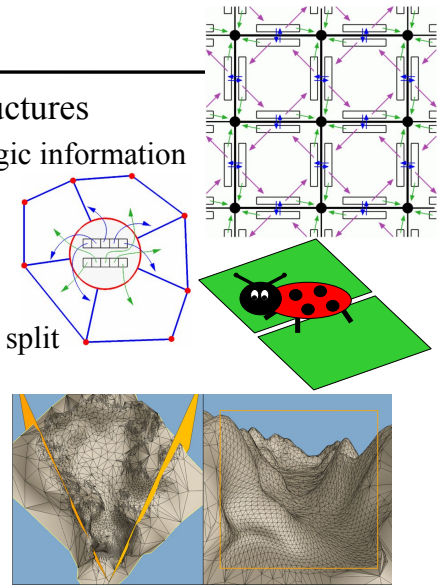


# Curves & Surfaces

## Last Time?

- Adjacency Data Structures
  - Geometric & topologic information
  - Dynamic allocation
  - Efficiency of access
- Mesh Simplification
  - edge collapse/vertex split
  - geomorphs
  - progressive transmission
  - view-dependent refinement



## Progressive Meshes

- Mesh Simplification
  - vertex split / edge collapse (only one operation!)
  - geometry & discrete/scalar attributes
  - priority queue
- Level of Detail
  - geomorphs
- Progressive Transmission
- Mesh Compression
- Selective Refinement
  - view dependent

## Selective Refinement

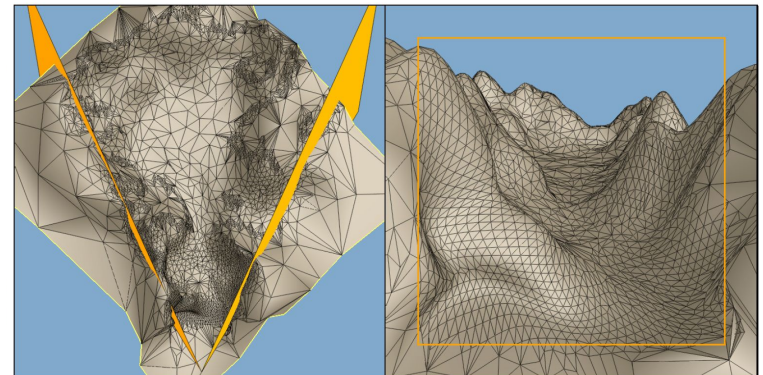


Figure 10: Selective refinement of a terrain mesh taking into account view frustum, silhouette regions, and projected screen size of faces (7,438 faces).

## Preserving Discontinuity Curves

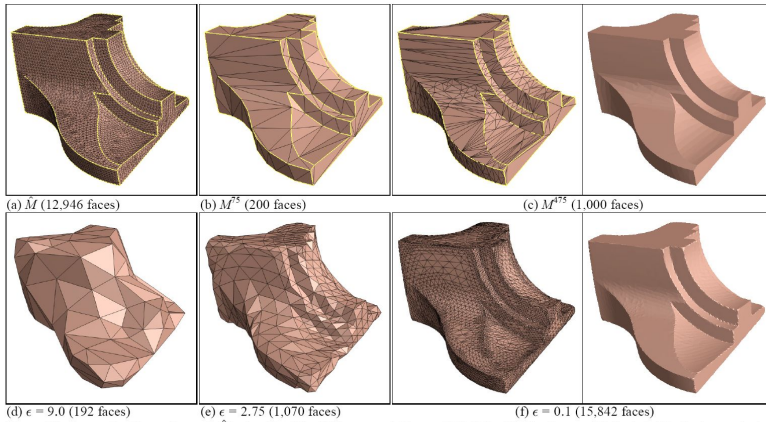
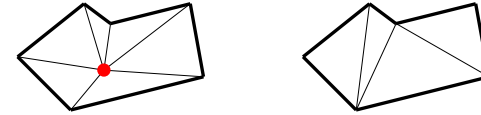


Figure 12: Approximations of a mesh  $\hat{M}$  using (b-c) the PM representation, and (d-f) the MRA scheme of Eck et al. [7]. As demonstrated, MRA cannot recover  $\hat{M}$  exactly, cannot deal effectively with surface creases, and produces approximating meshes of inferior quality.

## Other Simplification Strategies

- Remove a vertex & surrounding triangles, re-triangulate the hole



- Merge Nearby Vertices
  - will likely change the topology...

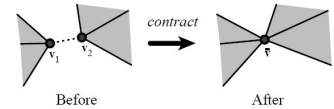


Figure 2: **Non-edge contraction.** When non-edge pairs are contracted, unconnected sections of the model are joined. The dashed line indicates the two vertices being contracted together.

from Garland & Heckbert, “Surface Simplification Using Quadric Error Metrics” SIGGRAPH 1997

## When to Preserve Topology?



Figure 3: On the left is a regular grid of 100 closely spaced cubes. In the middle, an approximation built using only edge contractions demonstrates unacceptable fragmentation. On the right, the result of using more general pair contractions to achieve aggregation is an approximation much closer to the original.

from Garland & Heckbert, “Surface Simplification Using Quadric Error Metrics” SIGGRAPH 1997

## Quadric Error Simplification

- Contract (merge) vertices  $v_i$  and  $v_j$  if:
  - $(v_i, v_j)$  is an edge, or
  - $\|v_i - v_j\| < t$ , where  $t$  is a threshold parameter
- Track cumulative error by summing 4x4 quadric error matrices after each operation:

