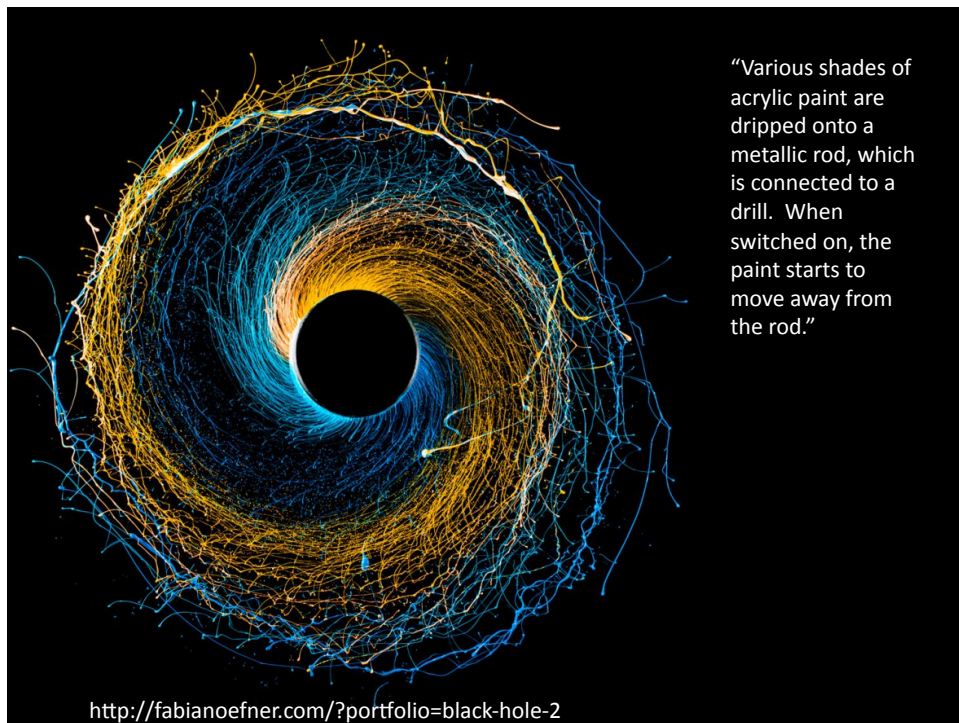
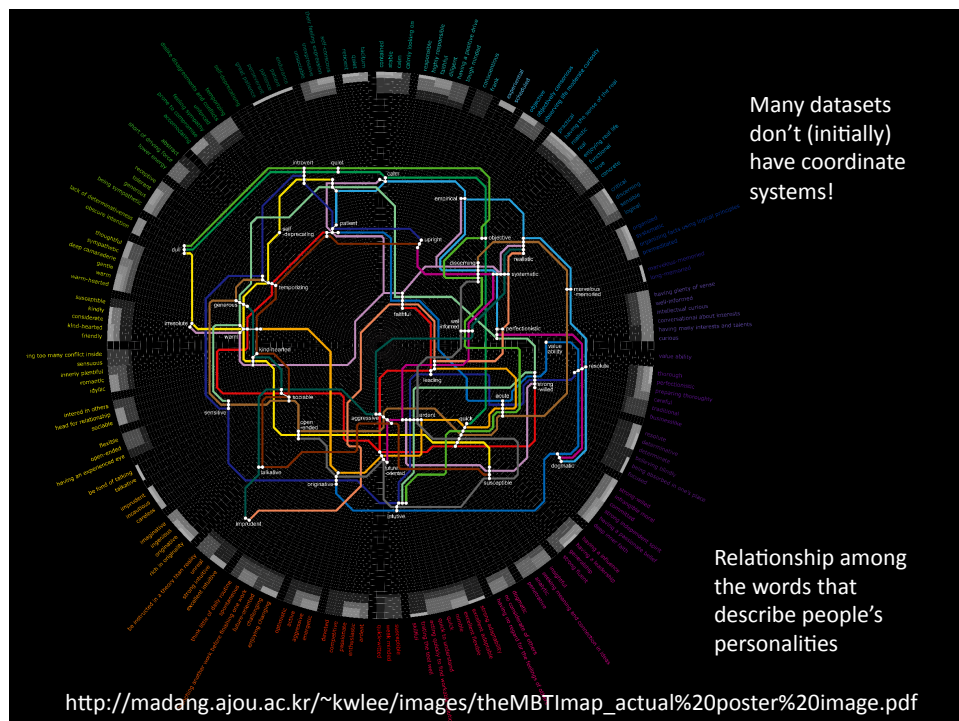
