

CSCI 4560/6560 Computational Geometry

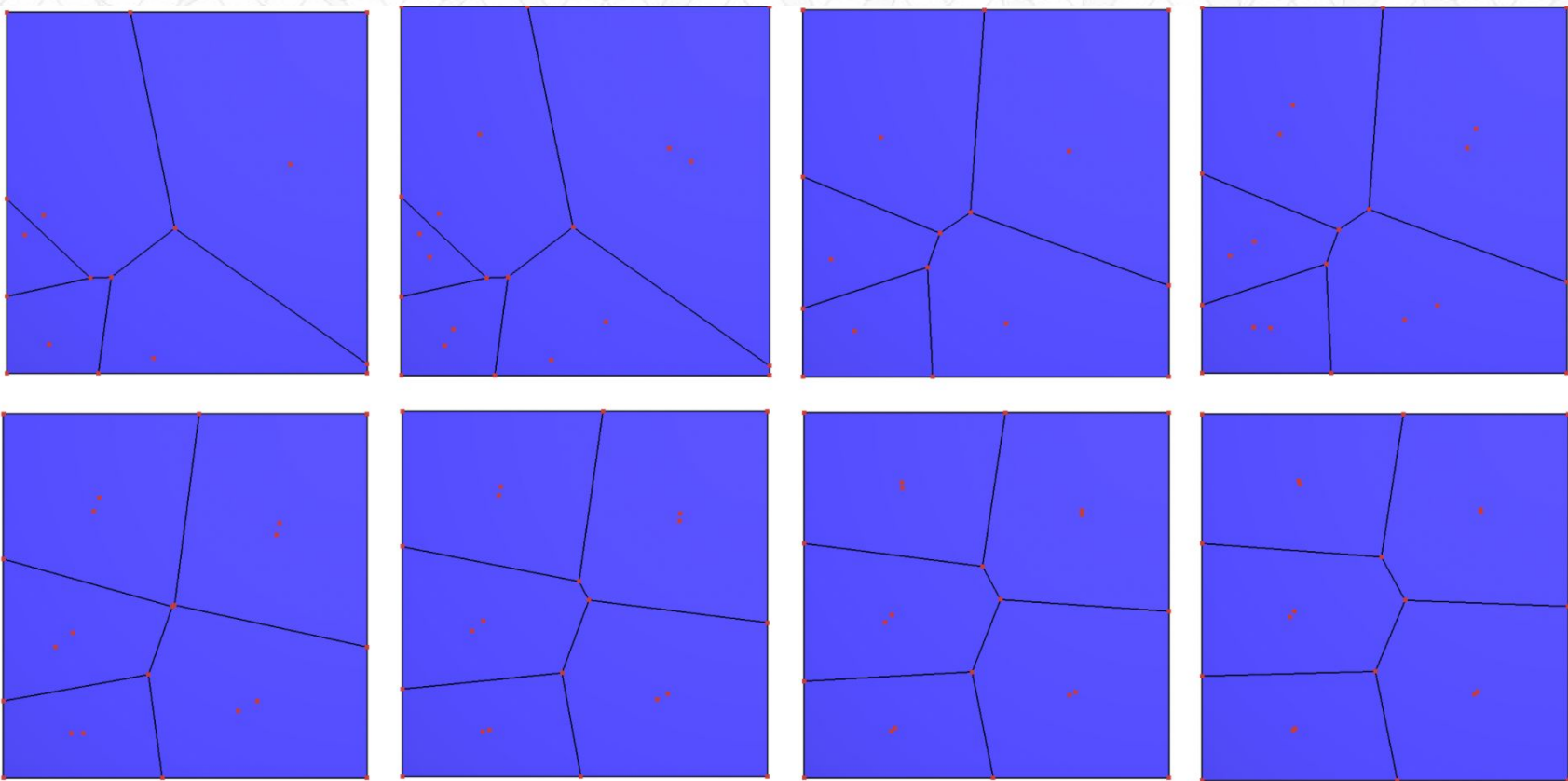
<https://www.cs.rpi.edu/~cutler/classes/computationalgeometry/S22/>

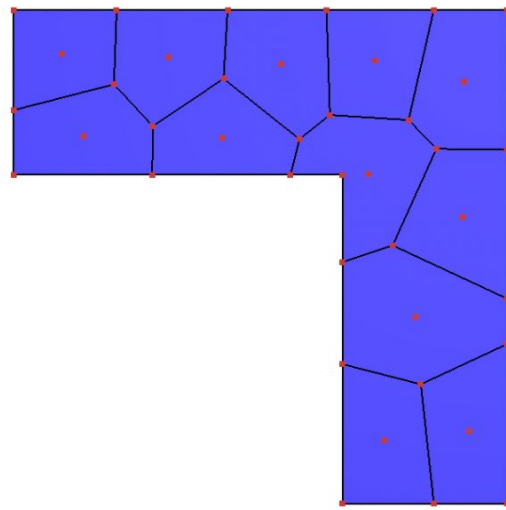
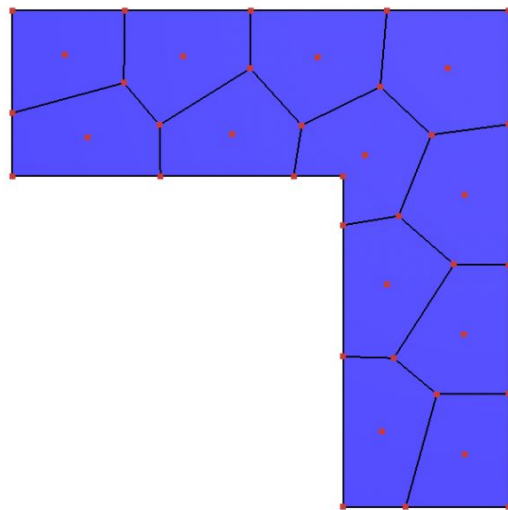
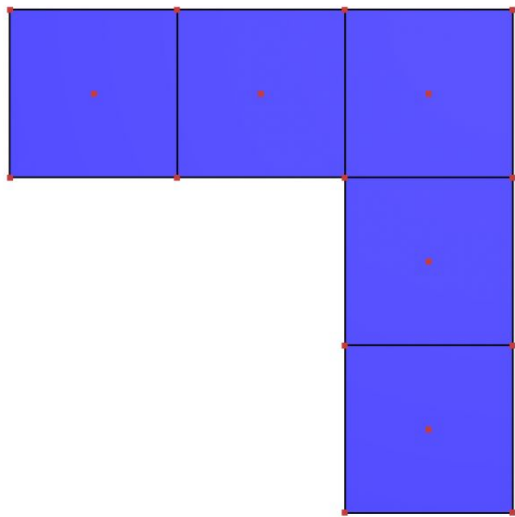
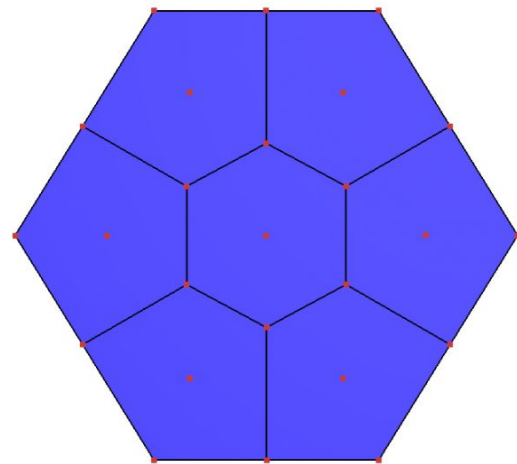
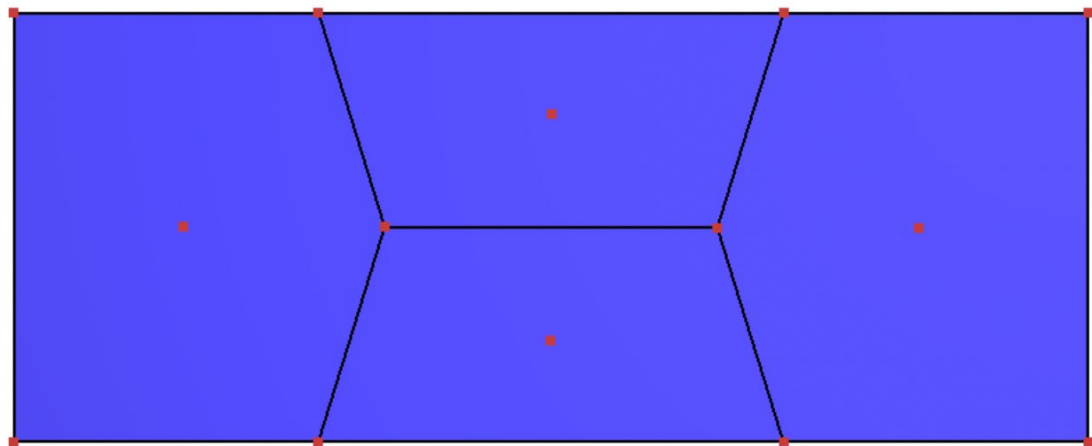
Lecture 17: Quad Trees

Outline for Today

- Homework 5 Questions?
- Last Time: Windowing, Interval Trees & Segments Trees
- Motivation: FEM & CFD Simulation
- Uniform & Non-Uniform Meshing
- k-D Tree vs Quad Tree
- Maximum Depth, Number of Nodes
- Implicit Adjacency, Balanced Quad Tree
- Advanced Topics: $\sqrt{3}$ Subdivision & Octree Textures
- Remeshing for Interactive Deformation
- Next Time: Signed Distance Fields & Level Sets

Homework 5 Questions?