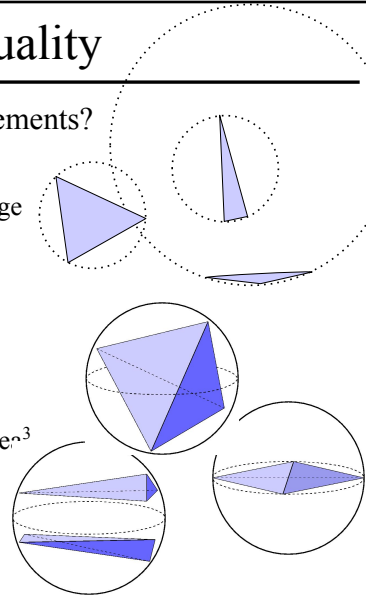
$$\begin{aligned} \Delta(v) &= \sum_{p \in \text{planes}(v)} (v^T p)(p^T v) \\ &= \sum_{p \in \text{planes}(v)} v^T (p p^T) v \\ &= v^T \left( \sum_{p \in \text{planes}(v)} \kappa_p \right) v \end{aligned}$$

$$\kappa_p = p p^T = \begin{bmatrix} a^2 & ab & ac & ad \\ ab & b^2 & bc & bd \\ ac & bc & c^2 & cd \\ ad & bd & cd & d^2 \end{bmatrix}$$

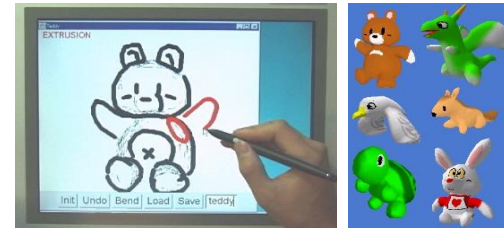
Garland & Heckbert,  
“Surface Simplification  
Using Quadric Error Metrics”  
SIGGRAPH 1997

## Judging Element Quality

- How “equilateral” are the elements?
- For Triangles?
  - Ratio of shortest to longest edge
  - Ratio of area to perimeter<sup>2</sup>
  - Smallest angle
  - Ratio of area to area of smallest circumscribed circle
- For Tetrahedra?
  - Ratio of volume<sup>2</sup> to surface area<sup>3</sup>
  - Smallest *solid* angle
  - Ratio of volume to volume of smallest circumscribed sphere

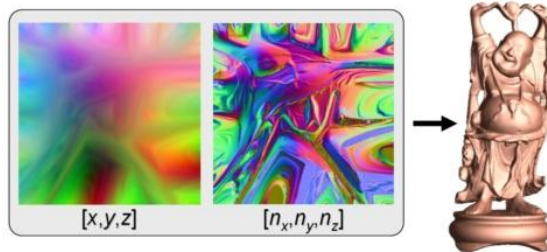


## Reading for Today (option A)



- "Teddy: A Sketching Interface for 3D Freeform Design", Igarashi et al., SIGGRAPH 1999
- How do we represent objects that don't have flat polygonal faces & sharp corners? What are the right tools to design/construct digital models of blobby, round, or soft things? What makes a user interface intuitive, quick, and easy-to-use for beginners?

## Reading for Today (option B)



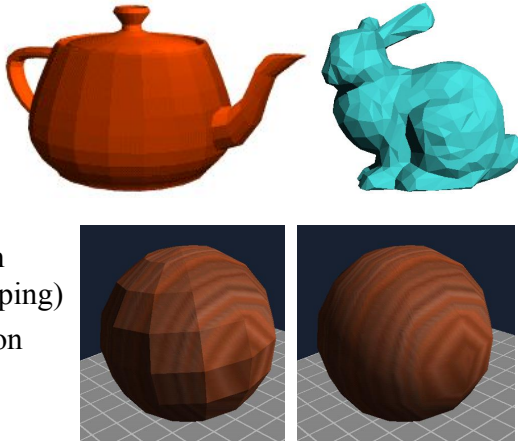
- "Geometry Images", Gu, Gortler, & Hoppe, SIGGRAPH 2002
- Can we leverage existing image formats and image compression methods to store geometry? How do we take a complex 3D shape an unroll/flatten/stretch it to a square image? File size? Quality?

## Today

- **Limitations of Polygonal Models**
  - Interpolating Color & Normals in OpenGL
  - Some Modeling Tools & Definitions
- What's a Spline?
  - Interpolation Curves vs. Approximation Curves
  - Linear Interpolation
- Bézier Spline
- BSpline (NURBS)
- Extending to Surfaces – Tensor Product

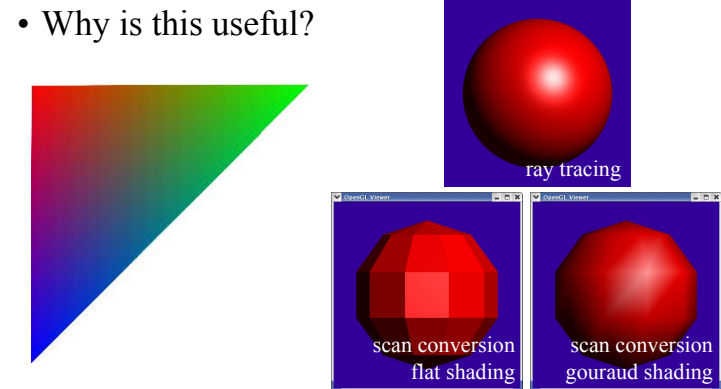
## Limitations of Polygonal Meshes

- Planar facets (& silhouettes)
- Fixed resolution
- Deformation is difficult
- No natural parameterization (for texture mapping)
- Incorrect collision detection
- Solid texturing problems



