

CSCI 4560/6560 Computational Geometry

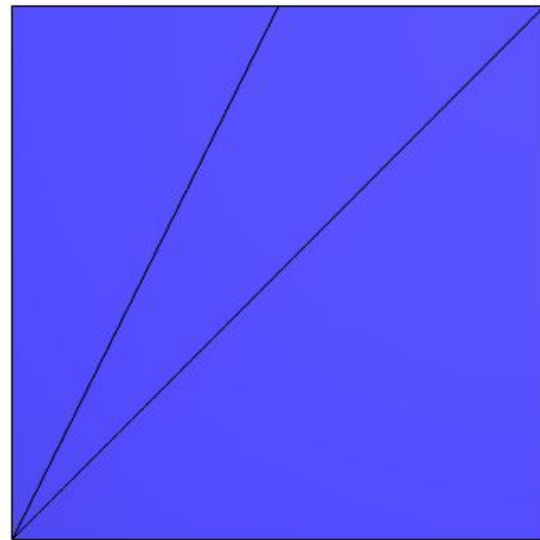
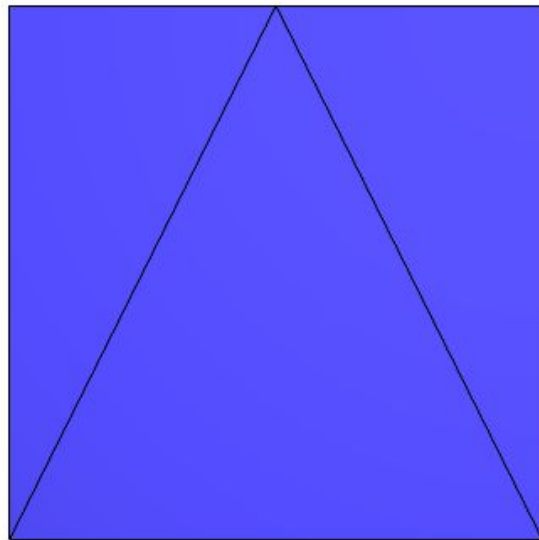
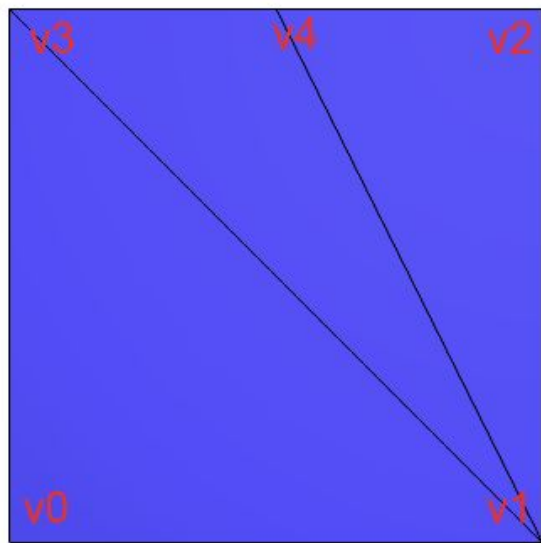
<https://www.cs.rpi.edu/~cutler/classes/computationalgeometry/F23/>

Lecture 17: Quad Trees

Outline for Today

- Homework 7 Posted
- Last Time: Windowing, Interval Trees & Segments Trees
- Motivation: FEM & CFD Simulation
- Uniform & Non-Uniform Meshing
- k-D Tree vs Quad Tree
- Maximum Depth, Number of Nodes
- Implicit Adjacency, Balanced Quad Tree
- Advanced Topics: $\sqrt{3}$ Subdivision & Octree Textures
- Remeshing for Interactive Deformation
- Next Time: Signed Distance Fields & Level Sets

Homework 7: Delaunay Triangulation Edge Flips



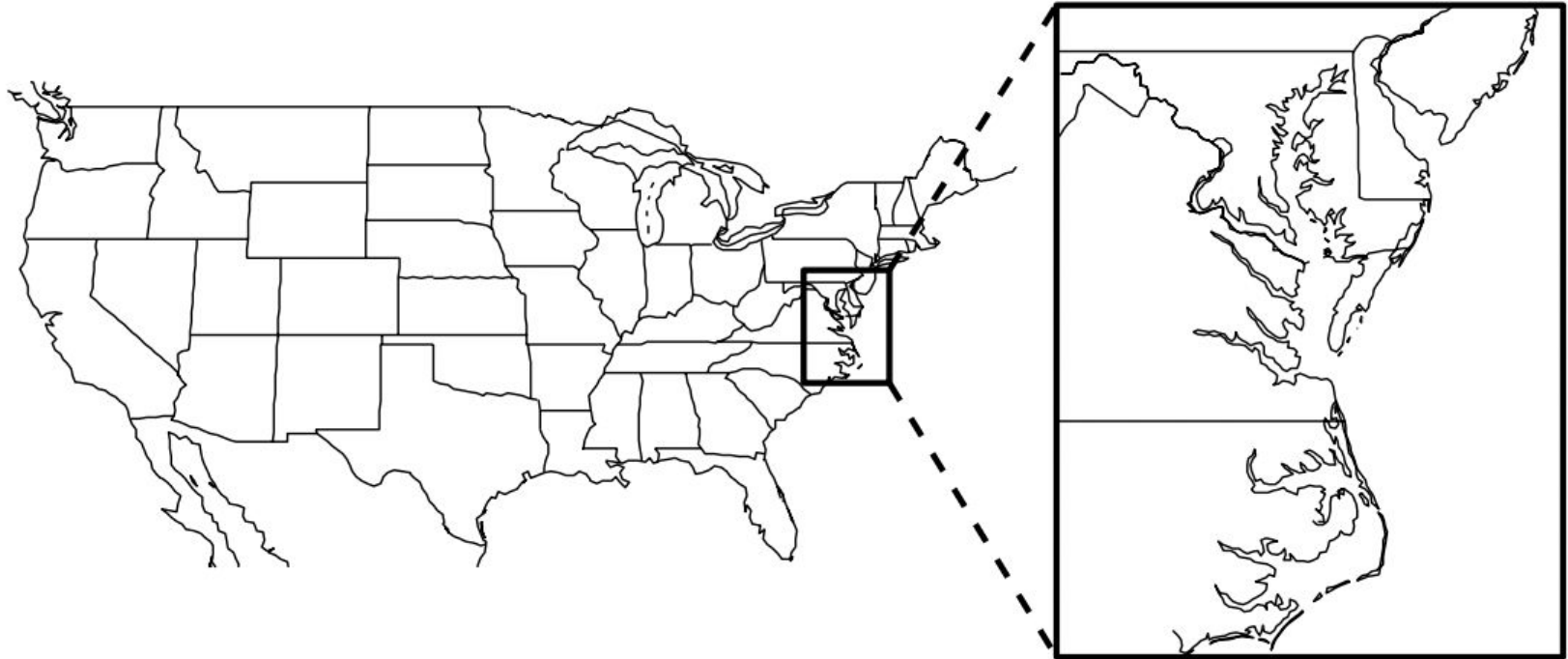
$v_1-v_3 \rightarrow v_0-v_4$
 $v_1-v_4 \rightarrow v_0-v_2$

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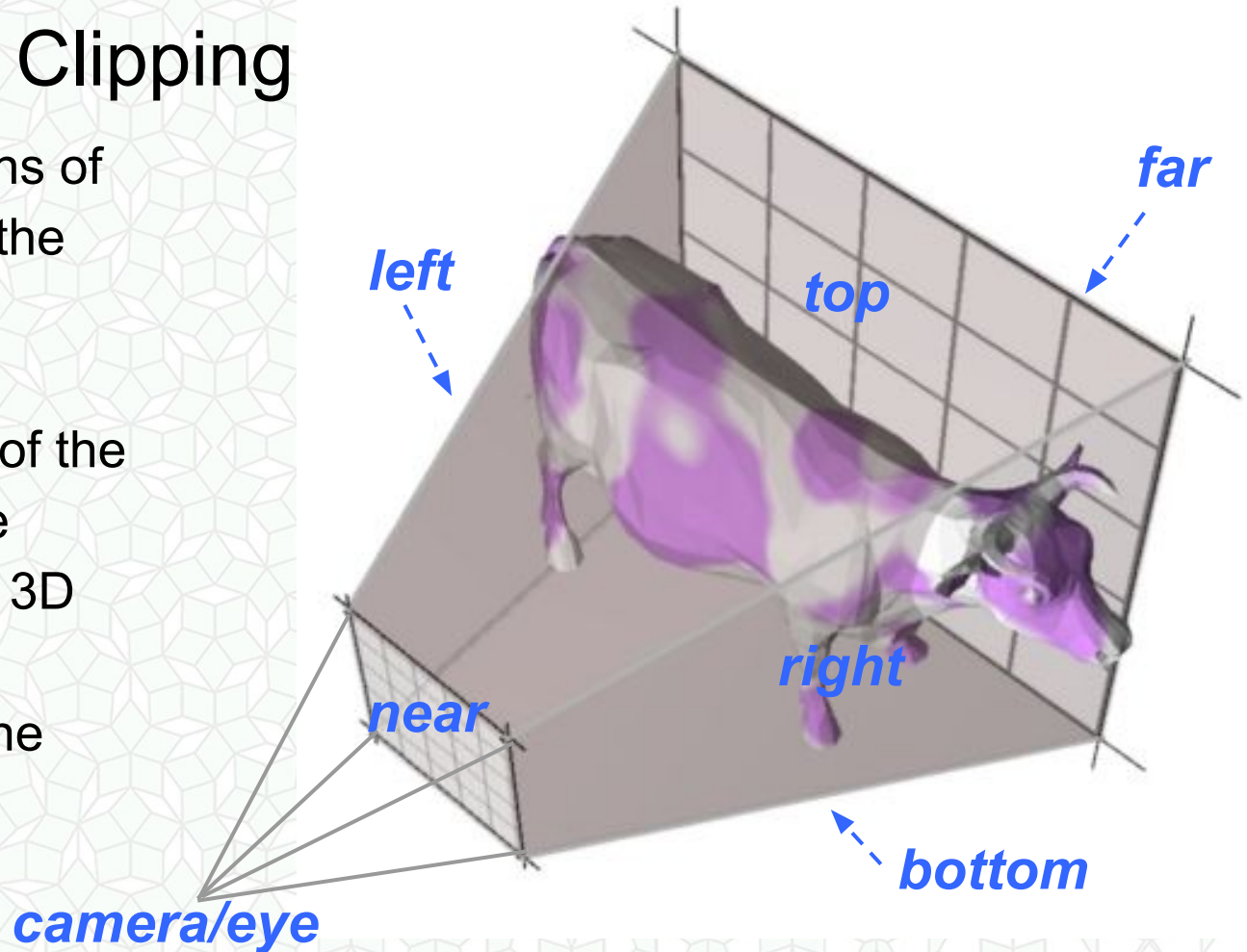
Motivation: Cartography (Map-Making)

- Select a small rectangular region to display in a window at larger scale

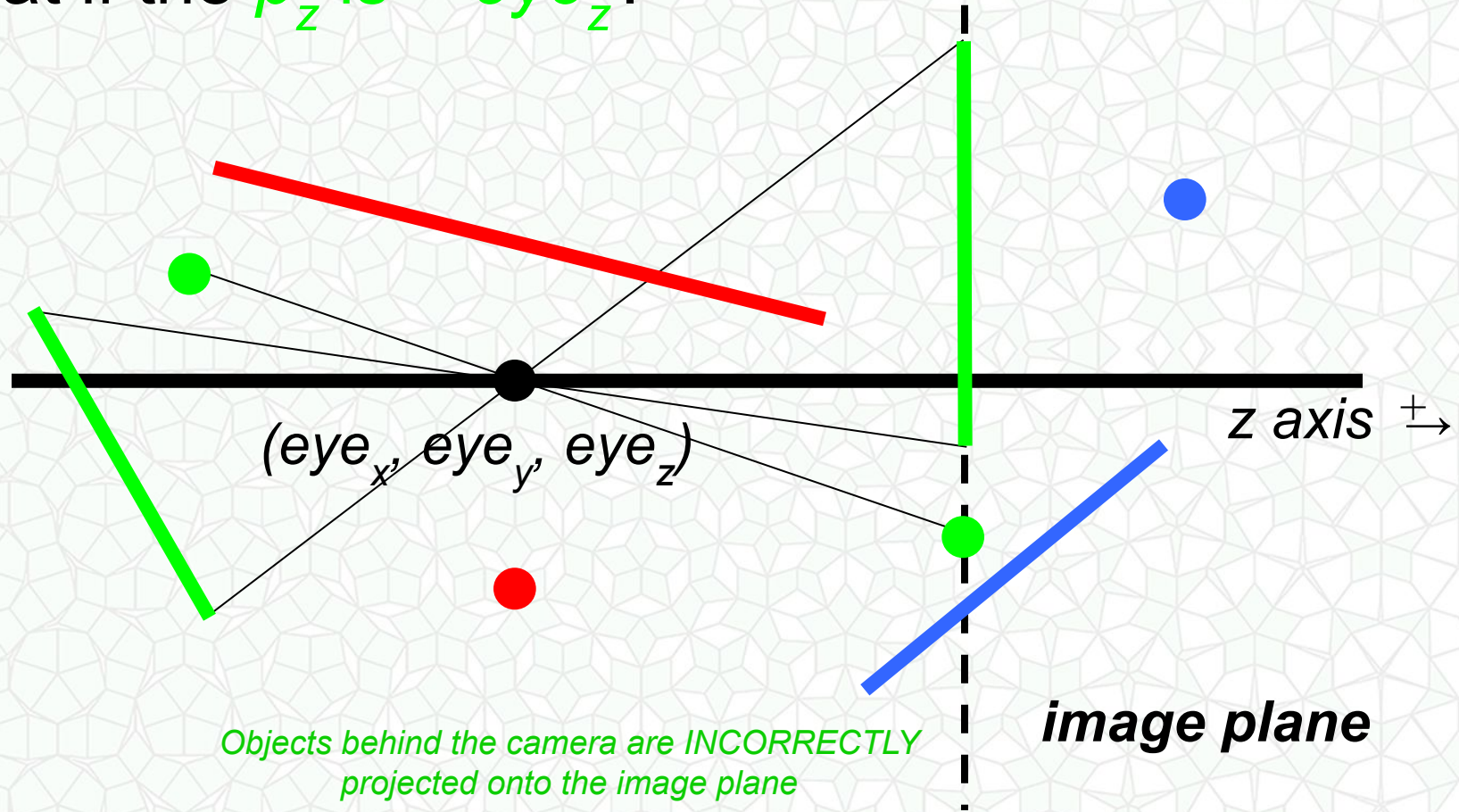


Graphics: 3D Clipping

- Eliminate portions of objects outside the viewing frustum
- View Frustum
 - boundaries of the image plane projected in 3D
 - a near & far clipping plane

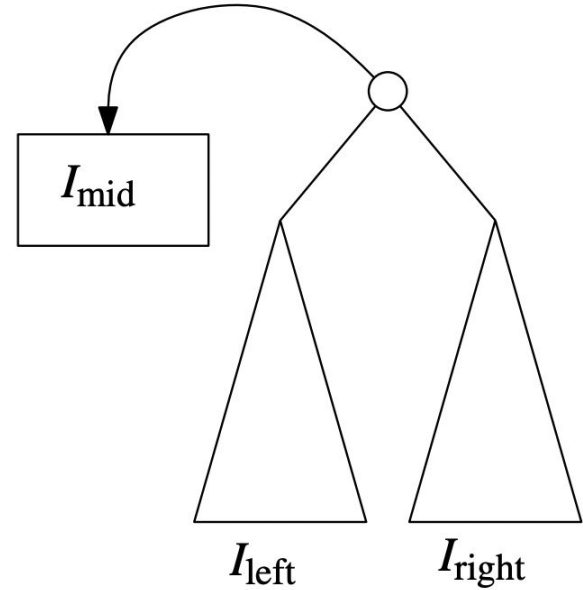
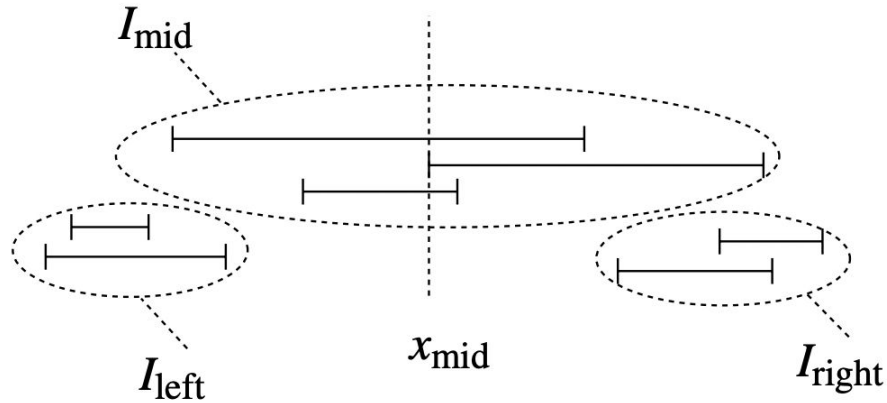


What if the p_z is $< eye_z$?