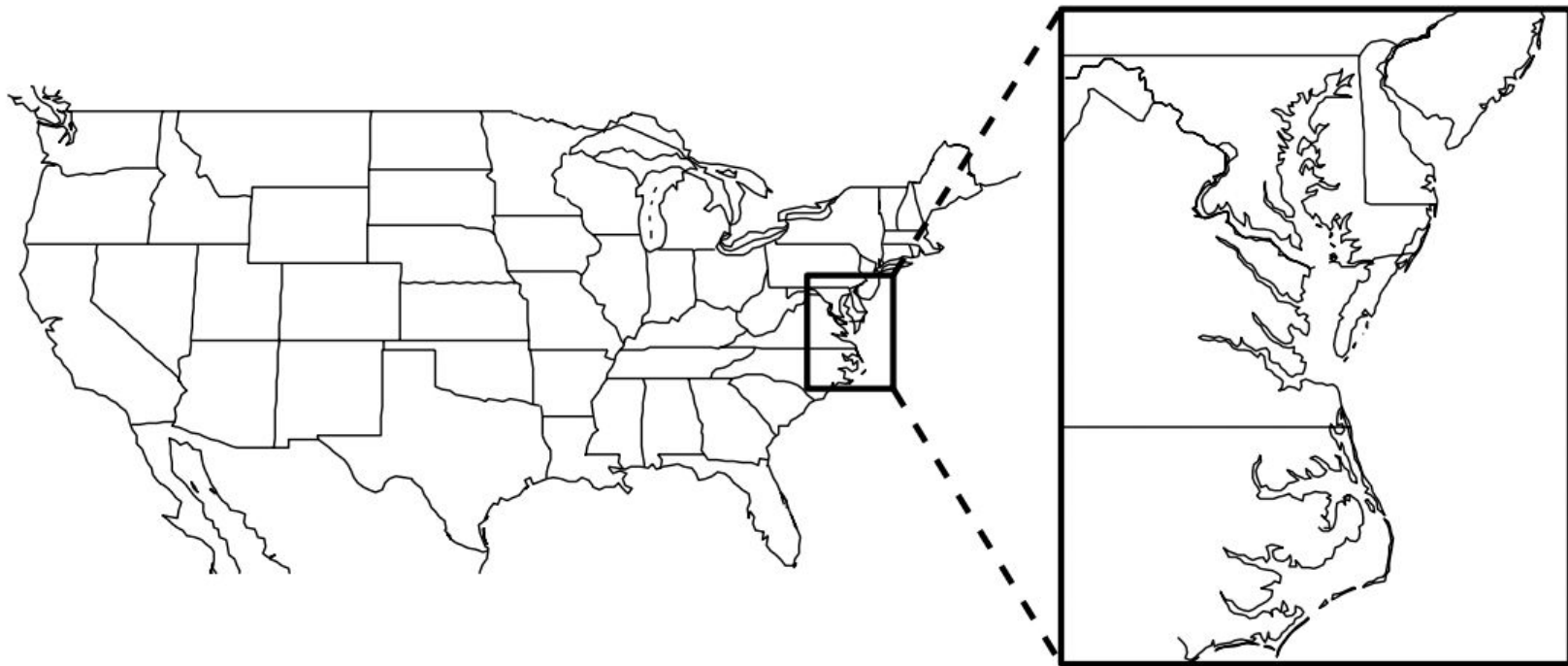


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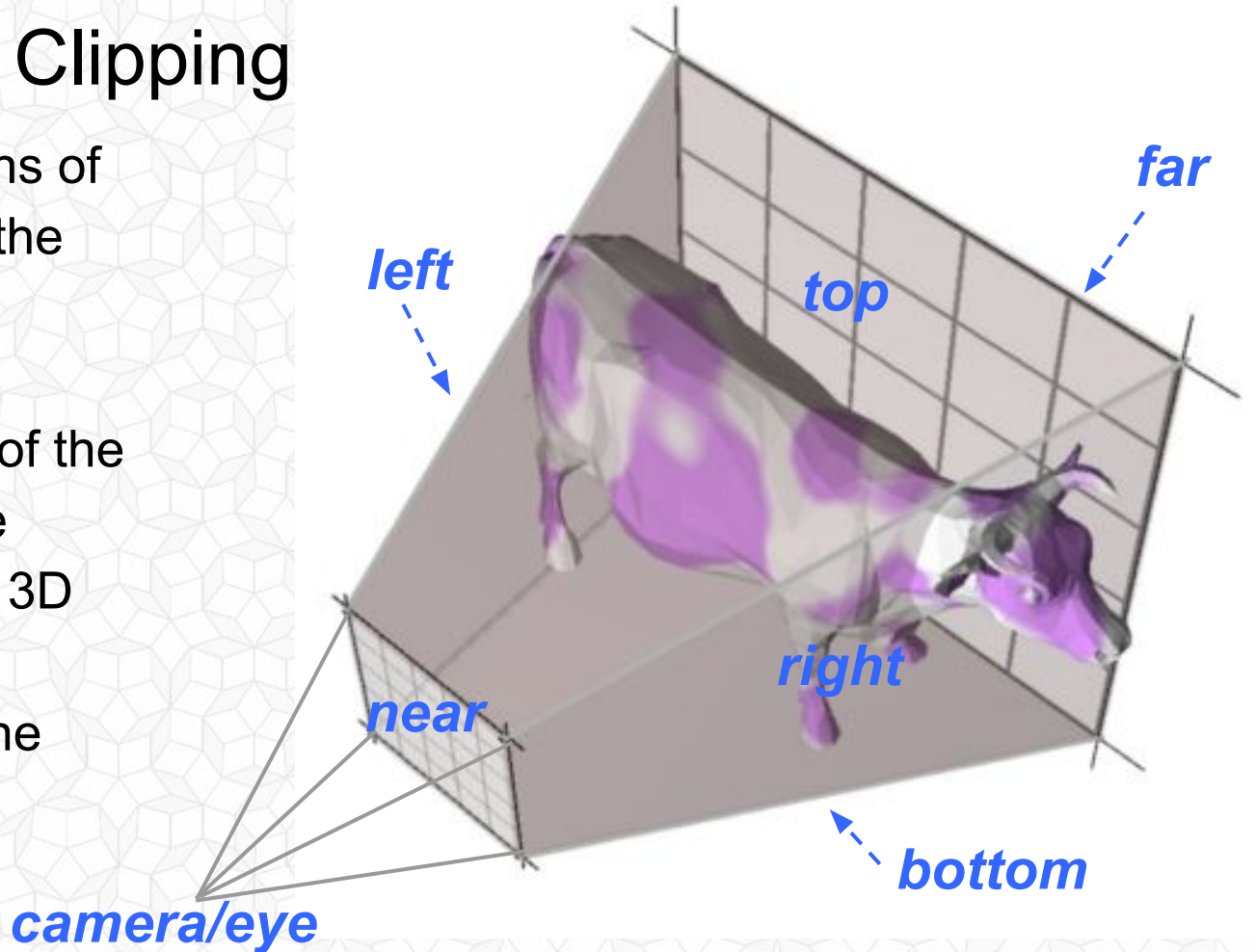
Motivation: Cartography (Map-Making)

- Select a small rectangular region to display in a window at larger scale



Graphics: 3D Clipping

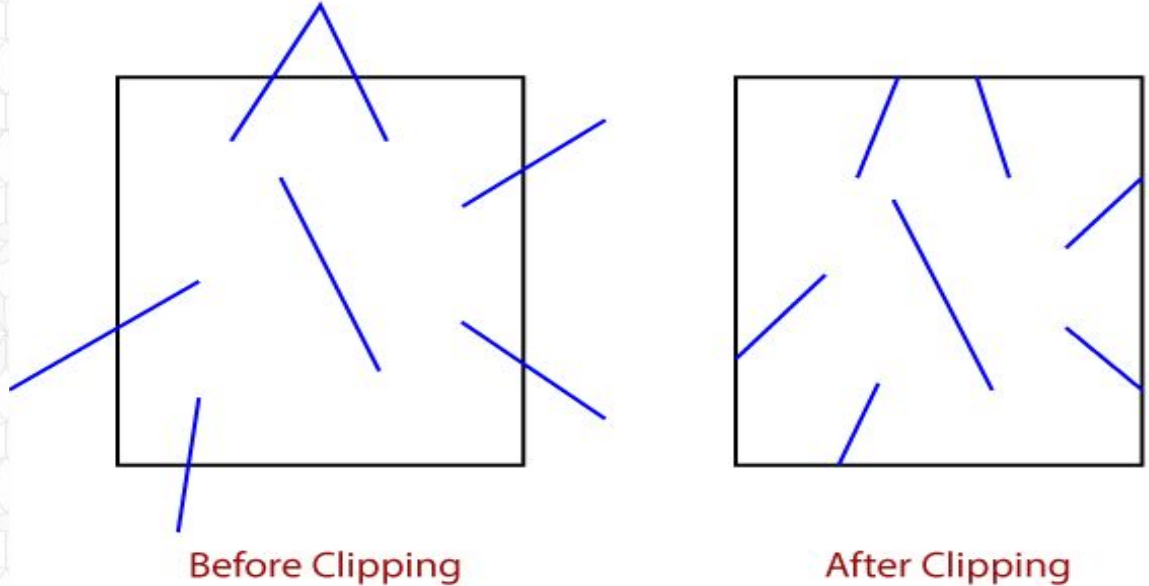
- Eliminate portions of objects outside the viewing frustum
- View Frustum
 - boundaries of the image plane projected in 3D
 - a near & far clipping plane



Graphics: 2D Clipping

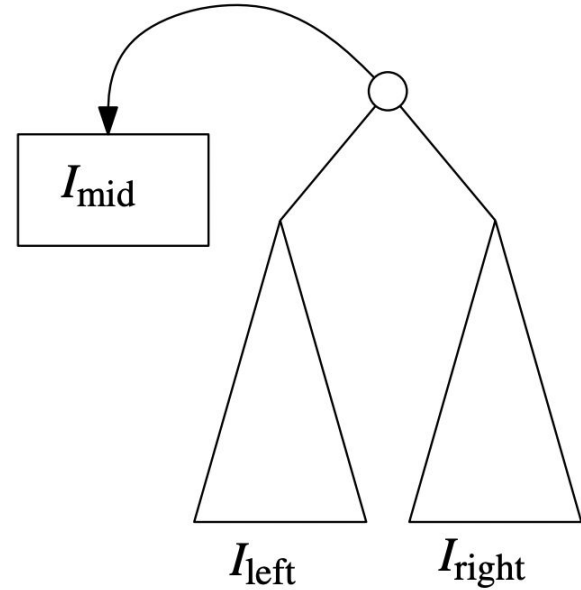
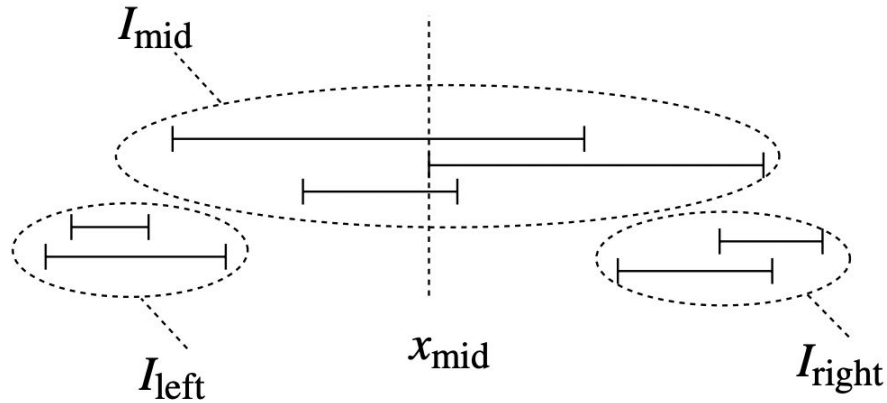
Why do it?

- Reduce amount of geometry going through graphics pipeline
- Prevent rendering bugs from overflow, wraparound, things behind the camera, etc.



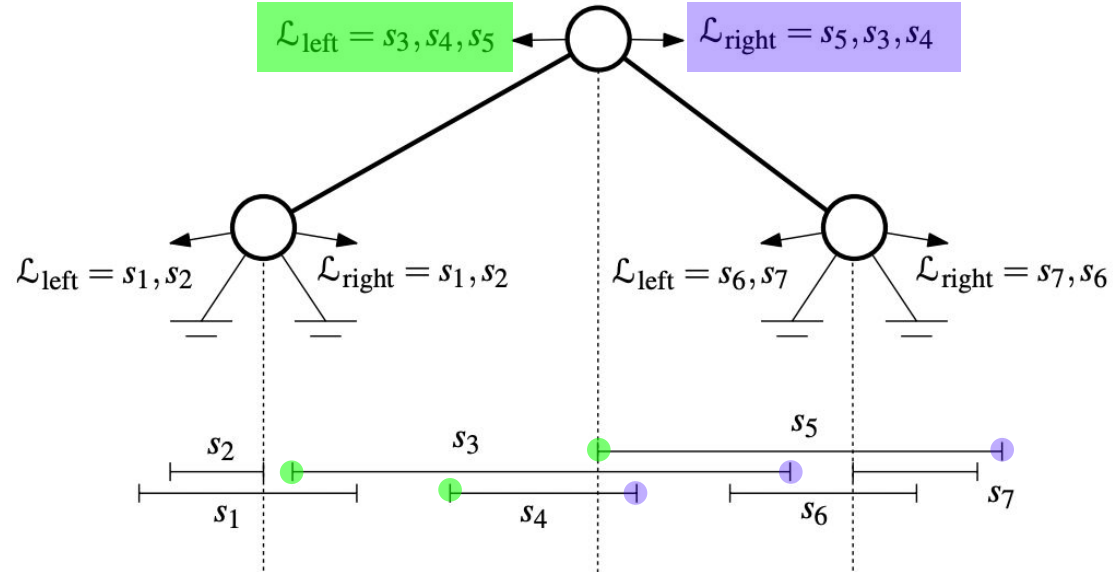
Interval Tree

- Recurse down the tree only with items that DO NOT overlap the split point.



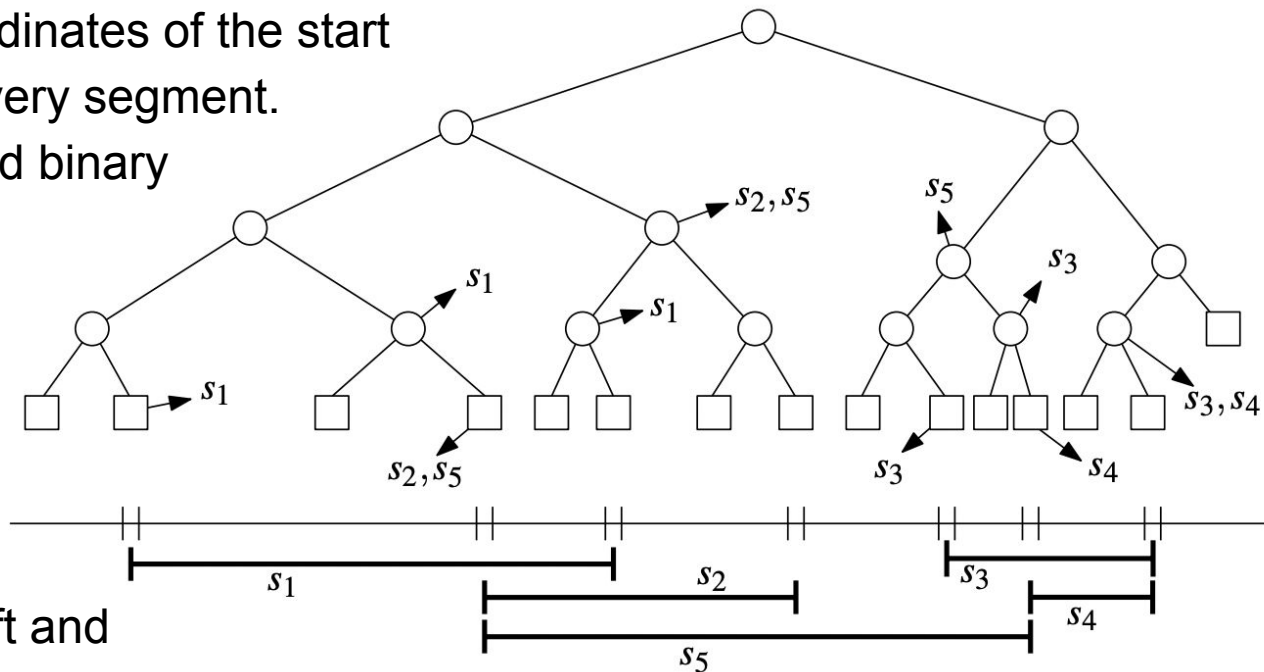
Interval Tree

- Items in I_{mid} group will stay at the current node
- Each node stores two sorted lists:
 - $\mathcal{L}_{\text{left}} = I_{\text{mid}}$ sorted by left endpoint (increasing)
 - $\mathcal{L}_{\text{right}} = I_{\text{mid}}$ sorted by right endpoint (decreasing)



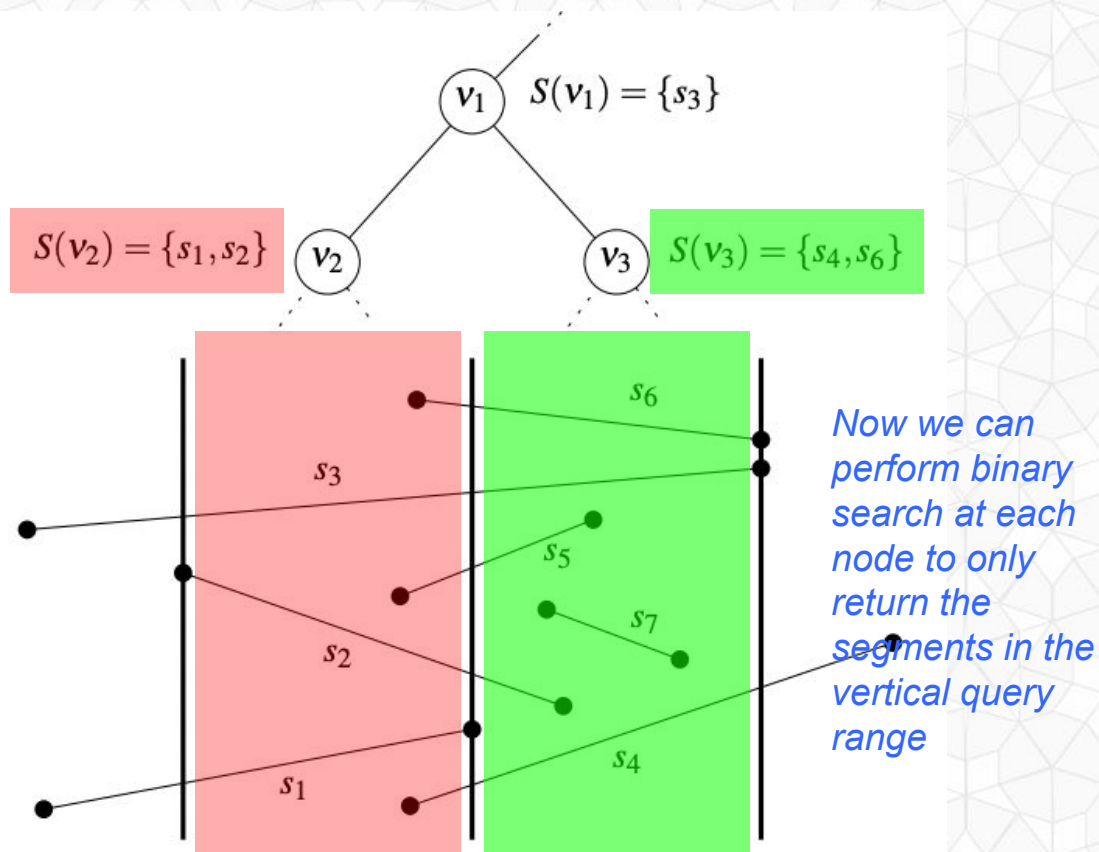
Segment Tree - First Dimension (x)

