

CSCI 4560/6560 Computational Geometry

<https://www.cs.rpi.edu/~cutler/classes/computationalgeometry/F23/>

# Lecture 5: Triangulation, part 2

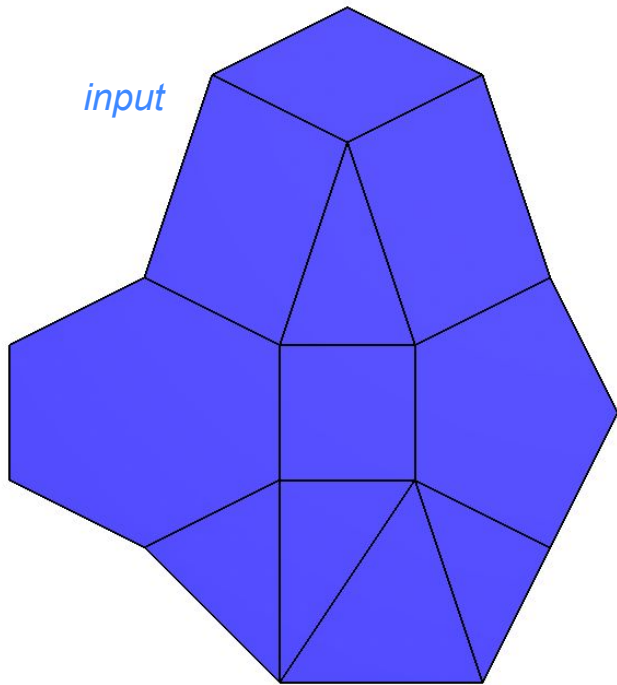
# Outline for Today

- Homework 2 Questions?
- Last Time: Art Gallery Problem & Triangulation
- Improved Triangulation Algorithm
- Definition: Monotone Polygon
- Splitting into Monotone Polygons
- Triangulating a Monotone Polygon
- Analysis of Improved Triangulation Algorithm
- Future Lecture: Additional Triangulation Goals

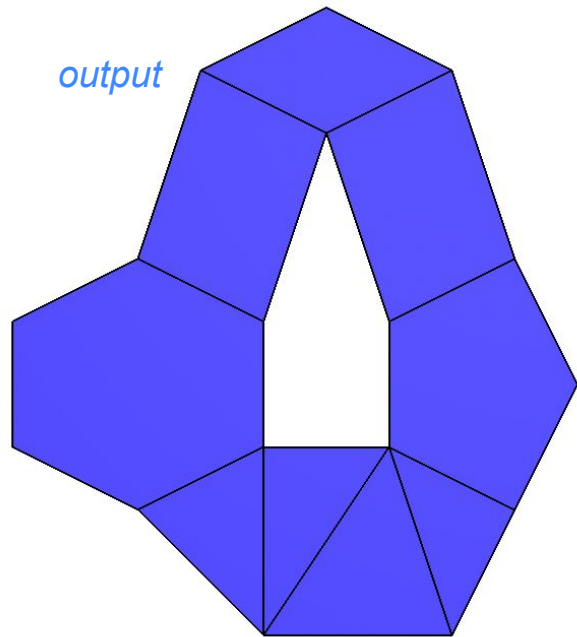
# Homework 2

- Use CGAL's Surface Mesh (Halfedge) data structure
- 
- Input: all edges
  - Output: all faces on any boundary

*input*



*output*



*use case 1*

- Input: 1 edge on a boundary
- Output: all faces on that boundary

*use case 2*

# Homework 2

- Each Halfedge stores:
  - **vertex** at end of directed edge
  - **symmetric** halfedge
  - **face** to left of edge
  - **next** points to the Halfedge counter-clockwise around face on left

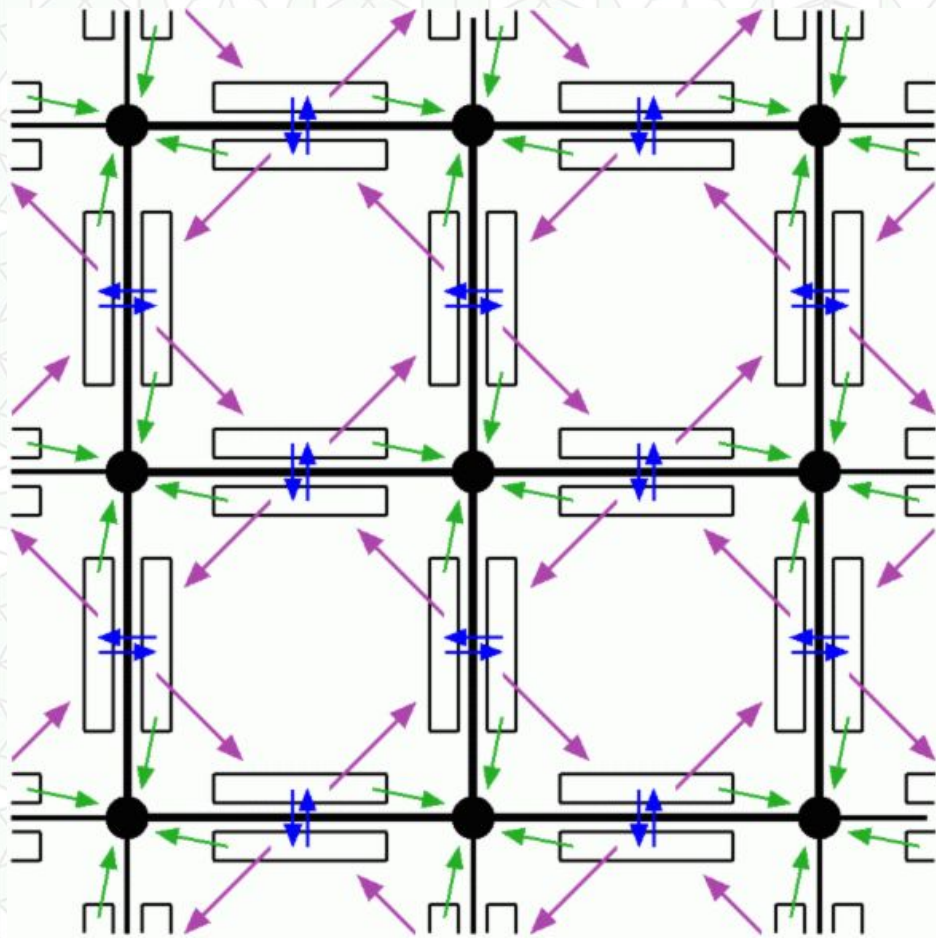


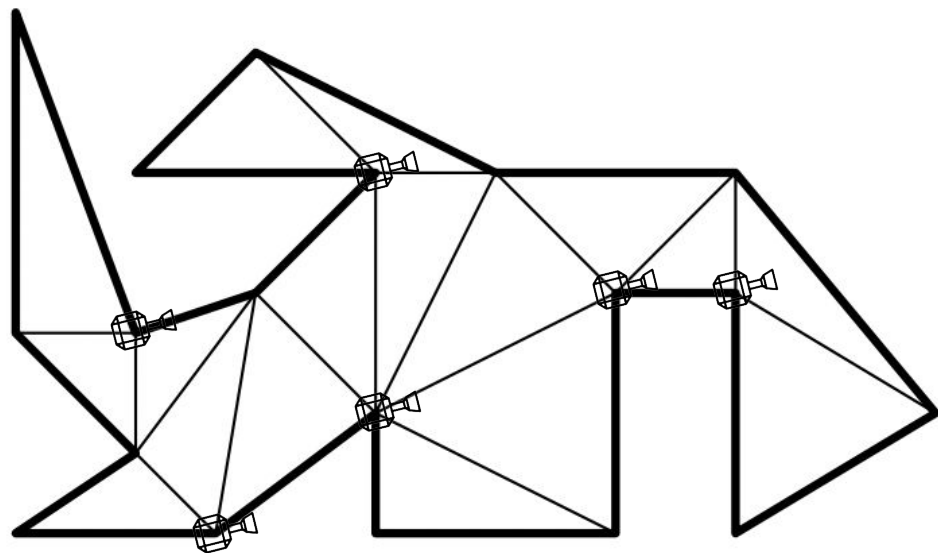
Image from Justin Legakis

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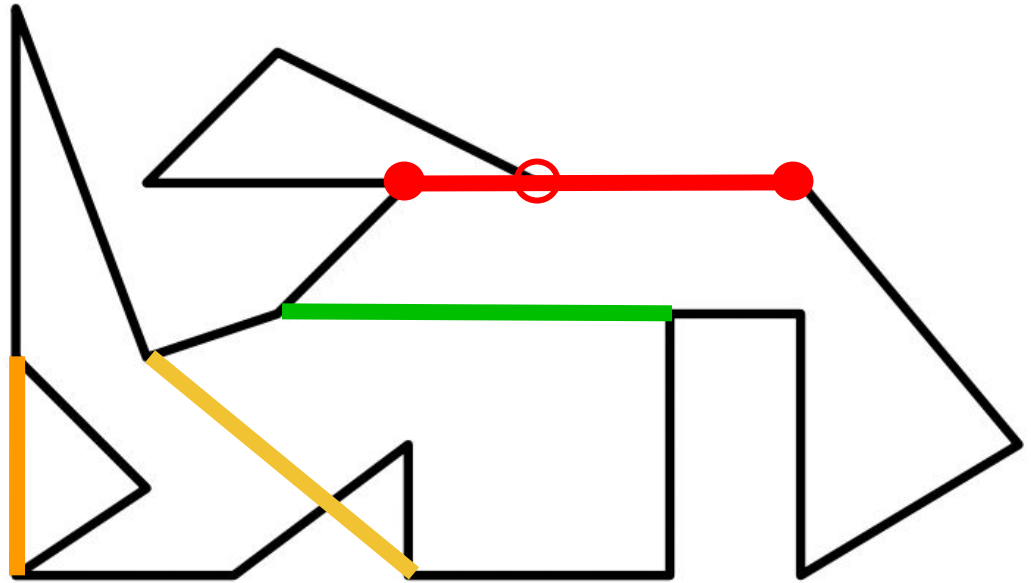
# Last Time?

- The Art Gallery Problem: Place cameras for 100% coverage of a simple polygon (no interior holes).
- Triangulate, and place cameras on the  $\sim \frac{1}{3}$  of the vertices, ensuring every triangle has one vertex with a camera.



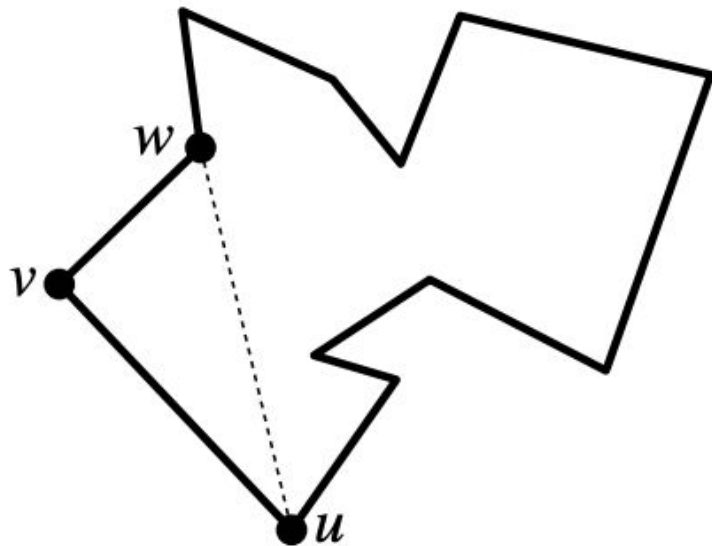
# Cut the input on a “Diagonal” & Recurse

- Diagonal should connect **two non-adjacent vertices** on the polygonal boundary.
- Diagonal must not be **outside the polygon**.
- Diagonal may not **cross any edge**.
- Diagonal should not **pass through any other vertex**.



# How do we find a Valid Diagonal?

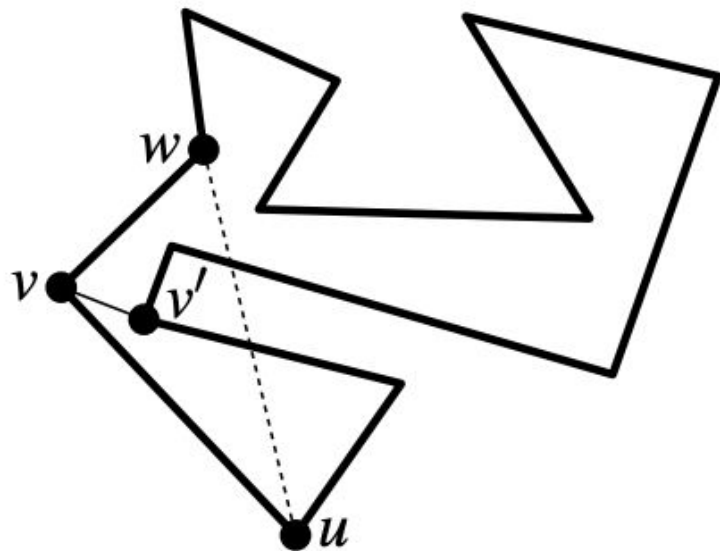
- Start at the leftmost vertex,  $v$ 
  - *NOTE: If two or more vertices have the same  $x$ , chose the one with smaller  $y$ .*
- Find vertices  $u$  and  $w$ , adjacent to  $v$
- Check if the line  $uw$  is a valid diagonal.
  - This line does not pass through  $v$ .
  - Does it intersect other line segments?
  - Does it pass through any other vertices?
  - Does it lie completely outside of the polygon? (possible if one of the vertices is the rightmost vertex)





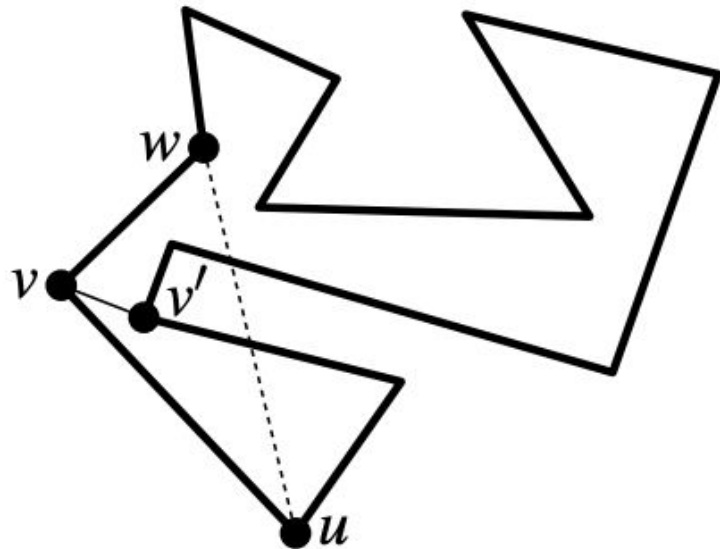
# How do we find a Valid Diagonal?