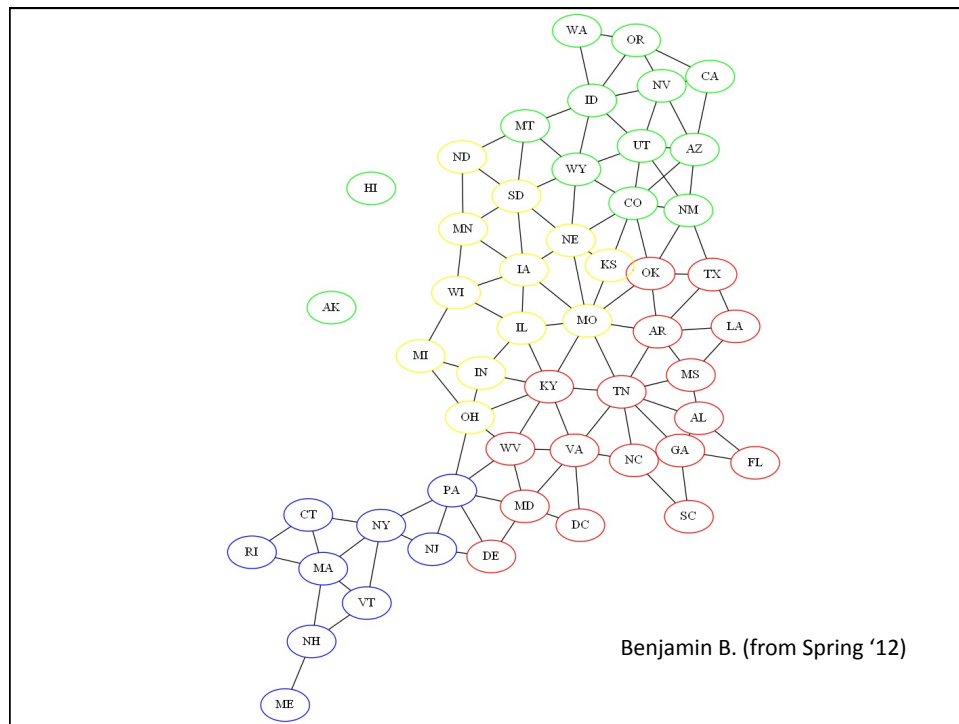
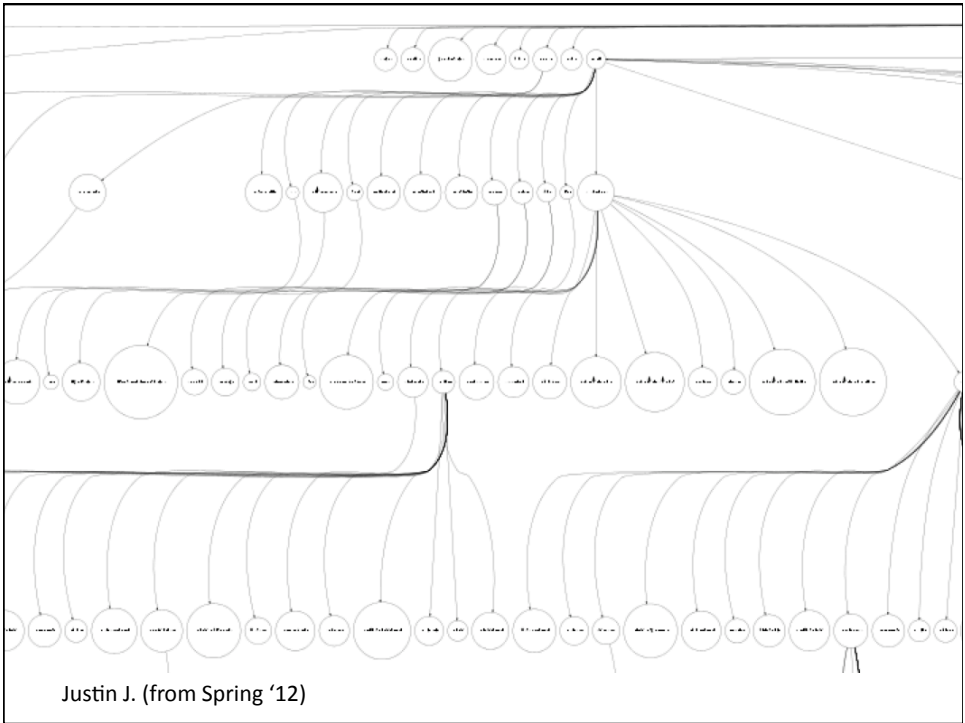
