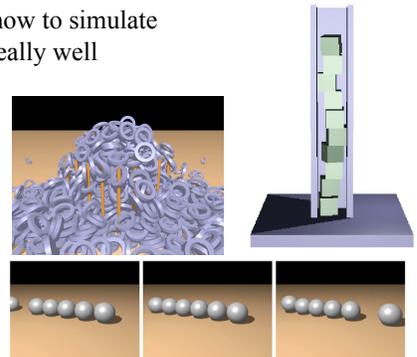


from: Darren Lewis  
<http://www-cs-students.stanford.edu/~dalewis/cs448a/rigidbody.html>

## Collisions

Victor J. Milenkovic & Harald Schmidl  
*Optimization-Based Animation*  
 SIGGRAPH 2001

- We know how to simulate bouncing really well
- But resting collisions are harder to manage



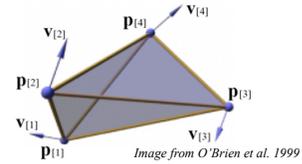
Guendelman, Bridson & Fedkiw  
*Nonconvex Rigid Bodies with Stacking*  
 SIGGRAPH 2003

## Today

- Rigid Body Dynamics
- **Finite Element Method**
- Deformation
- Fracture

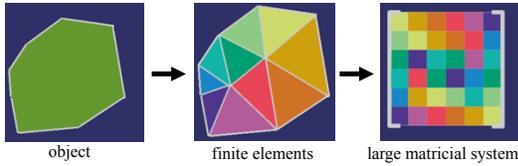
## Simulation of Non-Rigid Objects

- We modeled string & cloth using mass-spring systems. Can we do the same?
- Yes...
- But a more physically accurate model uses *volumetric elements*:



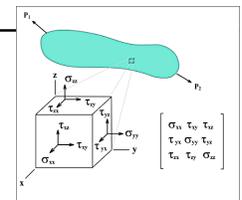
## Finite Element Method

- To solve the continuous problem (deformation of all points of the object)
  - Discretize the problem
  - Express the interrelationship
  - Solve a big linear system
- More principled than Mass-Spring



## Strain & Stress

- Stress
  - the internal distribution of forces within a body that balance and react to the loads applied to it
  - *normal stress & shear stress*
- Strain
  - material deformation caused by stress.
  - measured by the change in length of a line or by the change in angle between two lines



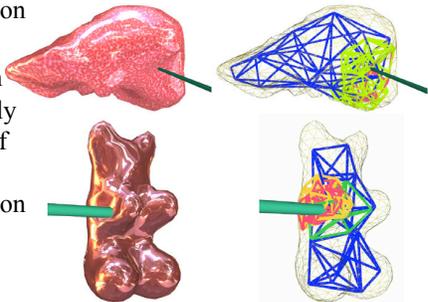
$$\epsilon = \frac{\Delta l}{l_0}$$

## Today

- Rigid Body Dynamics
- Finite Element Method
- **Deformation**
- Fracture

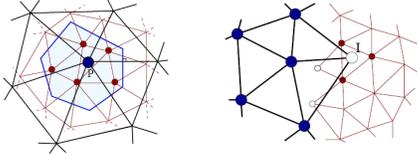
## Level of Detail

- Interactive shape deformation
- Use high-resolution model only in areas of extreme deformation



## Multi-Resolution Deformation

- Use Voronoi diagrams to match parent & child vertices.
- Interpolate values for inactive interface vertices from active parent/child vertices

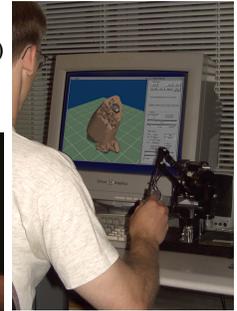


- *Need to avoid interference of vibrations between simulations at different resolutions*

Debonne et al. "Dynamic Real-Time Deformations using Space & Time Adaptive Sampling", 2001