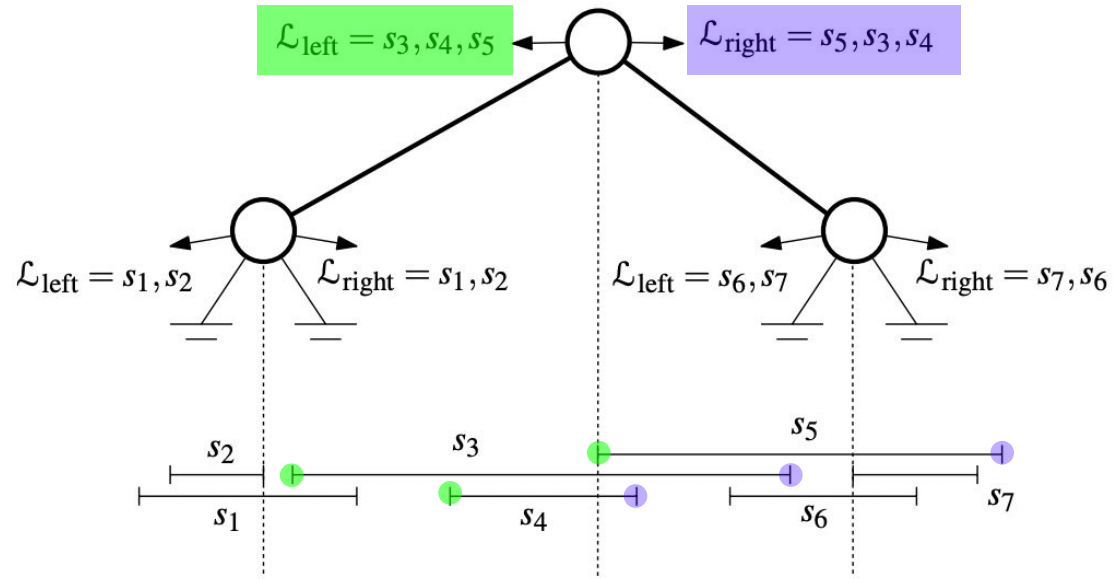
Interval Tree

- Recurse down the tree only with items that DO NOT overlap the split point.



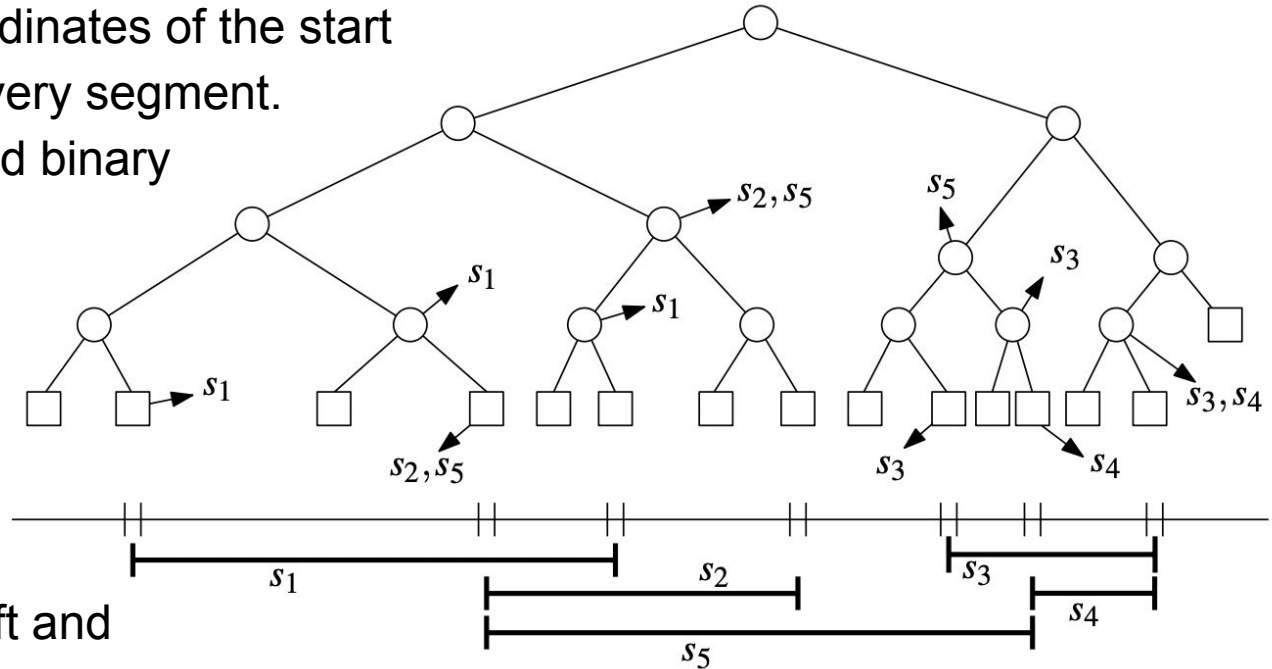
Interval Tree

- Items in I_{mid} group will stay at the current node
- Each node stores two sorted lists:
 - $\mathcal{L}_{\text{left}} = I_{\text{mid}}$ sorted by left endpoint (increasing)
 - $\mathcal{L}_{\text{right}} = I_{\text{mid}}$ sorted by right endpoint (decreasing)



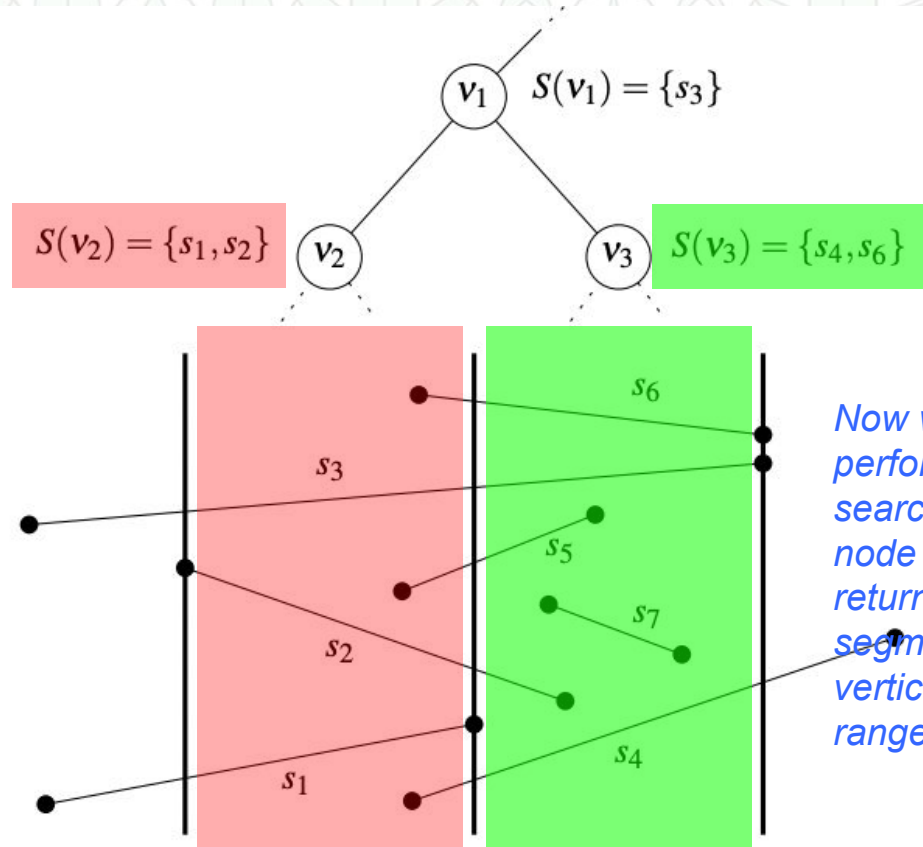
Segment Tree - First Dimension (x)

- First, sort the x coordinates of the start and end points of every segment.
- Construct a balanced binary search tree with these x values.
- Insert every segment into the structure
- If a segment overlaps both the left and right subranges of the node store it at the node (do not recurse)



Segment Tree - Second Dimension (y)

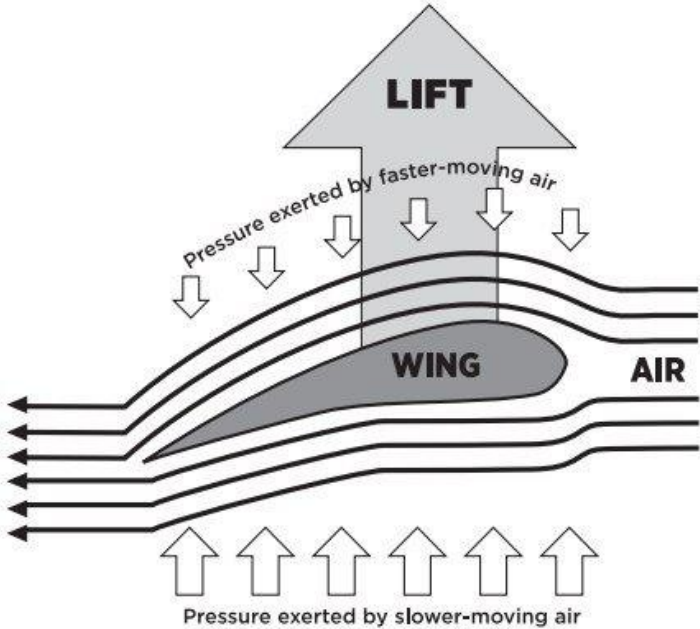
- To efficiently query a vertical range in addition to the horizontal range:
- Sort the segments stored at each node by y
- *Remember: this is only the segments that completely overlaps the node's range*
- Note: this is why we require no crossings in the input segments



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Motivation: Finite Element Modeling (FEM) & Computational Fluid Dynamics



<https://www.scienceworld.ca/resource/plane-wing-simulator/>

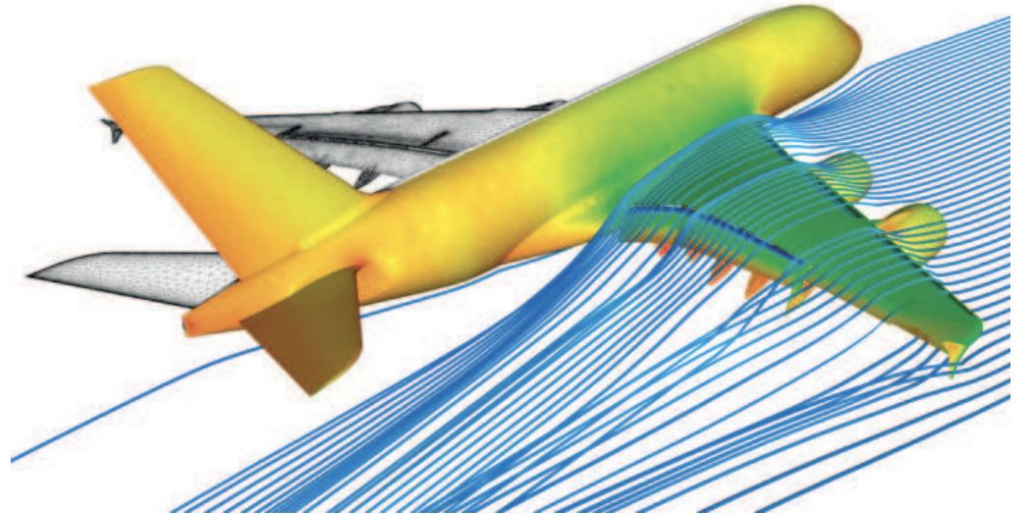
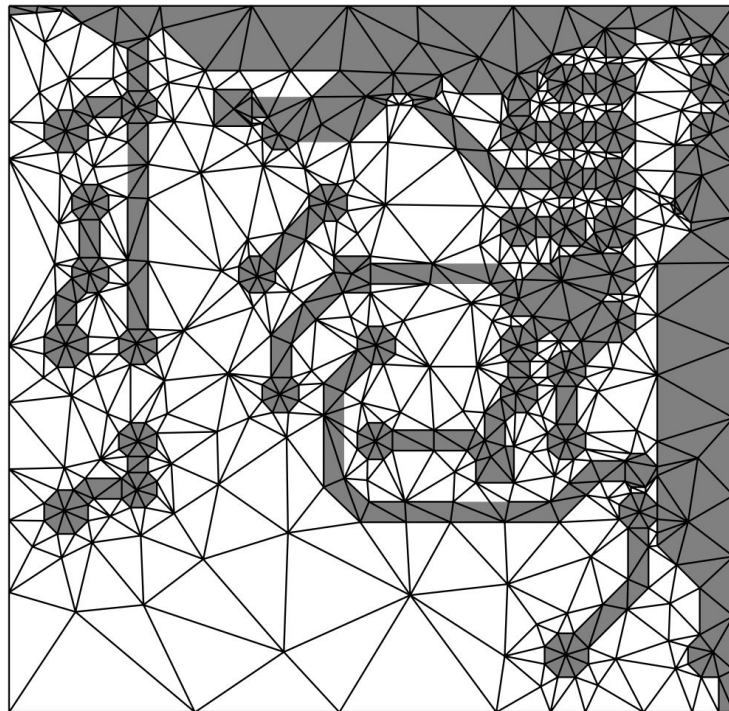


Figure 9: Numerical flow simulation for the Airbus A380 (picture credit: Airbus. Copyright: Dr. Klaus Becker, Senior Manager Aerodynamic Strategies, EGAA, Airbus, Bremen, Germany)