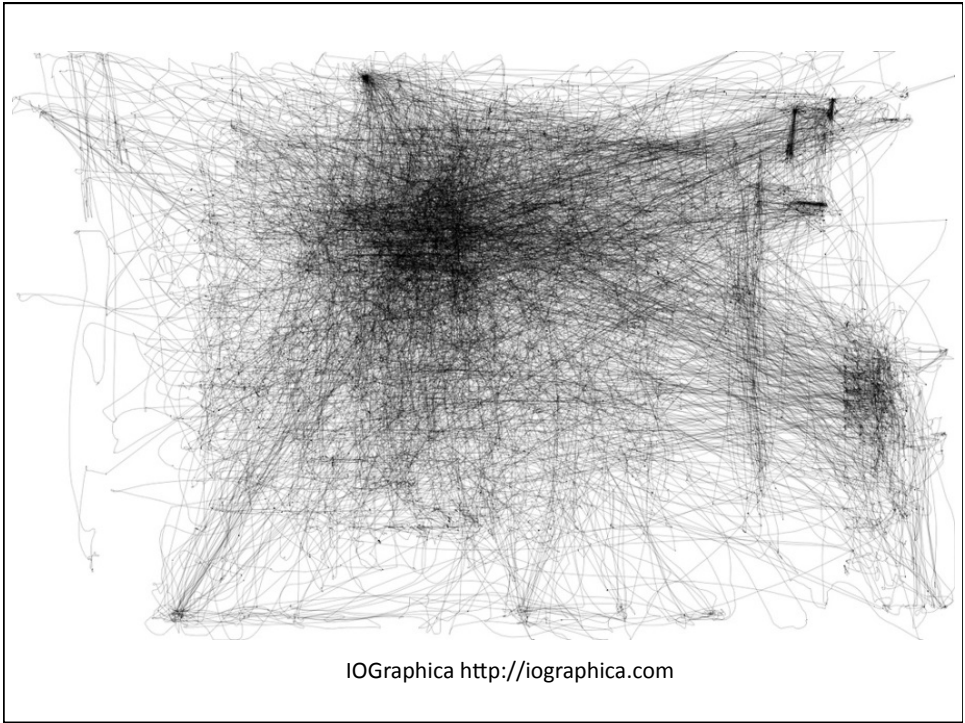
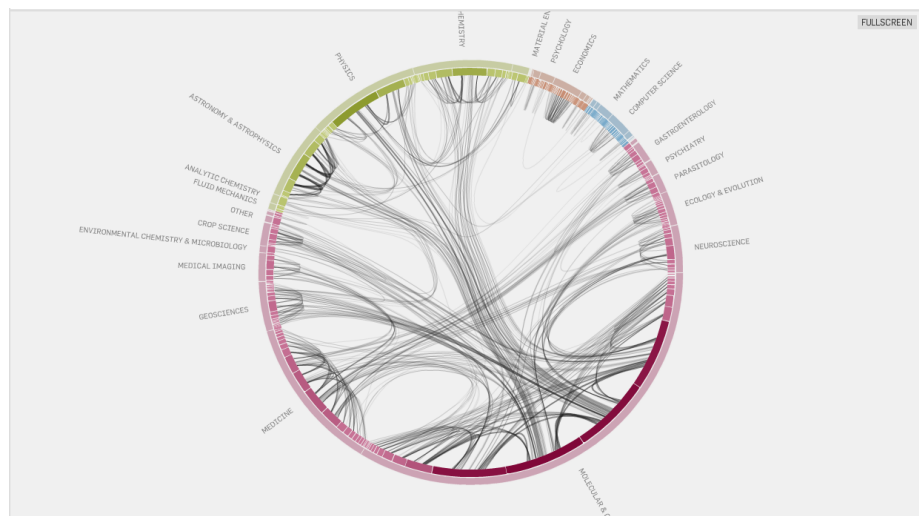