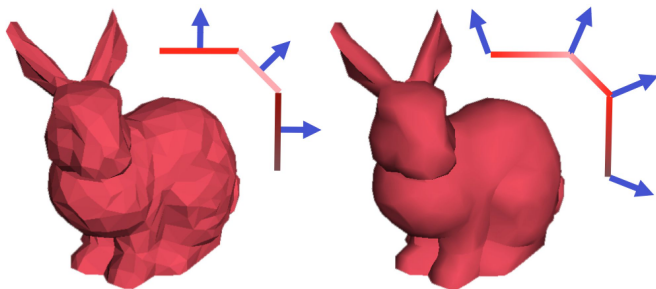
## Color & Normal Interpolation

- It's easy in OpenGL to specify different colors and/or normals at the vertices of triangles:



## What is Gouraud Shading?

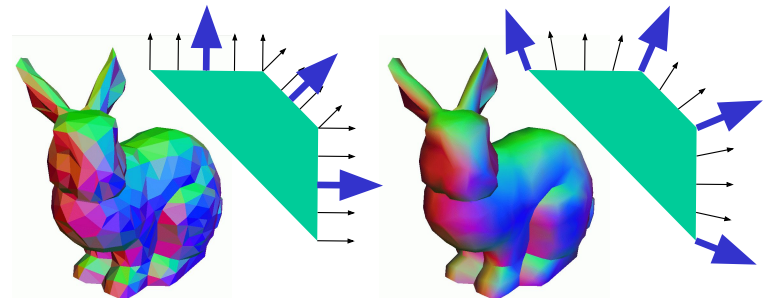
- Instead of shading with the normal of the triangle, we'll shade the vertices with *the average normal* and *interpolate the shaded color* across each face
  - This gives the *illusion of a smooth surface* with smoothly varying normals



- How do we compute Average Normals? Is it expensive??

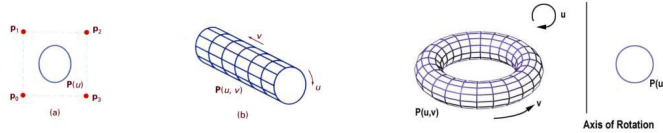
## Phong Normal Interpolation (Not Phong Shading)

- *Interpolate the average vertex normals* across the face and compute *per-pixel shading*
  - Normals should be re-normalized (ensure length=1)



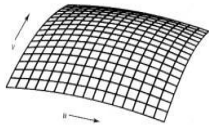
- Before shaders, per-pixel shading was not possible in hardware (Gouraud shading is actually a decent substitute!)

## Some Non-Polygonal Modeling Tools

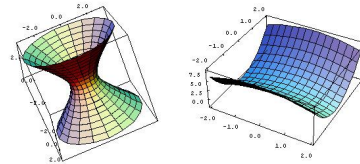


Extrusion

Surface of Revolution



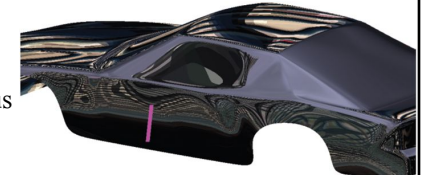
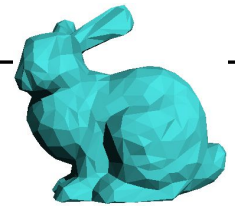
Spline Surfaces/Patches



Quadrics and other implicit polynomials

## Continuity definitions:

- $C^0$  continuous
  - curve/surface has no breaks/gaps/holes
- $G^1$  continuous
  - tangent at joint has same direction
- $C^1$  continuous
  - curve/surface derivative is continuous
  - tangent at joint has same direction *and* magnitude
- $C^n$  continuous
  - curve/surface through  $n^{\text{th}}$  derivative is continuous
  - important for shading



"Shape Optimization Using Reflection Lines", Tosun et al., 2007

## Questions?

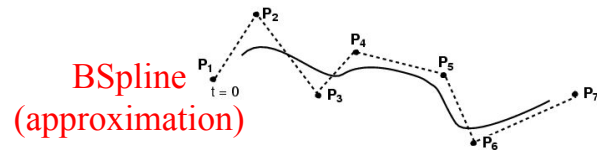
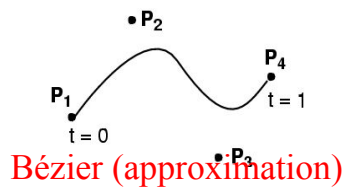
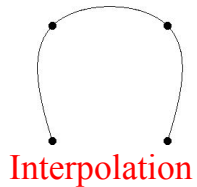
## Today

- Limitations of Polygonal Models
  - Interpolating Color & Normals in OpenGL
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- What's a Spline?
  - Interpolation Curves vs. Approximation Curves
  - Linear Interpolation
- Bézier Spline
- BSpline (NURBS)
- Extending to Surfaces – Tensor Product

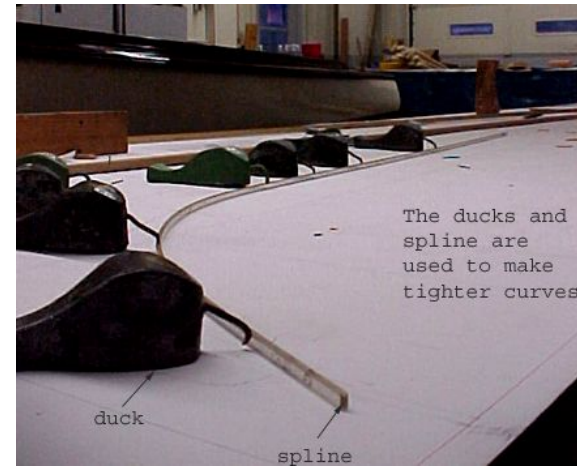


## Definition: What's a Spline?

- Smooth curve defined by some control points
- Moving the control points changes the curve



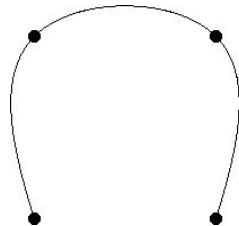
## Interpolation Curves / Splines



www.abm.org

## Interpolation Curves

- Curve is constrained to pass through all control points
- Given points  $P_0, P_1, \dots, P_n$ , find lowest degree polynomial which passes through the points