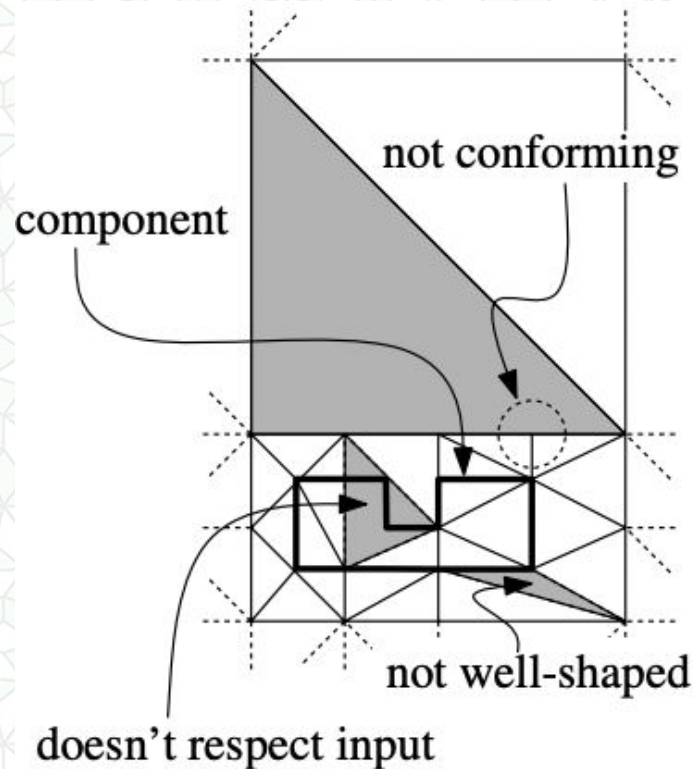
Motivation: Meshing Goals & Requirements

- Triangular Mesh
- Conforming (no T junctions)
- Respect (align) with input surface
- Well shaped (minimum & maximum angle requirements)
- Non-uniform
 - Fine when near input surface (ensure accurate simulation)
 - Coarse when far from the input surface (reduce computation waste)



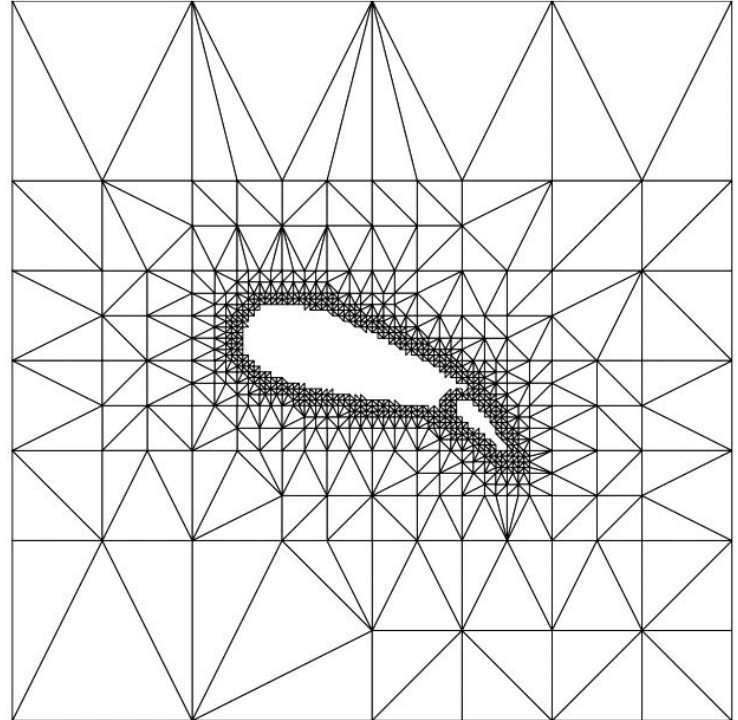
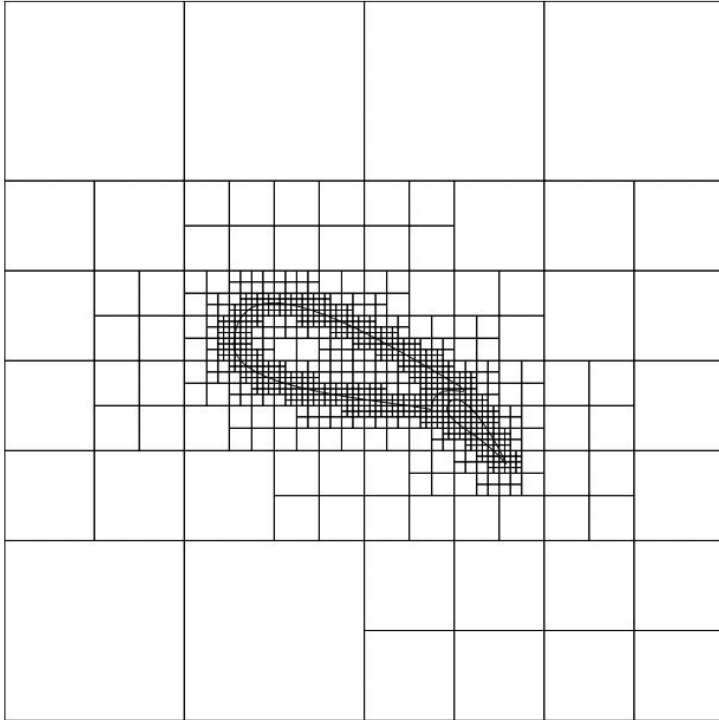
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Motivation: Finite Element Modeling (FEM) & Computational Fluid Dynamics

“Delaunay Refinement for Curved Complexes”,
Adriano Chaves
Lisboa, 2008.

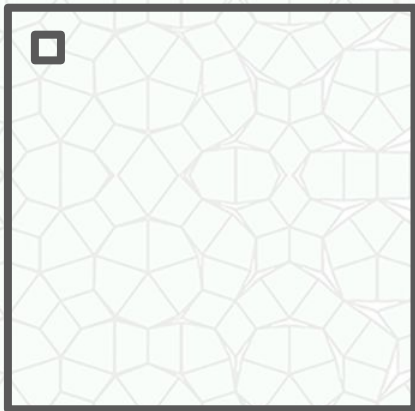


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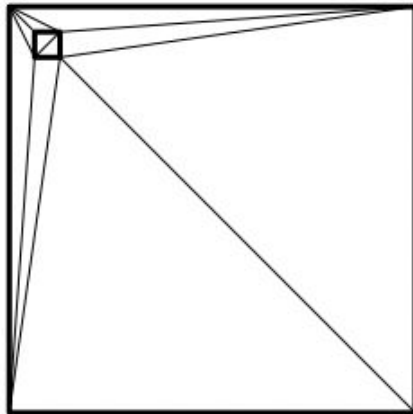
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Uniform vs. Non-Uniform Meshing

Input

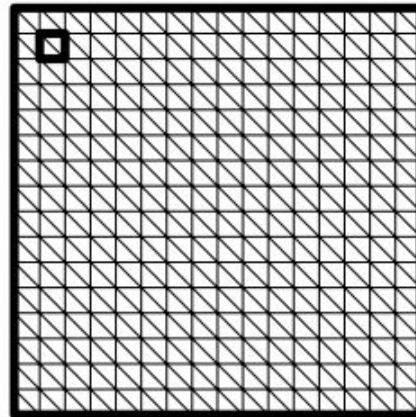


Delaunay

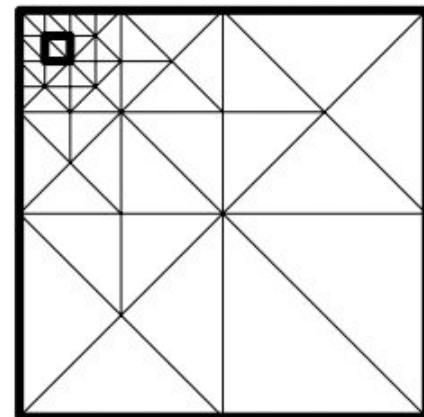


*Only uses the
input vertices*

Uniform



Non-Uniform



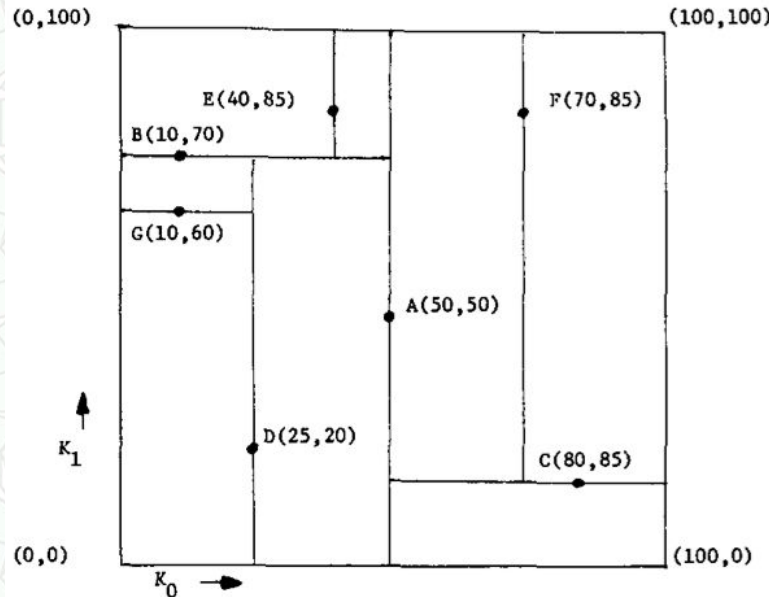
*Addition of “Steiner vertices” is allowed to improve
shape (minimum/maximum triangle angle)*

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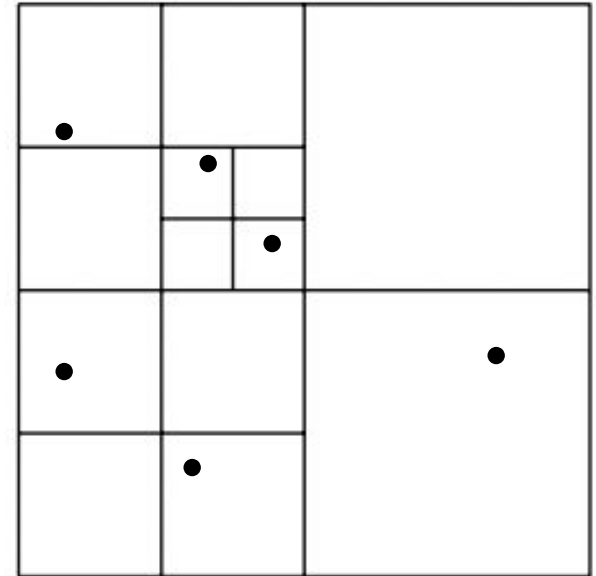
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QuadTree - Basically a special case of k-D Tree

- Split all dimensions at once (instead of alternating one dimension per level)
- Always split at the midpoint (generally not perfectly balanced!)



k-D Tree

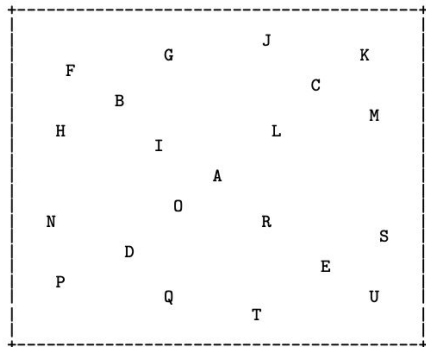


Quad Tree

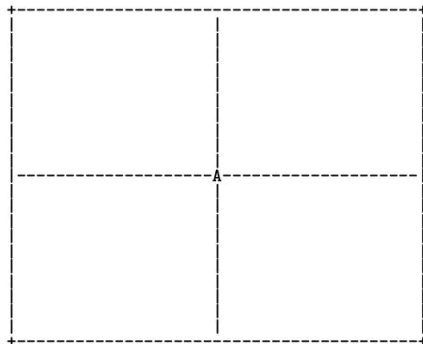
"Multidimensional Binary Search Trees Used for Associative Searching",
Communications of the ACM, Bentley 1975

Data Structures Homework 8: Quad Tree

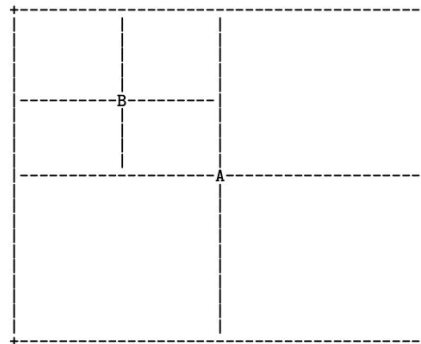
input points



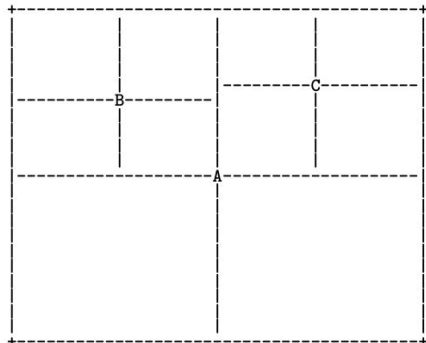
after adding the 1st point



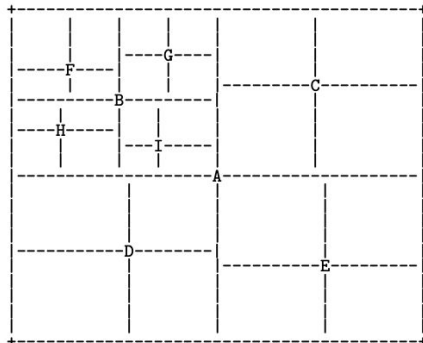
after adding the 2nd point



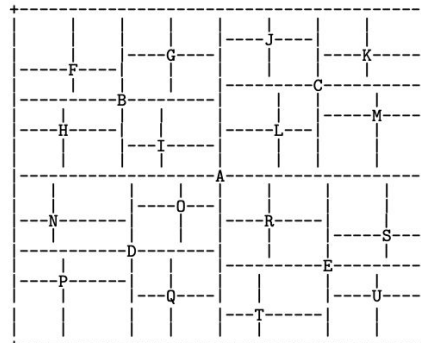
after adding the 3rd point



after adding 9 points



after adding all 21 points



Technically this is a variant of a classic QuadTree.

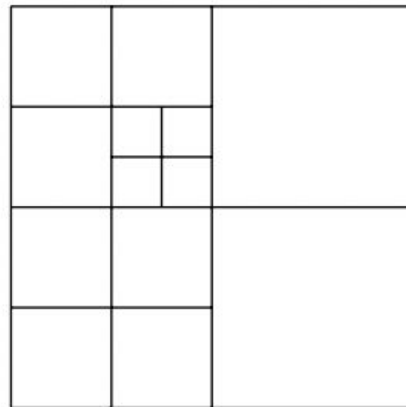
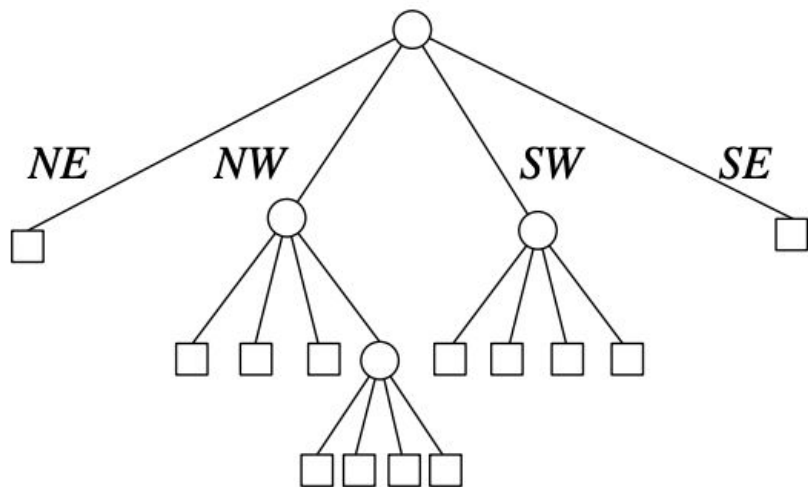
Instead of splitting at the dimension midpoint, we split at a specific data point...