- If it does cross another line segment, there must be one or more vertices inside the triangle  $uvw$ .
- Starting at the intersection, walk along the boundary to find those vertices.
- Choose the vertex  $v'$ , furthest from the line segment  $uw$ .
- Draw the diagonal from  $v$  to  $v'$ .



# Cut on Diagonal & Recurse Analysis

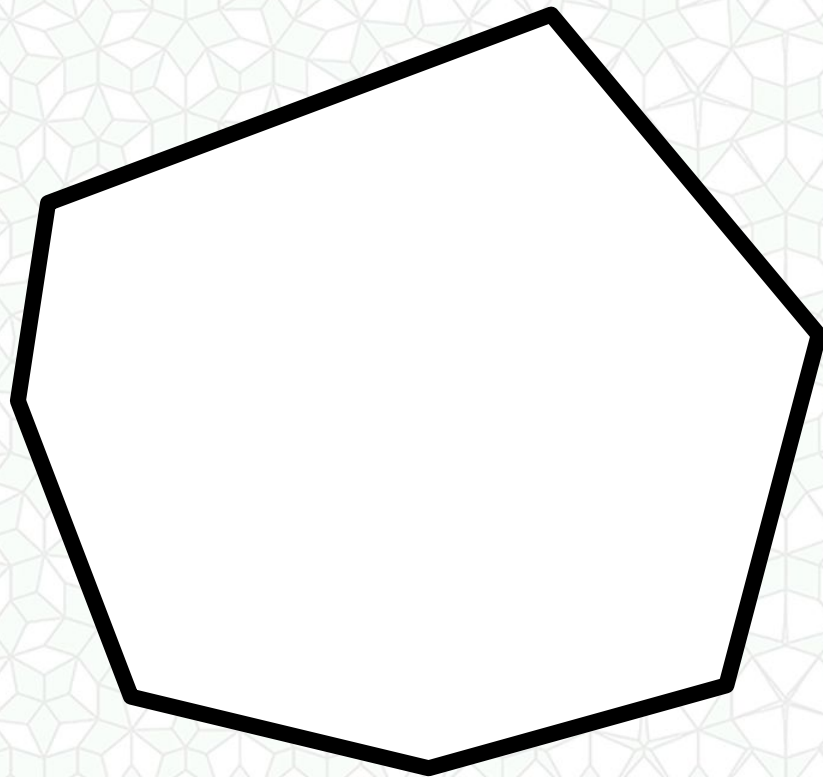
- What is the worst case running time to triangulate a non-convex, simple polygon with  $n$  vertices?
- Identify a legal diagonal
  - $O(n)$  in worst case
- Split into two smaller polygons
  - *Worst case:*  
 $m_1 = 3$  vertices and  
 $m_2 = n-1$  vertices
- Overall:  $O(n^2)$  running time



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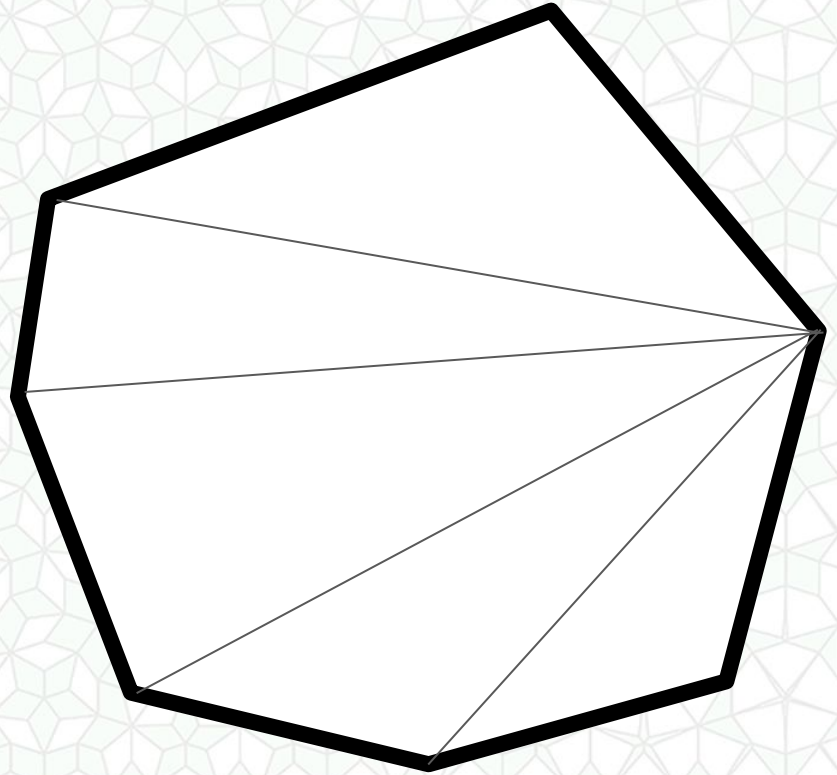
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A Convex Polygon is easy to Triangulate



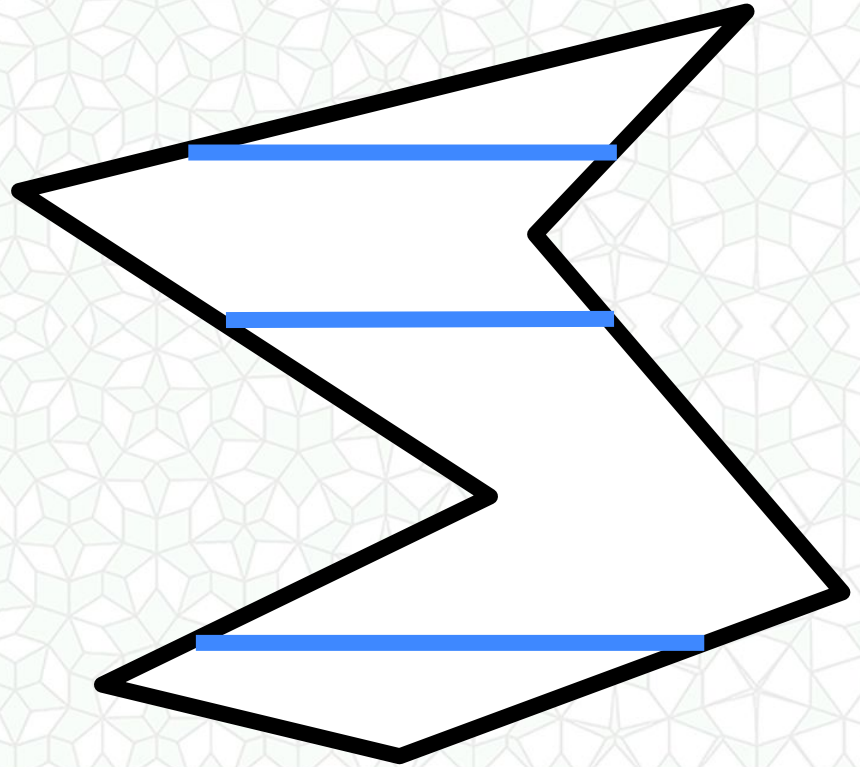
# A Convex Polygon is easy to Triangulate

- Pick any vertex and connect it to every other vertex (except 2 adjacent vertices)
- *Unfortunately, breaking a non-convex polygon into convex polygons is not easy.*



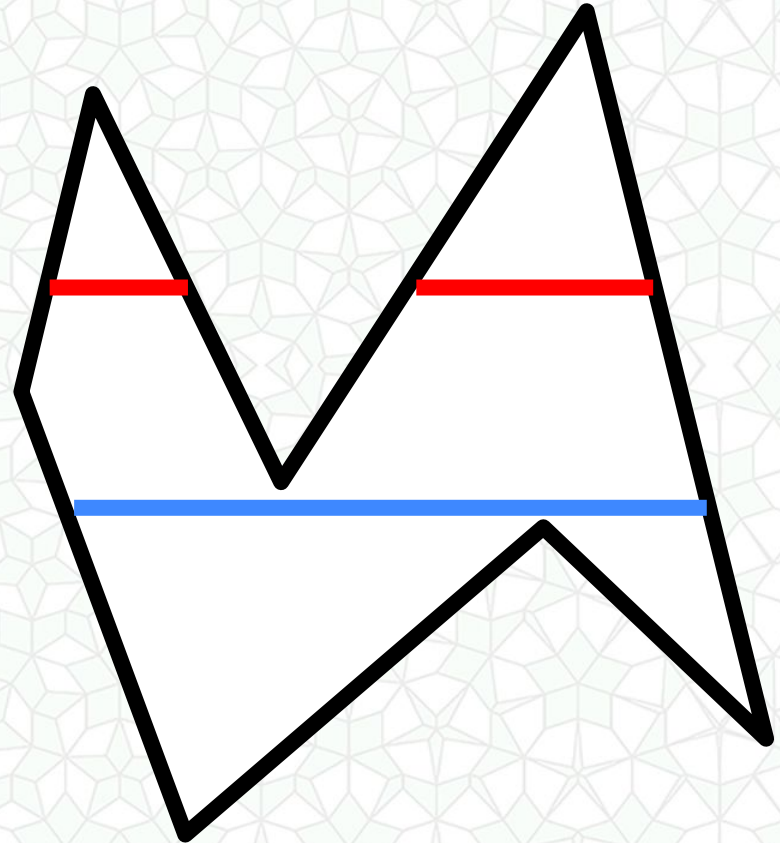
# Definition: Monotone with Respect to Y-Axis

- The intersection of the polygon with any line perpendicular to the y-axis is connected.
- The intersection is either
  - empty (above or below the polygon),
  - one point (top or bottom vertex), or
  - *a line segment.*



# Not Monotone, with Respect to Y-Axis

- The intersection of the polygon with any line perpendicular to the y-axis is connected.
- The intersection is either
  - empty (above or below the polygon),
  - one point (top or bottom vertex), or
  - *a line segment.*

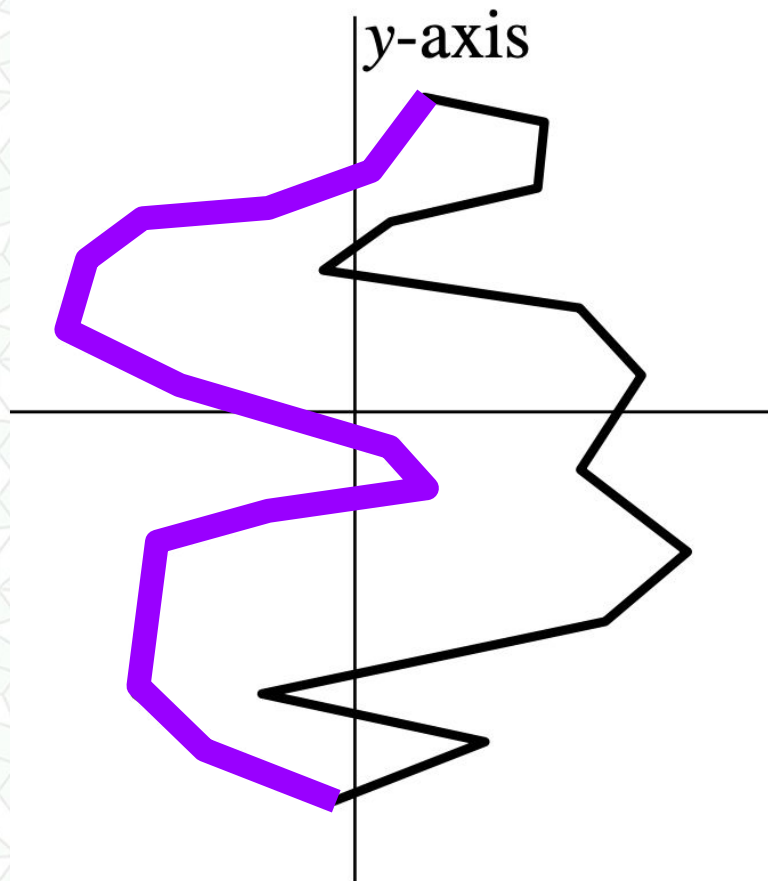


# If a Polygon is Monotone...

- We can start from the top vertex (largest y coordinate), **and walk “down” the left side** to the bottom vertex (smallest y coordinate)

Each step moves downwards or horizontally – *never upwards*.

- Similarly we can walk down the right side of the polygon.