Graph Visualization I









Stefaner, Moritz. "Citation Patterns." *Wellformed Eigenfactor*. N.p., 2008. Web.

Today

- Questions about Homework 2?
- Some Graph Terminology
- Graph Drawing Goals, Questions, & Challenges
- Some Related Terms/Algorithms
(mentioned indirectly in the reading)
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Homework Assignment 2: due Thursday @ 11:59pm

Graph Visualization w/ GraphViz

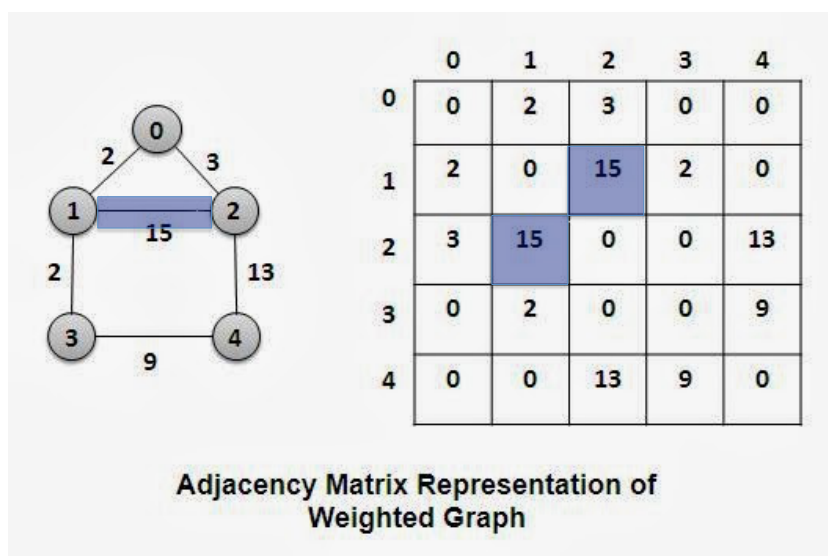
- Download GraphViz and explore the examples
- Using your favorite programming language, write code to create a range of synthetic input files
 - a tree, a clique, a planar graph, bipartite graph, etc.
 - medium size (a “good, ~optimal” layout *could* be done by hand)
- Experiment with the visual options (layout, color, line style, label font, shapes, etc.)
- Create a graph (or multiple) of our social network, using the data we gathered in Lecture 1.
- Analyze the quality of the results.
Note strengths & weaknesses of GraphViz.

- Please enter your data (if you haven't already)

Testing our Hypotheses

- What (if anything) surprised you about the data?

knew before RPI	share(d) dormroom or apartment	met in CSCI 1200 Data Structures	met at RPI	met today!	total
0	0	11	7	22	40
0	1	2	3	34	40
0	0	2	1	37	40
0	1	3	7	29	40
0	0	2	5	33	40
0	0	2	3	35	40
0	2	1	4	33	40
0	0	4	5	31	40
0	0	1	5	34	40
0	0	1	6	33	40
0	4	2	3	31	40
0	0	0	4	36	40
0	0	1	8	31	40
0	0	0	2	38	40
0	1	1	1	37	40
0	0	8	4	28	40
0	1	2	9	28	40
0	0	1	5	34	40
0	0	4	1	35	40
0	0	3	6	31	40
0	0	1	4	35	40
0	0	1	0	39	40
0	0	0	3	37	40
0	0	0	5	35	40
1	0	2	1	36	40
					0
0.04	0.4	2.2	4.08	33.28	



<http://www.thecrazyprogrammer.com/2014/03/representation-of-graphs-adjacency-matrix-and-adjacency-list.html>

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Graph Terminology I

- Directed / Undirected Edges
- Tree – no cycles
- Cycle – A path along edges through the graph starting & ending at the same vertex. Variants: closed walk, simple cycle, directed cycle, ...
- Valence (a.k.a. Degree) of a Vertex - # of edges incident on the vertex
- Regular – Each vertex has same valence, a 3-regular graph is also called cubic
- Polygon – 2D flat or on a sphere, with straight or great circle edges
Polyhedron – 3D solid formed by flat faces
Polytope – flat sides in any dimension
- Bipartite – vertices can be split into two groups, A & B. No edge connects a vertex in A to another vertex in A. Same for B.

Graph Terminology II

- Clique – subset of vertices in an undirected graph with an edge connecting every pair of vertices in the subset.
- Upward Drawing (of a tree) – no child is drawn with vertically above (higher y value than) its parent.
- Plane Graph – A 2D drawing of the graph where no edges cross (touching at the endpoint vertices they share is ok)
- Planar Graph – A graph for which a Plane Graph exists.
- Euler's Theorem for planar graphs. For a plane graph with n vertices, m edges and f faces, we have $n - m + f = 2$.

Graph Drawing Goals

- Automated!
- Can read all of the labels
- Can follow the line and see exactly which 2 vertices it connects
- Aesthetically pleasing
- Layout should display as much symmetry as possible
- Crossing free or minimal-crossing layout
- All edge lengths are approximately equal
- Even vertex distribution
- Distance between nodes in final layout should be as close as possible to “graph distance” (# of edges on shortest path between those nodes)

Graph Drawing Questions

- What is the metric of success for each of our goals?
- Can we guarantee to find a solution? The optimal or best solution?
- Can we use randomness? Does it help?
- How expensive/slow are the different algorithms to draw graphs?
- How does it scale with more nodes/edges?
 - Does it lose effectiveness in meeting our goals?
 - How is the running time affected?
- How do we label the nodes/edges with color/words/images?