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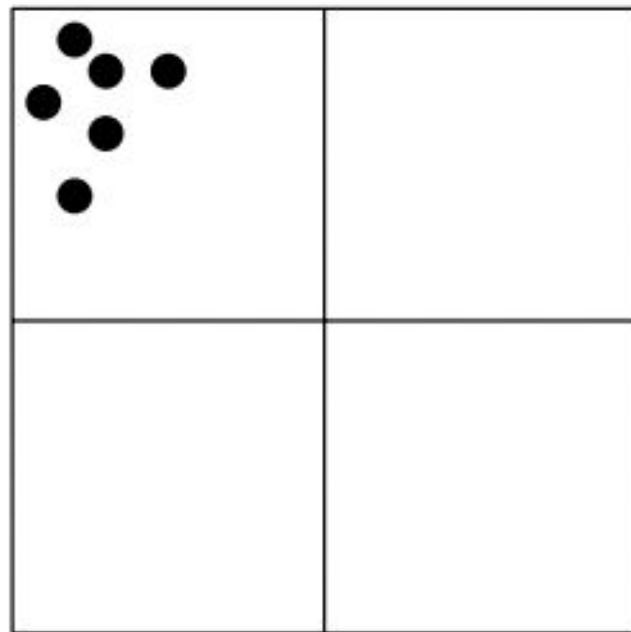
QuadTree Structure Consistency

- Let's split a cell into 4 children if 2 nodes are placed into the same cell
- Points that lie on a vertical split, assigned to left child
- Points that lie on a horizontal split, assigned to bottom child



Maximum Quad Tree Depth

- We always split a cell into 4 children if 2 nodes are placed into the same cell....
- **Lemma 14.1:** The depth of a quadtree for a set P of points in the plane is at most $\log(s/c) + 3/2$, where c is the smallest distance between any two points in P and s is the side length of the initial square that contains P .



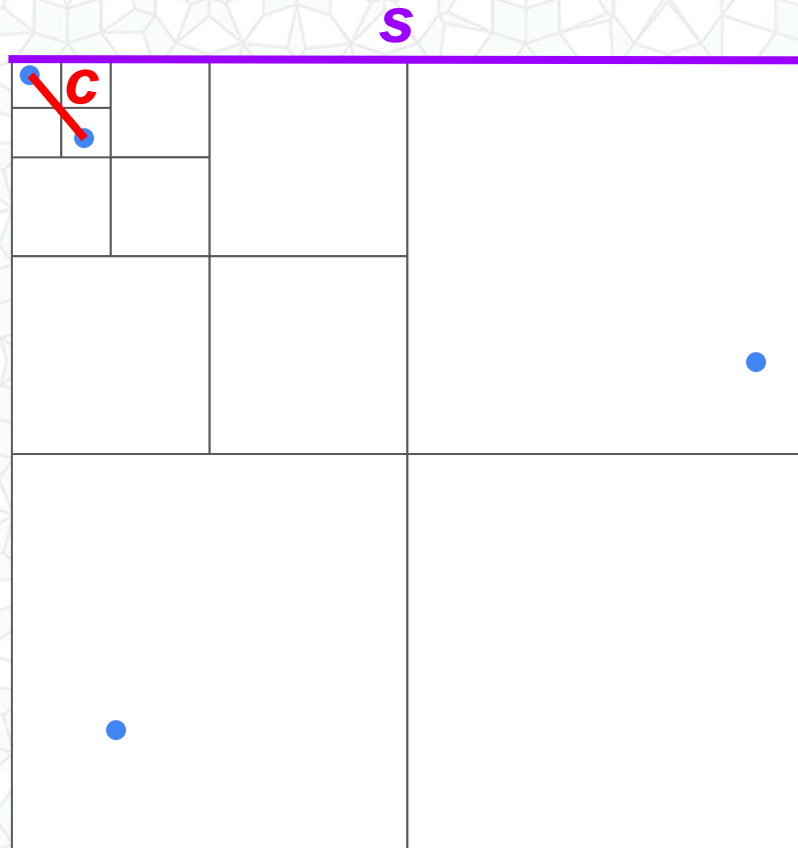
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$$c * 2^d \approx s$$

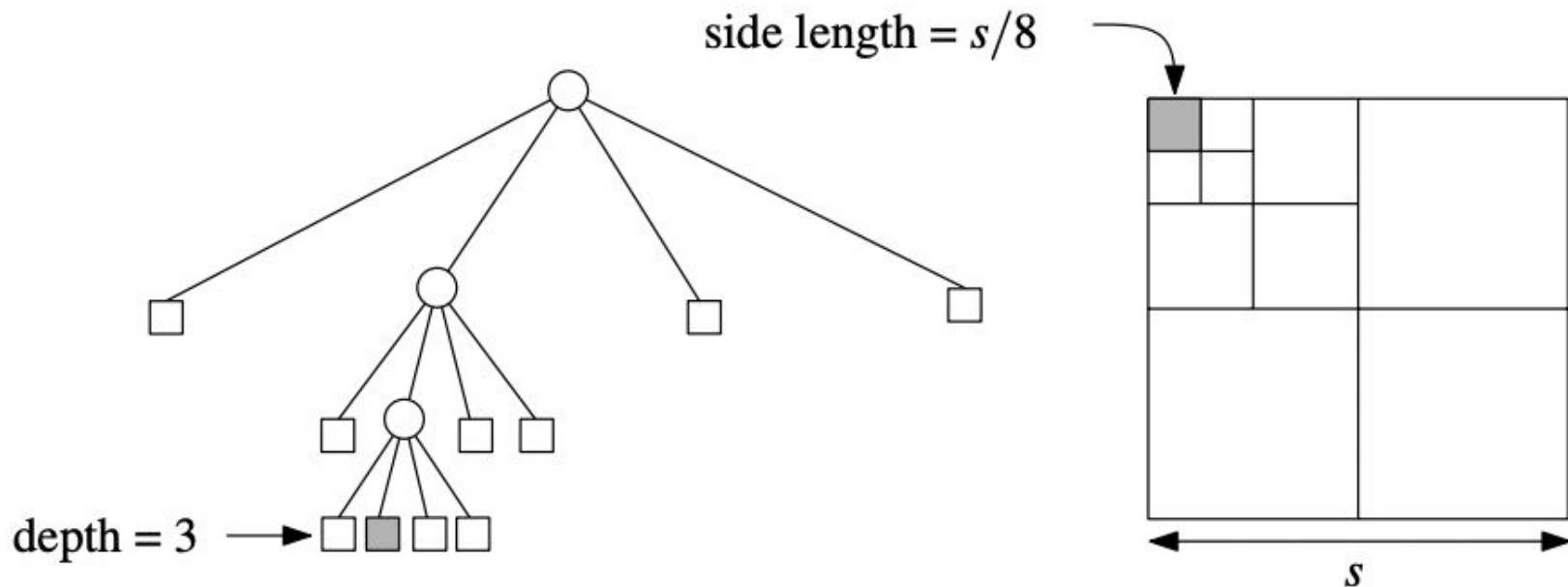
$$2^d \approx s / c$$

$$\log_2 (s / c) \approx d$$



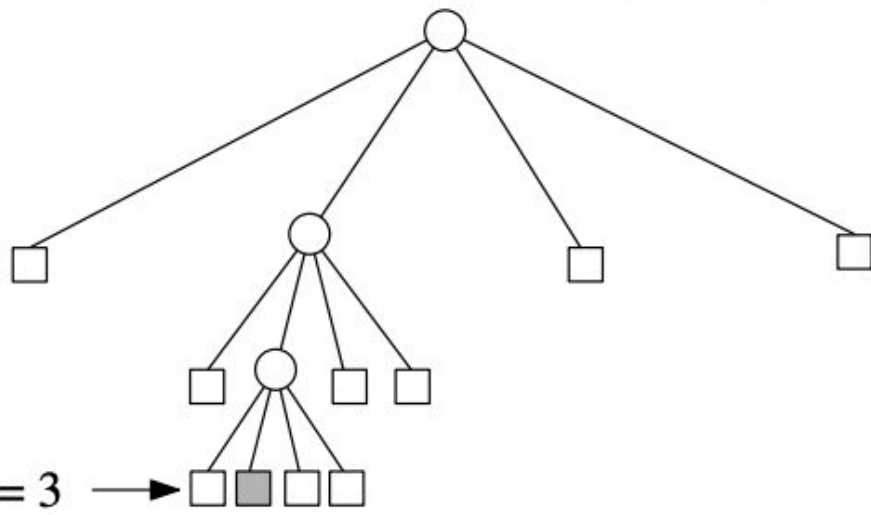
Maximum Number of Nodes

- **Theorem 14.2:** A quadtree of depth d storing a set of n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.



Maximum Number of Nodes

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Computational Geometry Algorithms and Applications,
de Berg, Cheong, van Kreveld and Overmars, Chapter 14

If newly inserted point is placed at maximal depth (because it is very close to an existing point)

*We will add AT MOST 4 new nodes at each level of the tree
→ $4 * d = O(d)$ per point*

NOTE: Hopefully the points are evenly distributed and we have a balanced tree and $d \approx O(\log n)$

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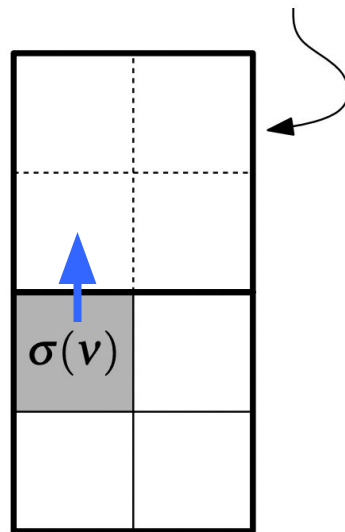
QuadTree and Implicit Adjacency

- We don't need to explicitly store pointers to adjacent cells.
- For example:

Which cell is my neighbor to the north?

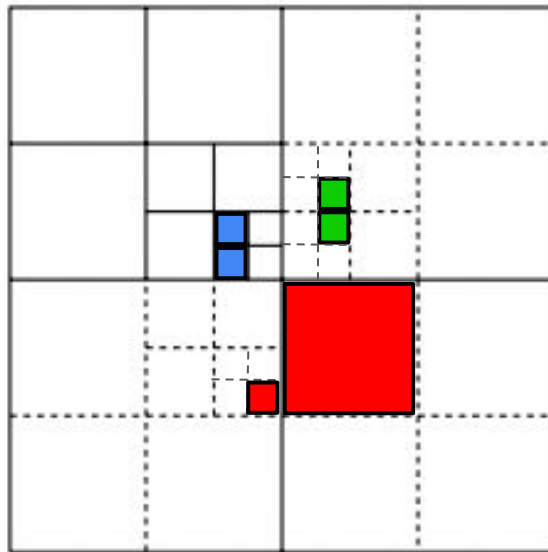
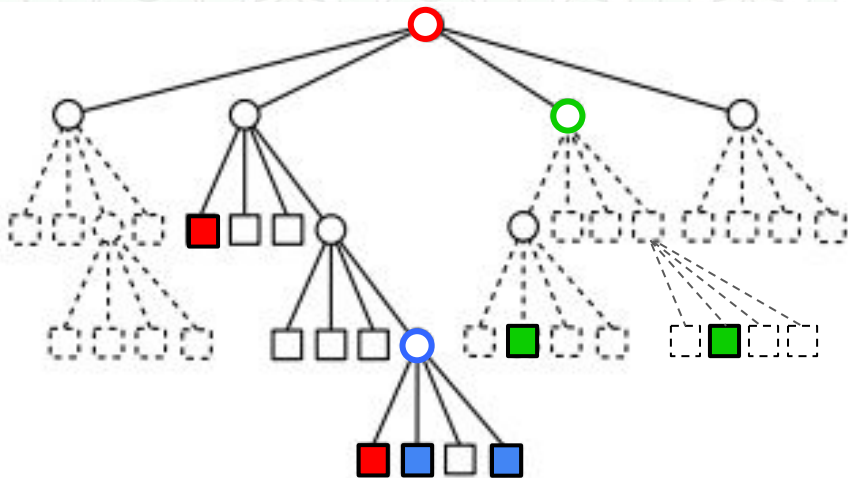
Is it the same size cell?

north-neighbor of $parent(v)$



QuadTree and Implicit Adjacency

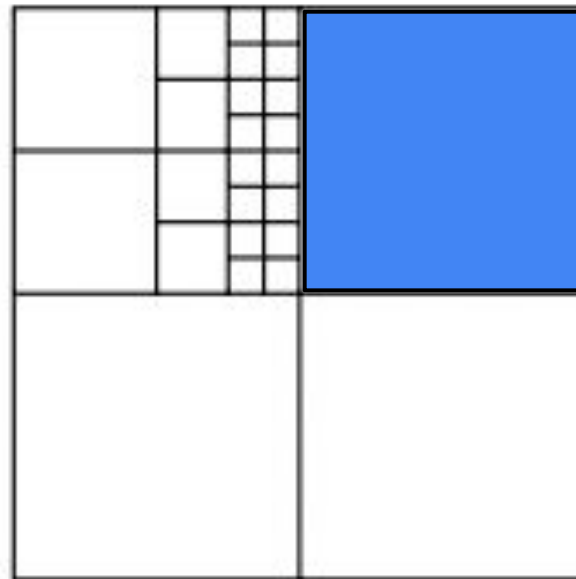
- *The neighbor may share the same parent node (sibling)*
- *Or it may share the parent of the parent node (first cousin)*
- *Or we may need to walk up and then back down many levels! (distant cousins)*



- Is it the same size cell? *Maybe not!*

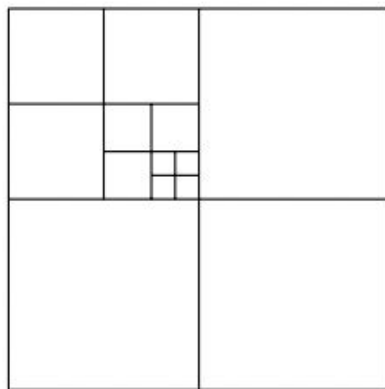
QuadTree and Implicit Adjacency

- However, it is disadvantageous to have adjacent cells that are subdivided to a significantly different tree level.
 - *For example:*
Which cell(s) are my left neighbor?
- So let's do something to make the tree more balanced....