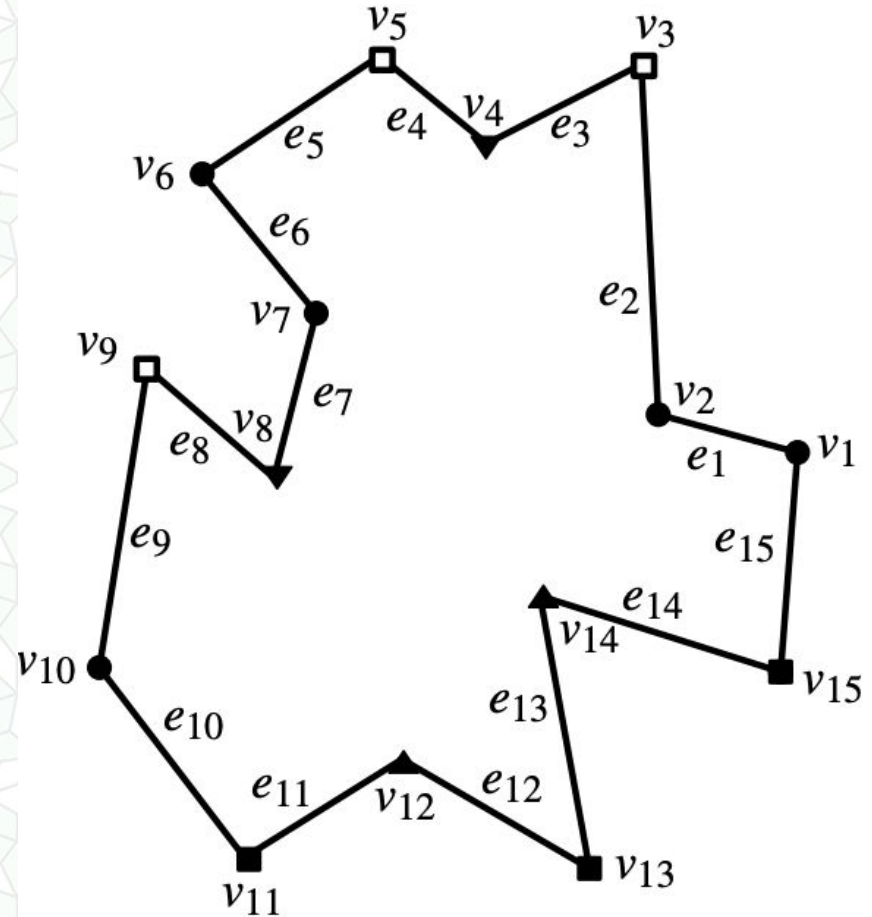




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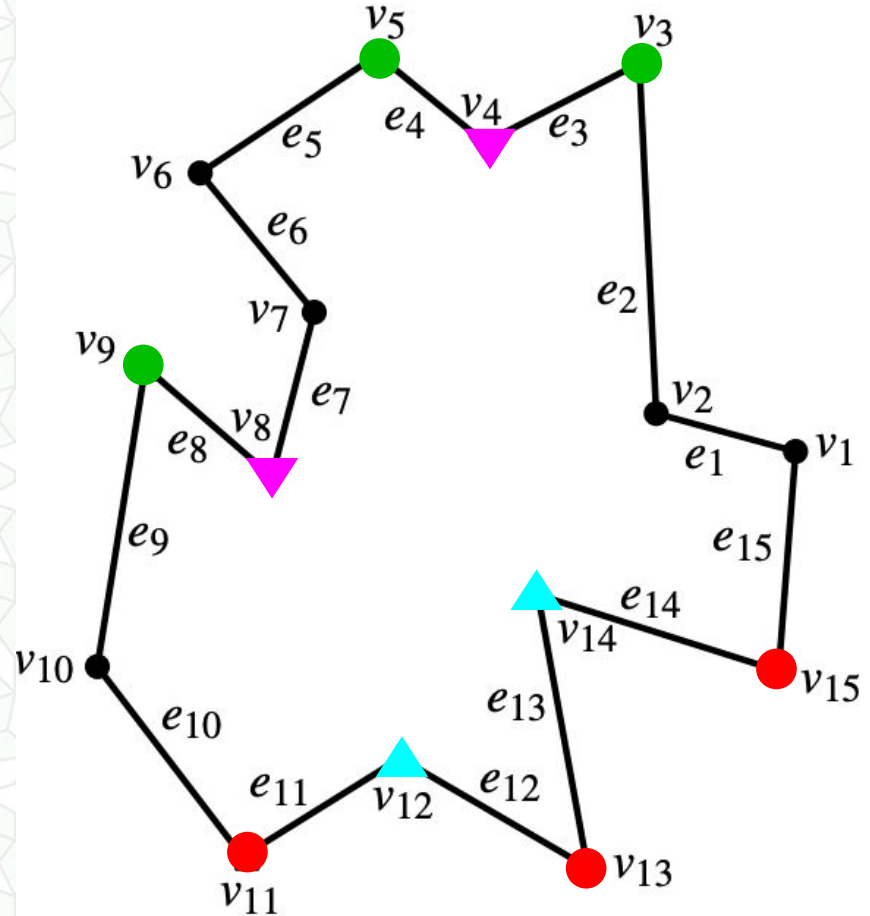
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# Identify Vertex Types



# Identify Vertex Types

- = start vertex
- = end vertex
- = regular vertex
- ▲ = split vertex
- ▼ = merge vertex

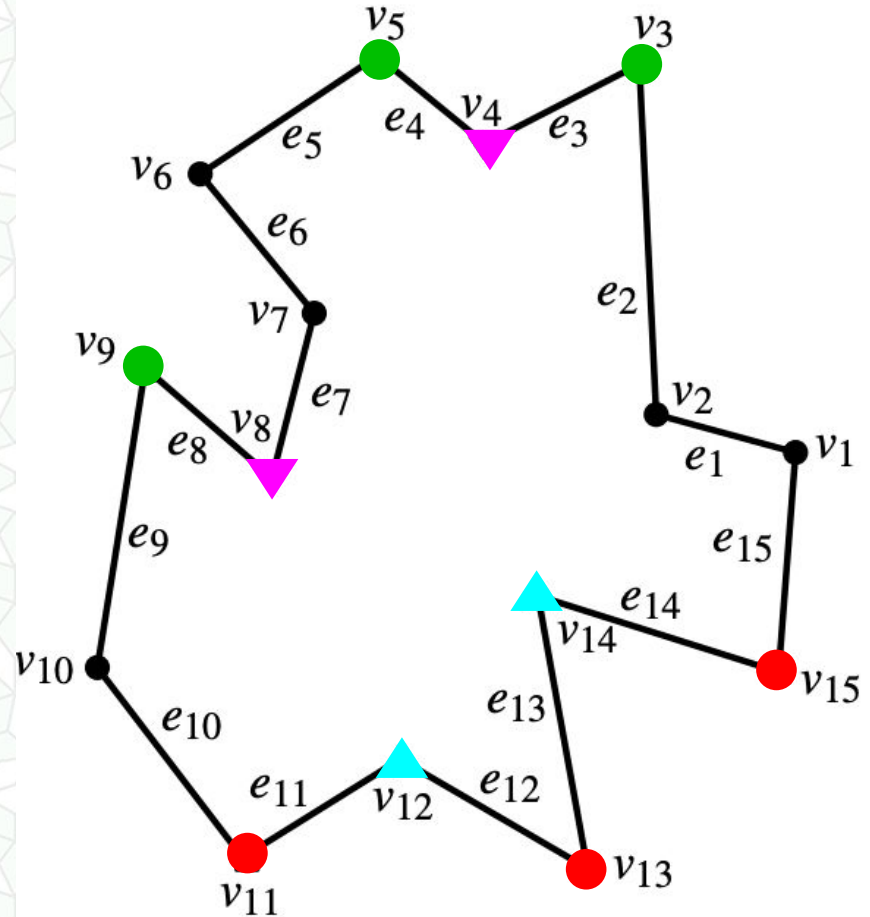


# Identify Vertex Types

- Direction (up or down) of adjacent edges

- Interior angle at vertex ( $> 180^\circ$  or  $< 180^\circ$ )

- = start vertex
- = end vertex
- = regular vertex
- ▲ = split vertex
- ▼ = merge vertex



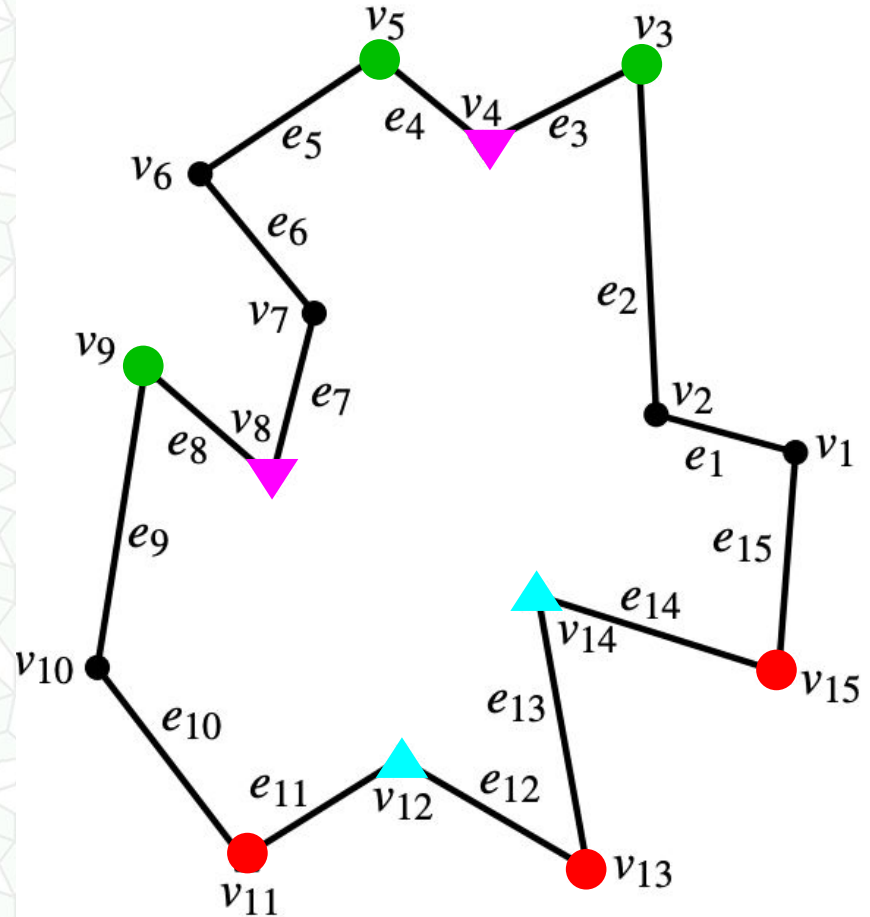
## *DEGENERACY NOTE*

“Break Ties” consistently

- $p$  is “below”  $q$  if  $p_y < q_y$  or  $p_y = q_y$  and  $p_x > q_x$
- $p$  is “above”  $q$  if  $p_y > q_y$  or  $p_y = q_y$  and  $p_x < q_x$

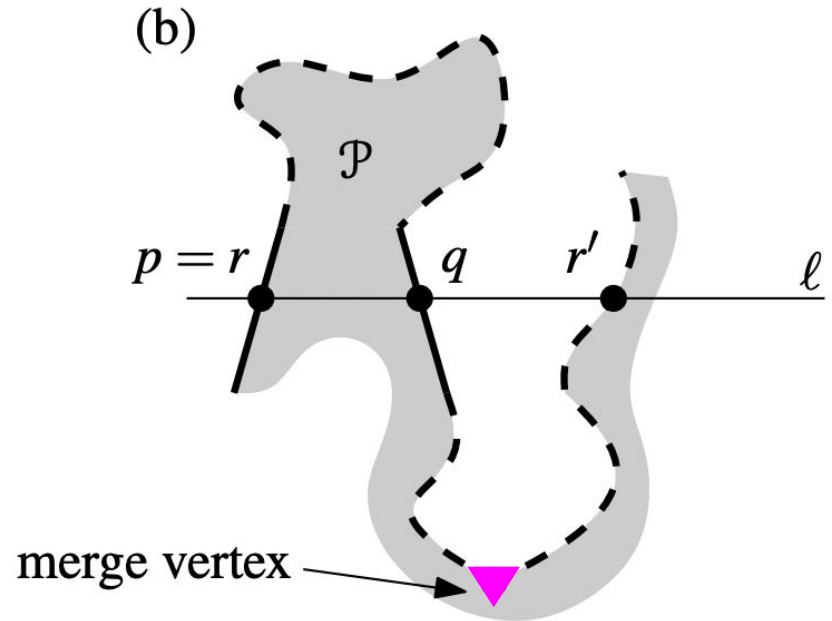
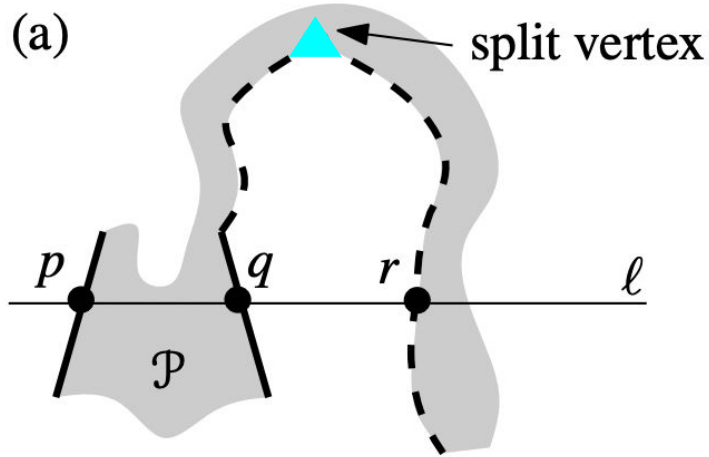
**Lemma 3.4:** A polygon is  $y$ -monotone if it has no split vertices or merge vertices.

- = start vertex
- = end vertex
- = regular vertex
- ▲ = split vertex
- ▼ = merge vertex



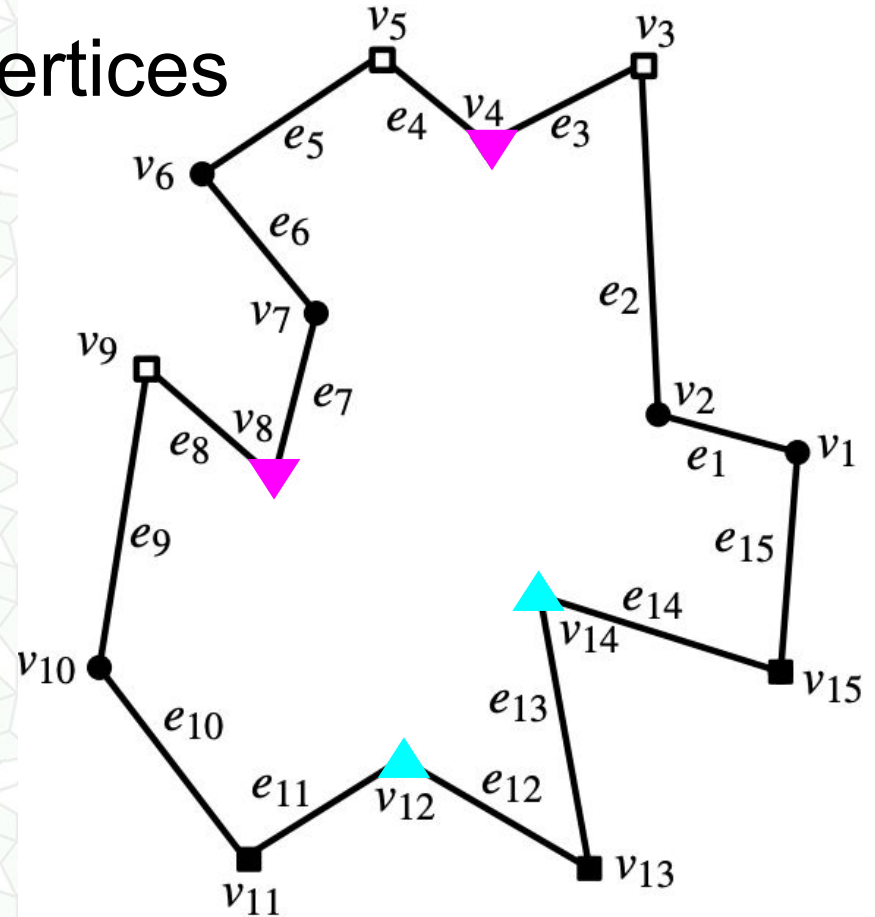
**Lemma 3.4:** A polygon is  $y$ -monotone if it has no split vertices or merge vertices.