- First, sort the x coordinates of the start and end points of every segment.
- Construct a balanced binary search tree with these x values.
- Insert every segment into the structure
- If a segment overlaps both the left and right subranges of the node store it at the node (do not recurse)



Segment Tree - Second Dimension (y)

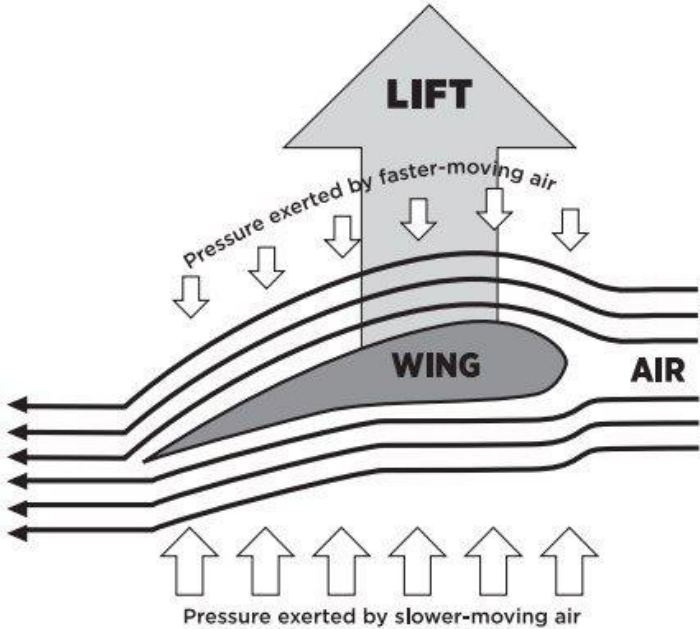
- To efficiently query a vertical range in addition to the horizontal range:
- Sort the segments stored at each node by y
- *Remember: this is only the segments that completely overlaps the node's range*
- Note: this is why we require no crossings in the input segments



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Motivation: Finite Element Modeling (FEM) & Computational Fluid Dynamics



<https://www.scienceworld.ca/resource/plane-wing-simulator/>

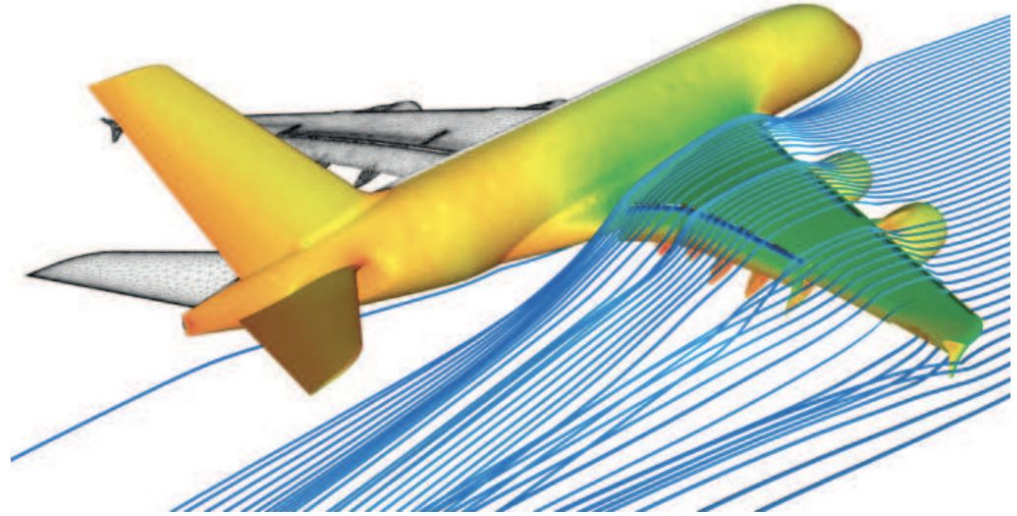
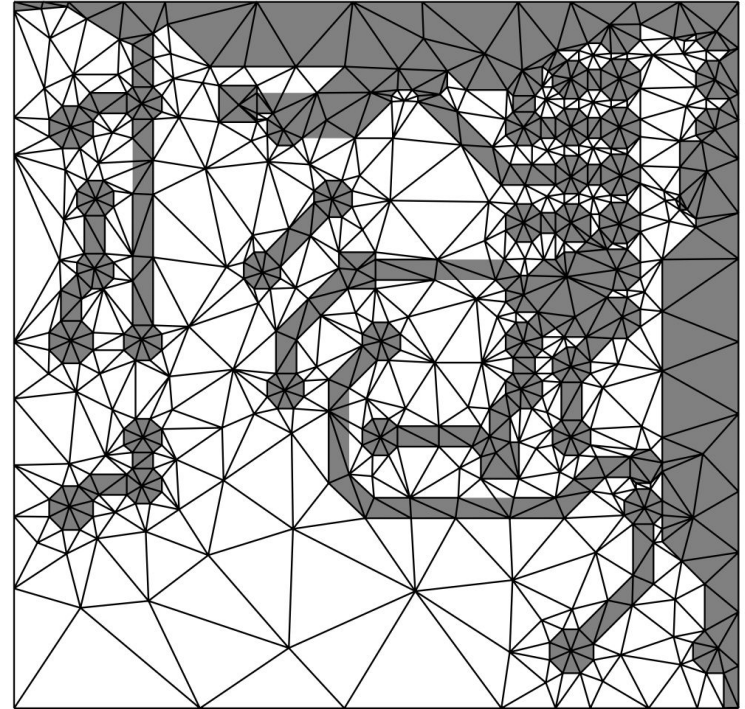


Figure 9: Numerical flow simulation for the Airbus A380 (picture credit: Airbus. Copyright: Dr. Klaus Becker, Senior Manager Aerodynamic Strategies, EGAA, Airbus, Bremen, Germany)

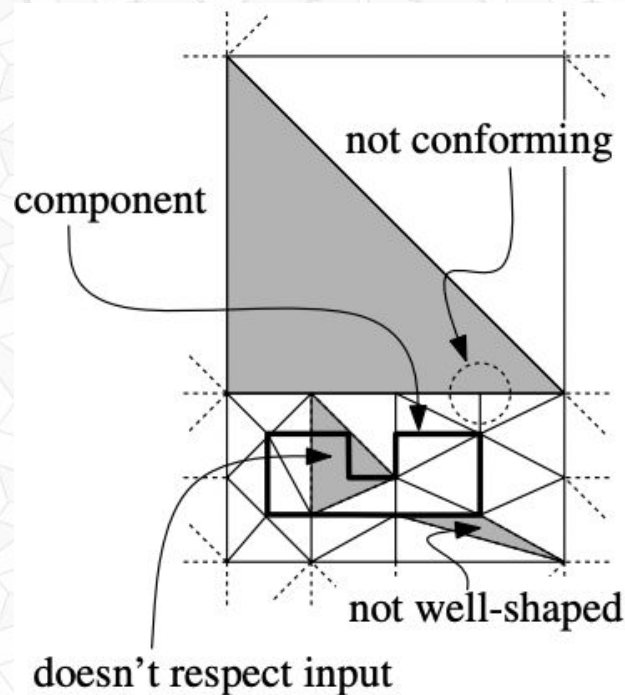
Motivation: Meshing Goals & Requirements

- Triangular Mesh
- Conforming (no T junctions)
- Respect (align) with input surface
- Well shaped (minimum & maximum angle requirements)
- Non-uniform
 - Fine when near input surface (ensure accurate simulation)
 - Coarse when far from the input surface (reduce computation waste)



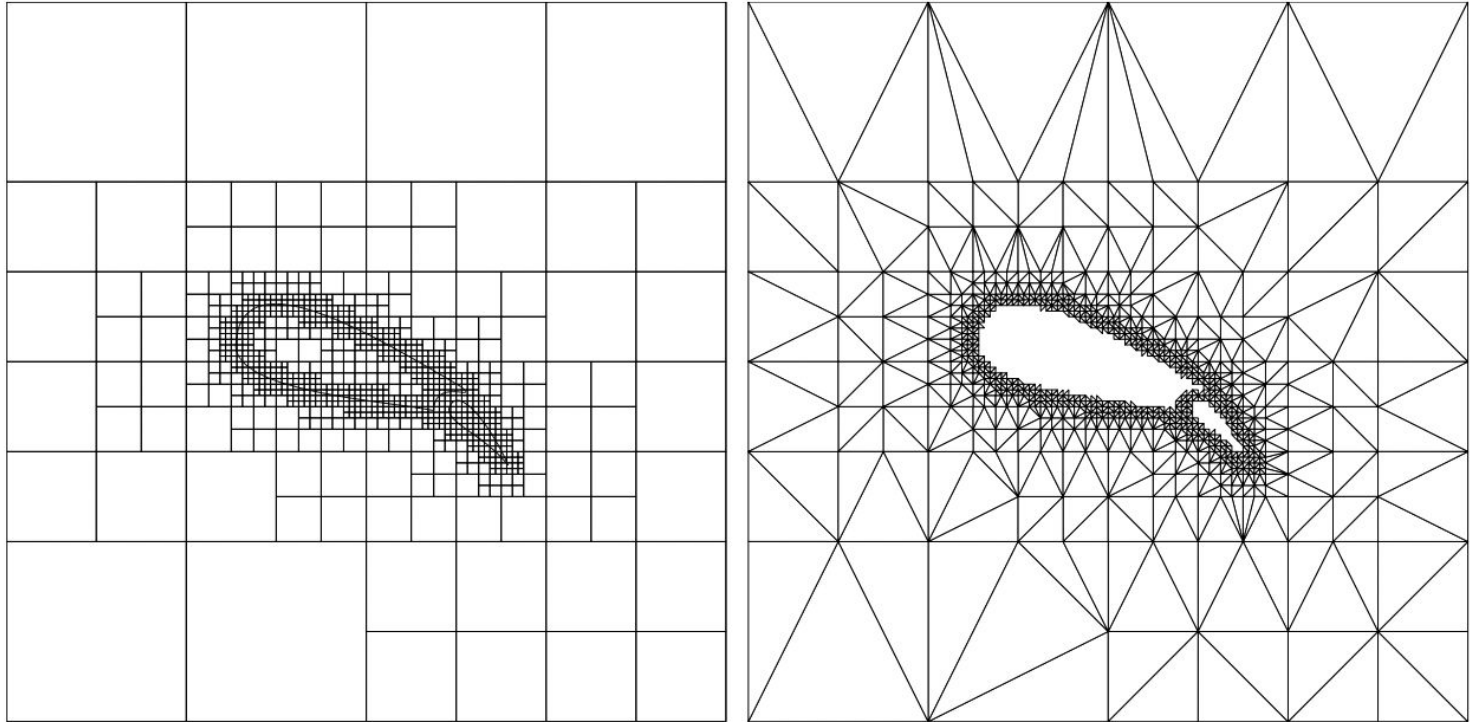
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Motivation: Finite Element Modeling (FEM) & Computational Fluid Dynamics

“Delaunay
Refinement
for Curved
Complexes”,
Adriano Chaves
Lisboa, 2008.

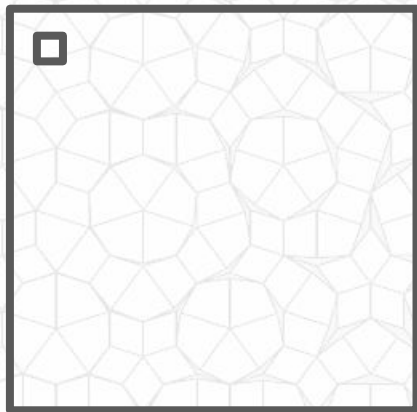


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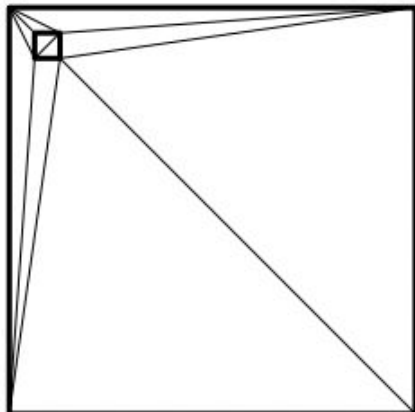
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Uniform vs. Non-Uniform Meshing