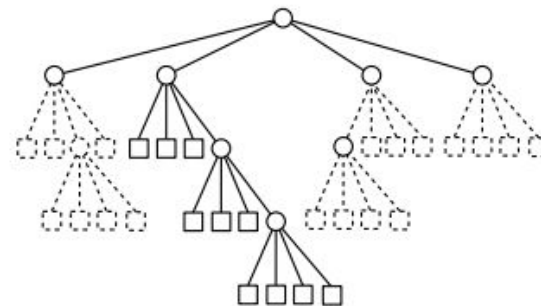
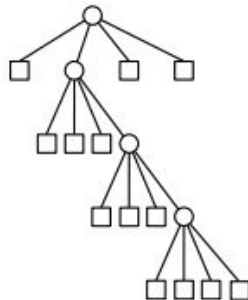
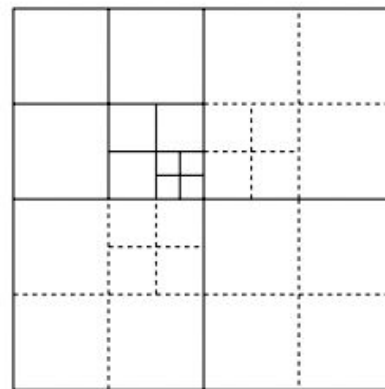


Balanced Quad Tree

- **Additional Requirement:** Adjacent cells of the tree are no more than 1 split different



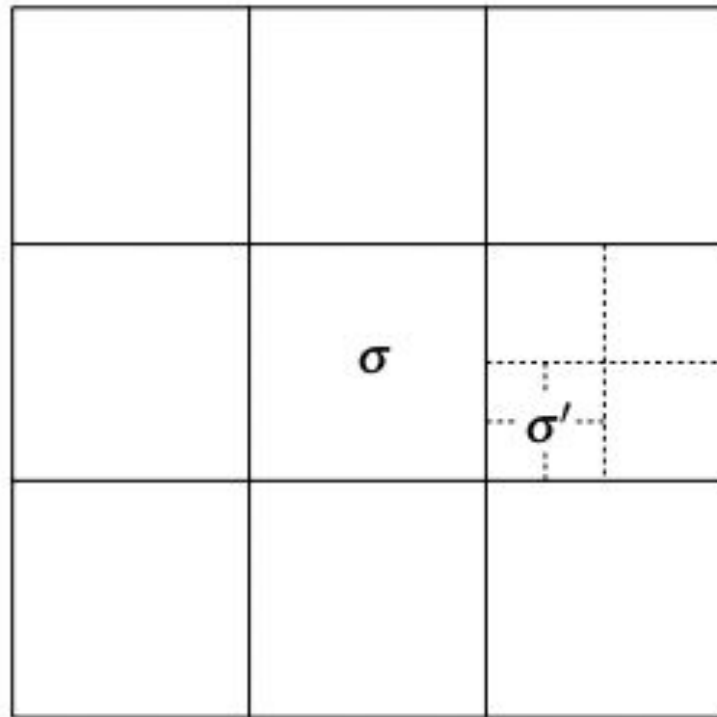
balancing



*Computational Geometry
Algorithms and Applications,
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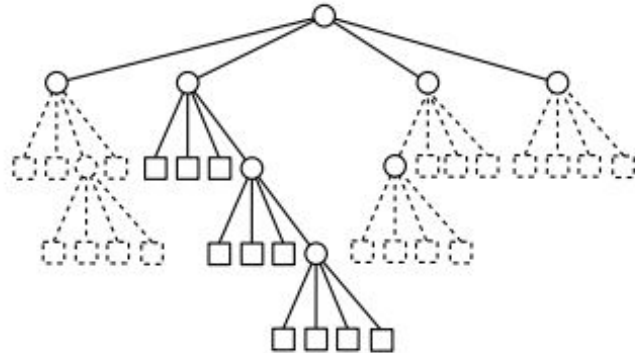
of Splits Required to Balance a QuadTree?

- **Theorem 14.4:** Let T be a quadtree with m nodes. Then the balanced version of T has $O(m)$ nodes and it can be constructed in $O((d + 1)m)$ time.

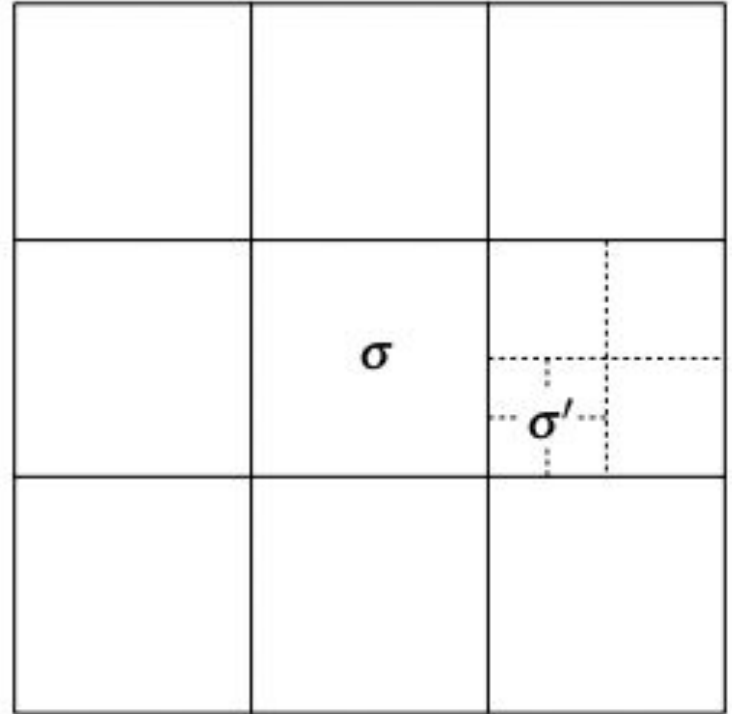


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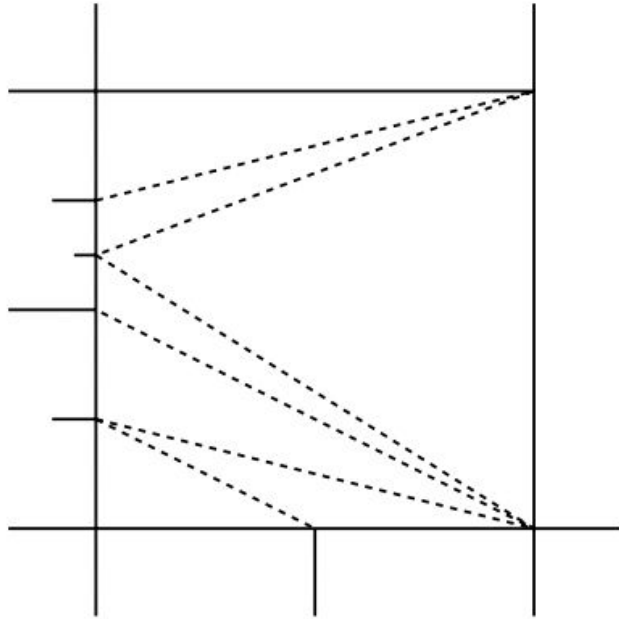


See book for a proof by contradiction

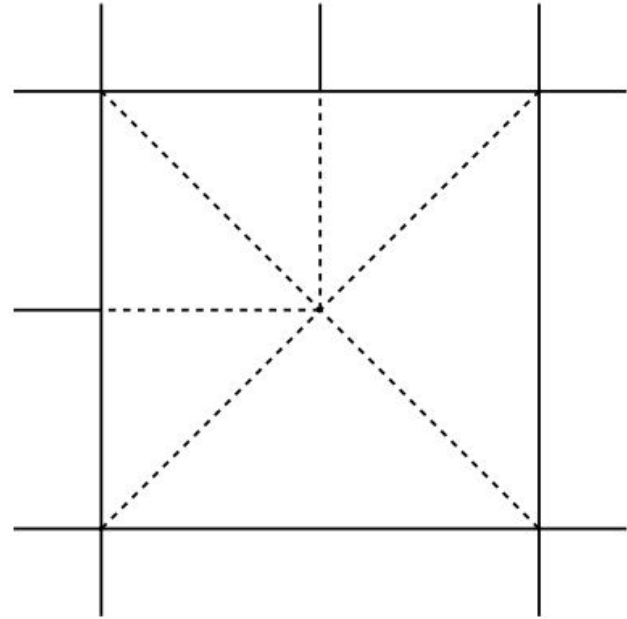


Balanced Quad Tree Triangulation

- A Balanced Quad Tree can be triangulated with all $45^\circ/45^\circ/90^\circ$ triangles!



unbalanced Quad Tree



Balanced Quad Tree

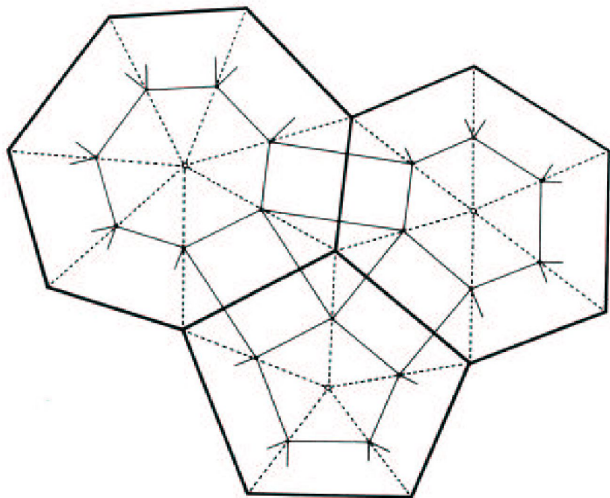
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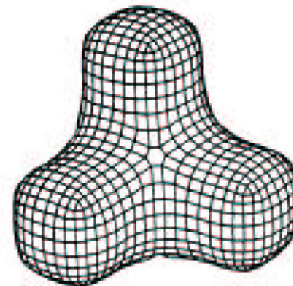
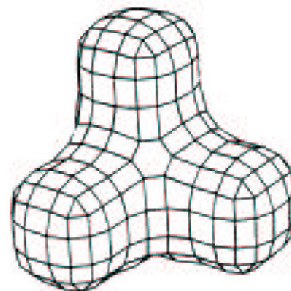
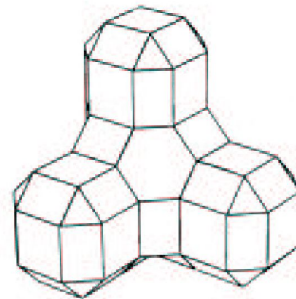
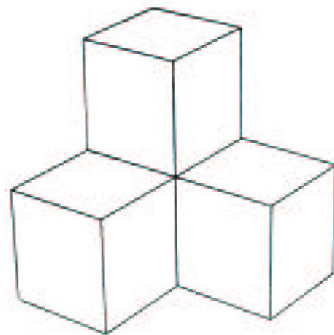
Doo-Sabin Subdivision

*An early subdivision
surfaces method!*

Idea: introduce a new vertex for each face
At the midpoint of old vertex, face centroid



“Behavior of Recursive Subdivision
Surfaces near Extraordinary Points”
Doo and Sabin 1978



Geri's Game

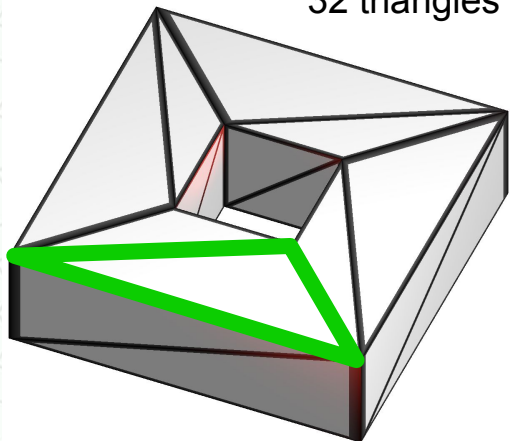
Pixar Animation Studios, 1997

*A short film highlighting use
of subdivision surfaces!*

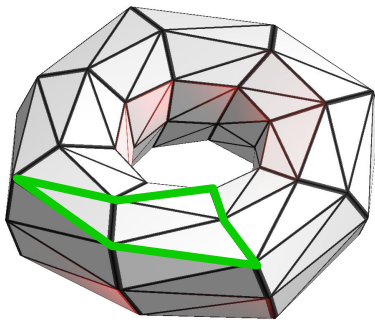


*Loop Subdivision - replace each triangle with 4 triangles
(and smooth / average the vertex positions with neighboring vertices)*

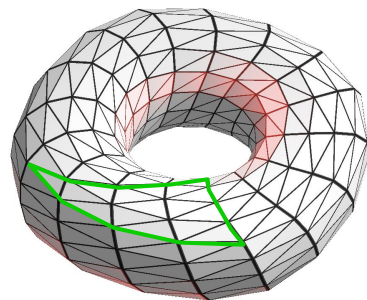
32 triangles



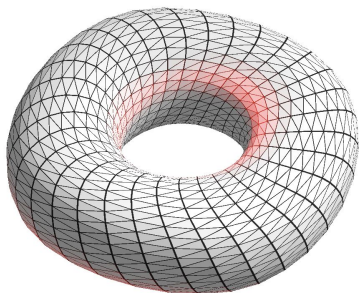
128 triangles



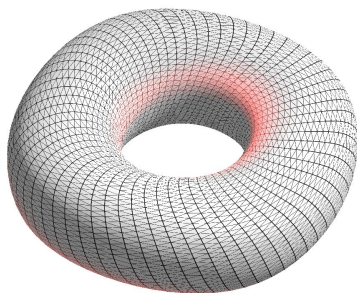
512 triangles



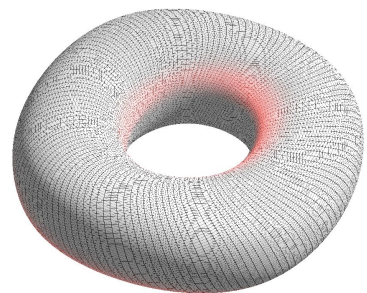
2048 triangles



8192 triangles



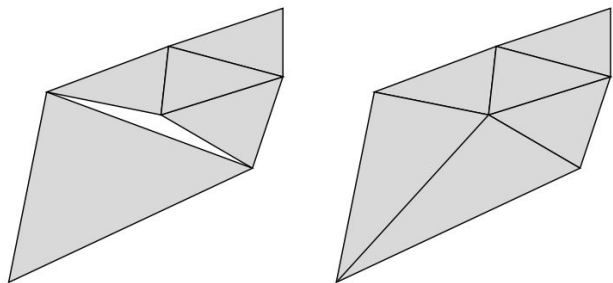
32768 triangles



*Yikes!
That's a lot of
triangles after
just 5 iterations
of smoothing.*

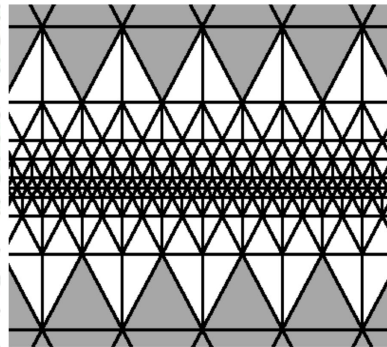
*Can we just
subdivide locally?
Only where we
need extra
smoothness?*

$\sqrt{3}$ Subdivision, Kobbelt, SIGGRAPH 2000

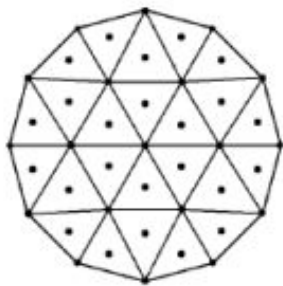


Adaptive Subdivision (Loop): Need to close gaps between different levels of refinement