*A connected shape that crosses a horizontal sweep line at  $\geq 3$  points must either have a split vertex or a merge vertex!*



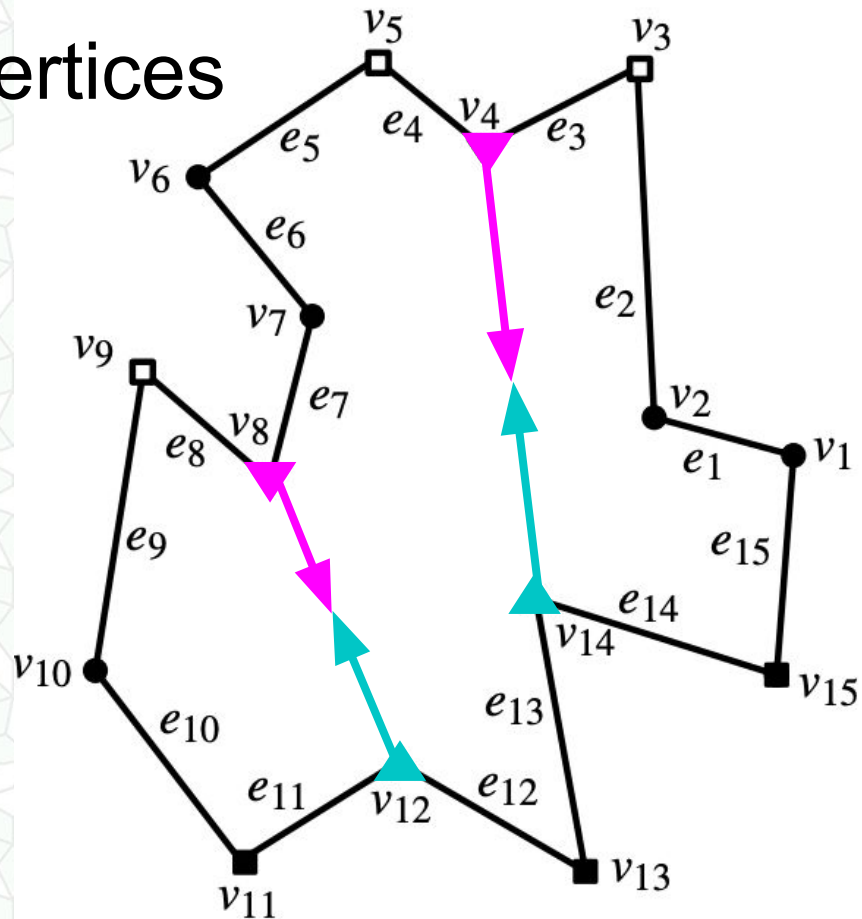


# Eliminate Merge & Split Vertices



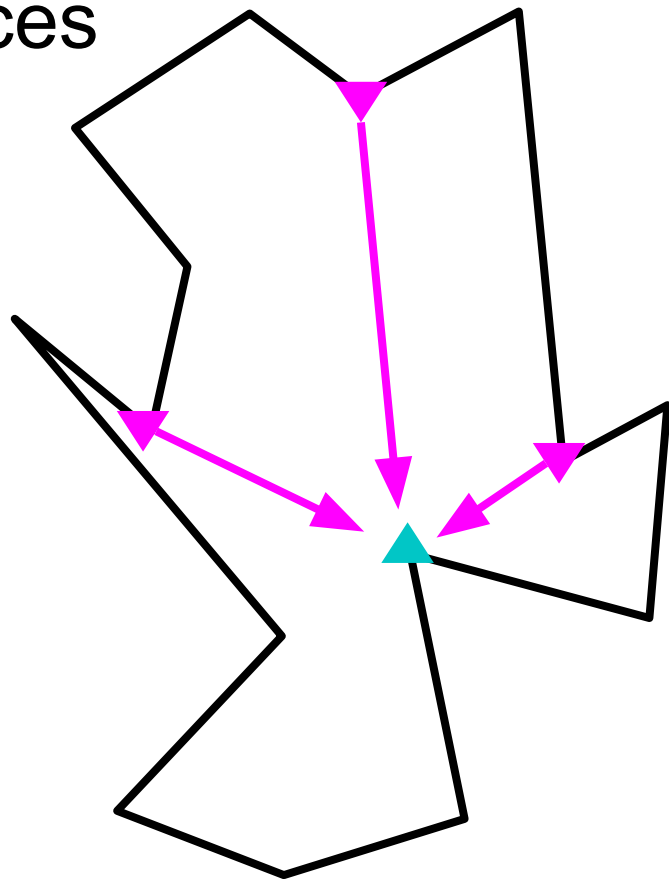
# Eliminate Merge & Split Vertices

- In some cases you might be able to neatly pair each **merge vertex** with a **split vertex**.....
- *But how do you match them up to form diagonals?*



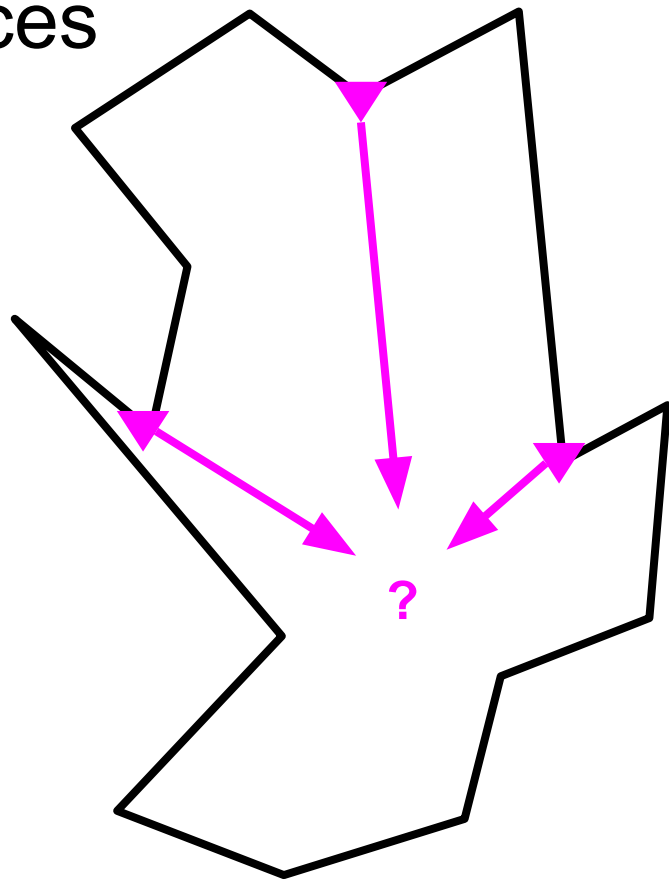
# Eliminate Merge & Split Vertices

- In some cases you might be able to neatly pair each **merge vertex** with a **split vertex**.....
- *But what if  
# merge vertices  $\neq$  # split vertices?*
- *Can multiple merge vertices  
connect to the same  
split vertex?  
(or vice versa)*



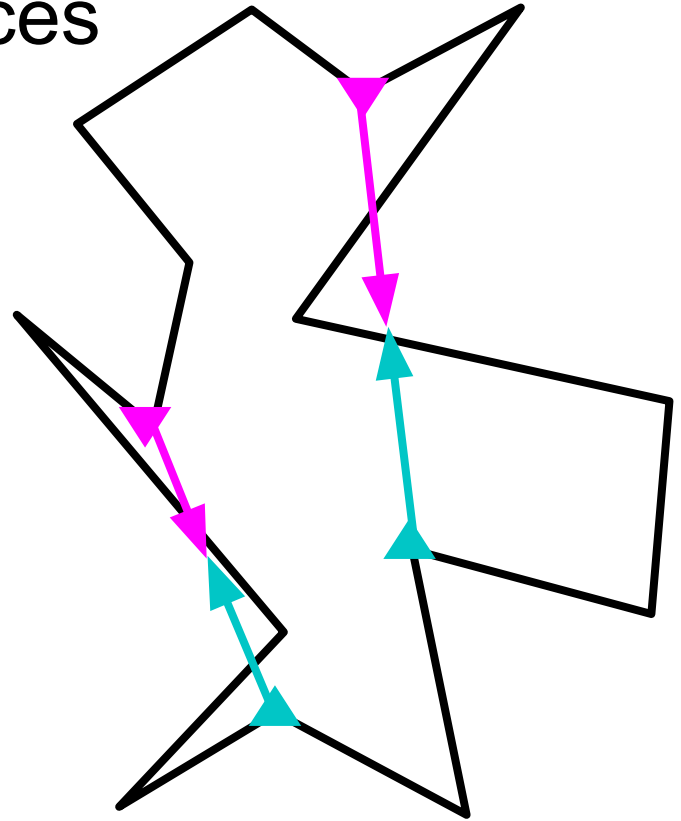
# Eliminate Merge & Split Vertices

- In some cases you might be able to neatly pair each **merge vertex** with a **split vertex**.....
- *What if there are no split vertices?*
- *What should the other end of the diagonal be?*



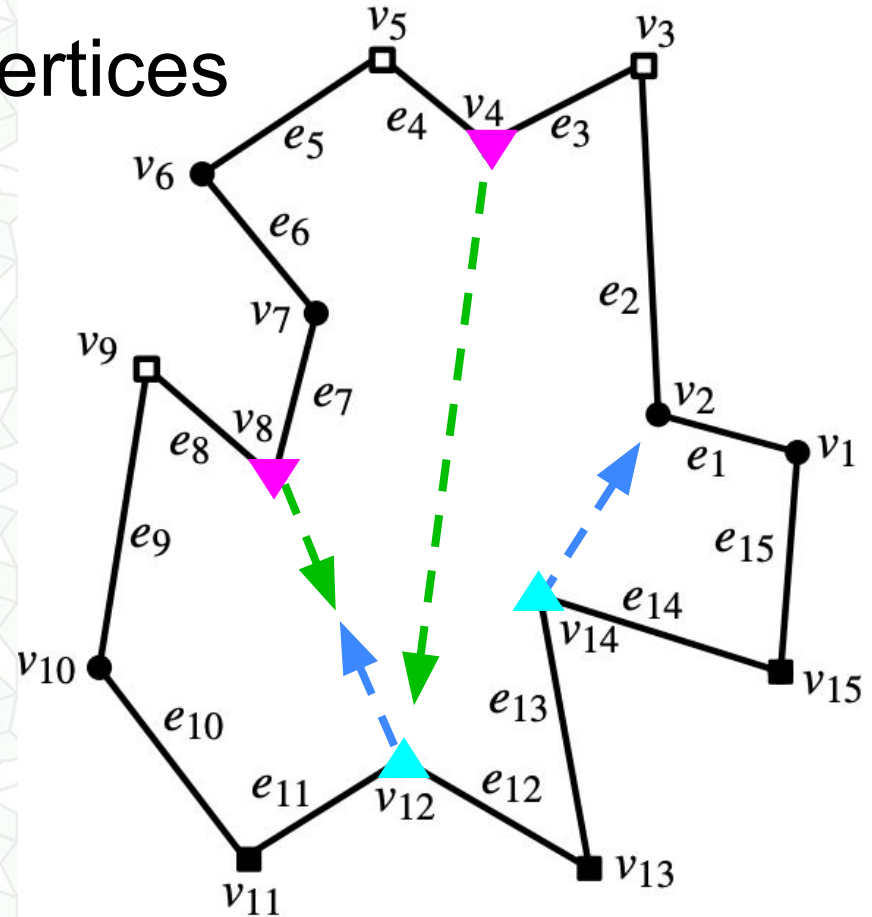
# Eliminate Merge & Split Vertices

- In some cases you might be able to neatly match each **merge vertex** with a **split vertex**.....
- *What if the diagonals intersect the original polygon?*
- *What if the diagonals intersect each other?*
- *UGH*