Input

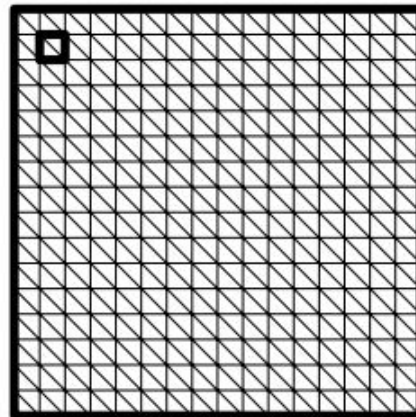


Delaunay

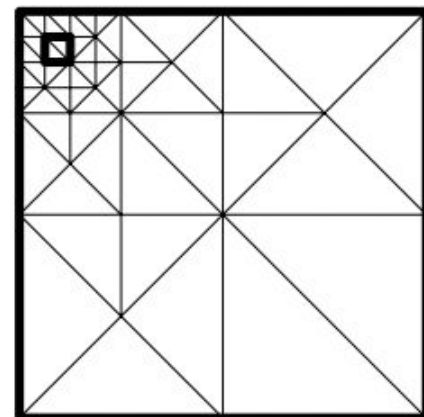


*Only uses the
input vertices*

Uniform



Non-Uniform



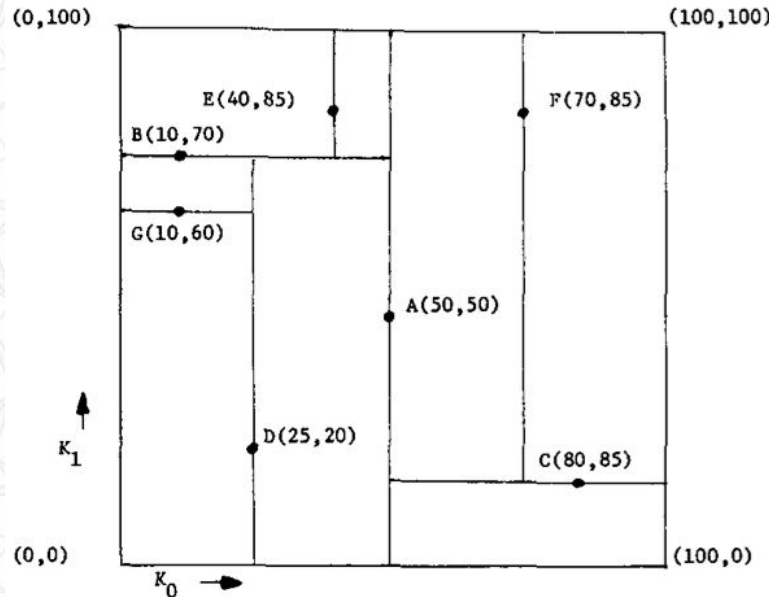
*Addition of “Steiner vertices” is allowed to improve
shape (minimum/maximum triangle angle)*

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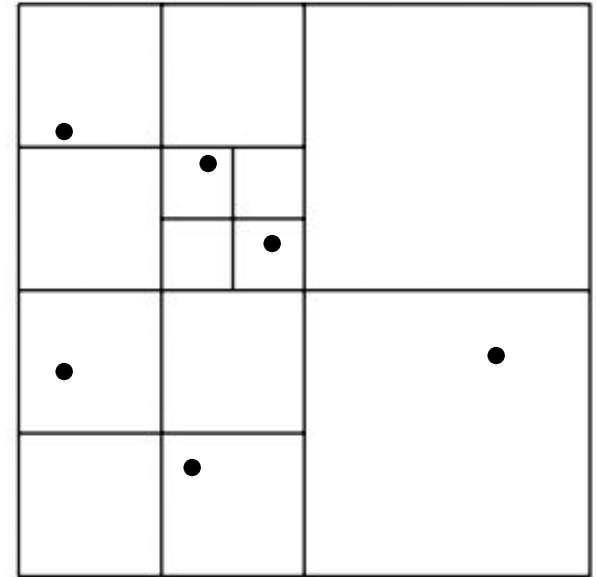
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QuadTree - Basically a special case of k-D Tree

- Split all dimensions at once (instead of alternating one dimension per level)
- Always split at the midpoint (generally not perfectly balanced!)



k-D Tree

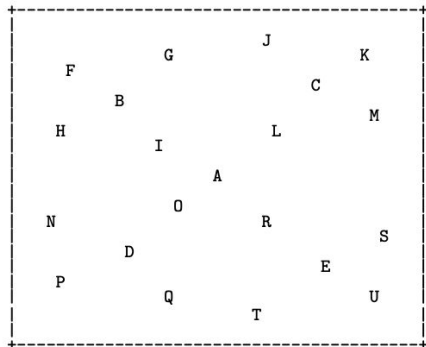


Quad Tree

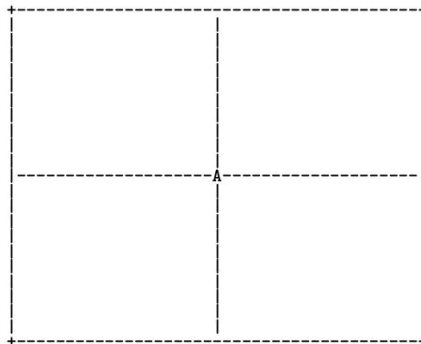
"Multidimensional Binary Search Trees Used for Associative Searching",
Communications of the ACM, Bentley 1975

Data Structures Homework 8: Quad Tree

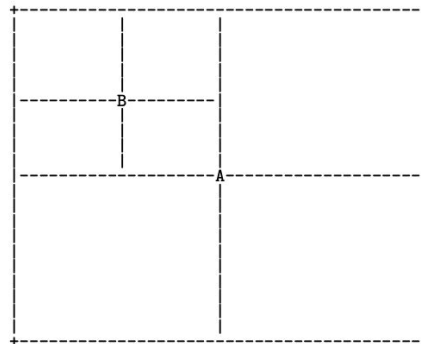
input points



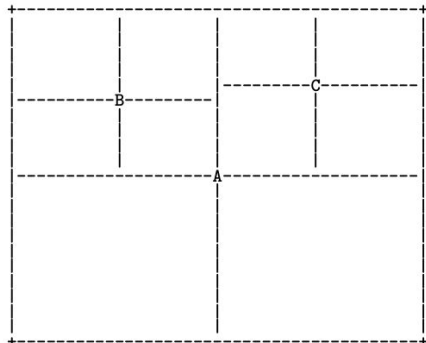
after adding the 1st point



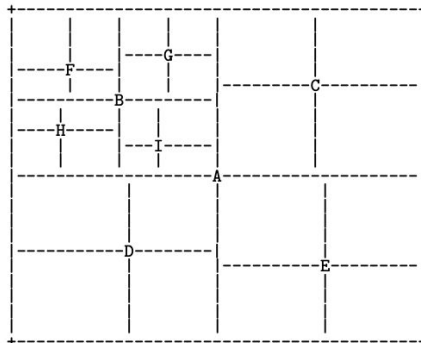
after adding the 2nd point



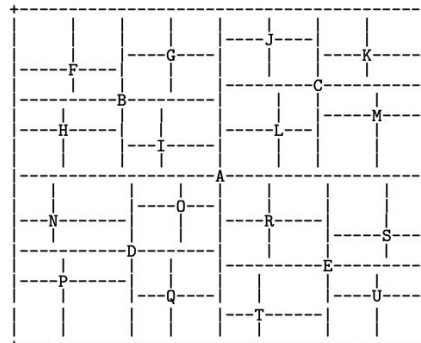
after adding the 3rd point



after adding 9 points



after adding all 21 points



Technically this is a variant of a classic QuadTree.

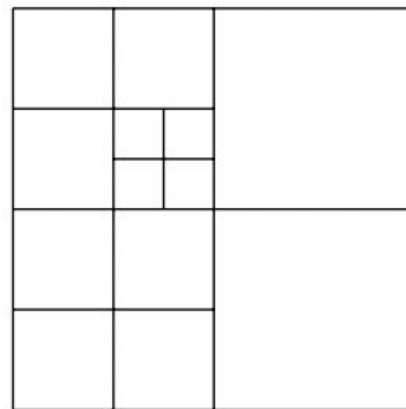
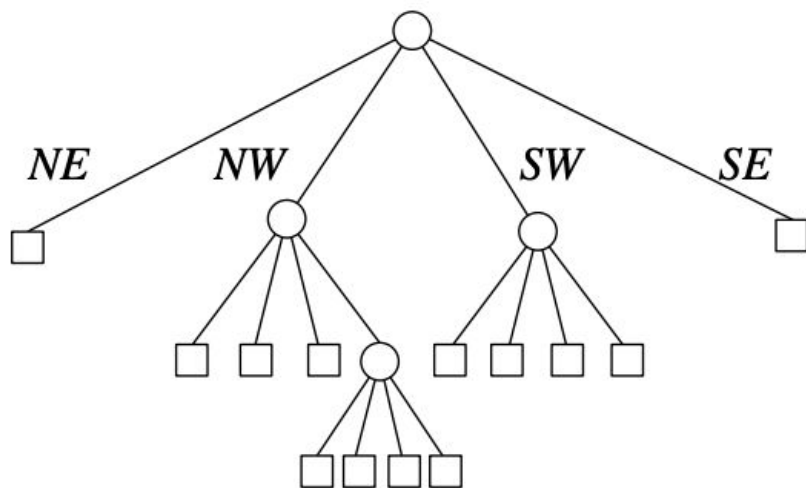
Instead of splitting at the dimension midpoint, we split at a specific data point...

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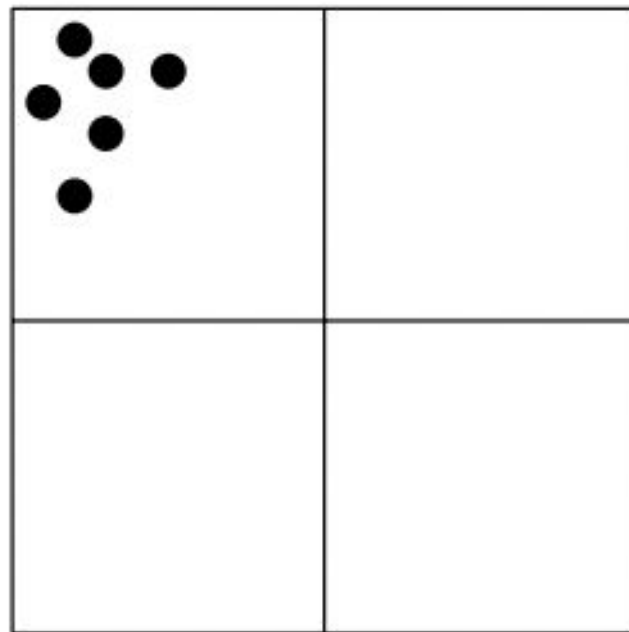
QuadTree Structure Consistency

- Let's split a cell into 4 children if 2 nodes are placed into the same cell
- Points that lie on a vertical split, assigned to left child
- Points that lie on a horizontal split, assigned to bottom child



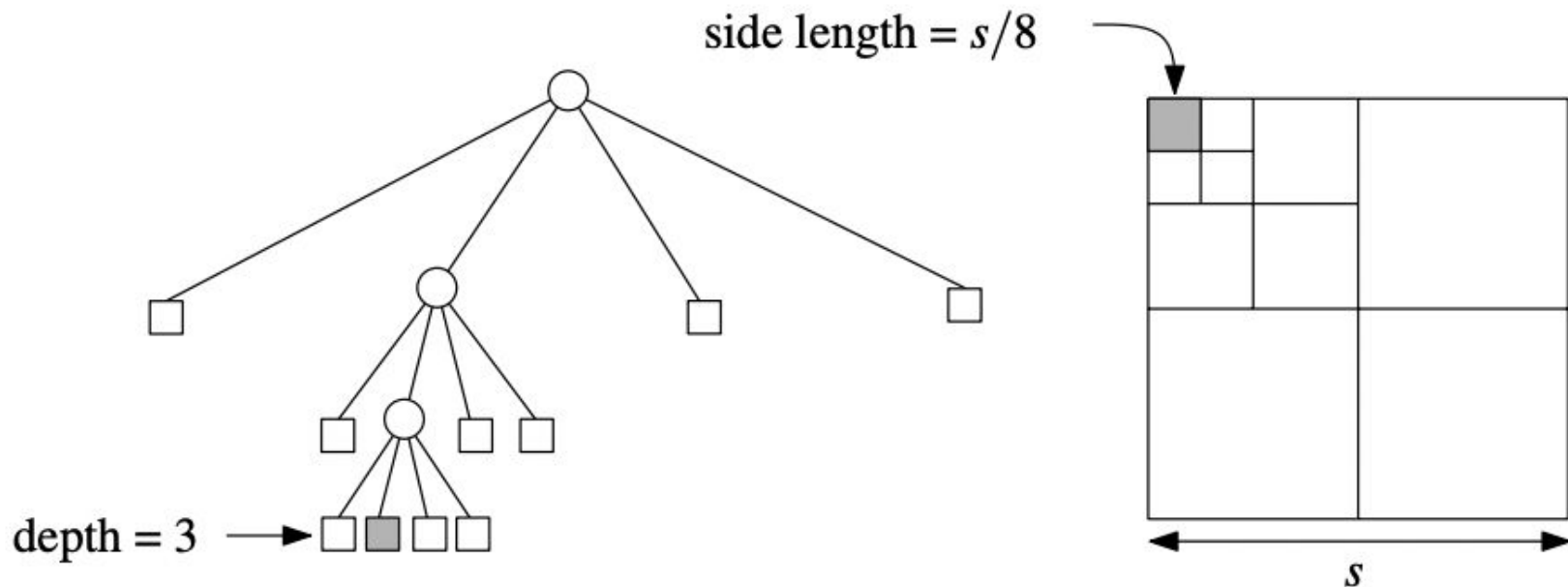
Maximum Quad Tree Depth

- We always split a cell into 4 children if 2 nodes are placed into the same cell....
- **Lemma 14.1:** The depth of a quadtree for a set P of points in the plane is at most $\log(s/c) + 3/2$, where c is the smallest distance between any two points in P and s is the side length of the initial square that contains P .



Maximum Number of Nodes

- **Theorem 14.2:** A quadtree of depth d storing a set of n points has $O((d + 1)n)$ nodes and can be constructed in $O((d + 1)n)$ time.

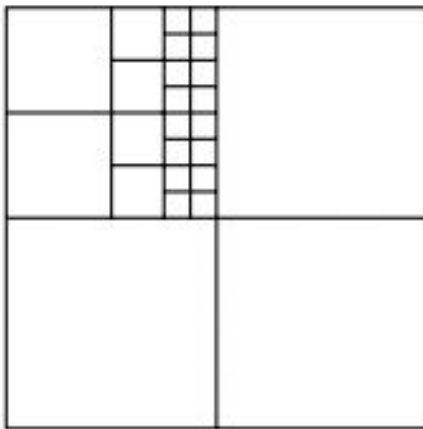


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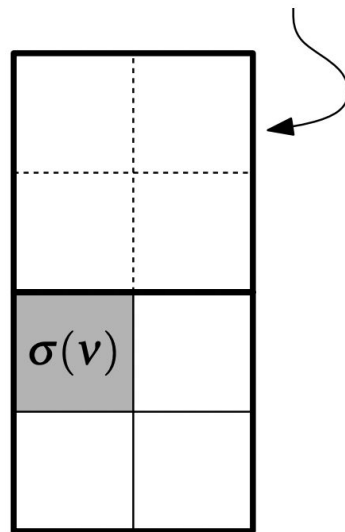
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QuadTree and Implicit Adjacency

- We don't need to explicitly store pointers to adjacency cell.
- However, it is disadvantageous to have adjacent cells that are subdivided to a significantly different tree level.
- Let's do something to make the tree more balanced....