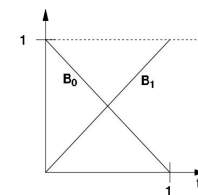
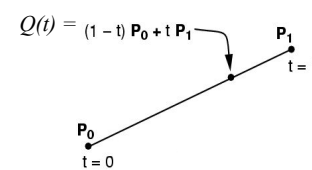


$$x(t) = a_{n-1}t^{n-1} + \dots + a_2t^2 + a_1t + a_0$$

$$y(t) = b_{n-1}t^{n-1} + \dots + b_2t^2 + b_1t + b_0$$

## Linear Interpolation

- Simplest "curve" between two points

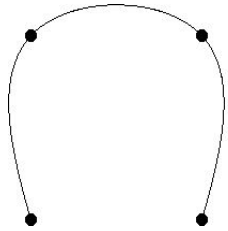


Spline Basis Functions  
a.k.a. Blending Functions

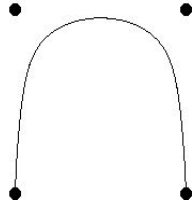
$$Q(t) = \begin{pmatrix} Q_x(t) \\ Q_y(t) \\ Q_z(t) \end{pmatrix} = \begin{pmatrix} P_0 & P_1 \end{pmatrix} \begin{pmatrix} -1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} t \\ 1 \end{pmatrix}$$

$$Q(t) = \mathbf{G}\mathbf{B}\mathbf{T}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

## Interpolation vs. Approximation Curves



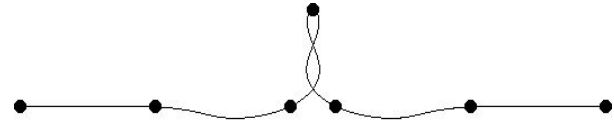
**Interpolation**  
curve must pass  
through control points



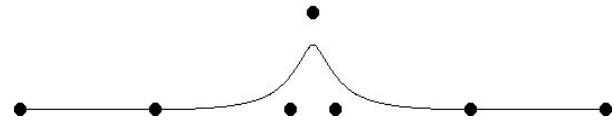
**Approximation**  
curve is influenced  
by control points

## Interpolation vs. Approximation Curves

- Interpolation Curve – over constrained → lots of (undesirable?) oscillations



- Approximation Curve – more reasonable?



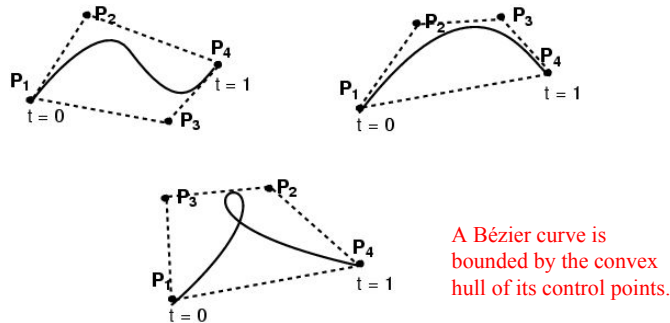
## Questions?

## Today

- Limitations of Polygonal Models
  - Interpolating Color & Normals in OpenGL
  - Some Modeling Tools & Definitions
- What's a Spline?
  - Interpolation Curves vs. Approximation Curves
  - Linear Interpolation
- **Bézier Spline**
- BSpline (NURBS)
- Extending to Surfaces – Tensor Product

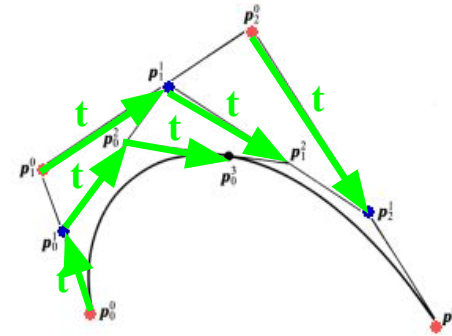
## Cubic Bézier Curve

- 4 control points
- Curve passes through first & last control point
- Curve is tangent at  $P_1$  to  $(P_2 - P_1)$  and at  $P_4$  to  $(P_4 - P_3)$

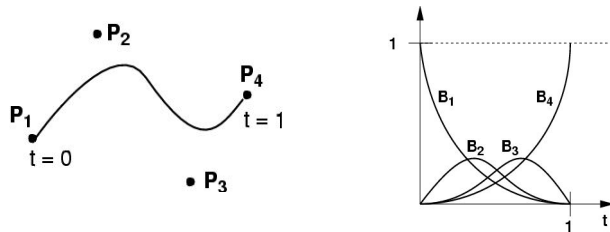


## Cubic Bézier Curve

- de Casteljau's algorithm for constructing Bézier curves



## Cubic Bézier Curve



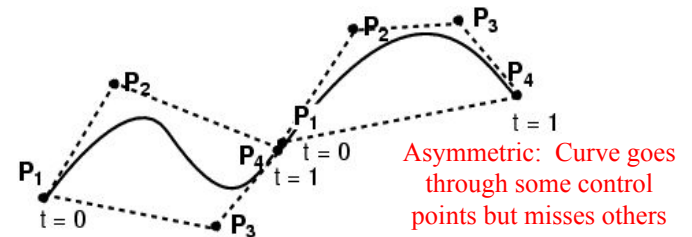
$$Q(t) = (1-t)^3 P_1 + 3t(1-t)^2 P_2 + 3t^2(1-t) P_3 + t^3 P_4$$

$$Q(t) = \mathbf{GBT}(t) \quad B_{\text{Bezier}} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