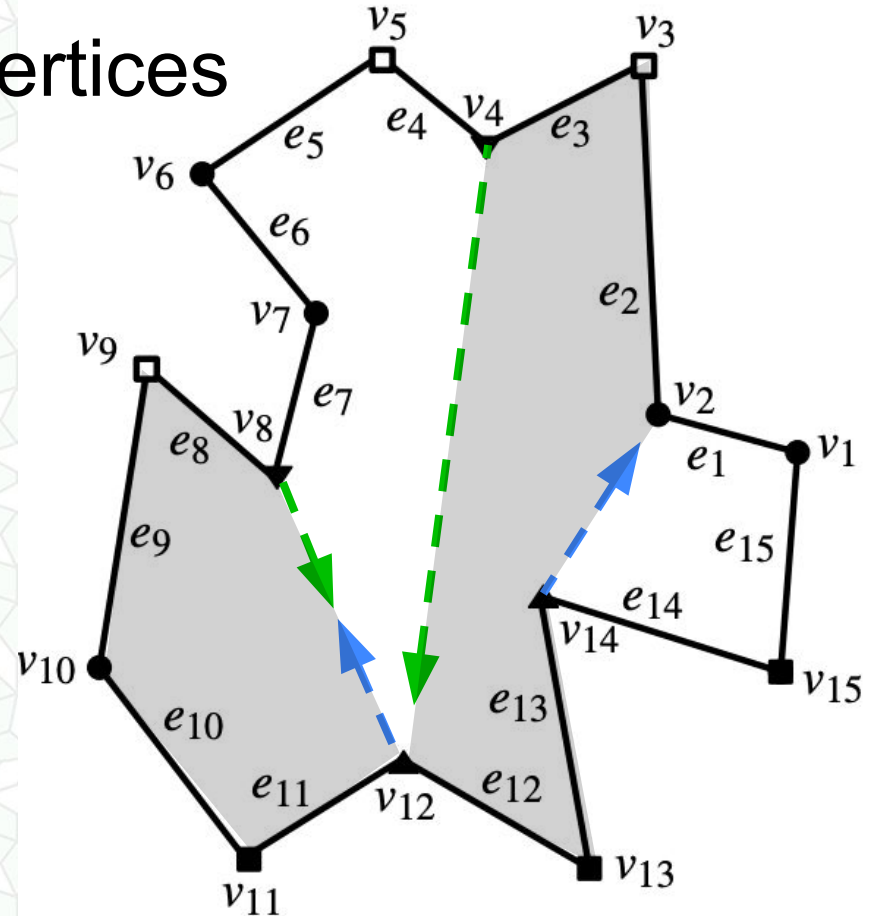
# Eliminate Merge & Split Vertices

- Cut polygon on a diagonal going upwards from every split vertex.
- And downwards from every merge vertex.
- *Make sure these diagonals don't intersect the polygon or another diagonal!*



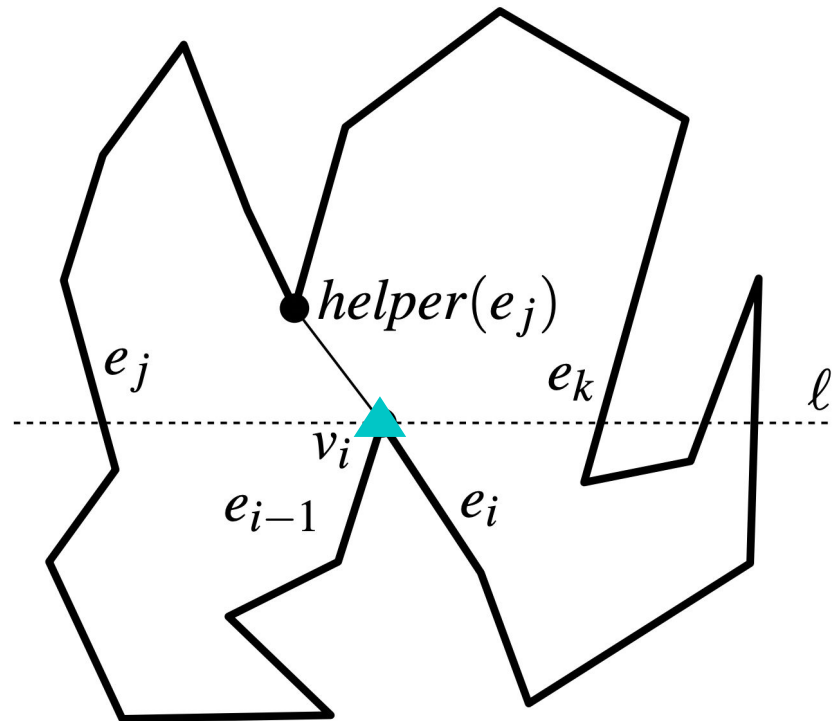
# Eliminate Merge & Split Vertices

- Cut polygon on a diagonal going upwards from every split vertex.
- And downwards from every merge vertex.
- *Make sure these diagonals don't intersect the polygon or another diagonal!*
- *End result is monotone polygons!*



# How do we decide what to connect them to?

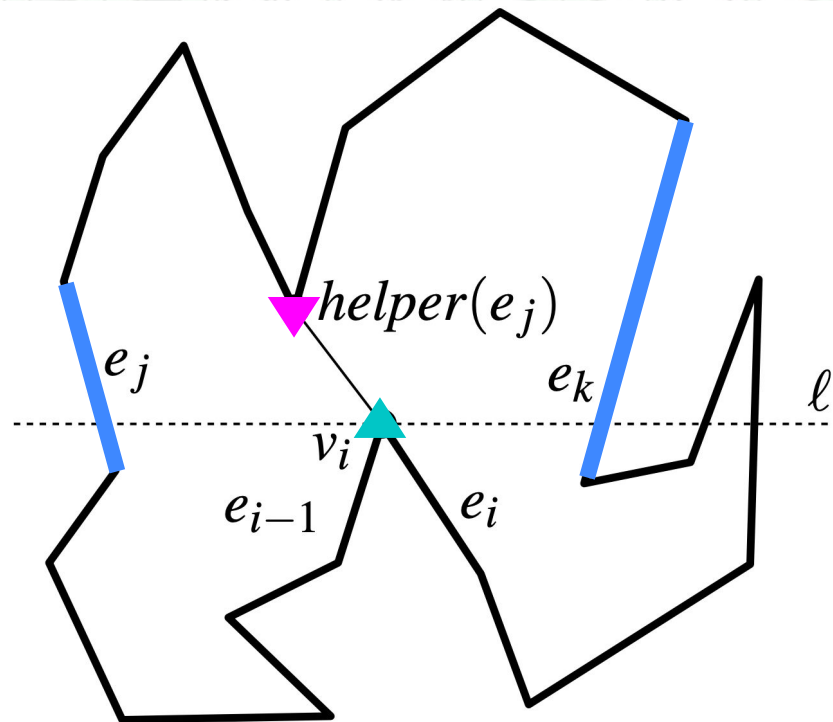
- Perform line sweep from top to bottom
- When we find **split vertex  $v_i$** , connect it to a vertex above us...
- Which vertex?





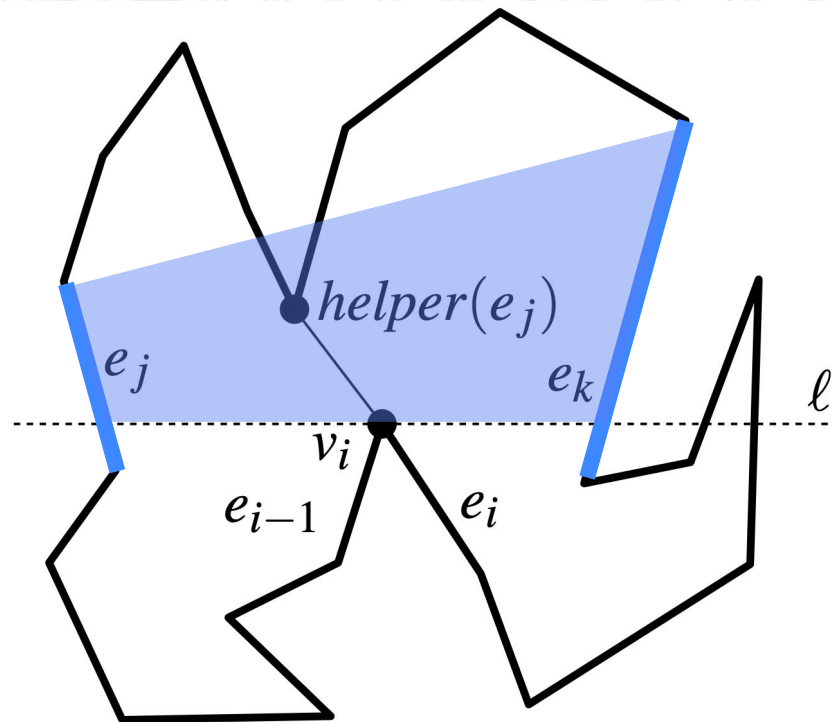
# How do we decide what to connect them to?

- Perform line sweep from top to bottom
- When we find **split vertex  $v_i$** , connect it to a vertex above us...
- Which vertex?
- Find **line to left,  $e_j$** , and to right,  **$e_k$** , of  $v_i$  on the current sweep line.
- Locate the lowest point between these two lines (a **merge vertex**)
- If none, take the upper end point of edge  $e_j$  or edge  $e_k$



# How do we decide what to connect them to?

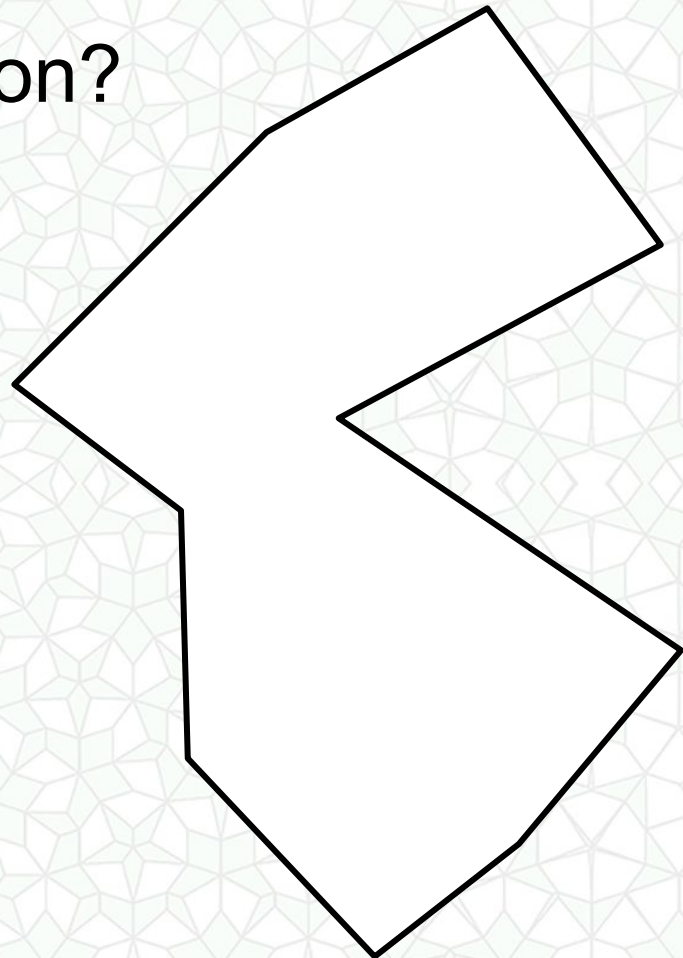
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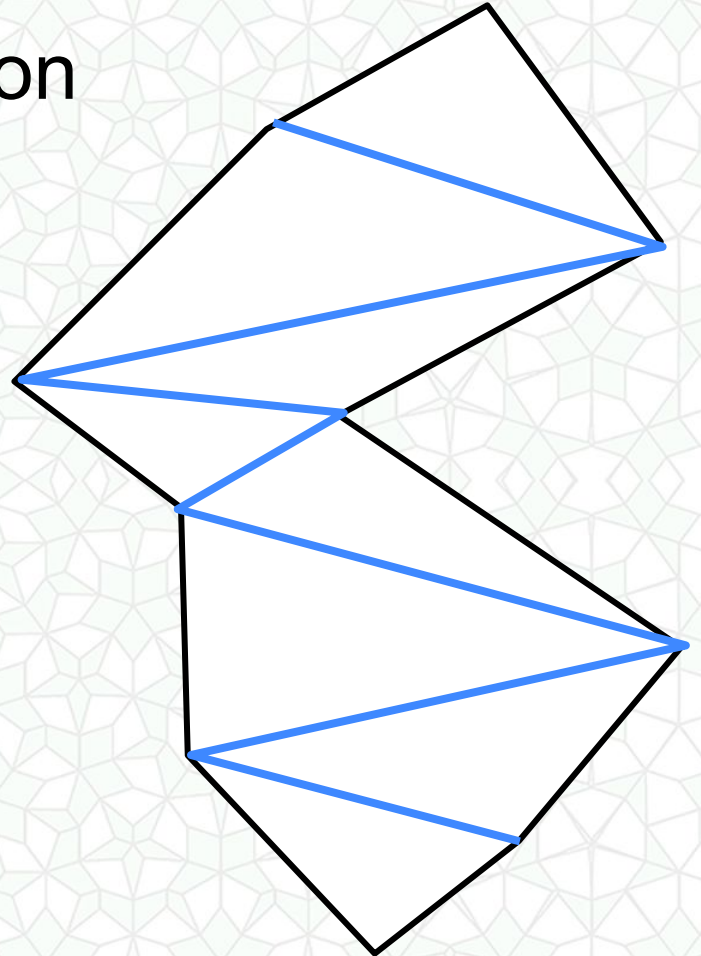
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Triangulate a Monotone Polygon?