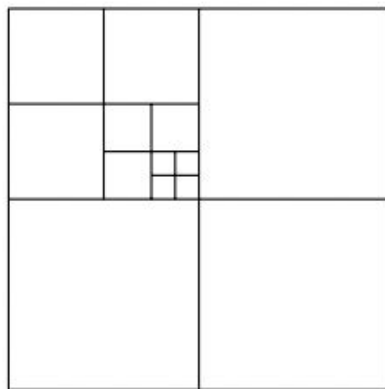


north-neighbor of $parent(v)$

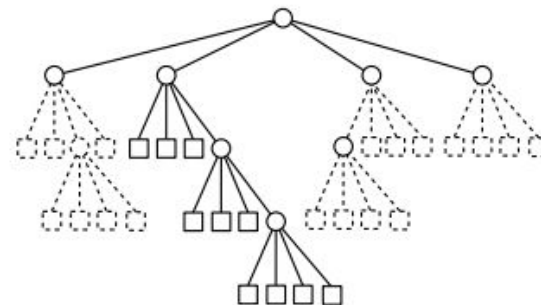
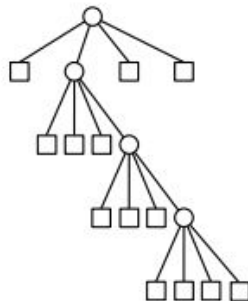
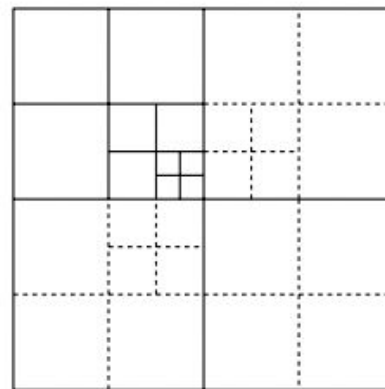


Balanced Quad Tree

- Adjacent cells of the tree are no more than 1 split different



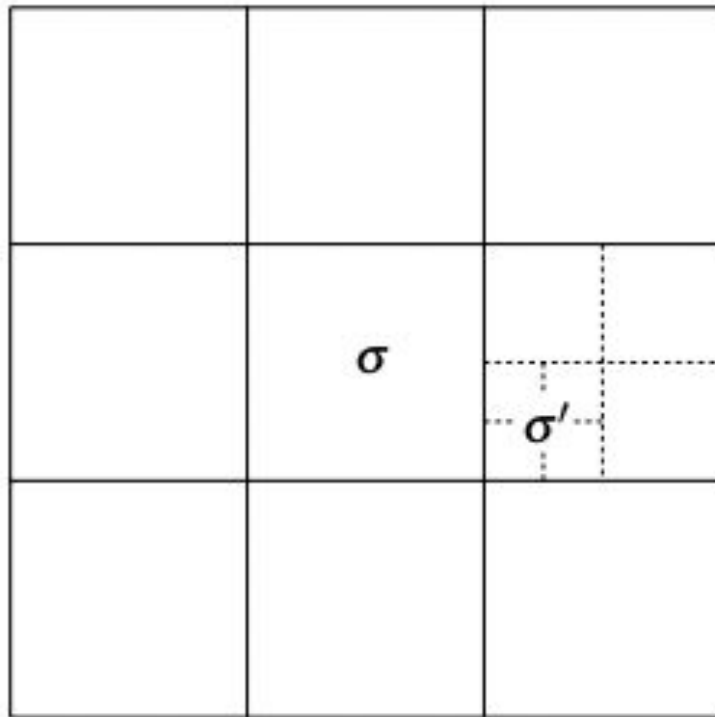
balancing



*Computational Geometry
Algorithms and Applications,
de Berg, Cheong, van Kreveld
and Overmars, Chapter 14*

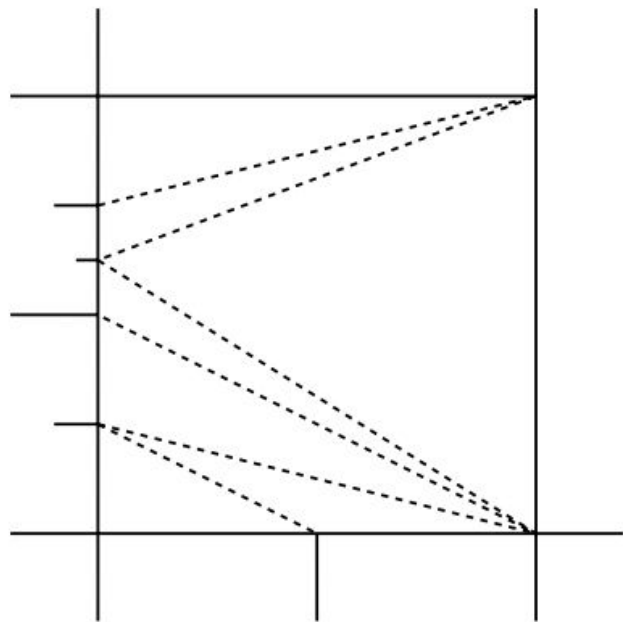
of Splits Required to Balance a QuadTree?

- **Theorem 14.4:** Let T be a quadtree with m nodes. Then the balanced version of T has $O(m)$ nodes and it can be constructed in $O((d + 1)m)$ time.

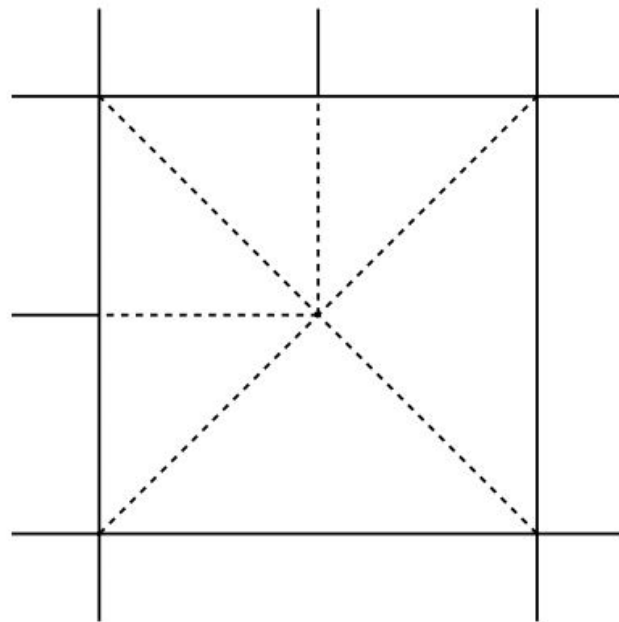


Balanced Quad Tree Triangulation

- A Balanced Quad Tree can be triangulated with all $45^\circ/45^\circ/90^\circ$ triangles!



unbalanced Quad Tree

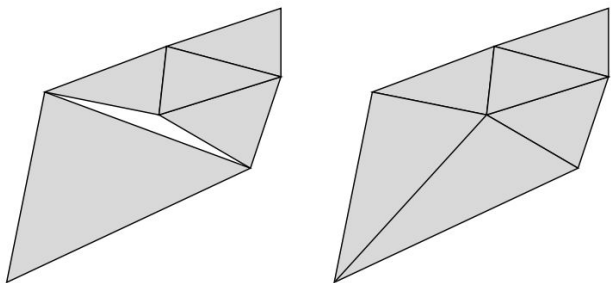


Balanced Quad Tree

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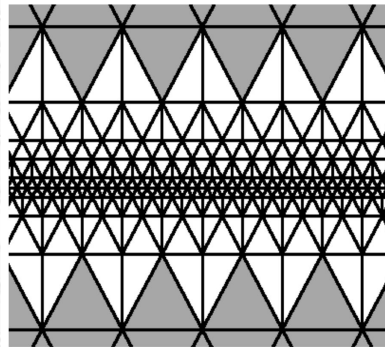
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$\sqrt{3}$ Subdivision, Kobbelt, SIGGRAPH 2000

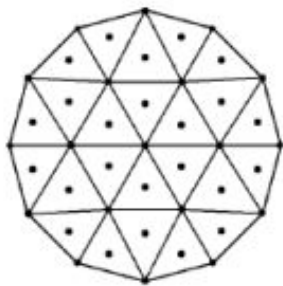


Adaptive Subdivision (Loop): Need to close gaps between different levels of refinement

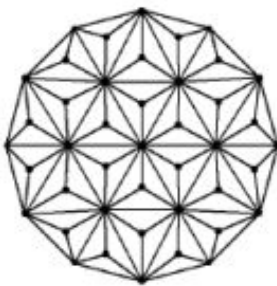
Loop: less localized refinement



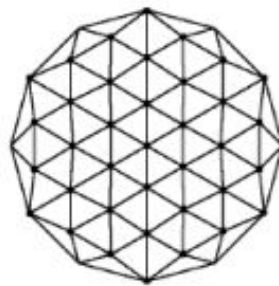
$\sqrt{3}$ Subdivision:
No intermediate special case



the split operation places a midvertex at the centre of each triangle

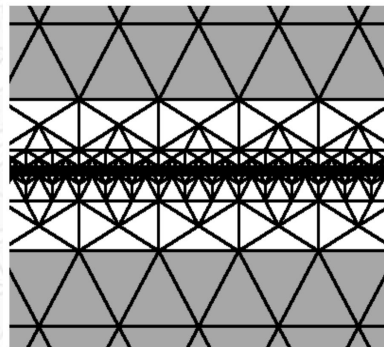


joining the midvertex to the vertices of the triangle realises the 1-to-3 split



after smoothing each old vertex, edges are flipped to connect pairs of midvertices

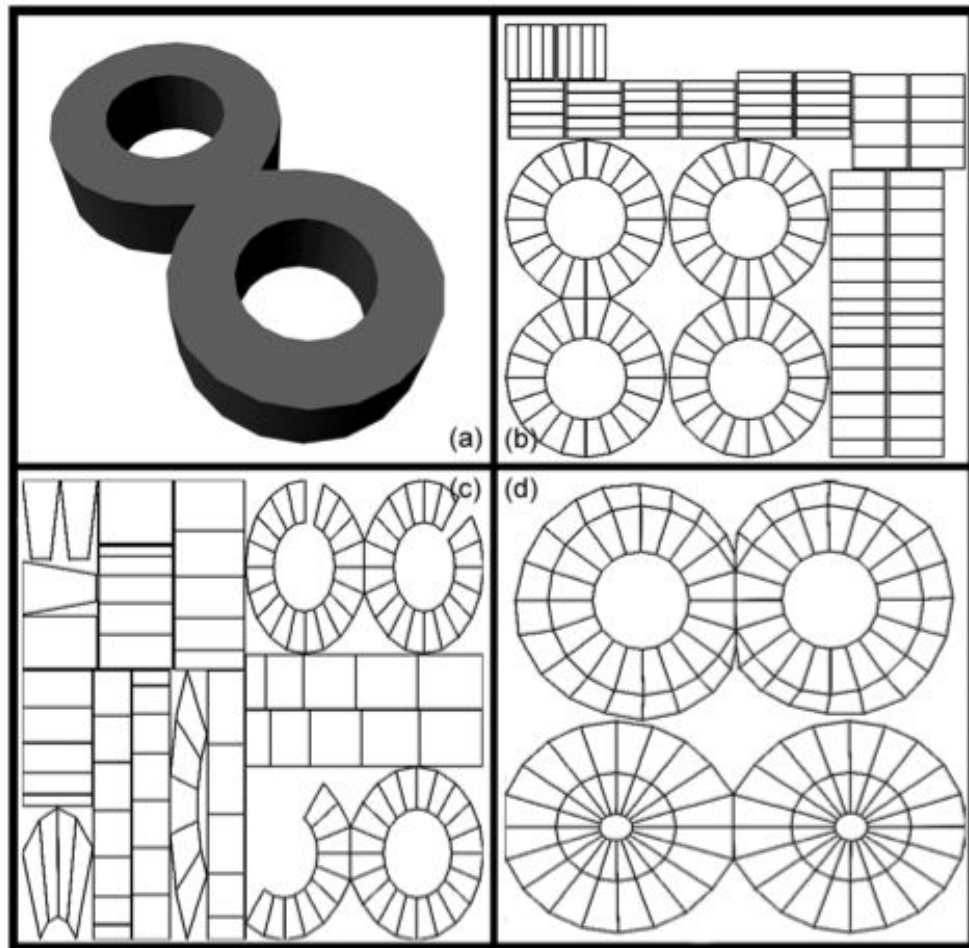
$\sqrt{3}$: more localized refinement



Traditional Texture Mapping

- Unroll / Unwrap the object to 2D
- Parameterize / Correspond 3D \leftrightarrow 2D
- “Paint” 2D texture

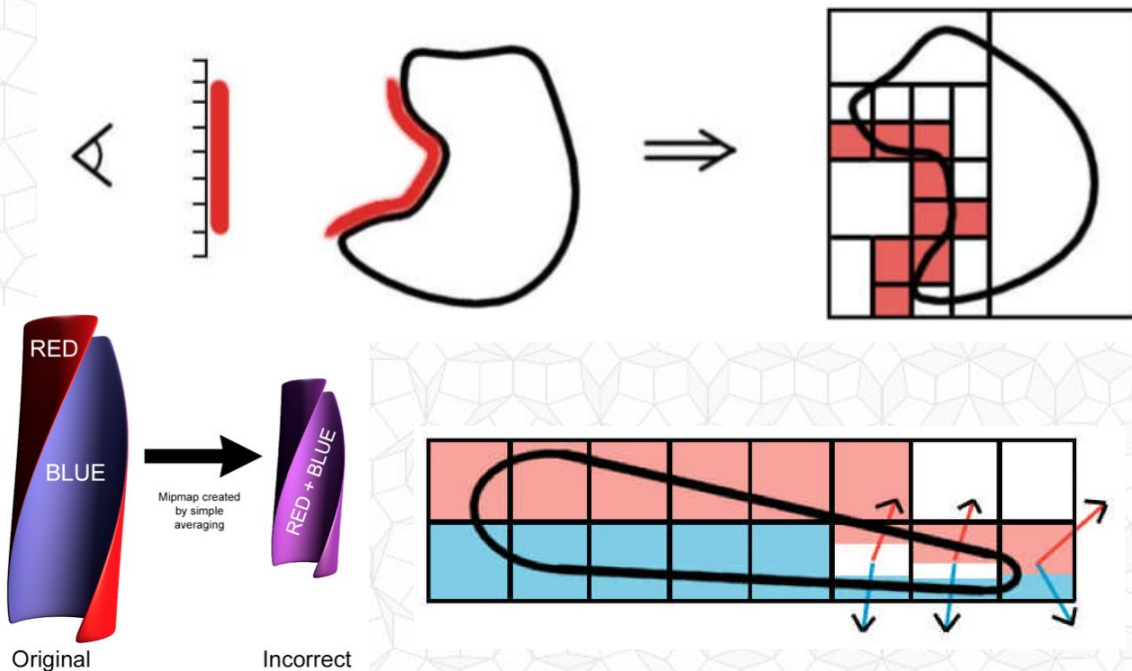
“Painting and Rendering Textures on
Unparameterized Models”,
DeBry, Gibbs, DeLeon, and Robins,
SIGGRAPH 2002