Graph Drawing Challenges

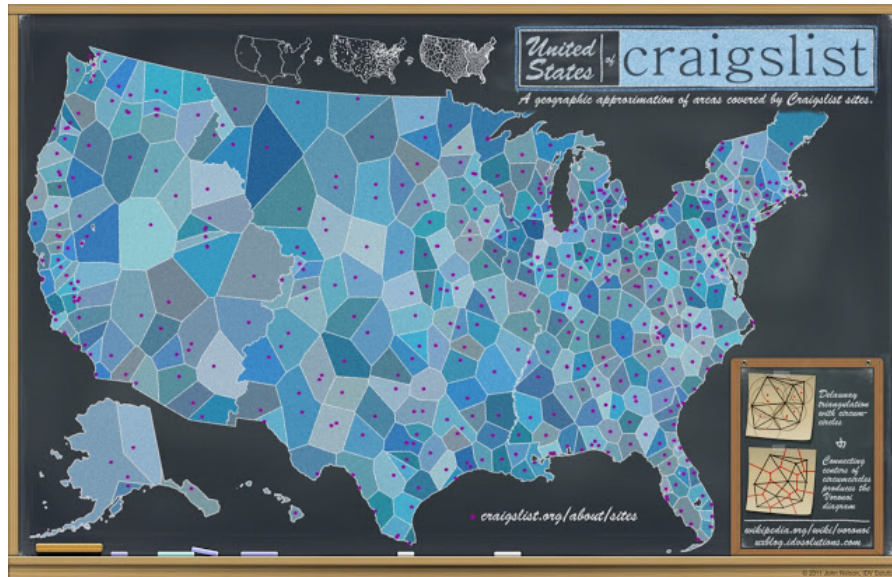
- What if the graph is non planar?
- What if the graph has many nodes & edges?
 - ~40-100 works well for simple force-based methods
 - # of springs = # of edges?
Or # of springs \gg # of edges?
 - Computation & convergence & getting stuck in a local minimum
- Does 3D (or 4D or ...) or layout on the surface of a sphere or torus or ... non Euclidean space help?

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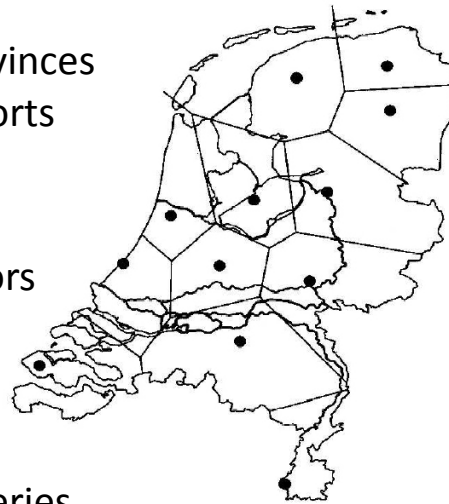
Voronoi Diagram

<http://uxblog.idvsolutions.com/2011/07/chalkboard-maps-united-states-of.html>



Voronoi Diagram/Cells/Regions

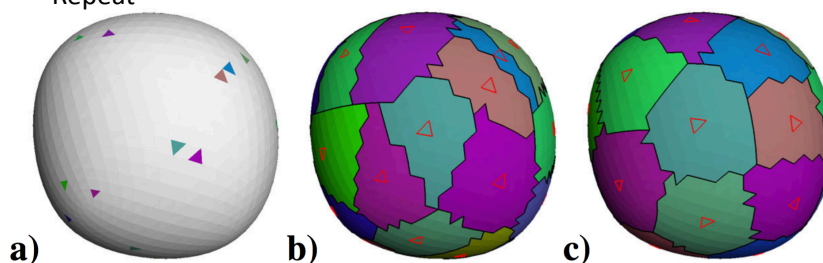
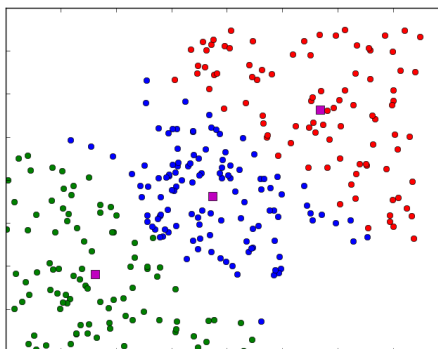
- How to re-district the Netherlands into provinces so that everyone reports to the closest capital
- Cell edges are the perpendicular bisectors of nearby points
- 2D or 3D
- Supports efficient *Nearest Neighbor* queries



<http://ccc.inaoep.mx/~rodrigo/robotica/Trigui.pdf>

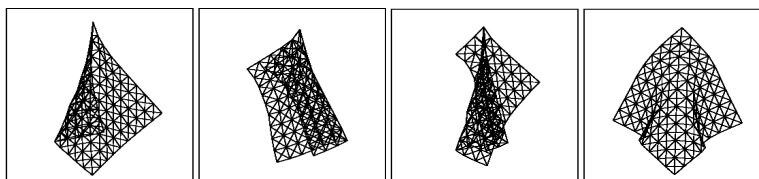
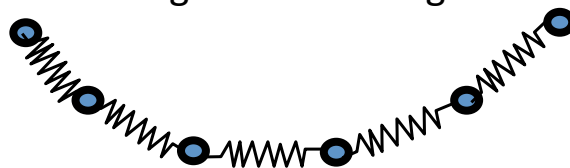
K-means clustering