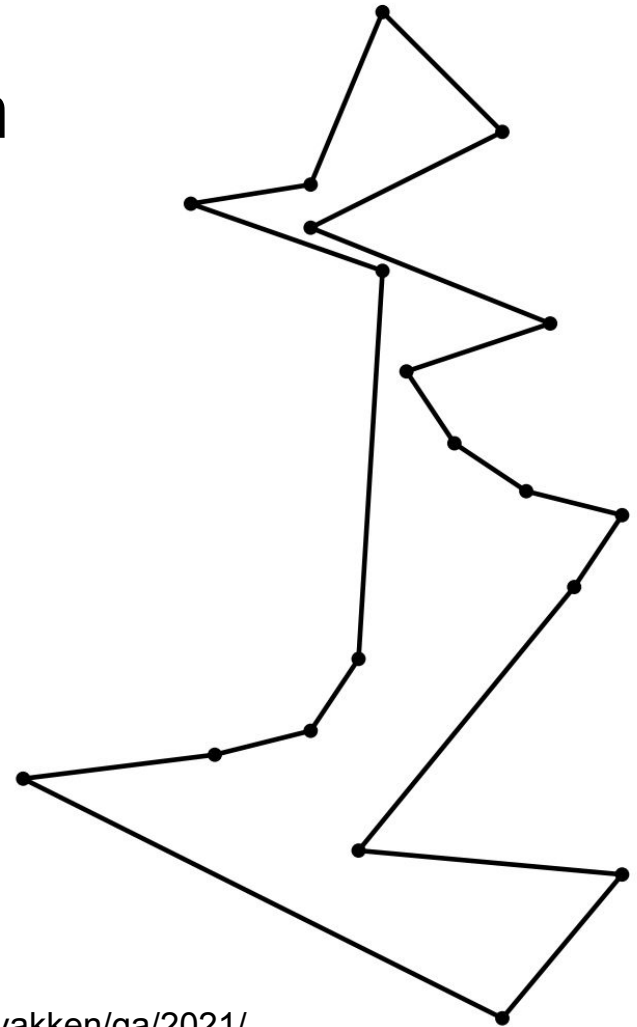


# Triangulate a Monotone Polygon

- Can we always just draw a zig zag down the middle of a monotone polygon?
- Unfortunately no, it's a little more complicated

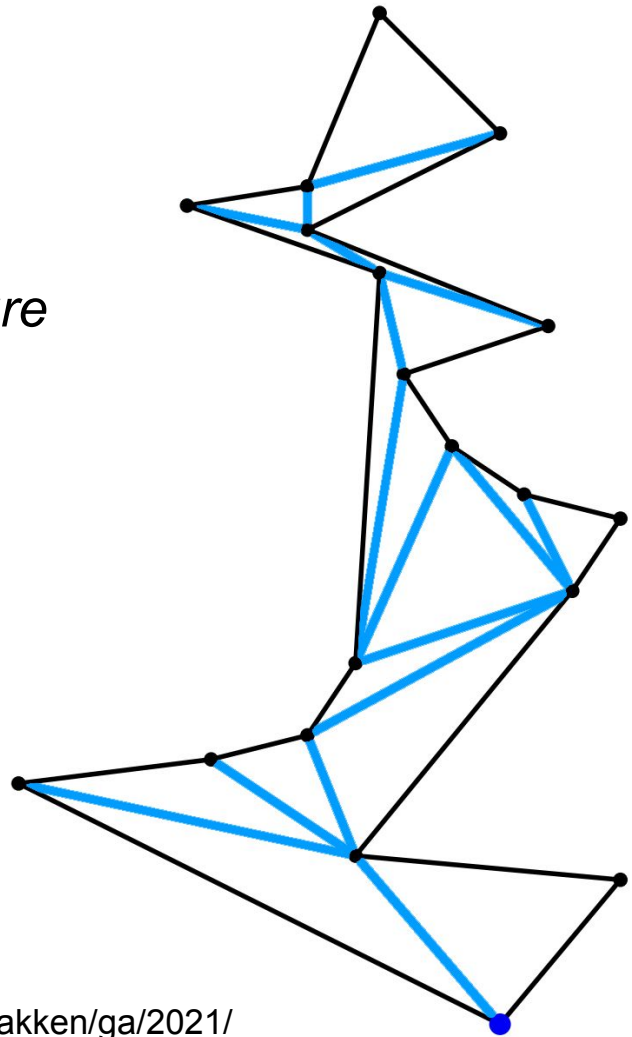


# Triangulate a Monotone Polygon



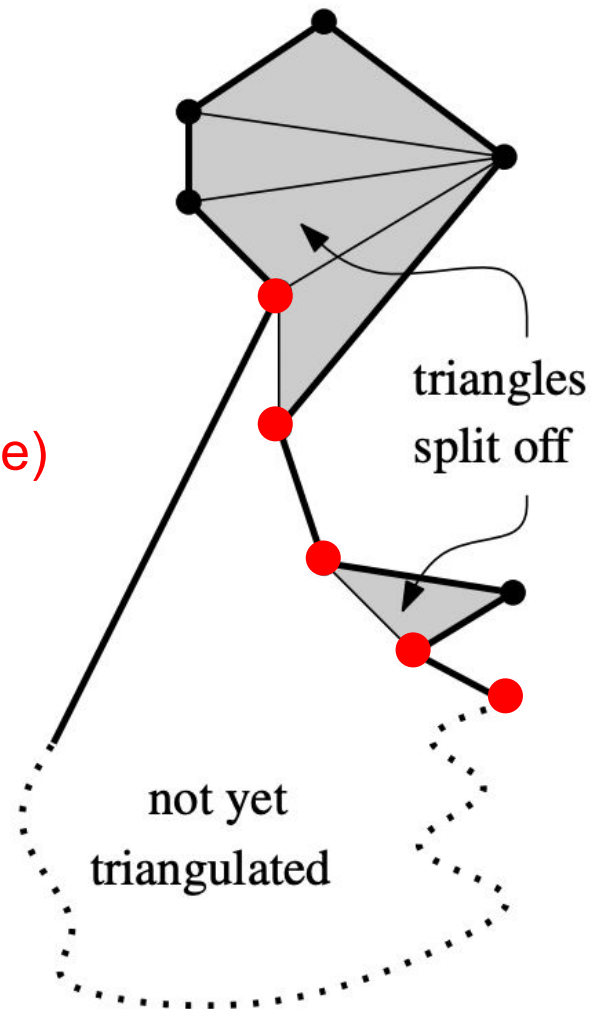
# Triangulate a Monotone Polygon

- Sort all of the points vertically
- Push top two points onto a *stack data structure*
- Process the remaining points, one at a time, from top to bottom
- If you can...
  - make a triangle with the new point and the last two points on the stack
  - & remove 1 point
  - & repeat
- If not, push the new point on the stack



# Triangulate a Monotone Polygon

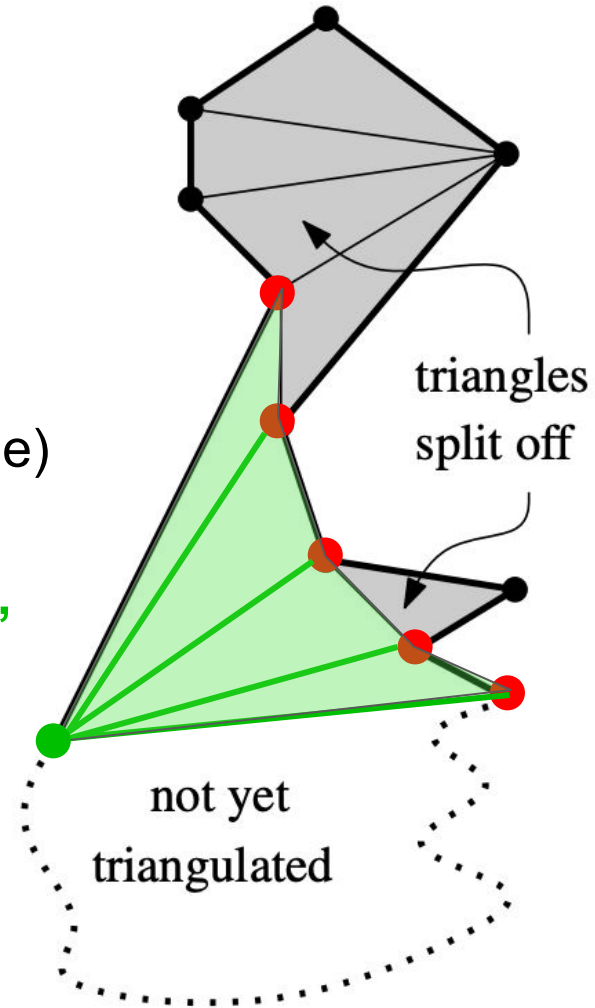
- **Vertices that have been finished**
- Triangles that have already been added
- Vertices currently on the stack form an “upside down funnel” on one side (e.g., right side)





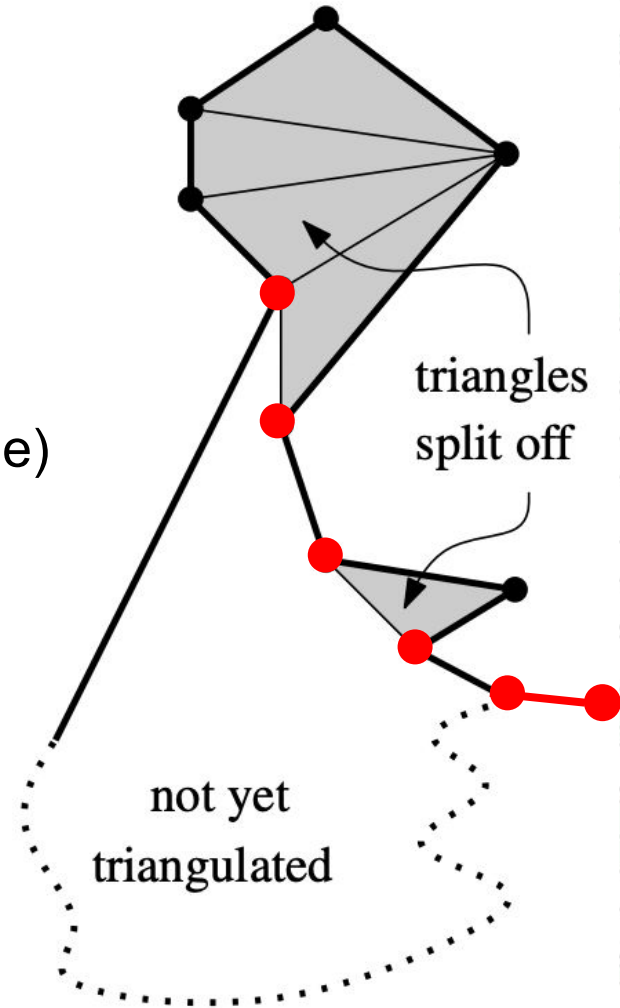
# Triangulate a Monotone Polygon

- Vertices that have been finished
- Triangles that have already been added
- Vertices currently on the stack form an “upside down funnel” on one side (e.g., right side)
- The next vertex below us will:
  - **Be from the (left) side and create a “fan”, Leaving only 2 vertices on the stack**



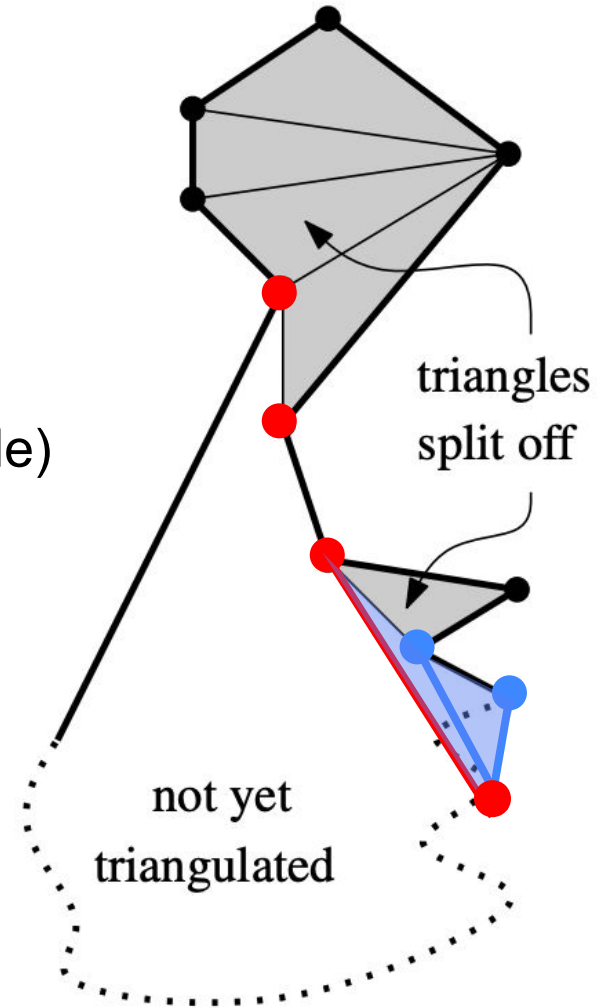
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- The next vertex below us will:
  - Be from the (left) side and create a “fan”, Leaving only 2 vertices on the stack
  - Be on the (right) side and:
    - **Bend the funnel further from vertical axis**



# Triangulate a Monotone Polygon

- Vertices that have been finished
- Triangles that have already been added
- Vertices currently on the stack form an “upside down funnel” on one side (e.g., right side)
- The next vertex below us will:
  - Be from the (left) side and create a “fan”, Leaving only 2 vertices on the stack
  - Be on the (right) side and:
    - Bend the funnel further from vertical axis
    - **Form one or more triangles**



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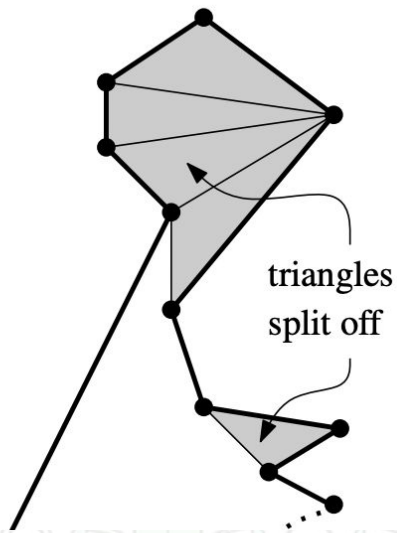
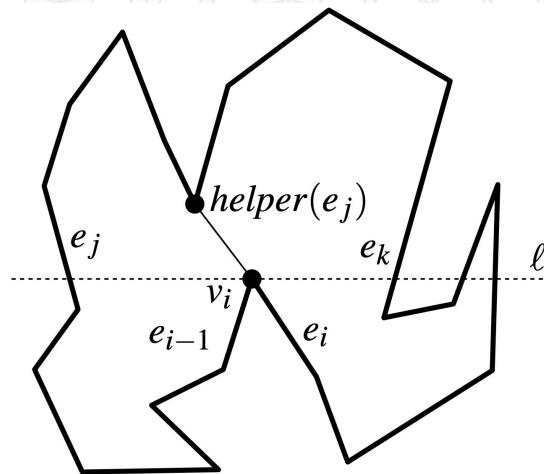
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# Analysis?