Octree Texture Mapping

"Octree Textures", Benson & Davis, SIGGRAPH 2002

"Painting and Rendering Textures on Unparameterized Models",
DeBry, Gibbs, DeLeon, and Robins, SIGGRAPH 2002



2D Texture Maps



Max Depth 8 (256)



Max Depth 9 (512)



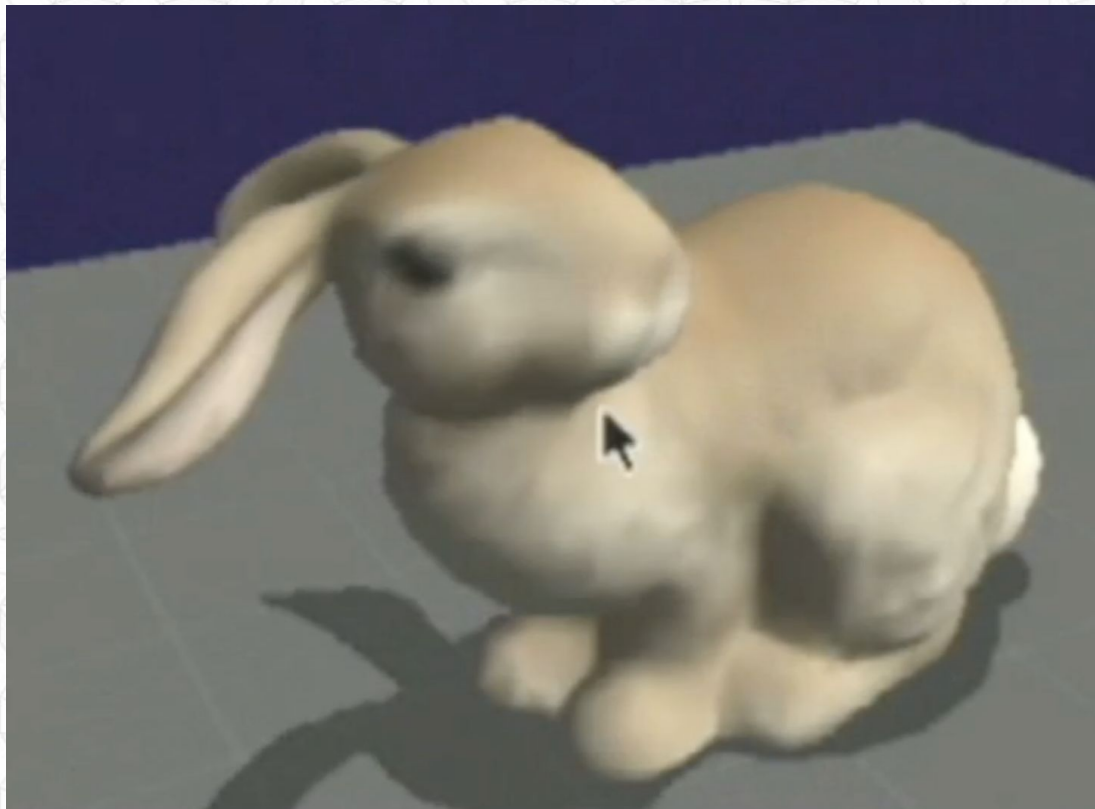
Max Depth 10 (1024)

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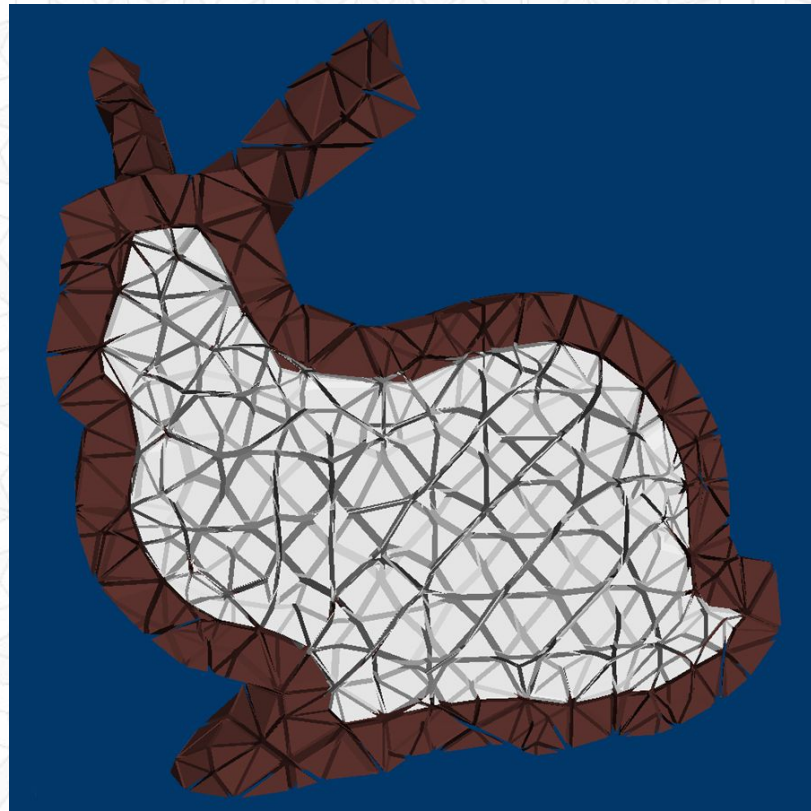
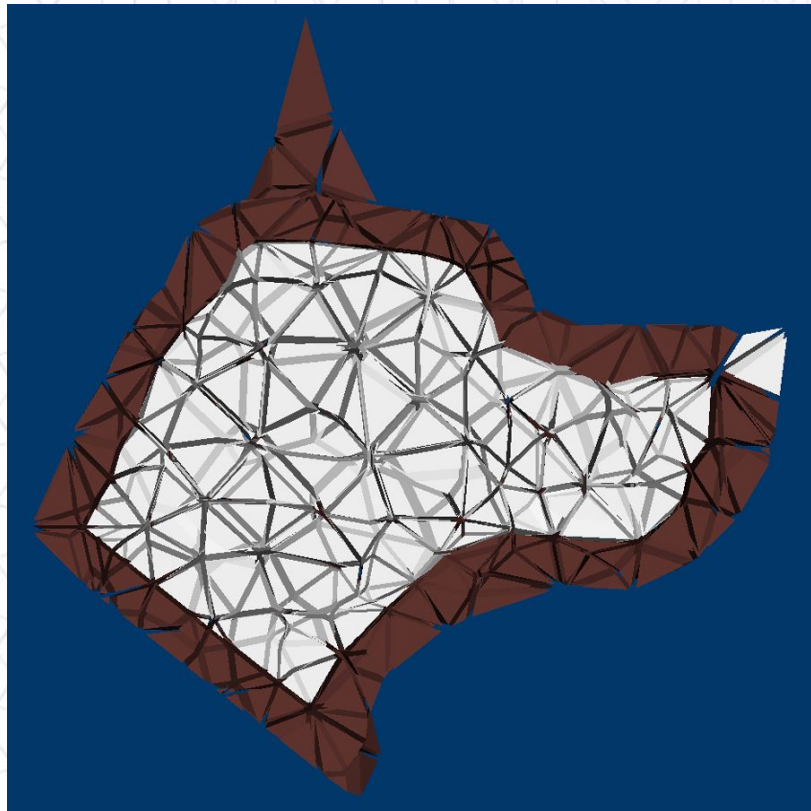
Deformation Simulation

Mueller, Dorsey, McMillan, Jagnow, & Cutler
Stable Real-Time Deformations
Symposium on Computer Animation 2002



Deformation Simulation

Mueller, Dorsey, McMillan, Jagnow, & Cutler
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3D Mesh Simplification

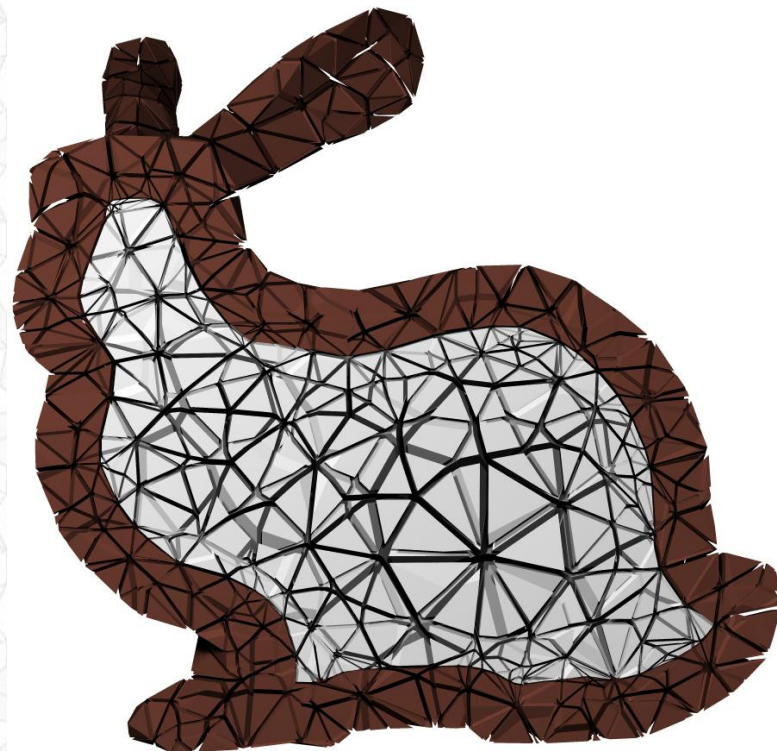
“Simplification and Improvement of
Tetrahedral Models for Simulation”

Cutler, Dorsey, and McMillan

SGP 2004



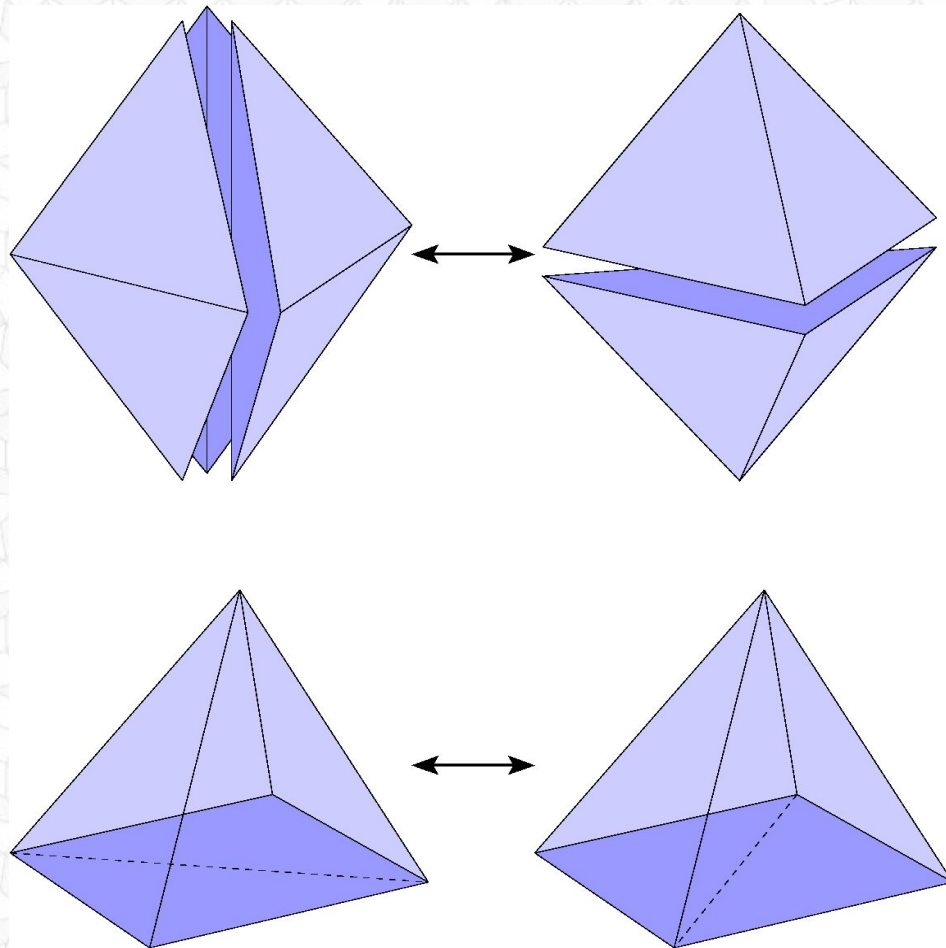
1,050K tetras
(133K faces)



10K tetras
(3K faces)