Bernstein  
Polynomials

$$B_1(t) = (1-t)^3, B_2(t) = 3t(1-t)^2, B_3(t) = 3t^2(1-t), B_4(t) = t^3$$

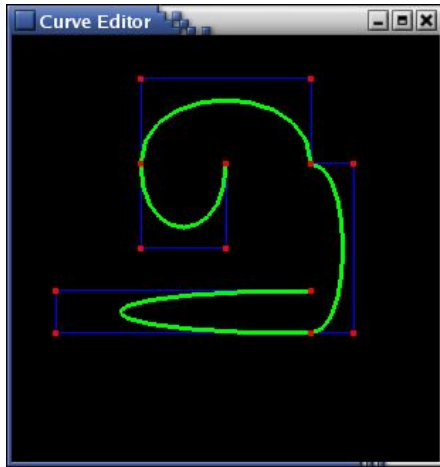
## Connecting Cubic Bézier Curves



- How can we guarantee  $C^0$  continuity?
- How can we guarantee  $G^1$  continuity?
- How can we guarantee  $C^1$  continuity?
- Can't guarantee higher  $C^2$  or higher continuity



## Connecting Cubic Bézier Curves



- Where is this curve
  - $C^0$  continuous?
  - $G^1$  continuous?
  - $C^1$  continuous?
- What's the relationship between:
  - the # of control points, and
  - the # of cubic Bézier subcurves?

## Higher-Order Bézier Curves

- $> 4$  control points
- Bernstein Polynomials as the basis functions

$$B_i^n(t) = \frac{n!}{i!(n-i)!} t^i (1-t)^{n-i}, \quad 0 \leq i \leq n$$

- Every control point affects the entire curve
  - Not simply a local effect
  - More difficult to control for modeling

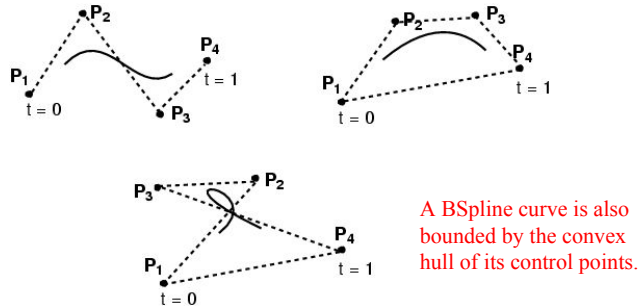
## Questions?

## Today

- Limitations of Polygonal Models
  - Interpolating Color & Normals in OpenGL
  - Some Modeling Tools & Definitions
- What's a Spline?
  - Interpolation Curves vs. Approximation Curves
  - Linear Interpolation
- Bézier Spline
- **BSpline (NURBS)**
- Extending to Surfaces – Tensor Product

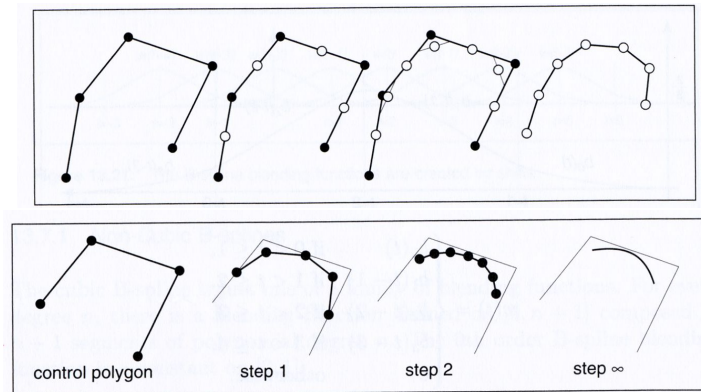
## Cubic BSplines

- $\geq 4$  control points
- Locally cubic
- Curve is not constrained to pass through any control points



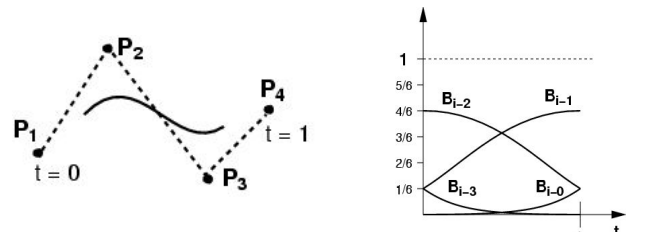
## Cubic BSplines

- Iterative method for constructing BSplines



Shirley, Fundamentals of Computer Graphics

## Cubic BSplines

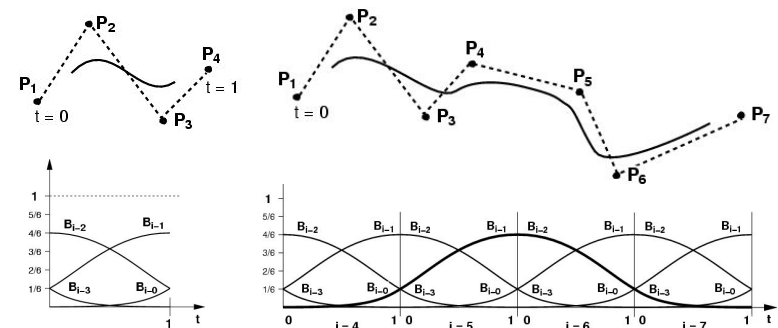


$$Q(t) = \frac{(1-t)^3}{6}P_{i-3} + \frac{3t^3 - 6t^2 + 4}{6}P_{i-2} + \frac{-3t^3 + 3t^2 + 3t + 1}{6}P_{i-1} + \frac{t^3}{6}P_i$$