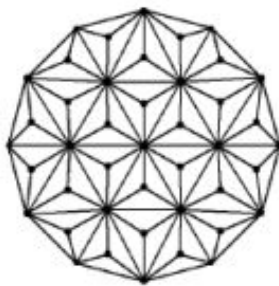
Loop: less localized refinement



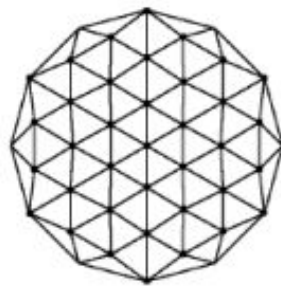
$\sqrt{3}$ Subdivision:
No intermediate special case



the split operation places a midvertex at the centre of each triangle

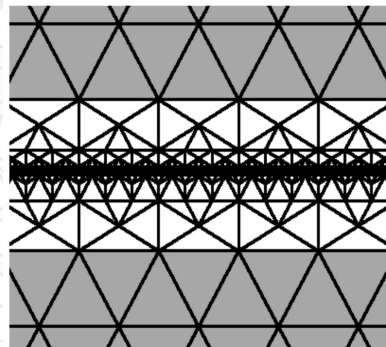


joining the midvertex to the vertices of the triangle realises the 1-to-3 split



after smoothing each old vertex, edges are flipped to connect pairs of midvertices

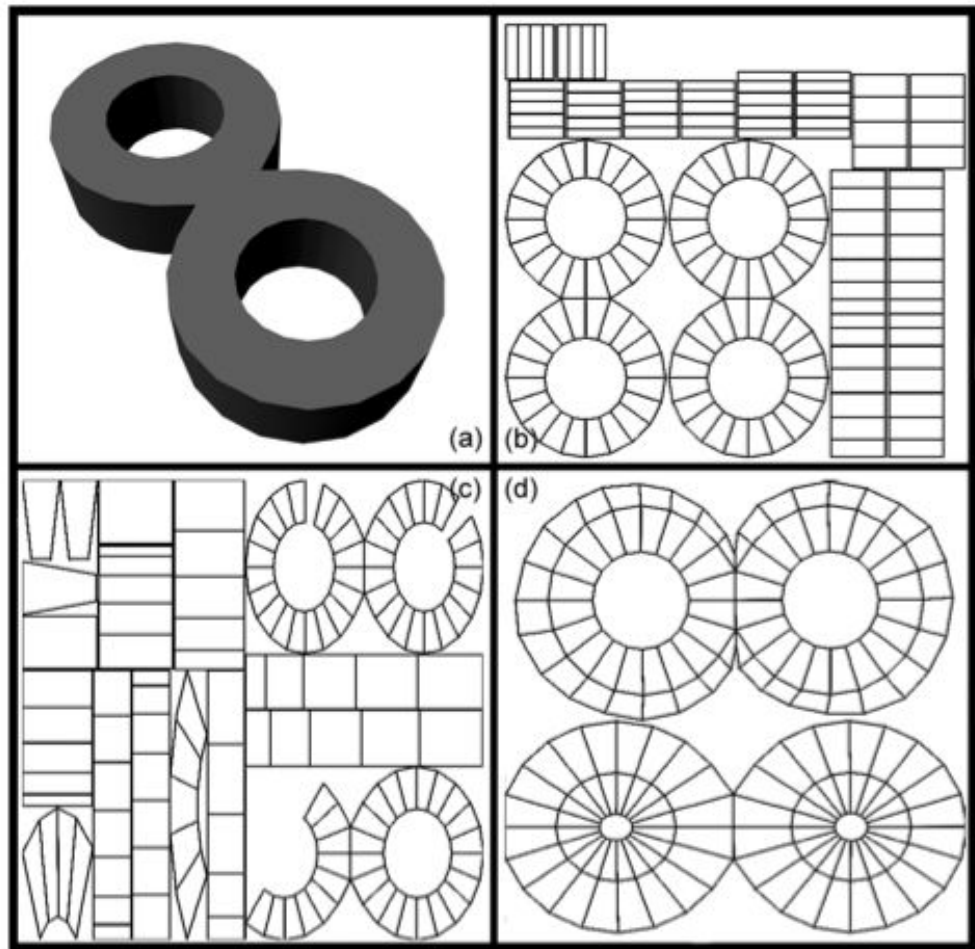
$\sqrt{3}$: more localized refinement



Traditional Texture Mapping

- Unroll / Unwrap the object to 2D
- Parameterize / Correspond 3D \leftrightarrow 2D
- “Paint” 2D texture

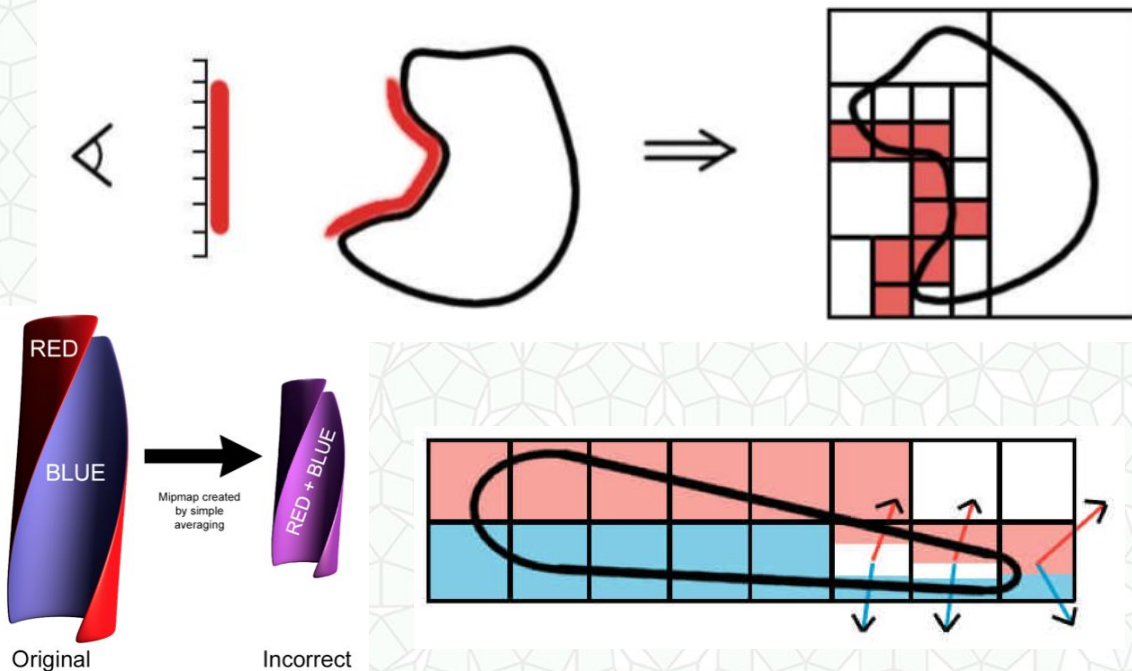
“Painting and Rendering Textures on
Unparameterized Models”,
DeBry, Gibbs, DeLeon, and Robins,
SIGGRAPH 2002



Octree Texture Mapping

"Octree Textures", Benson & Davis, SIGGRAPH 2002

"Painting and Rendering Textures on Unparameterized Models",
DeBry, Gibbs, DeLeon, and Robins, SIGGRAPH 2002

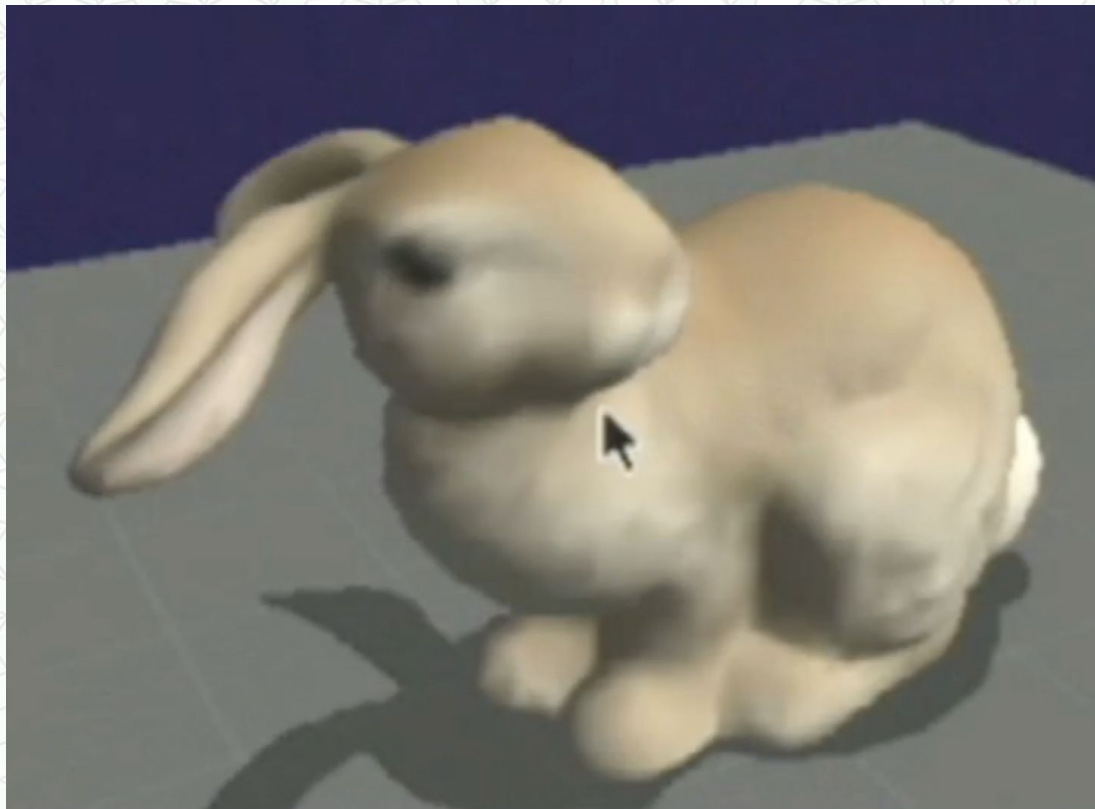


Outline for Today

- Homework 7 Posted
- Last Time: Windowing, Interval Trees & Segments Trees
- Motivation: FEM & CFD Simulation
- Uniform & Non-Uniform Meshing
- k-D Tree vs Quad Tree
- Maximum Depth, Number of Nodes
- Implicit Adjacency, Balanced Quad Tree
- Advanced Topics: $\sqrt{3}$ Subdivision & Octree Textures
- **Remeshing for Interactive Deformation**
- Next Time: Signed Distance Fields & Level Sets

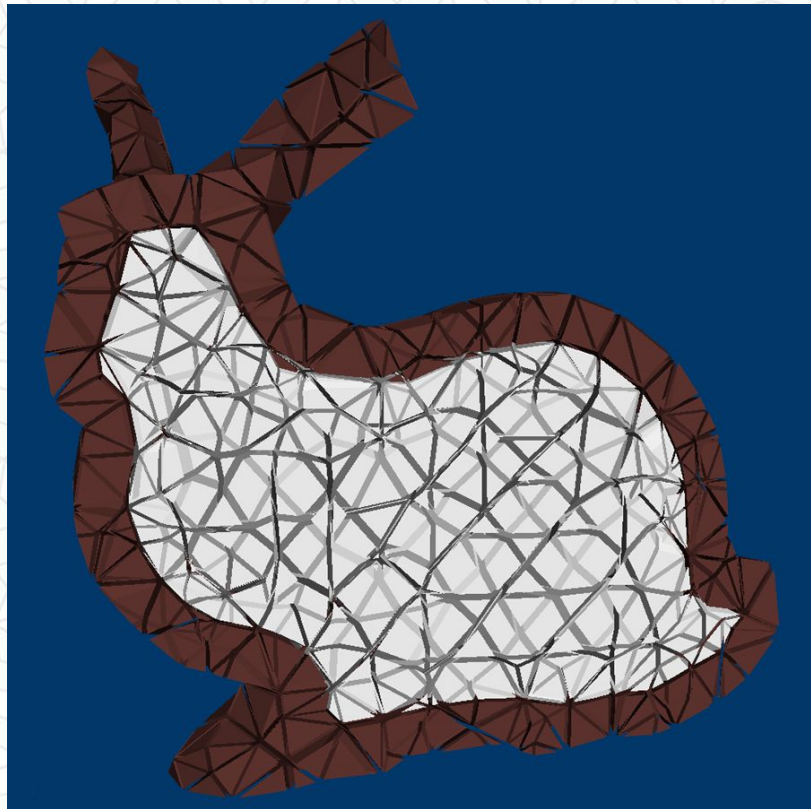
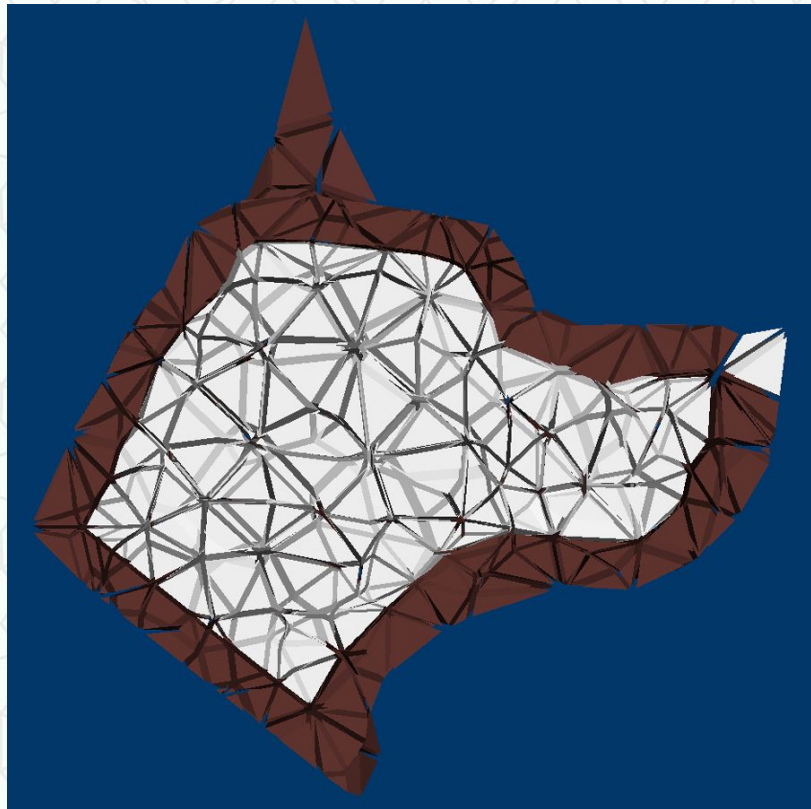
Deformation Simulation

Mueller, Dorsey, McMillan, Jagnow, & Cutler
Stable Real-Time Deformations
Symposium on Computer Animation 2002



Deformation Simulation

Mueller, Dorsey, McMillan, Jagnow, & Cutler
Stable Real-Time Deformations
Symposium on Computer Animation 2002



3D Mesh Simplification

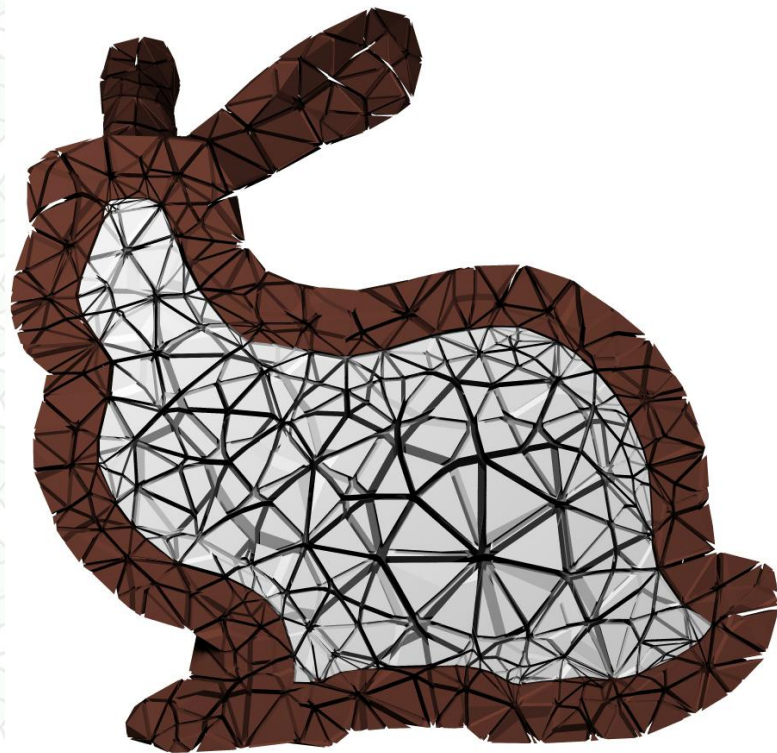
“Simplification and Improvement of
Tetrahedral Models for Simulation”