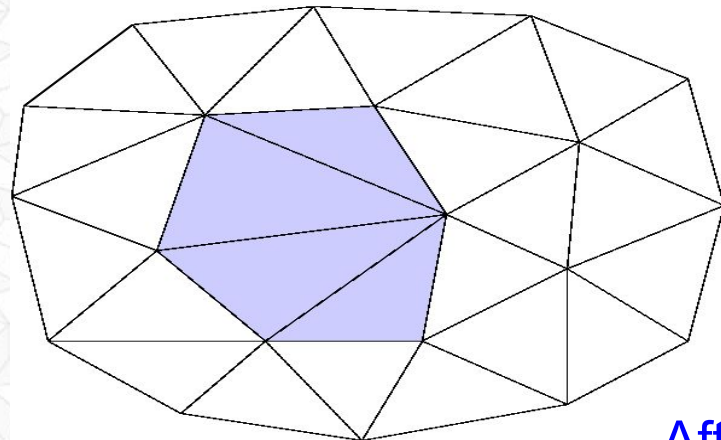
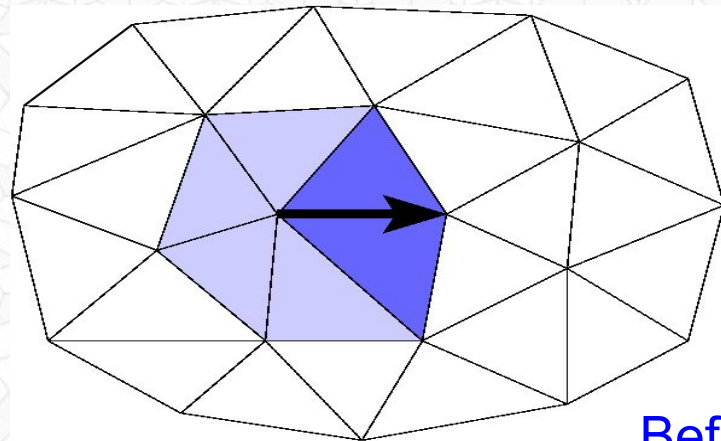
3D Mesh Operations

- Tetrahedral Swaps
 - Choose the configuration with the best local element shape
- Edge Collapse
- Vertex Smoothing
- Vertex Addition



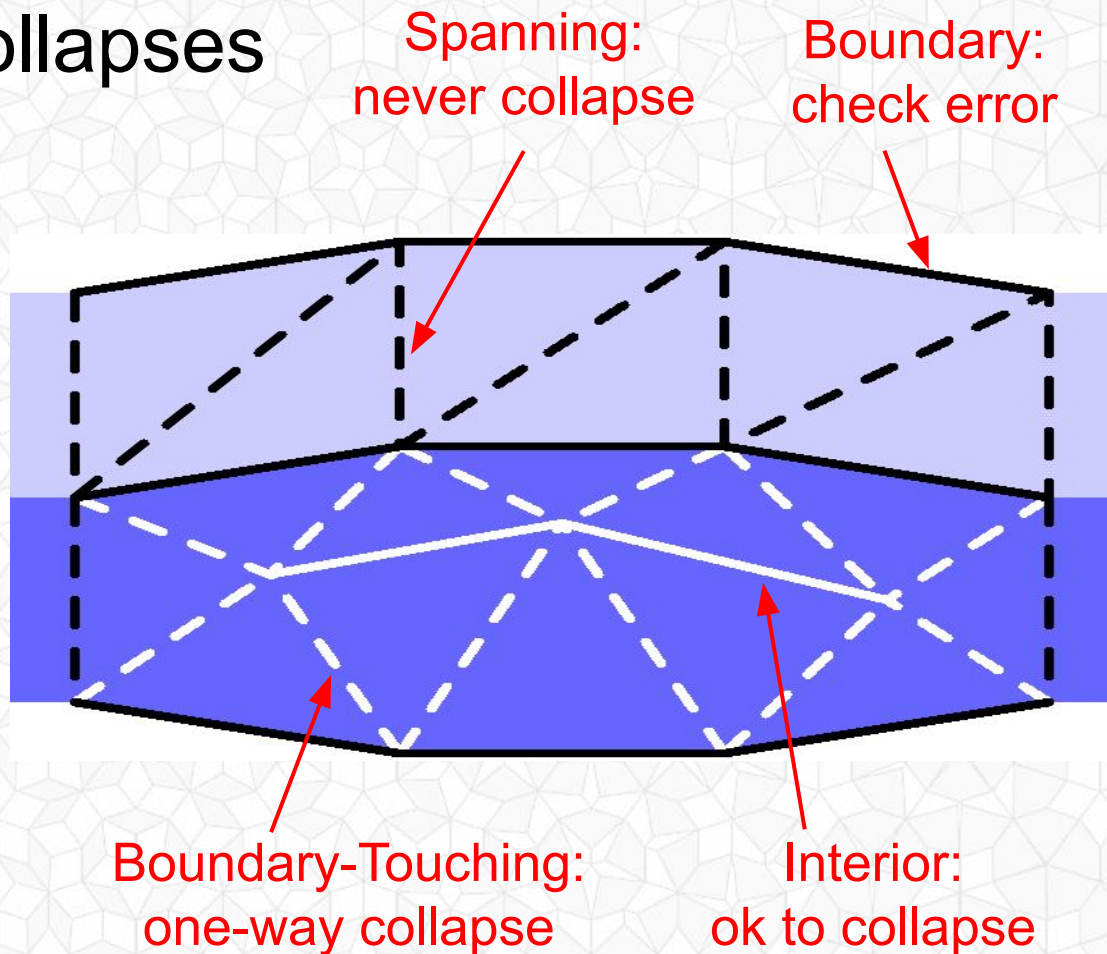
3D Mesh Operations

- Tetrahedral Swaps
- Edge Collapse
 - Delete a vertex & the elements around the edge
- Vertex Smoothing
- Vertex Addition



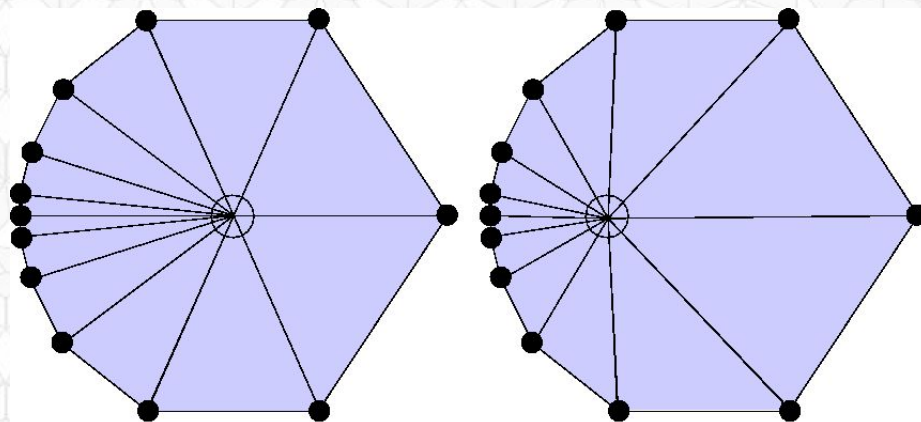
Prioritizing Edge Collapses

- Preserve topology
 - Thin layers should not pinch together
- Collapse weight
 - Edge length + boundary error
- No negative volumes
- Local element quality does not significantly worsen



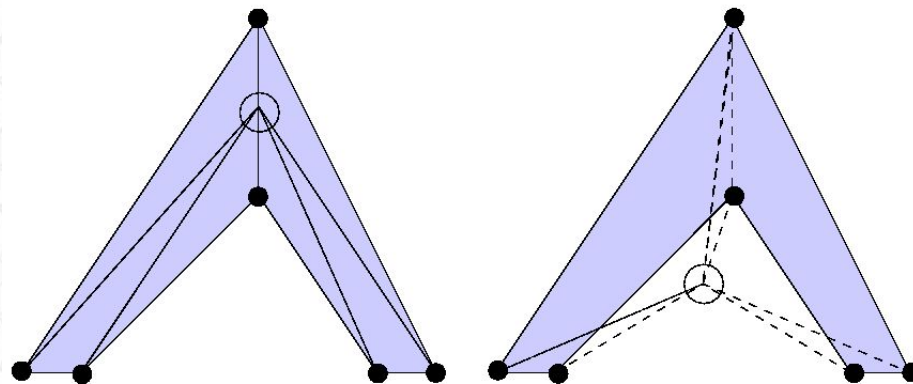
3D Mesh Operations

- Tetrahedral Swaps
- Edge Collapse
- **Vertex Smoothing**
 - Move a vertex to the centroid of its neighbors
 - Convex or concave, but avoid negative-volume elements
- Vertex Addition



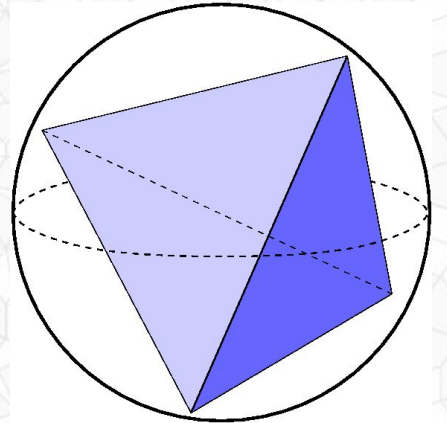
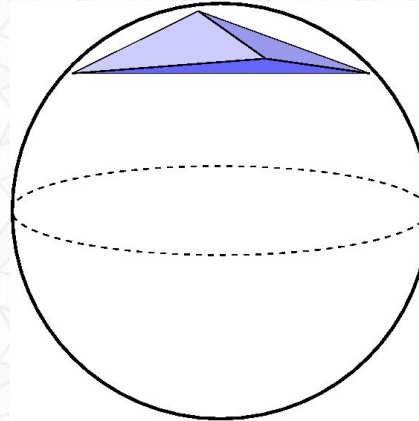
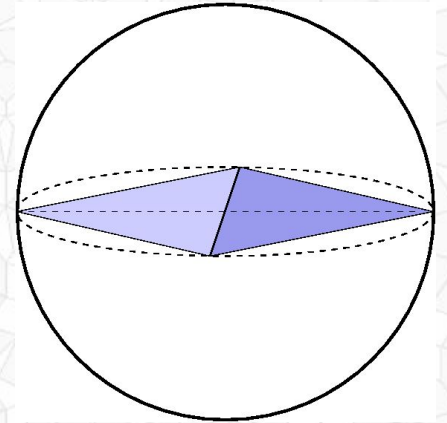
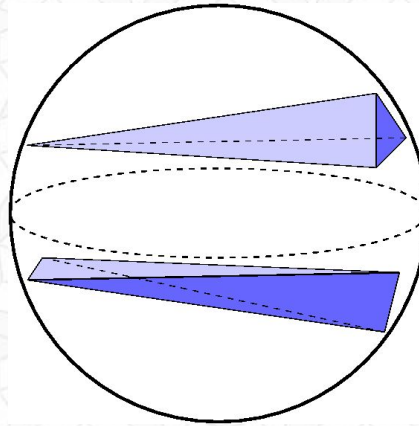
Before

After



3D Mesh Operations

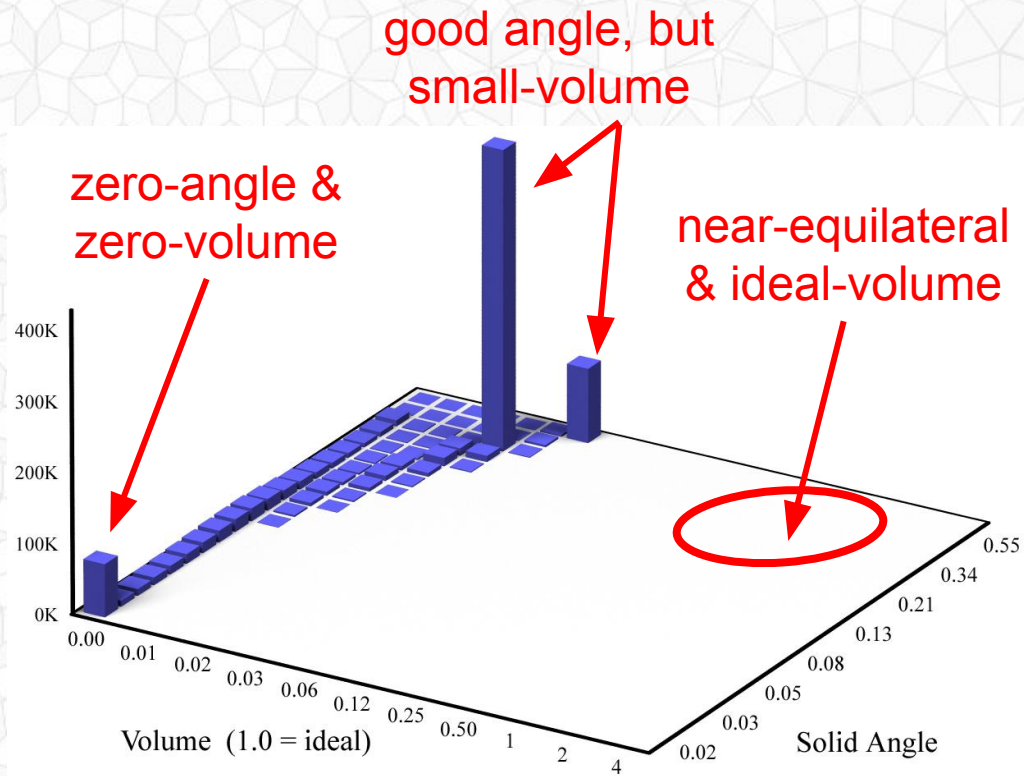
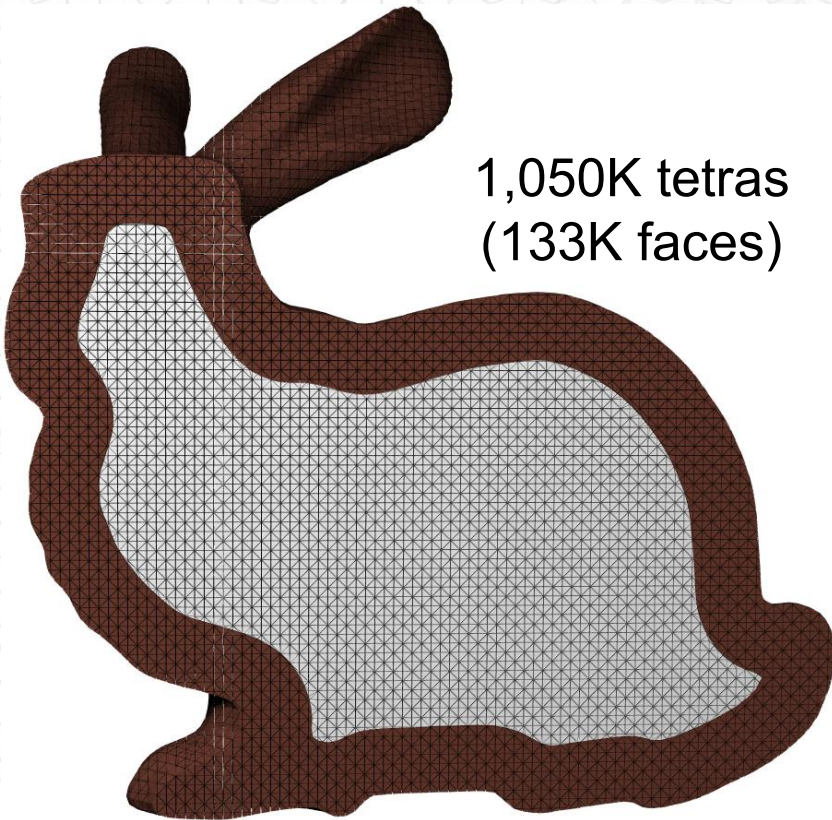
- Tetrahedral Swaps
- Edge Collapse
- Vertex Smoothing
- **Vertex Addition**
 - **At the center of a tetra, face, or edge**
 - **Useful when mesh is simplified, but needs further element shape improvement**