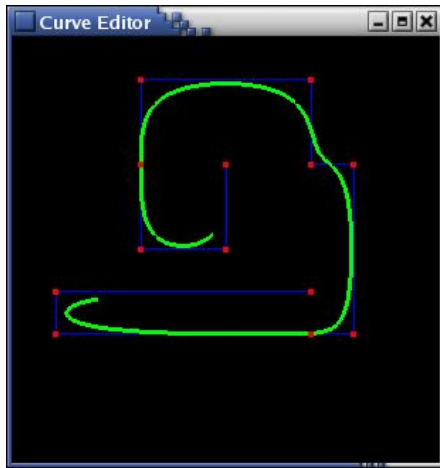
$$Q(t) = \mathbf{GBT}(t) \quad B_{B-Spline} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 0 & 4 \\ -3 & 3 & 3 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

## Connecting Cubic BSpline Curves

- Can be chained together
- Better control locally (windowing)

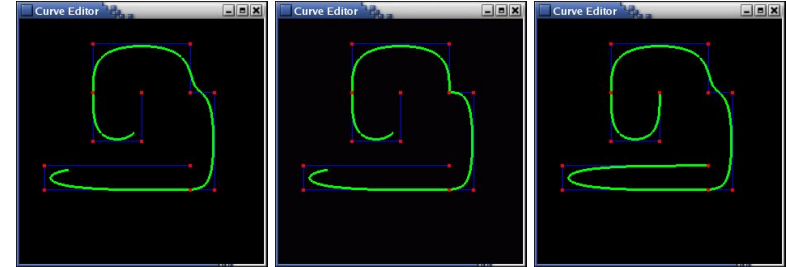


## Connecting Cubic BSpline Curves



- What's the relationship between
  - the # of control points, and
  - the # of cubic BSpline subcurves?

## BSpline Curve Control Points



Default BSpline

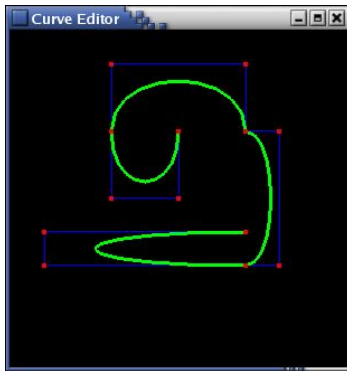
BSpline with Discontinuity

BSpline which passes through end points

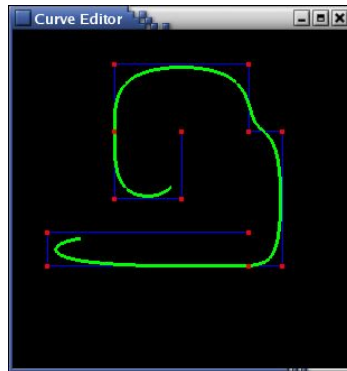
Repeat interior control point

Repeat end points

## Bézier is not the same as BSpline



Bézier

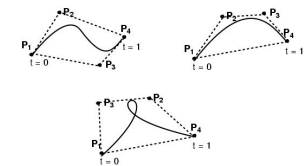
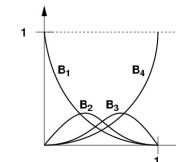


BSpline

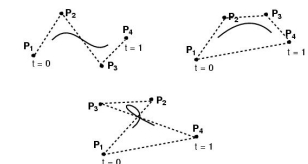
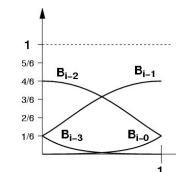
## Bézier is not the same as BSpline

- Relationship to the control points is different

Bézier

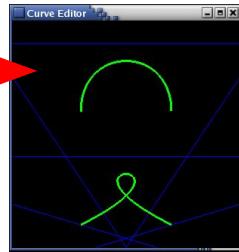
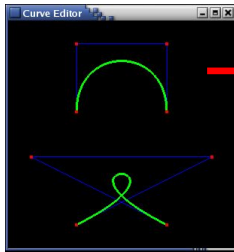


BSpline



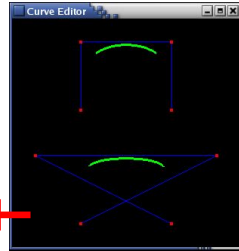
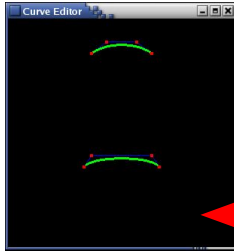
## Converting between Bézier & BSpline

original  
control  
points as  
Bézier



new  
BSpline  
control  
points to  
match  
Bézier

new  
Bézier  
control  
points to  
match  
BSpline



original  
control  
points as  
BSpline

## Converting between Bézier & BSpline

- Using the basis functions:

$$B_{\text{Bezier}} = \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 3 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

$$B_{\text{B-Spline}} = \frac{1}{6} \begin{pmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 0 & 4 \\ -3 & 3 & 3 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix}$$

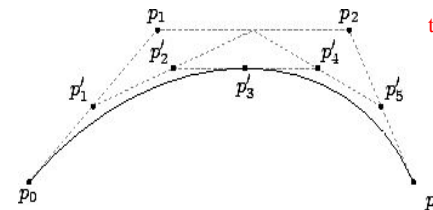
$$Q(t) = \mathbf{G}\mathbf{B}\mathbf{T}(t) = \text{Geometry } \mathbf{G} \cdot \text{Spline Basis } \mathbf{B} \cdot \text{Power Basis } \mathbf{T}(t)$$

## NURBS (generalized BSplines)

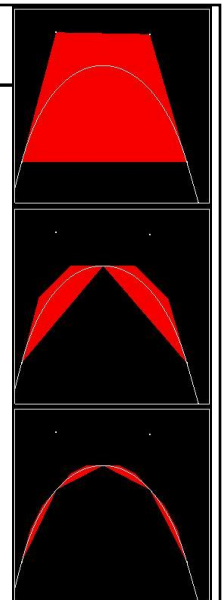
- BSpline: uniform cubic BSpline
- NURBS: Non-Uniform Rational BSpline
  - non-uniform = different spacing between the blending functions, a.k.a. knots
  - rational = ratio of polynomials (instead of cubic)