## Haptic Device

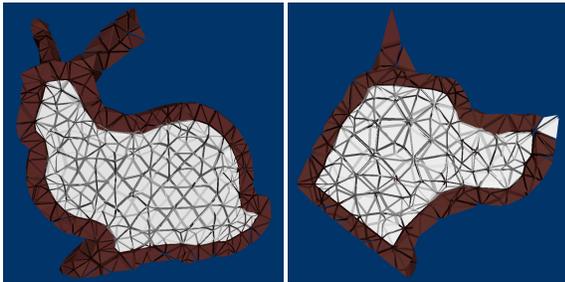
- "3D mouse" + force feedback
- 6 DOF (position & orientation)
- *requires 1000 Hz refresh (visual only requires ~30 Hz)*



Sensable's Phantom  
<http://www.sensable.com/>

## Multiple Materials

Mueller, Dorsey, McMillan,  
 Jagnow, & Cutler  
*Stable Real-Time Deformations*  
 Symposium on Computer  
 Animation 2002



## Tree Stump



Images from Cutler et al. 2002

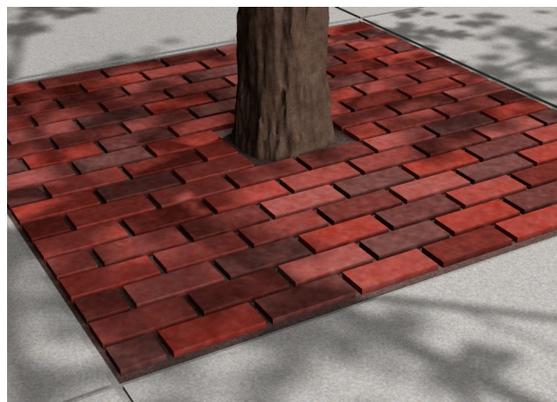


Image from Cutler et al. 2002



Image from Cutler et al. 2002

## Today

- Rigid Body Dynamics
- Finite Element Method
- Deformation
- **Fracture**

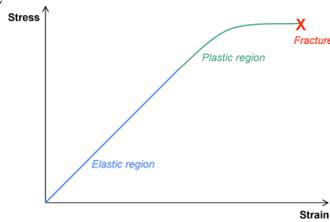
## Some Definitions

- *Isotropic*: is a property which does not depend on the direction.
- *Anisotropic*: is a property which is directionally dependent.



## Some Definitions

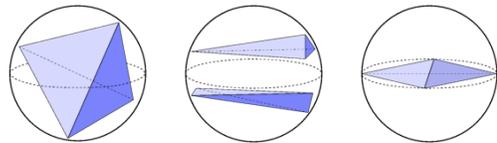
- *Elastic Deformation*: Once the forces are no longer applied, the object returns to its original shape.
- *Plastic Deformation*: An object in the plastic deformation range will first have undergone elastic deformation, which is reversible, so the object will return part way to its original shape.



<http://en.wikipedia.org/wiki/Image:Stress-strain1.png>

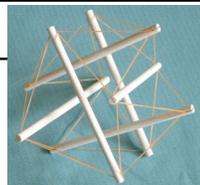
## Some Definitions

- *Degenerate/Ill-conditioned Element*: a.k.a. how “equilateral” are the elements?
  - Ratio of volume<sup>2</sup> to surface area<sup>3</sup>
  - Smallest *solid* angle
  - Ratio of volume to volume of smallest circumscribed sphere



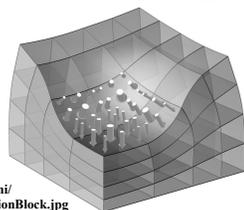
## Some Definitions

- *Tension*: The direction of the force of tension is parallel to the string, away from the object exerting the stretching force.



<http://fig.cox.miami.edu/~cmallery/258/255chem/tensegrity.sticks.jpg>

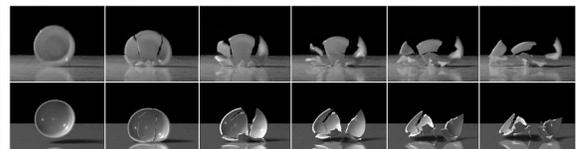
- *Compression*: resulting in reduction of volume



<http://www.aero.polimi.it/~merlini/SolidMechanics-FiniteElasticity/CompressionBlock.jpg>

## Reading for Today:

- James O'Brien & Jessica Hodgins “*Graphical Modeling and Animation of Brittle Fracture*” SIGGRAPH 1999.