- Line sweep algorithm: cut into monotone polygons

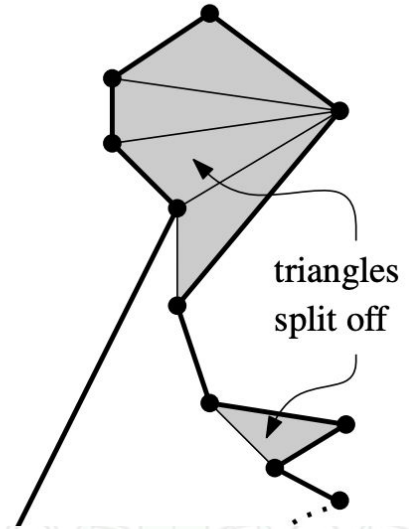
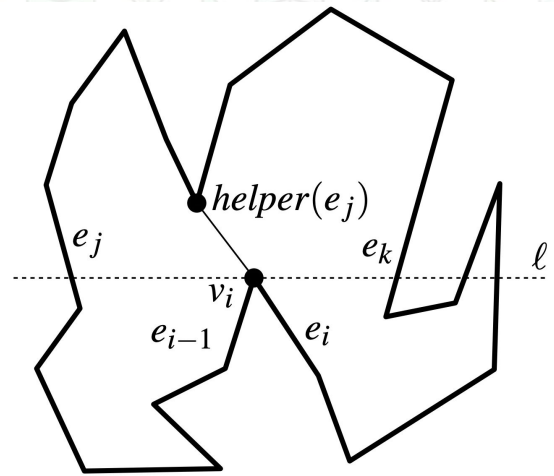
- Use stack to triangulate monotone polygon

- Overall →



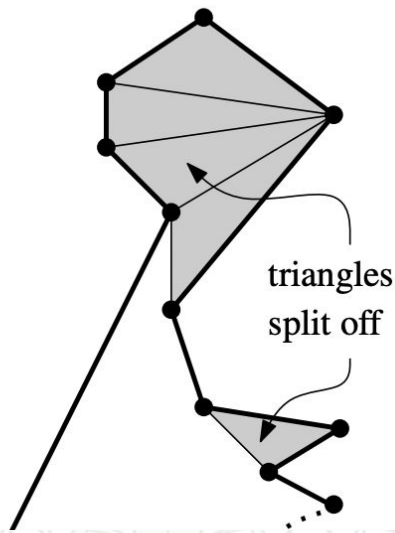
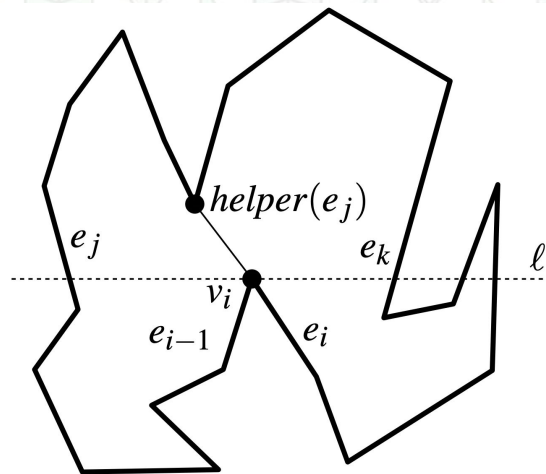
# Analysis?

- Line sweep algorithm: cut into monotone polygons
  - Sort all vertices vertically -
  - Maintain horizontal sorting of active vertices -
  - Locate “helper” vertex for each split/merge -
  - →
- Use stack to triangulate monotone polygon
  - Don't need to sort (just walk boundary)
  - Each vertex is added once -
  - Each vertex (beyond first two) adds one triangle when it is removed from stack -
  - →
- Overall →

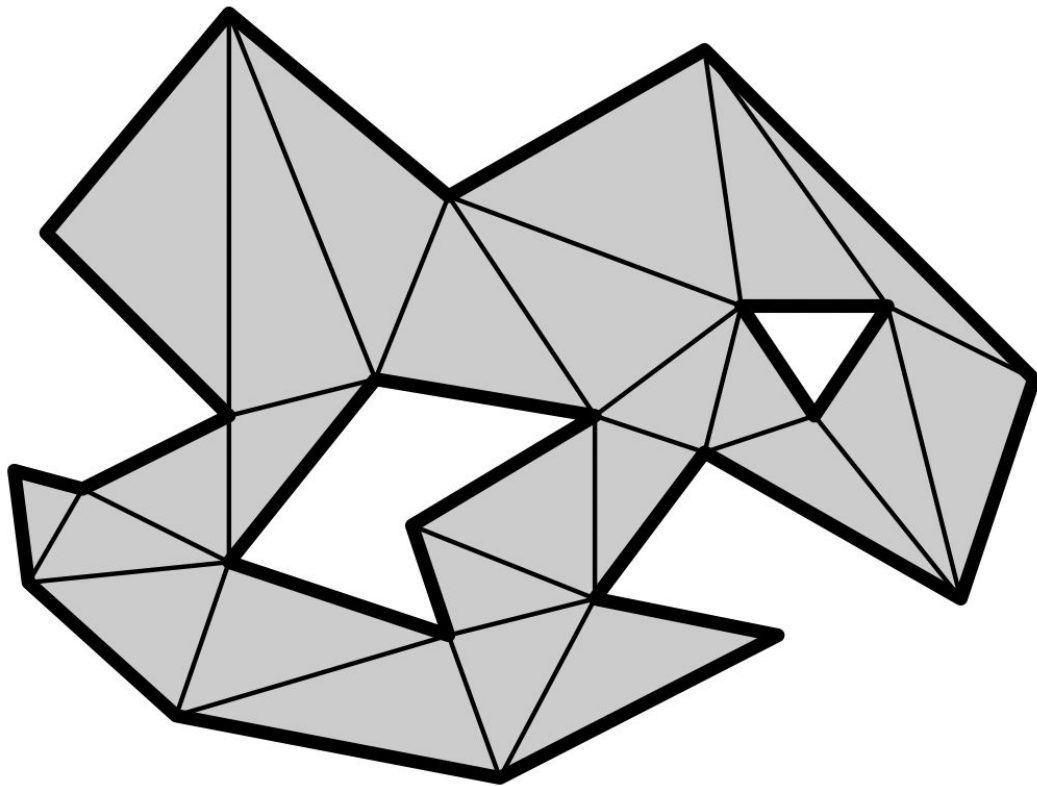


# Analysis?

- Line sweep algorithm: cut into monotone polygons
  - Sort all vertices vertically -  $O(n \log n)$
  - Maintain horizontal sorting of active vertices -  $O(\log n)$
  - Locate “helper” vertex for each split/merge -  $O(\log n)$
  - $\rightarrow O(n \log n)$
- Use stack to triangulate monotone polygon
  - Don't need to sort (just walk boundary)
  - Each vertex is added once -  $O(1)$
  - Each vertex (beyond first two) adds one triangle when it is removed from stack -  $O(1)$
  - $\rightarrow O(n)$
- Overall  $\rightarrow O(n \log n)$   
*Better than  $O(n^2)$  algorithm from previous lecture!*



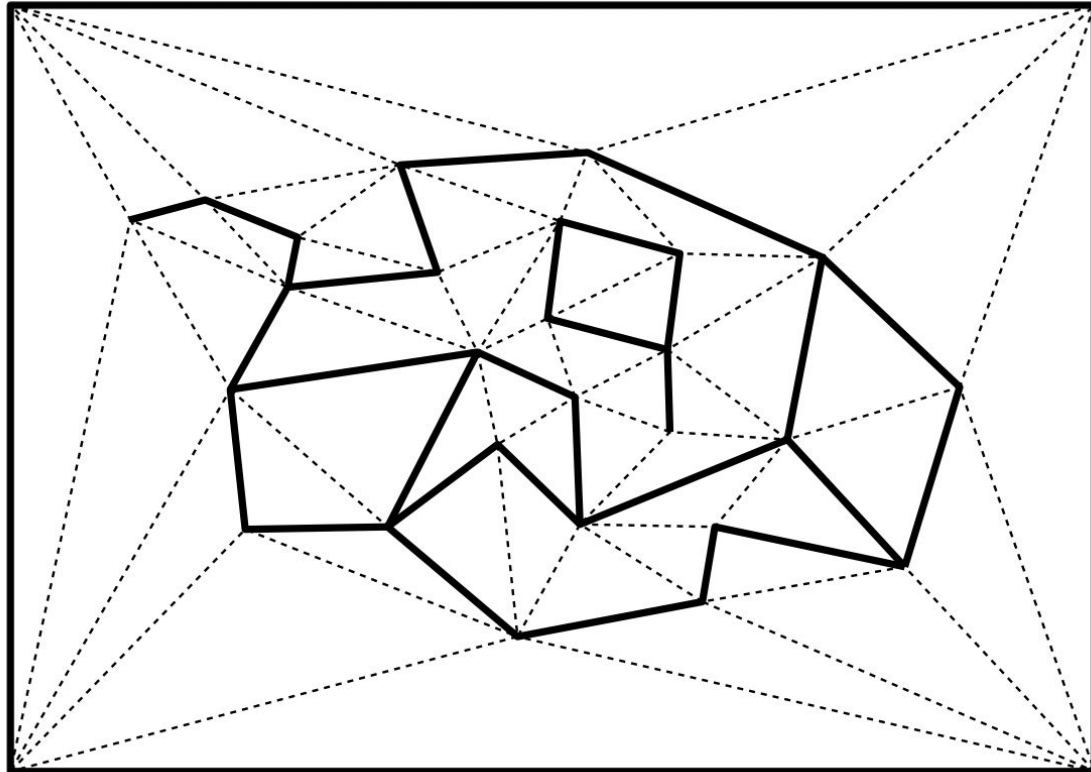
# Also Works for Non-Simple Polygons (w/ interior holes)



*Computational Geometry  
Algorithms and Applications,*  
de Berg, Cheong, van Kreveld  
and Overmars, Chapter 3



# And it also works for Arbitrary Planar Subdivisions



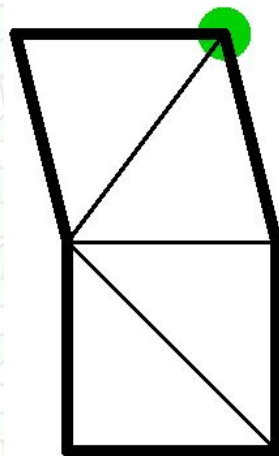
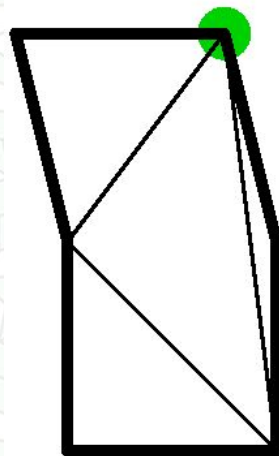
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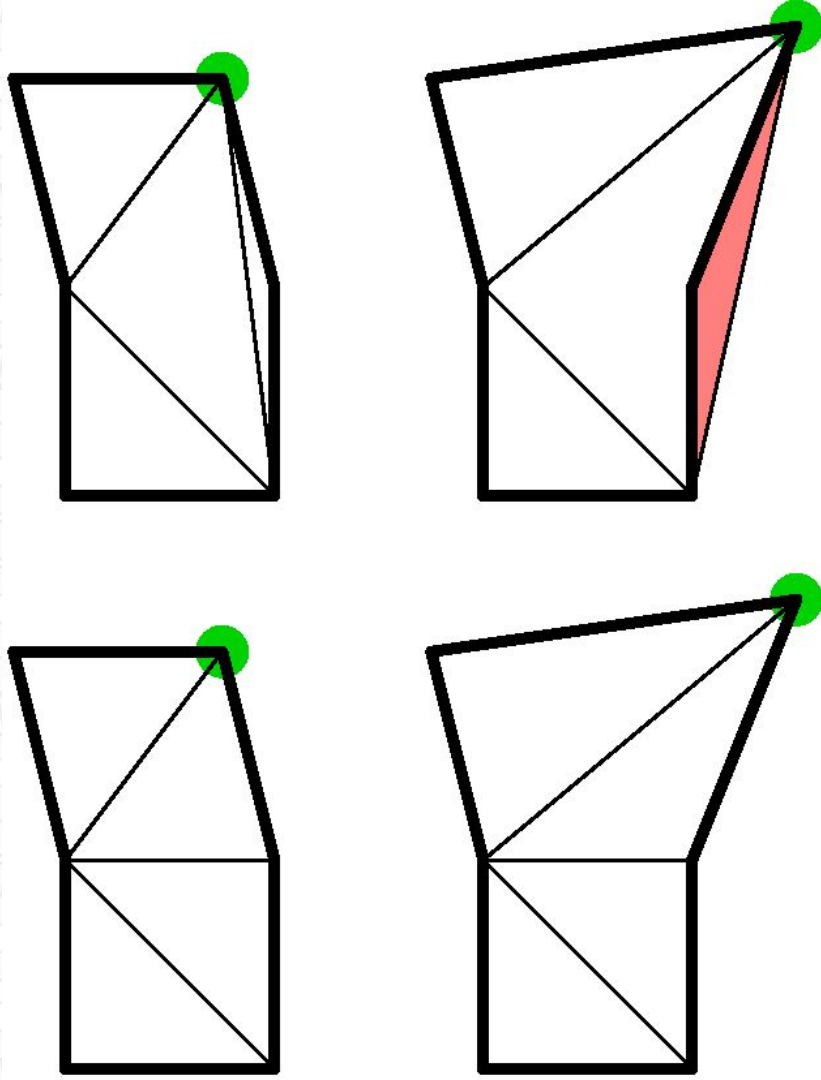
# Element Quality and Deformation Simulation

- The triangulation of a polygon is not unique!
- Do we care which triangulation is produced?
- Are some triangulations Better for some applications?