## Neat Bezier Spline Trick

- A Bezier curve with 4 control points:
  - $- P_0 \quad P_1 \quad P_2 \quad P_3$
- Can be split into 2 new Bezier curves:
  - $- P_0 \quad P'_1 \quad P'_2 \quad P'_3$
  - $- P'_3 \quad P'_4 \quad P'_5 \quad P_3$



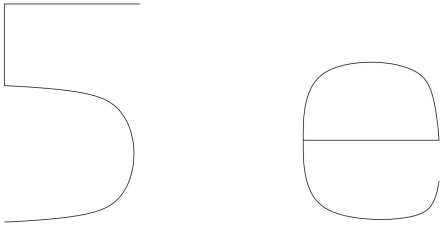
A Bézier curve  
is bounded by  
the convex hull  
of its control  
points.



## Pop Worksheet!

Teams of 2. NOT EITHER OF PEOPLE  
YOU WORKED WITH LAST WEEK!  
Hand in to Jeramey after we discuss.

- What is the minimum number of cubic Bezier curve segments needed to approximately reproduce the two curves below? Sketch the positions of the control vertices.



- Repeat for cubic BSplines curve segments.

## Today

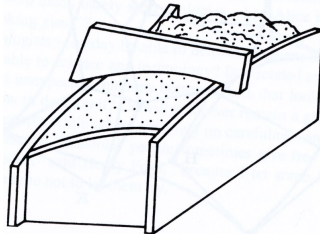
- Limitations of Polygonal Models
  - Interpolating Color & Normals in OpenGL
  - Some Modeling Tools & Definitions
- What's a Spline?
  - Interpolation Curves vs. Approximation Curves
  - Linear Interpolation
- Bézier Spline
- BSpline (NURBS)
- Extending to Surfaces – Tensor Product

## Spline Surface via Tensor Product

- Of two vectors:

$$\begin{bmatrix} a_1 & a_2 & a_3 \end{bmatrix} \otimes \begin{bmatrix} b_1 & b_2 & b_3 & b_4 \end{bmatrix} = \begin{bmatrix} a_1b_1 & a_2b_1 & a_3b_1 \\ a_1b_2 & a_2b_2 & a_3b_2 \\ a_1b_3 & a_2b_3 & a_3b_3 \\ a_1b_4 & a_2b_4 & a_3b_4 \end{bmatrix}$$

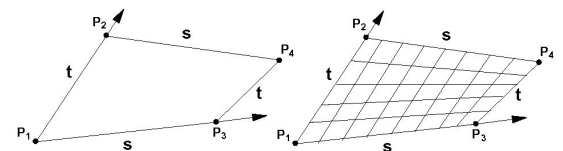
- Similarly, we can define a surface as the tensor product of two curves....



Farin, Curves and Surfaces for  
Computer Aided Geometric Design

## Bilinear Patch

Bi-lerp a (typically non-planar) quadrilateral

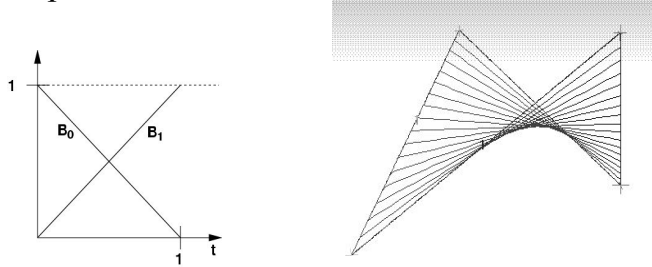


Notation:  $L(P_1, P_2, \alpha) \equiv (1 - \alpha)P_1 + \alpha P_2$

$$Q(s, t) = L(L(P_1, P_2, t), L(P_3, P_4, t), s)$$

## Bilinear Patch

- Smooth version of quadrilateral with non-planar vertices...



- But will this help us model smooth surfaces?
- Do we have control of the derivative at the edges?

## Ruled Surfaces in Art & Architecture

<http://www.bergenwood.no/wp-content/media/images/frozenmusic.jpg>

Chiras Iulia  
Astri Isabella  
Matiss Shteinerts



Antoni Gaudi  
Children's School  
Barcelona

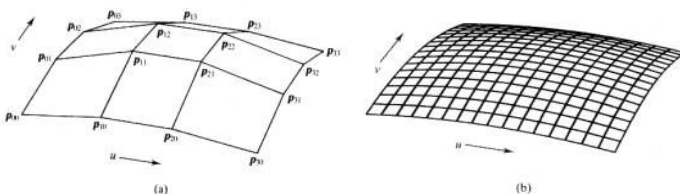
<http://www.lonelyplanetimages.com/images/399954>

## Bicubic Bezier Patch

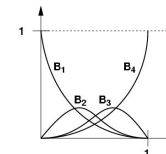
Notation:  $\mathbf{CB}(P_1, P_2, P_3, P_4, \alpha)$  is Bézier curve with control points  $P_i$  evaluated at  $\alpha$

Define "Tensor-product" Bézier surface

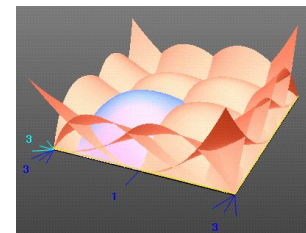
$$Q(s, t) = \mathbf{CB} \left( \begin{array}{l} \mathbf{CB}(P_{00}, P_{01}, P_{02}, P_{03}, t), \\ \mathbf{CB}(P_{10}, P_{11}, P_{12}, P_{13}, t), \\ \mathbf{CB}(P_{20}, P_{21}, P_{22}, P_{23}, t), \\ \mathbf{CB}(P_{30}, P_{31}, P_{32}, P_{33}, t), \\ s \end{array} \right)$$