- Choose K
- Select K items at random, these are your leaders for the first round
- While (not done)
 - Every item joins the group of their “closest” leader
 - Each group elects a new leader
 - Repeat



String/Hair/Cloth Simulation

- Springs link the particles
- Springs try to keep their rest lengths and preserve the length of the string



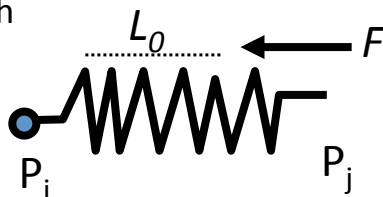
Interactive Animation of Structured Deformable Objects Desbrun, Schröder, & Barr 1999

Spring Forces

- Force in the direction of the spring and proportional to difference with rest length L_0

$$F(P_i, P_j) = K(L_0 - \|\vec{P_i P_j}\|) \frac{\vec{P_i P_j}}{\|\vec{P_i P_j}\|}$$

- K is the stiffness of the spring
 - When K gets bigger, the spring really wants to keep its rest length



Using Springs for Graph Drawing

- Value for Spring Rest Length?
 - Rest length = 0, spring only attracts (doesn't repel)
 - Alternately, forces could act in
 - Both attract & repel (have non zero edge length?)
 - Only repel?
- What is the correct spring constant?
 - Too high/stiff -> system explodes (does not converge)
 - Too low -> takes too long to converge

exerting attractive and repulsive forces from one another.” The attractive and repulsive forces are redefined to

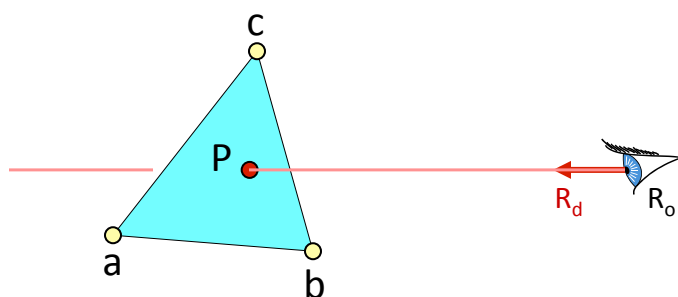
$$f_a(d) = d^2/k, \quad f_r(d) = -k^2/d,$$

in terms of the distance d between two vertices and the optimal distance between vertices k defined as

$$k = C \sqrt{\frac{\text{area}}{\text{number of vertices}}}.$$

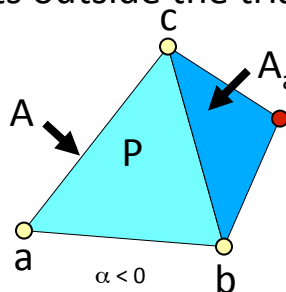
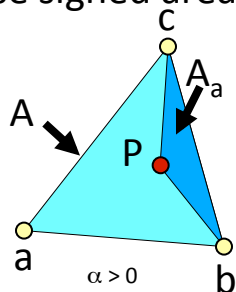
Barycentric Coordinates

- $P(\alpha, \beta, \gamma) = \alpha a + \beta b + \gamma c$
with $\alpha + \beta + \gamma = 1$
- If $0 < \alpha < 1$ & $0 < \beta < 1$ & $0 < \gamma < 1$
then the point is inside the triangle!



How Do We Compute α, β, γ ?

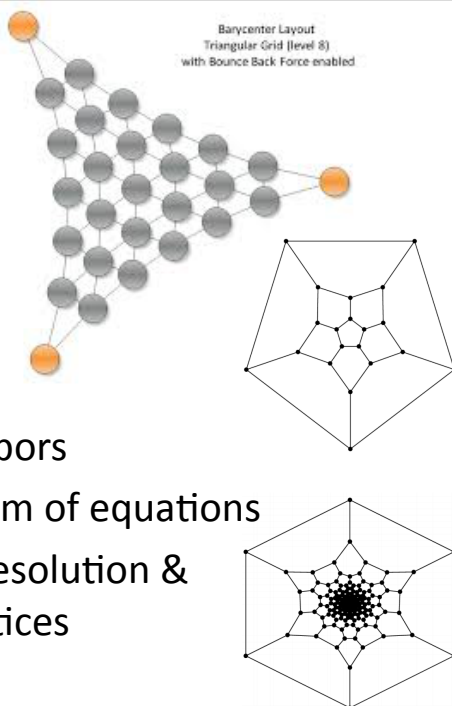
- Ratio of opposite sub-triangle area to total area
– $\alpha = A_a/A$ $\beta = A_b/A$ $\gamma = A_c/A$
- Use signed areas for points outside the triangle