Visualization of Tetrahedra Quality

“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004

1,050K tetras
(133K faces)

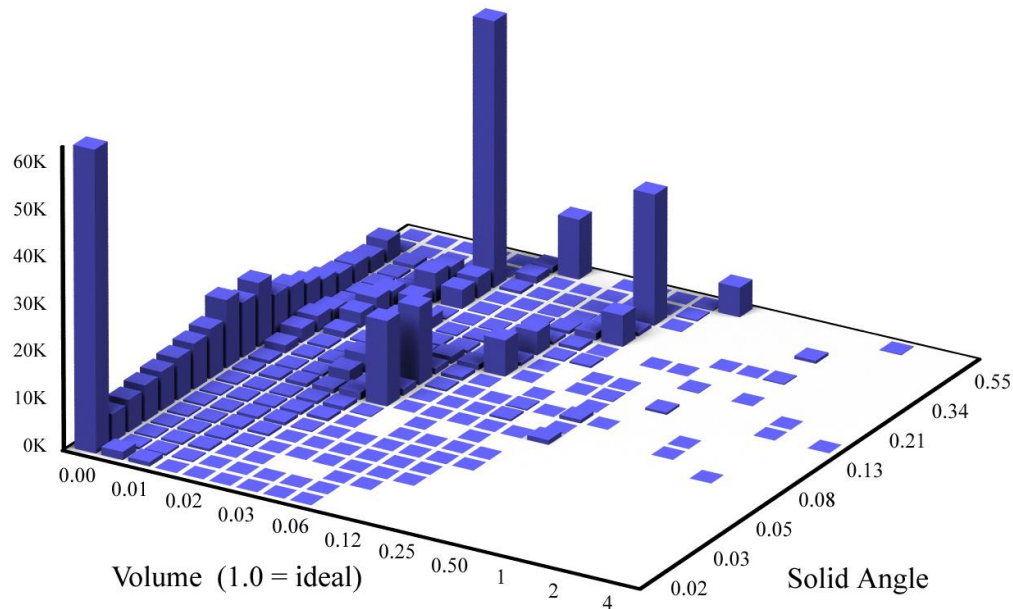


Visualization of Tetrahedra Quality

“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004

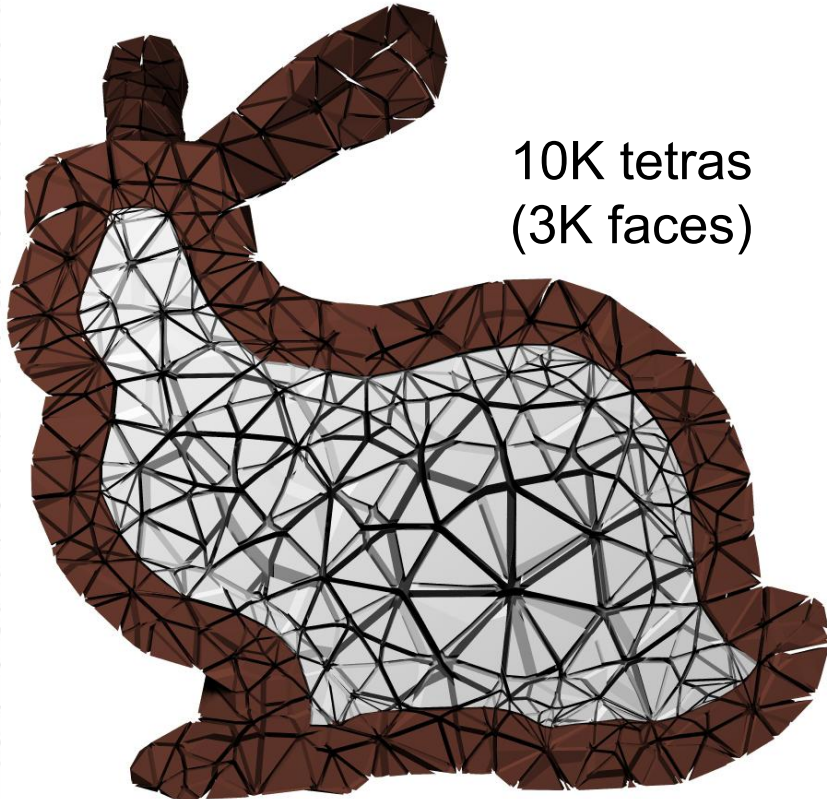
Octree or Adaptive
Distance Field (ADF)

461K tetras
(108K faces)

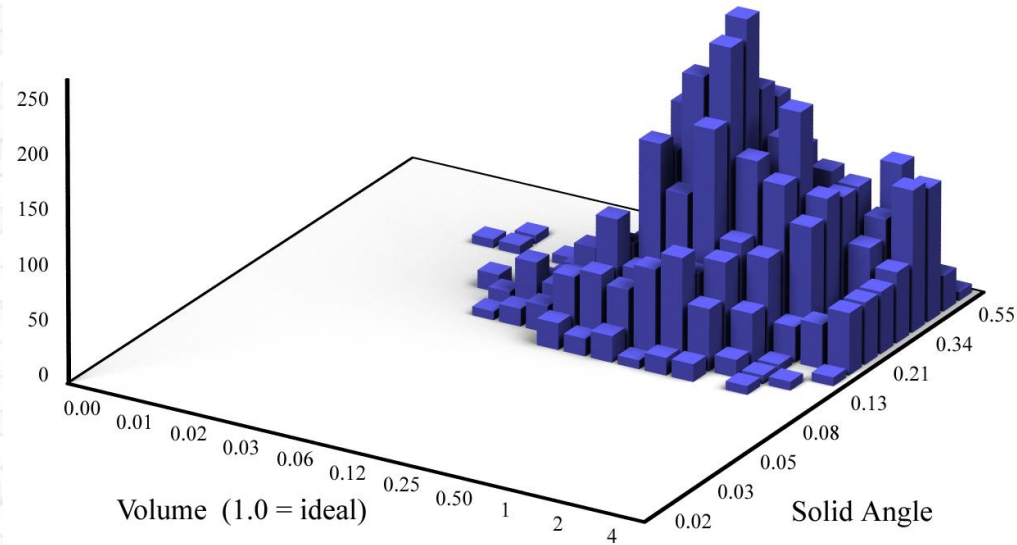


Visualization of Tetrahedra Quality

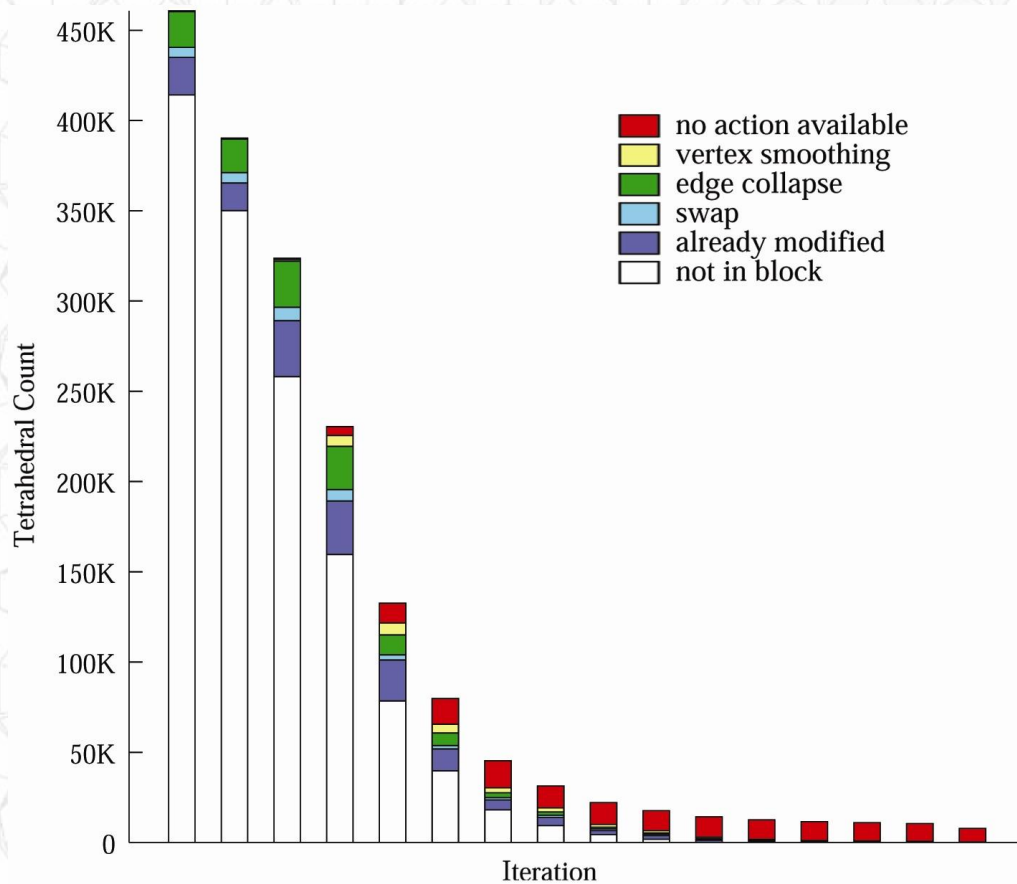
“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004



After Simplification
& Mesh Improvement



Visualization of Simplification Algorithm

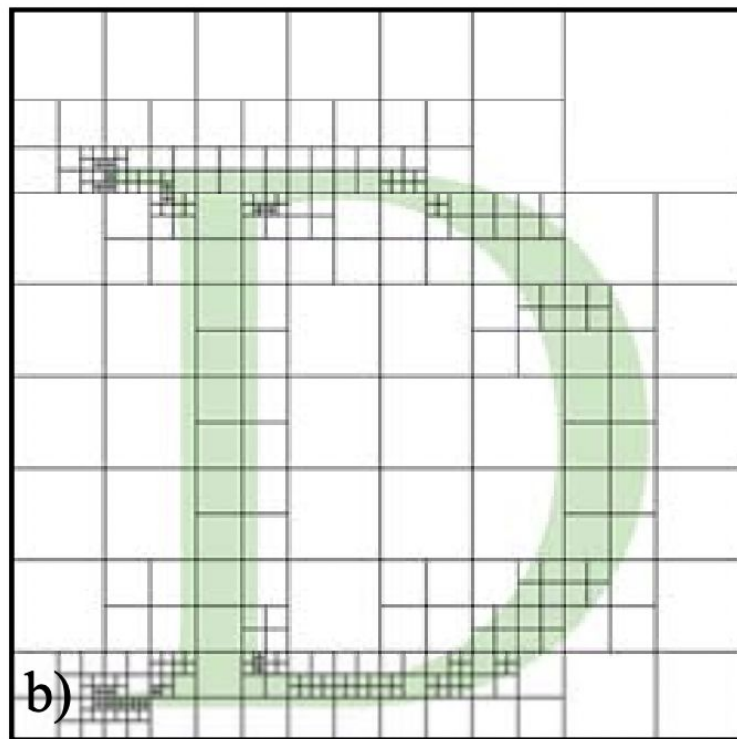
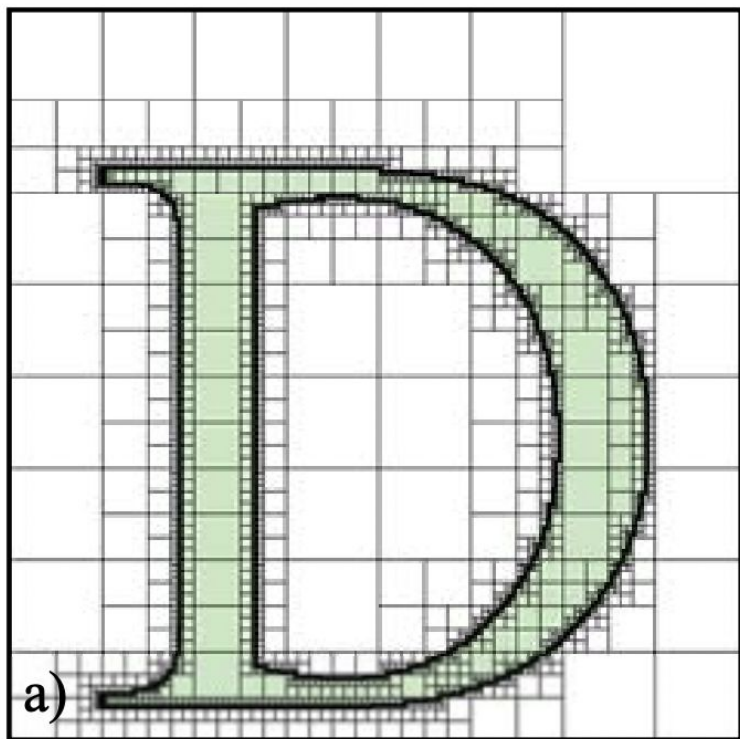


“Simplification and Improvement of
Tetrahedral Models for Simulation”
Cutler, Dorsey, and McMillan
SGP 2004

Outline for Today

- Homework 5 Questions?
- Last Time: Windowing, Interval Trees & Segments Trees
- Motivation: FEM & CFD Simulation
- Uniform & Non-Uniform Meshing
- k-D Tree vs Quad Tree
- Maximum Depth, Number of Nodes
- Implicit Adjacency, Balanced Quad Tree
- Advanced Topics: $\sqrt{3}$ Subdivision & Octree Textures
- Remeshing for Interactive Deformation
- **Next Time: Signed Distance Fields & Level Sets**

Next Time: Signed Distance Fields & Level Sets



“Adaptively Sampled Distance Fields: A General Representation of Shape for Computer Graphics”,
Friskén, Perry, Rockwood, and Jones, SIGGRAPH 2001
“Designing with Distance Fields”, Friskén and Perry, 2006