Cutler, Dorsey, and McMillan

SGP 2004



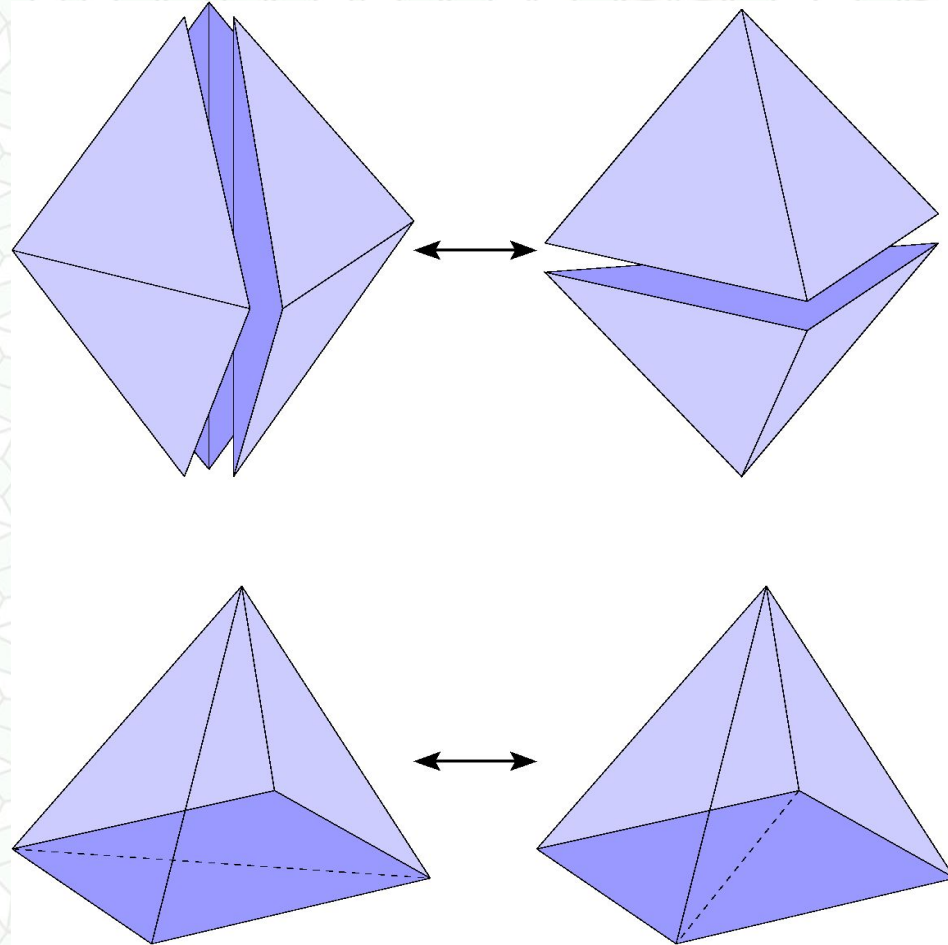
1,050K tetras
(133K faces)



10K tetras
(3K faces)

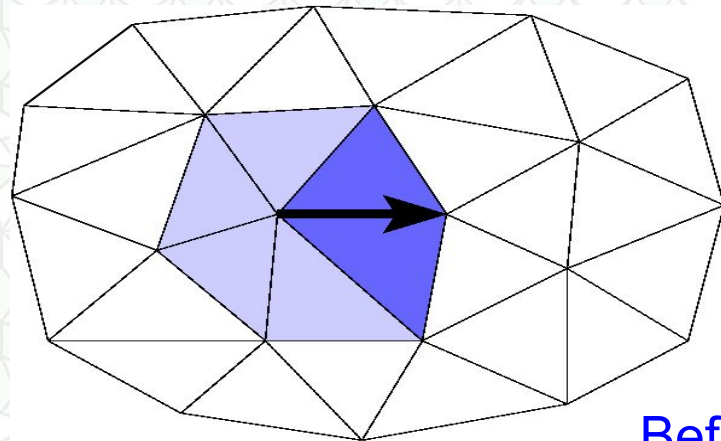
3D Mesh Operations

- Tetrahedral Swaps
 - Choose the configuration with the best local element shape
- Edge Collapse
- Vertex Smoothing
- Vertex Addition

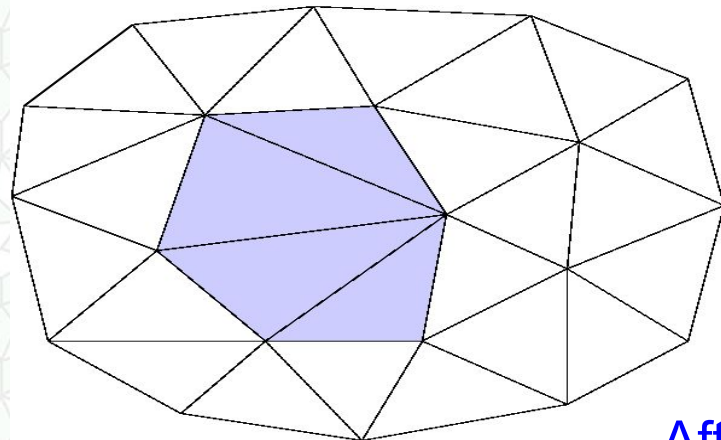


3D Mesh Operations

- Tetrahedral Swaps
- Edge Collapse
 - Delete a vertex & the elements around the edge
- Vertex Smoothing
- Vertex Addition



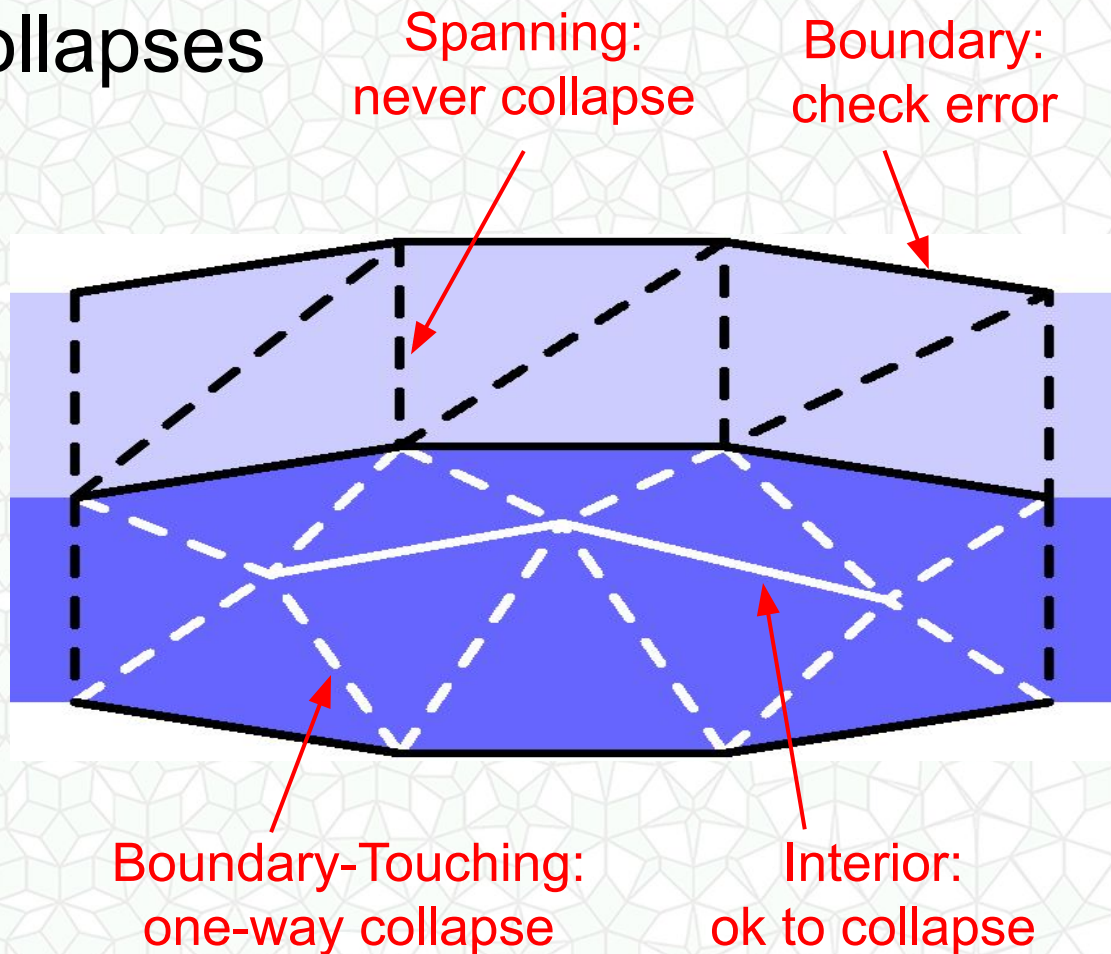
Before



After

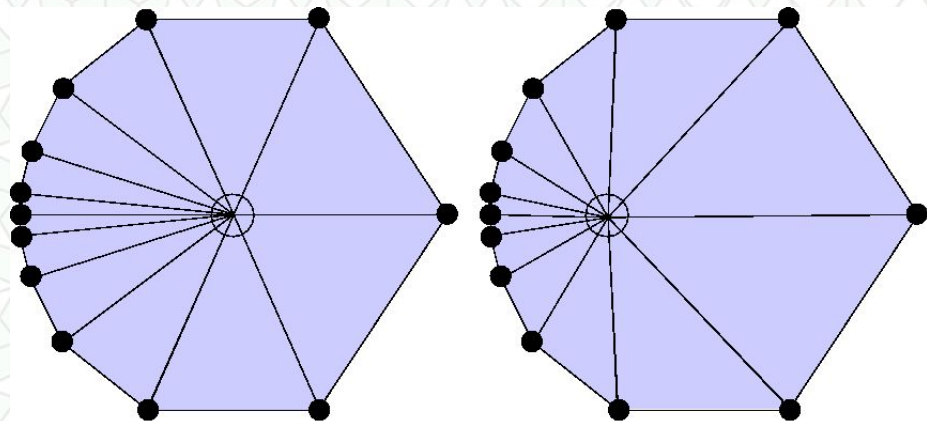
Prioritizing Edge Collapses

- Preserve topology
 - Thin layers should not pinch together
- Collapse weight
 - Edge length + boundary error
- No negative volumes
- Local element quality does not significantly worsen



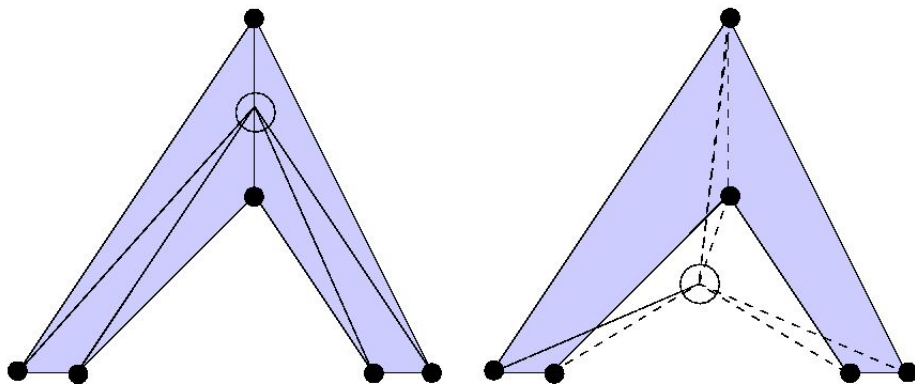
3D Mesh Operations

- Tetrahedral Swaps
- Edge Collapse
- **Vertex Smoothing**
 - Move a vertex to the centroid of its neighbors
 - Convex or concave, but avoid negative-volume elements
- Vertex Addition



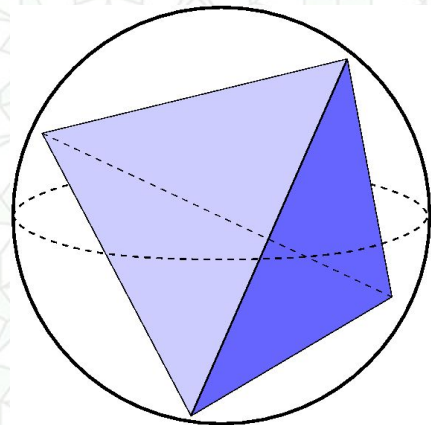
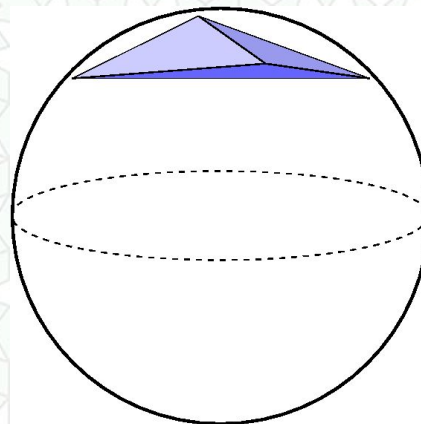
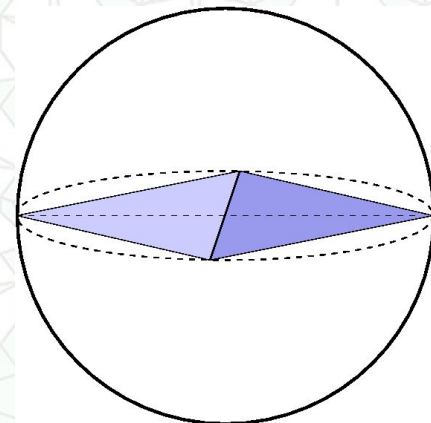
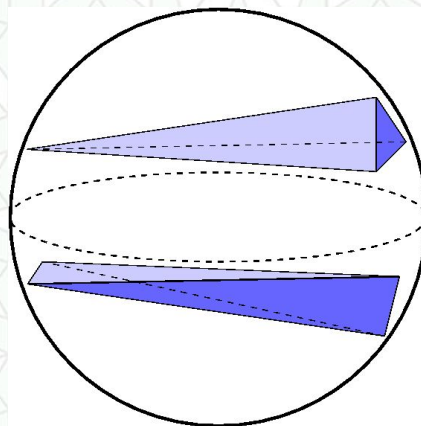
Before