*But how do I know if the point is outside the triangle?
That's what I was trying to determine!*

Barycentric Graph Layout

- Planar graphs (only?)
- Start with some fixed positions
- Each vertex is placed at the average of its neighbors
- Can be solved as a system of equations
- Results can have poor resolution & poor distribution of vertices



Non Euclidean

- Hyperbolic layout has better equal distance layout for leaves of a “complete tree”
- Related to
 - Fisheye view
 - Focus + context
 - assumption that center is more important



Daina Taimina

<http://www.math.cornell.edu/~dtaimina/Artexhibits.htm>

Simulated Annealing

- “Temperature” changes (constants within the algorithm change) as # of iterations of algorithm increase.

Genetic Algorithms

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Reading for Today

- “Force Directed Graph Drawing” chapter by Steven Kobourov from the book *Handbook of Graph Drawing and Visualization 2013*

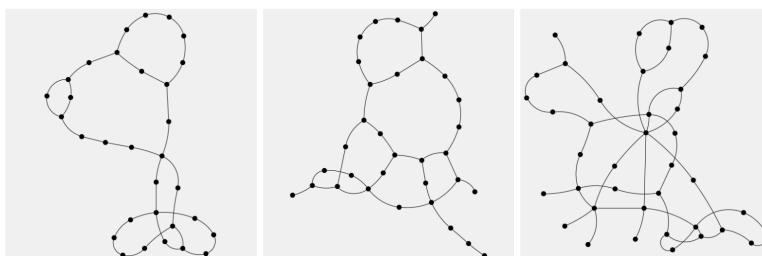


Figure 12.11 Examples of force-directed Lombardi drawings: note that every edge is a circular arc and every vertex has perfect angular resolution [CCG⁺11].

Your Comments

- Inspired by nature
 - RNA folding, molecular bonds
- Would be interesting to watch evolution of solution, incremental construction
- What about directed?
- Genetic algorithms too slow for graph drawing?
- Now understand why graph drawing algorithms crash when given 10,000 nodes
- Handle big graphs like divide & conquer for sorting
- Edge curvature can be detrimental
- Would like to see same graph, drawn by each different algorithm, and timing numbers for comparison
- Interesting to see inter-relations between publications, and which publications were most referenced

Force Directed Graph Drawing

- No domain-specific knowledge required
- Basic algorithm works well for ~100(s) nodes
 - Not good at larger, local minima, unreadably dense
- Use non linear forces (e.g., log), even distribution of vertices, temperature adjustments (simulated annealing)
- Keep vertices away from non-incident edges
 - How is this done? Extra vertices (w/ repulsion springs) in the middle of edges?

Other Graph Drawing Variants

- Optimize a planar layout (no crossings)
- Improve a layout with intentional, meaningful crossings
- Non-Euclidean spaces (allow uniform distribution vertices, not biased towards nodes in center of drawing)
 - How do this work with interactive visualization?
Would help for understanding of these non-Euclidean spaces.
- Multi-level layout technique
 - a.k.a. Hierarchical / Level of Detail

Dynamic Graphs

- Present relationships as they evolve over time
- Stack of graphs, slices of time, relationships in space & time
- Applications
 - Extracting information from a CVS version control system, what parts of the code are unstable over periods of time?
 - Inheritance graphs, program call stacks, control-flow graphs
- Goals:
 - Readability
 - Maintain mental model, consistency of placement of nodes over time
- Types
 - Aggregated views – multiple graphs displayed at once, in series?
 - Merged views – stacked on top of each other
 - Animations – one graph shown after the other
 - Morphing – fade in, fade out
- Animated vs Interactive?
 - User gets to move nodes around, expand, zoom in, focus, highlight nodes with certain properties

Writing quality/improvements

- Paper could have more illustrations *****
 - Problem of exponential area of barycentric method
 - Methods that prevent separation into clusters, or put high degree vertices at center
 - Is pseudocode effective/sufficient as an explanation?
 - Difficult to understand these algorithms without being able to form a mental model of how they work **
- Good overview, sufficient detail that could be implemented by person with a computer graphics background
 - but difficult to follow for students w/o ACG :(
- Want/need more details!
- Hard to keep track of papers (better to use technique/title than author name)
 - Chapter was somewhat disorganized
 - Order of papers was not always chronological
- Want more discussion, side-by-side comparison/contrast/pros-and-cons of the different algorithms
- Who is the audience for this chapter?
 - Chapter in book for new-to-field students –or– survey paper for experts in the field? Is there a difference?
- How do you choose which algorithm to use for specific data? No clear instructions
 - Show same (specially constructed to show differences) example graph stuffed into each algorithm
- Reads like a history book, would be nice to have more discussion of where these algorithms are used, which algorithms are more appropriate for what situations, etc.