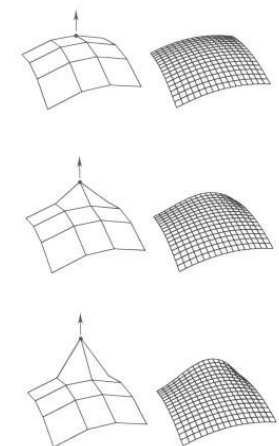
## Editing Bicubic Bezier Patches



Curve Basis Functions



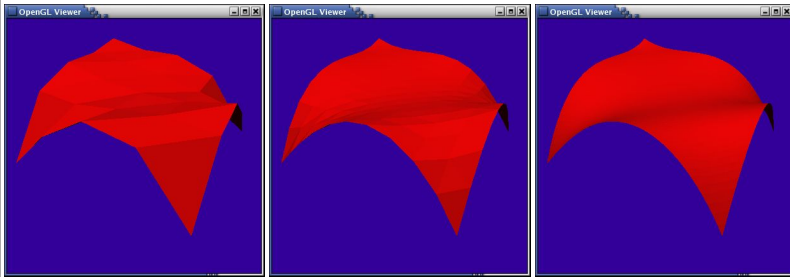
Surface Basis Functions





## Bicubic Bezier Patch Tessellation

- Given 16 control points and a tessellation resolution, we can create a triangle mesh



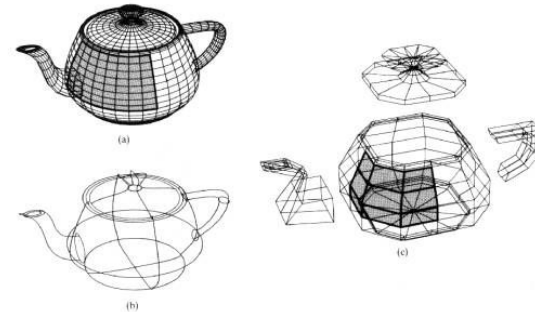
resolution:  
5x5 vertices

resolution:  
11x11 vertices

resolution:  
41x41 vertices

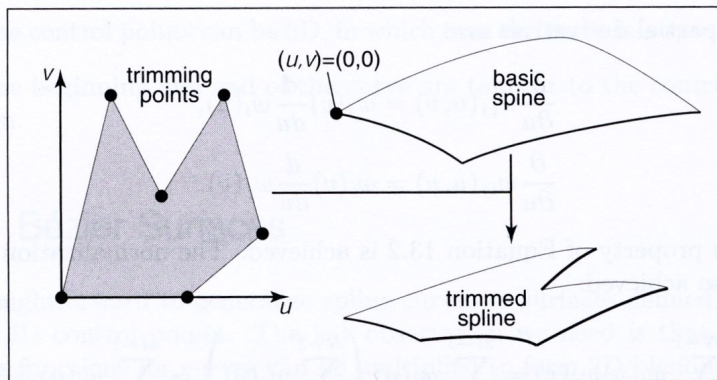
## Modeling with Bicubic Bezier Patches

- Original Teapot specified with Bezier Patches



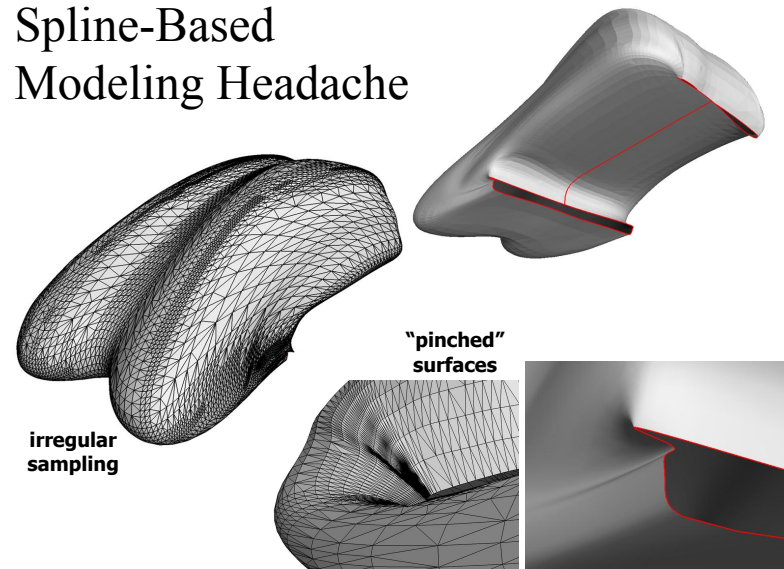
- But it's not "watertight": it has intersecting surfaces at spout & handle, no bottom, a hole at the spout tip, a gap between lid & base

## Trimming Curves for Patches



Shirley, Fundamentals of Computer Graphics

## Spline-Based Modeling Headache



## Questions?

- Bezier Patches?

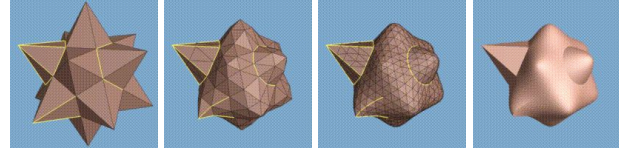
or

- Triangle Mesh?



## Readings for Friday (*pick one*)

- Hoppe et al., "Piecewise Smooth Surface Reconstruction" SIGGRAPH 1994



- DeRose, Kass, & Truong, "Subdivision Surfaces in Character Animation", SIGGRAPH 1998

*Post a comment or question on the LMS discussion by 10am on Tuesday*



## Homework 1:

- Questions/Comments?