After



3D Mesh Operations

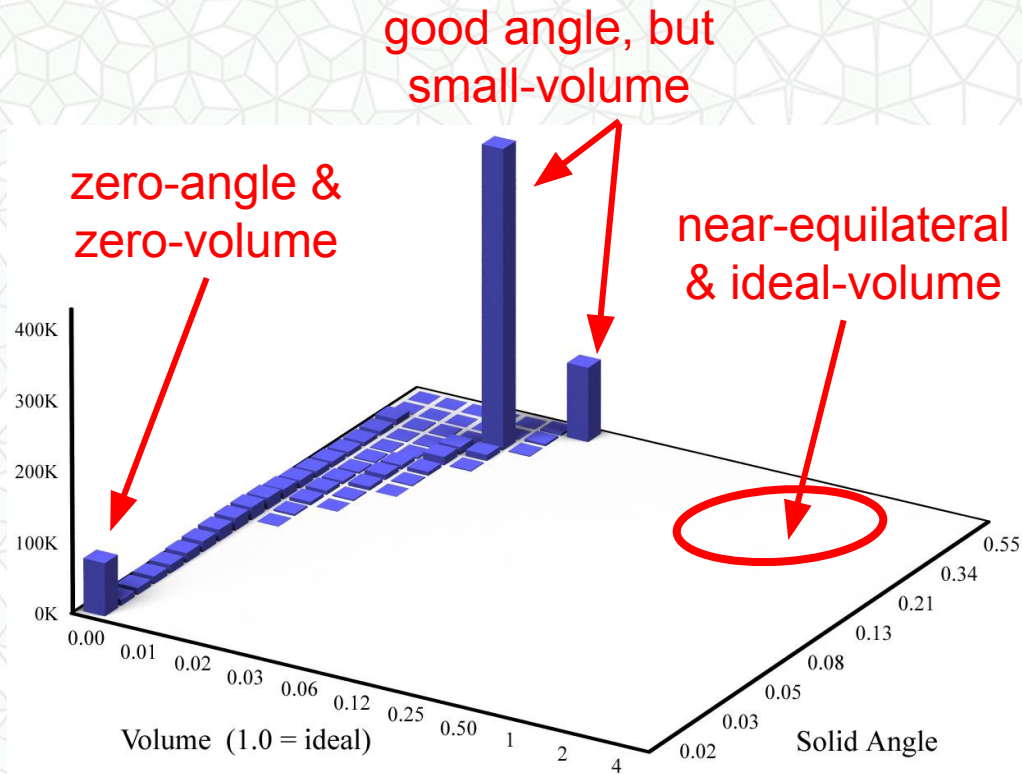
- Tetrahedral Swaps
- Edge Collapse
- Vertex Smoothing
- **Vertex Addition**
 - At the center of a tetra, face, or edge
 - Useful when mesh is simplified, but needs further element shape improvement



Visualization of Tetrahedra Quality

“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004

1,050K tetras
(133K faces)

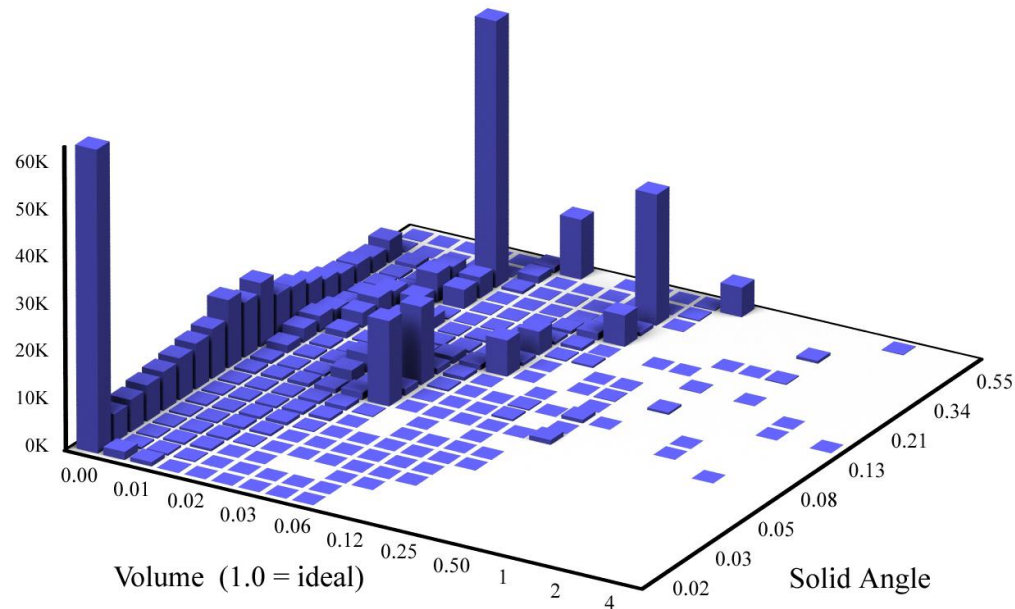


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SGP 2004

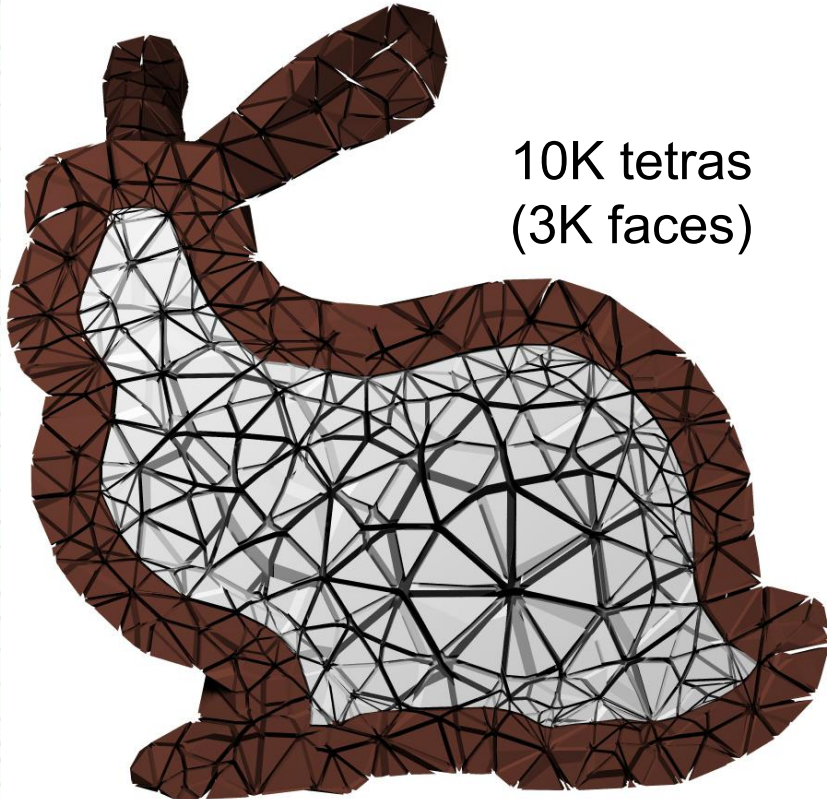
Octree or Adaptive
Distance Field (ADF)

461K tetras
(108K faces)

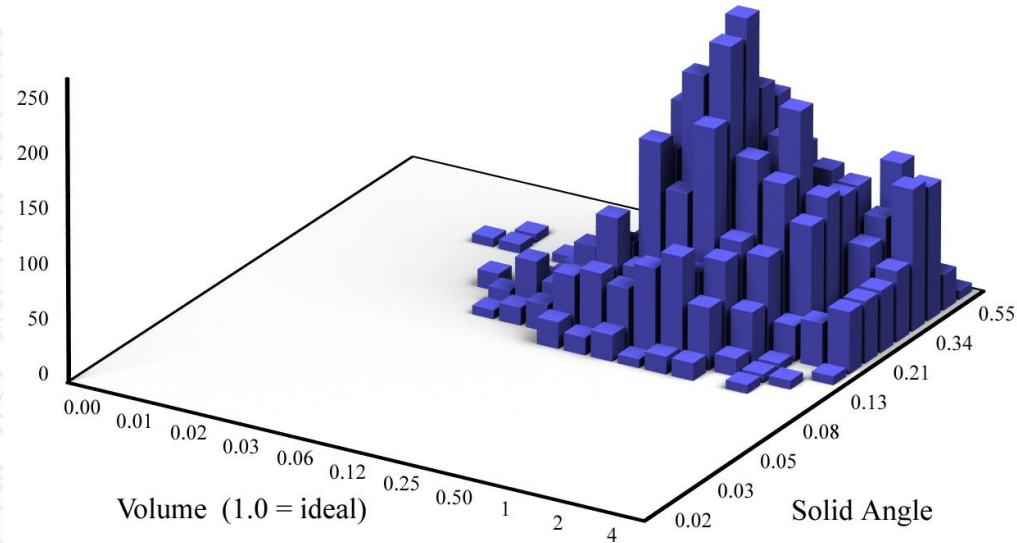


Visualization of Tetrahedra Quality

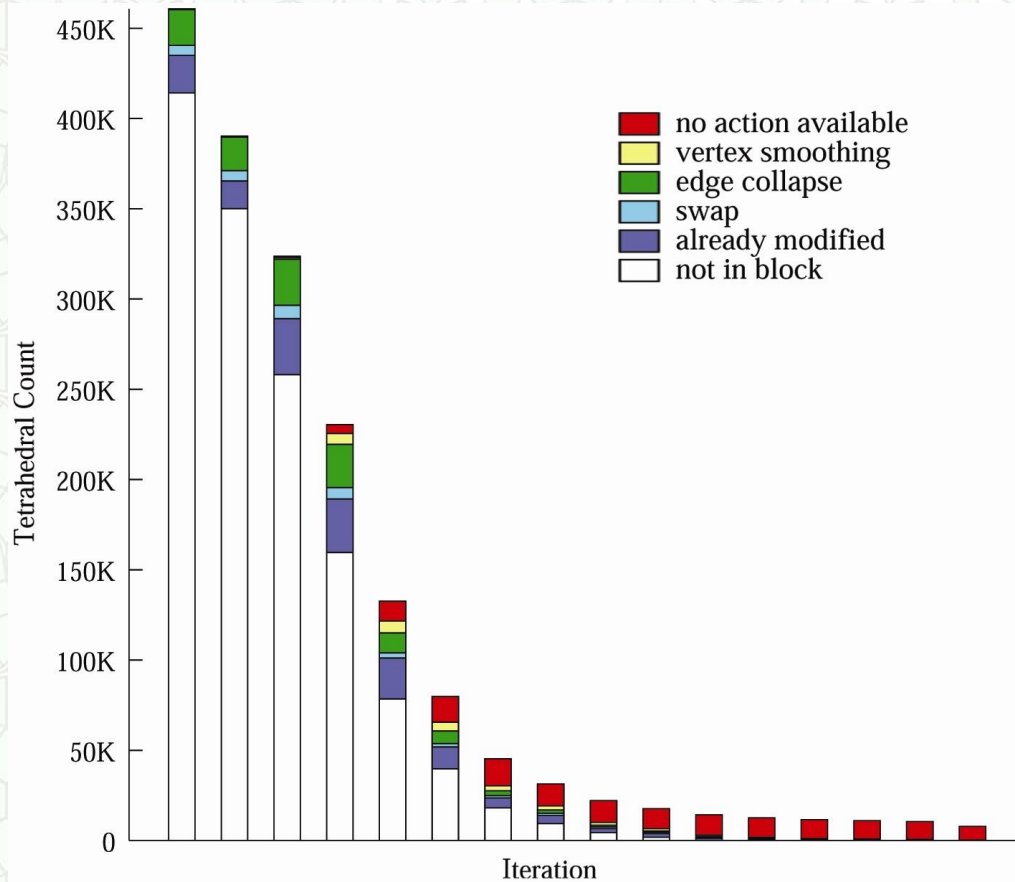
“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004



After Simplification
& Mesh Improvement



Visualization of Simplification Algorithm

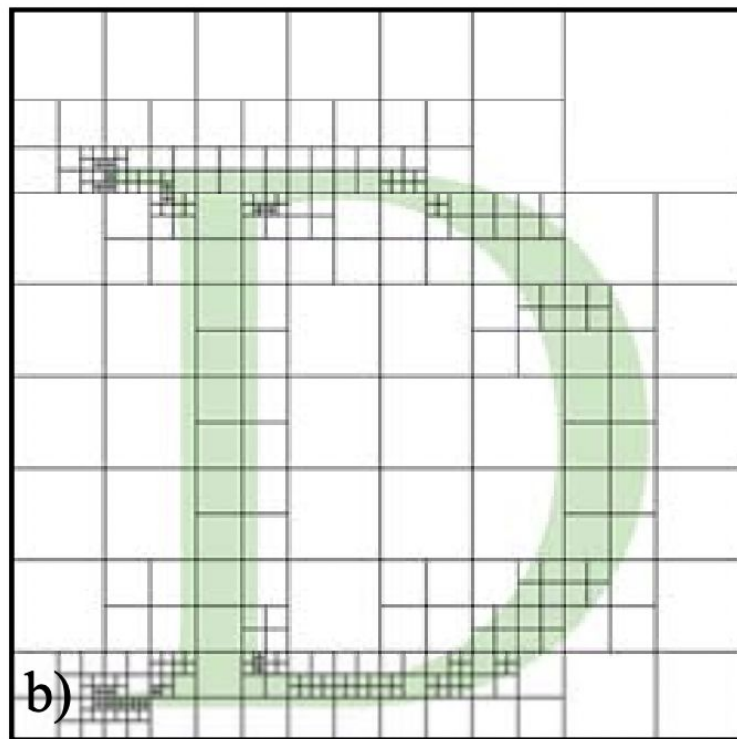
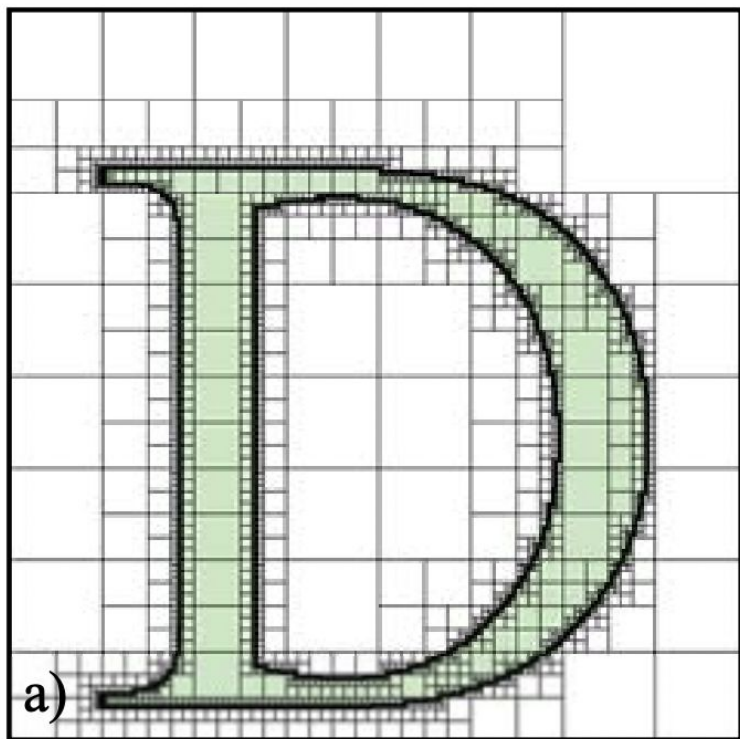


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Next Time: Signed Distance Fields & Level Sets



“Adaptively Sampled Distance Fields: A General Representation of Shape for Computer Graphics”,
Friskén, Perry, Rockwood, and Jones, SIGGRAPH 2001
“Designing with Distance Fields”, Friskén and Perry, 2006