- Fracture threshold
- Material properties
- Remeshing
- Parameter tuning
  - need connectivity info!

## Fracture Opening Modes

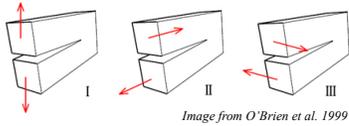
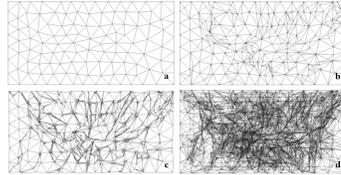
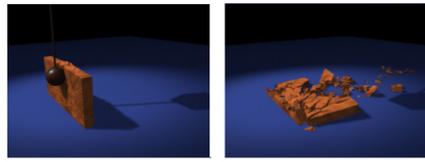


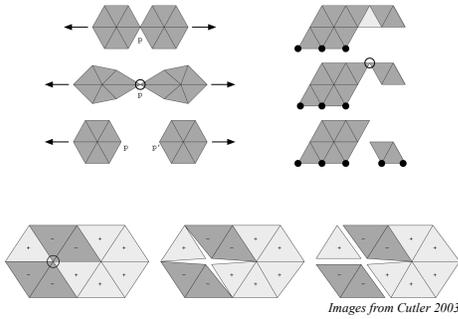
Figure 6: Three loading modes that can be experienced by a crack. Mode I: Opening, Mode II: In-Plane Shear, and Mode III: Out-of-Plane Shear. Adapted from Anderson [1].

## Local Mesh Refinement



Images from O'Brien et al. 1999

## Managing Fracture Adjacency



Images from Cutler 2003

## Fracture Propagation Difficulties

- Need to track direction of fracture propagation?

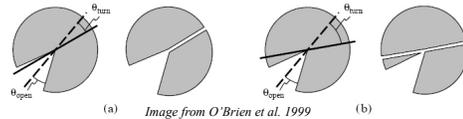


Image from O'Brien et al. 1999

- Need to track crack tip?

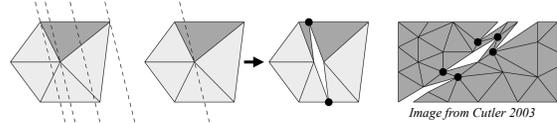
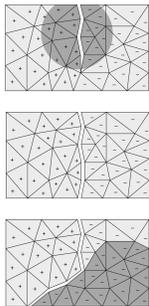
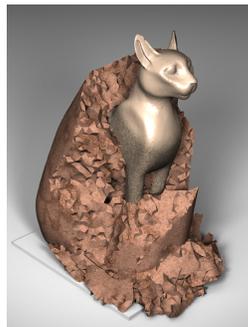


Image from Cutler 2003

## Controlling Speed of Propagation



(no remeshing)

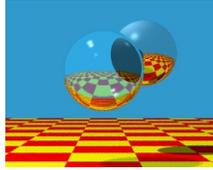


Images from Cutler 2003

## Questions?

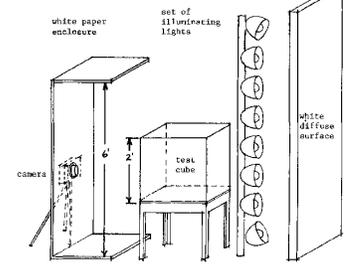
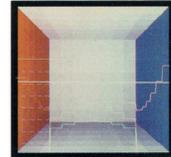
## Readings for Friday 2/20:

- "An improved illumination model for shaded display" Turner Whitted, 1980.
- "Distributed Ray Tracing", Cook, Porter, & Carpenter, SIGGRAPH 1984.
- "Interactive Depth of Field", Kass, Lefohn, and Owens, Pixar TR 2006.



## Reading for Friday 2/27:

- Goral, Torrance, Greenberg & Battaile "Modeling the Interaction of Light Between Diffuse Surfaces", SIGGRAPH '84



Post a comment or question on the LMS discussion by 10am on Friday 2/29