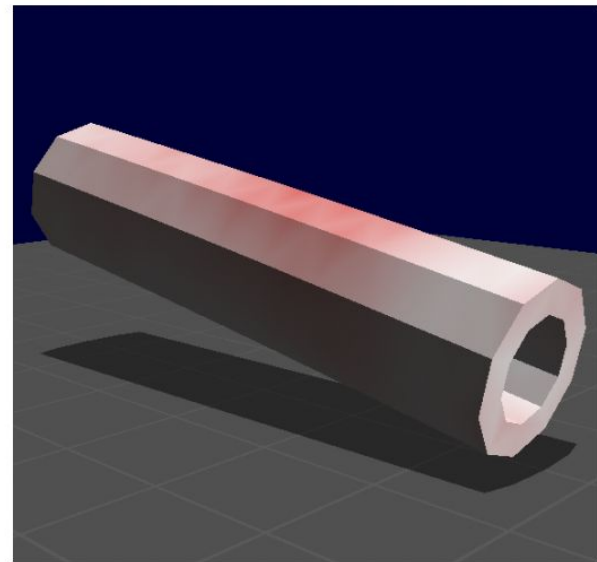
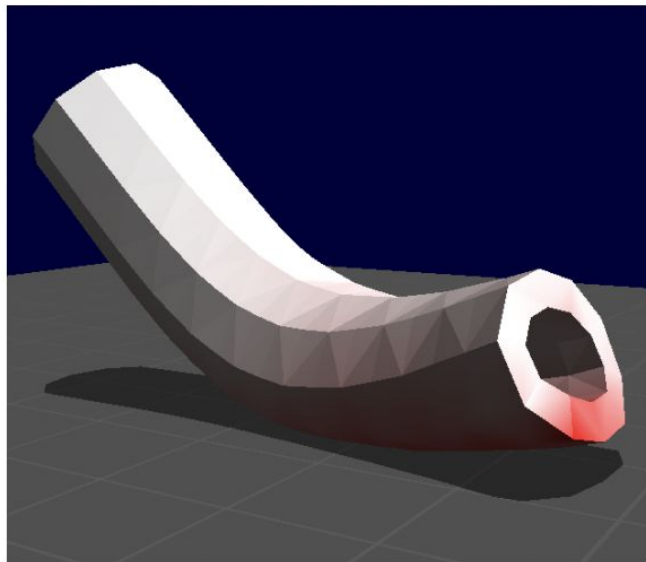
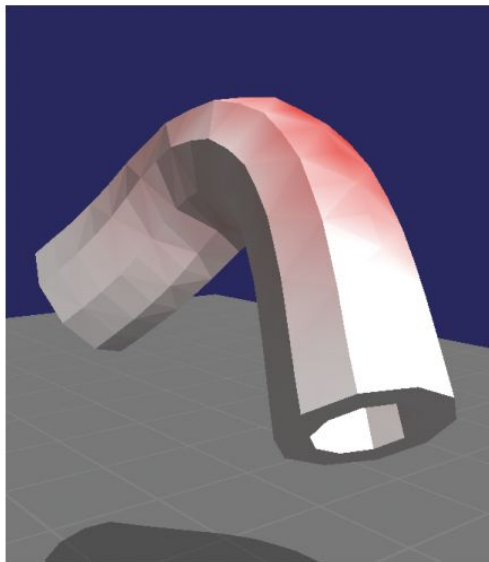


# Element Quality and Deformation Simulation

- The triangulation of a polygon is not unique!
- Do we care which triangulation is produced?
- Are some triangulations Better for some applications?



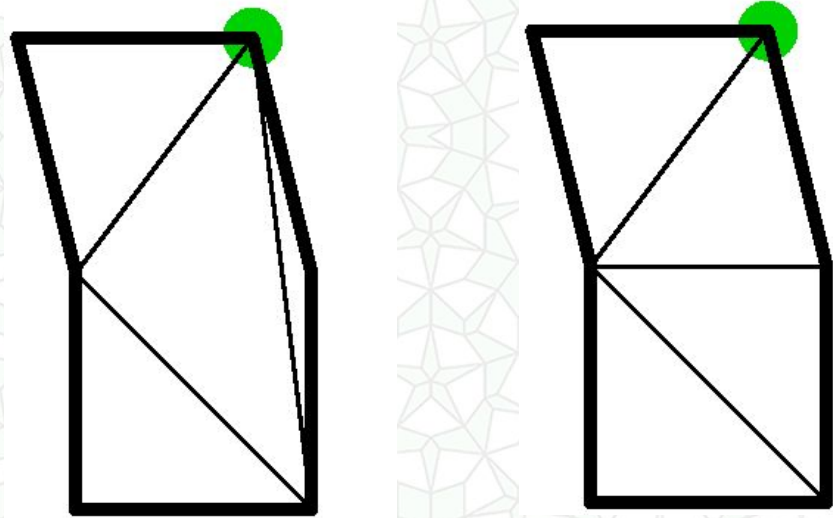
# Element Quality and Deformation Simulation



Mueller, Dorsey, McMillan, Jagnow, & Cutler  
*Stable Real-Time Deformations*  
Symposium on Computer Animation 2002

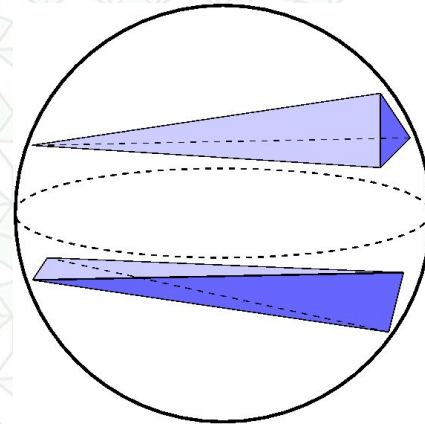
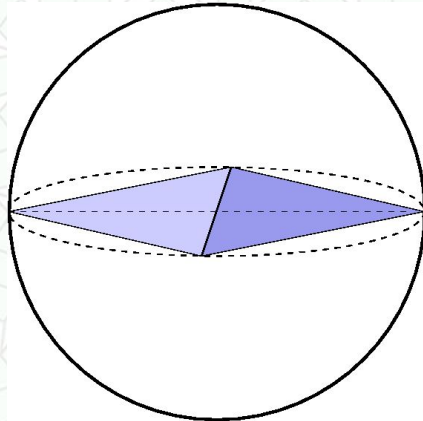
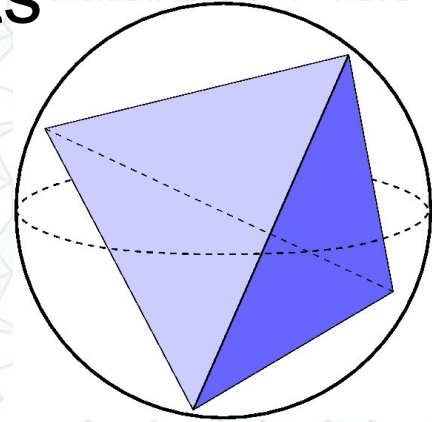
# Degenerate/ill-conditioned 2D Elements

- a.k.a. how “equilateral” are the *triangles*?
  - Maximize the minimum angle
  - Minimize the maximum angle
  - Maximize the shortest edge
  - Ratio of longest edge to shortest edge
  - Ratio of area to area of circumscribed circle



# Degenerate/ill-conditioned 3D Elements

- a.k.a. how “equilateral” are the *tetrahedra*?
  - Ratio of volume<sup>2</sup> to surface area<sup>3</sup>
  - Smallest *solid* angle
  - Ratio of volume to volume of smallest circumscribed sphere



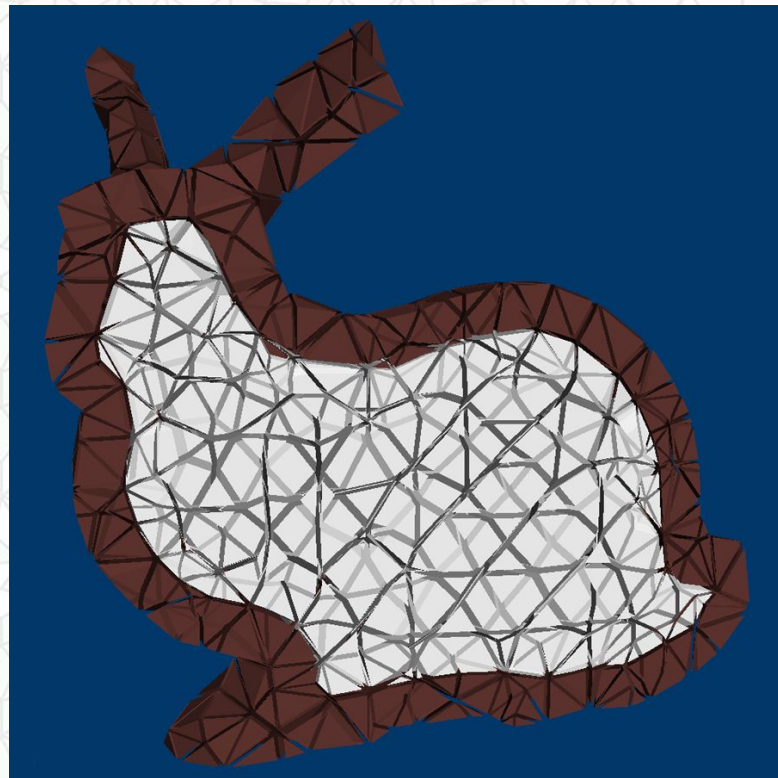
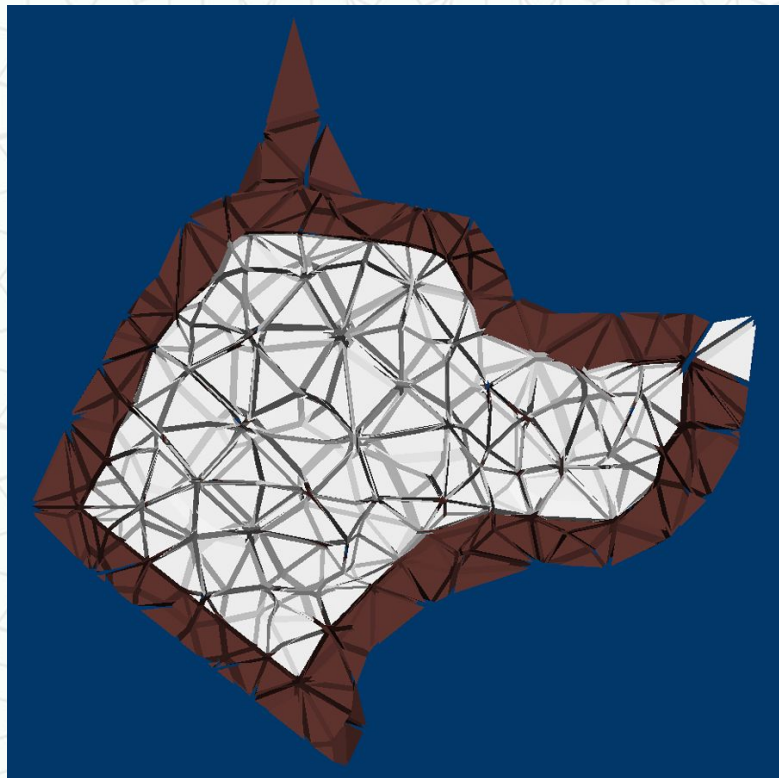
# Element Quality and Deformation Simulation

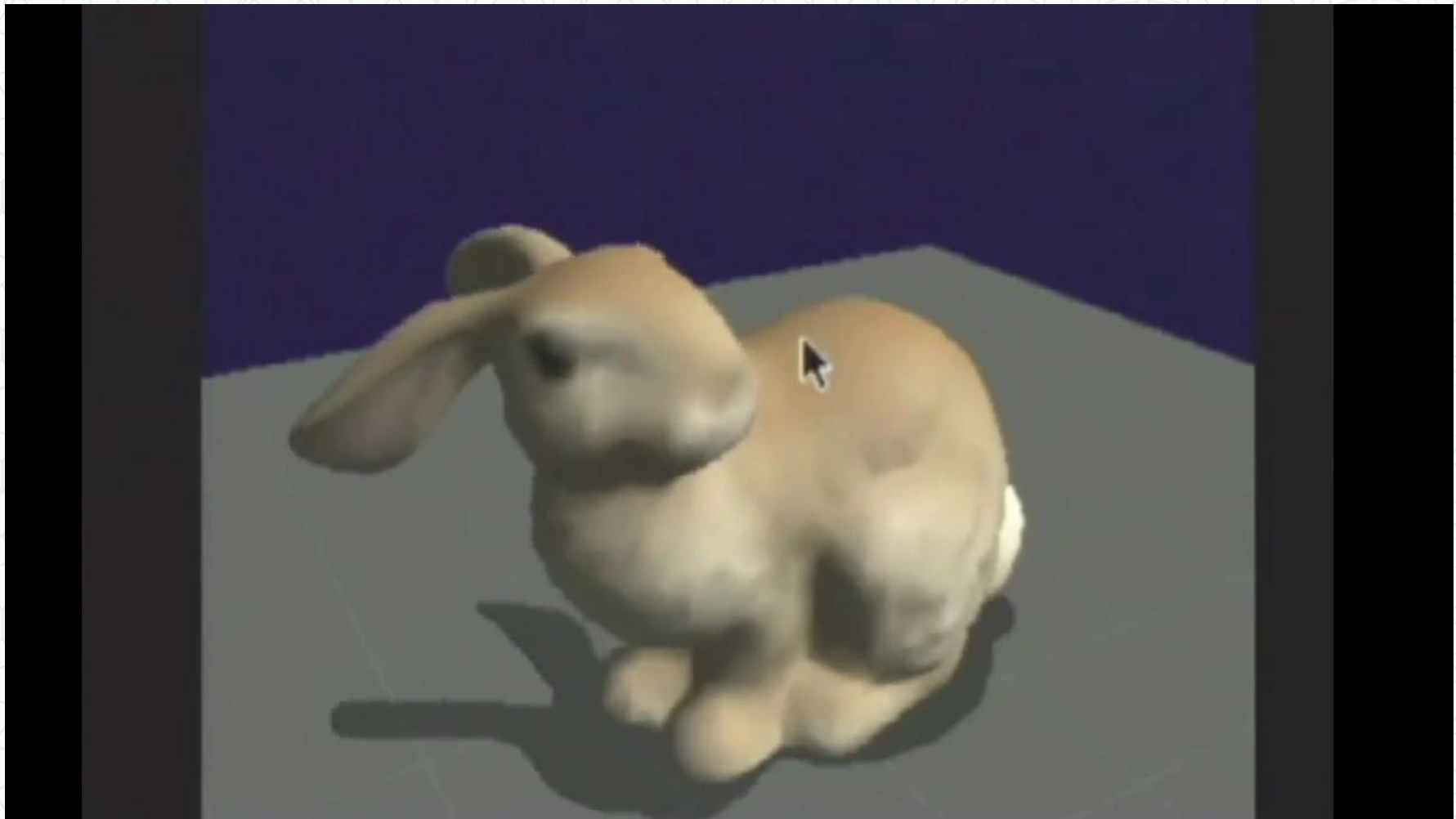




# Multiple Materials

Mueller, Dorsey, McMillan, Jagnow, & Cutler  
*Stable Real-Time Deformations*  
Symposium on Computer Animation 2002





# Next Lecture: Manufacturing by Mold Casting