Algorithms with arbitrary constants

- When reading an algorithm...

```

algorithm SPRING( $G$ :graph);
place vertices of  $G$  in random locations;
repeat  $M$  times
    calculate the force on each vertex;
    move the vertex  $c_4 * (\text{force on vertex})$ 
draw graph on CRT or plotter.
  
```

The values $c_1 = 2$, $c_2 = 1$, $c_3 = 1$, $c_4 = 0.1$, are appropriate for most graphs. Almost all graphs achieve a minimal energy state after the simulation step is run 100 times, that is, $M = 100$.

Using Non-Straight Edges

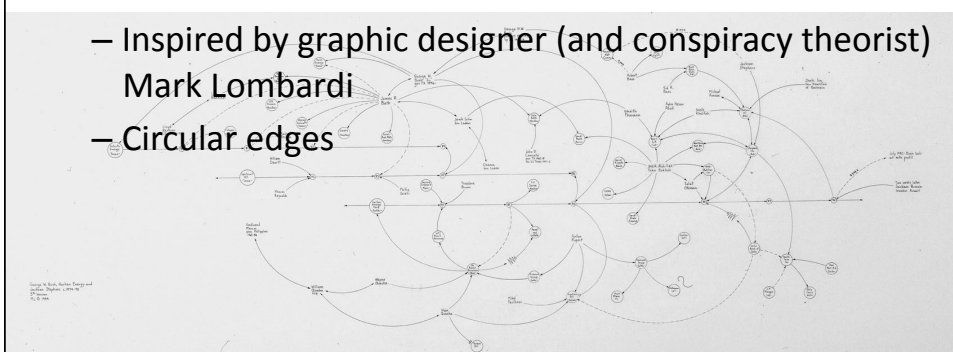
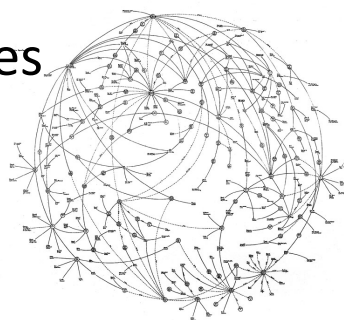
- Increase/maximize angular resolution at vertices

- Can use Bezier Curves

- Lombardi or “near-Lombardi”

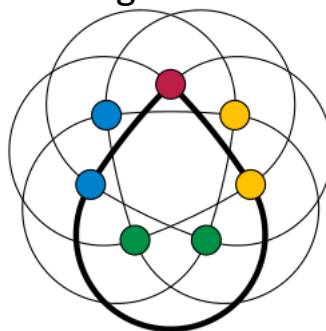
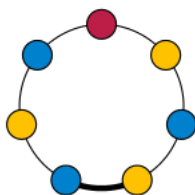
- Inspired by graphic designer (and conspiracy theorist) Mark Lombardi

- Circular edges



Effectiveness of Curved Edges

- What are the advantages of straight vs curved edges for the graph on the right?

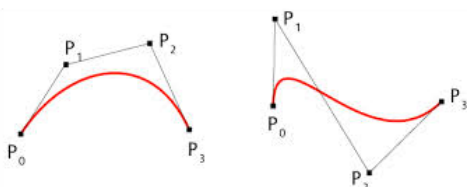


A seven-vertex cycle and its complement, showing in each case an optimal coloring and a maximum clique (shown with heavy edges). Since neither graph uses a number of colors equal to its clique size, neither is a “Perfect Graph”.

https://en.wikipedia.org/wiki/Perfect_graph#/media/File:7-hole_and_antihole.svg

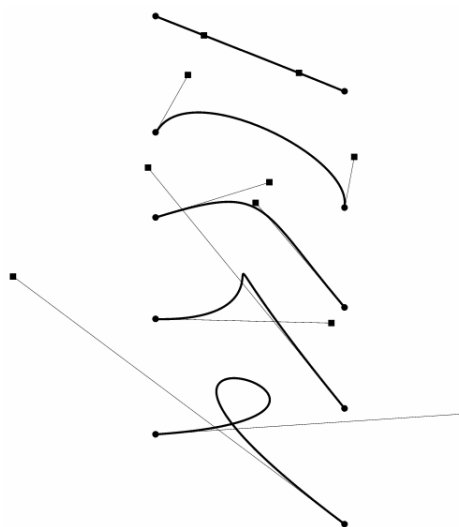
Cubic Bézier Curve

- 4 control points
- Curve passes through first & last control point
- Curve is tangent at P_0 to $(P_1 - P_0)$ and at P_3 to $(P_3 - P_2)$



http://www.e-cartouche.ch/content_reg/cartouche/graphics/en/html/Curves_learningObject2.html

<http://www.webreference.com/dlab/9902/bezier.html>

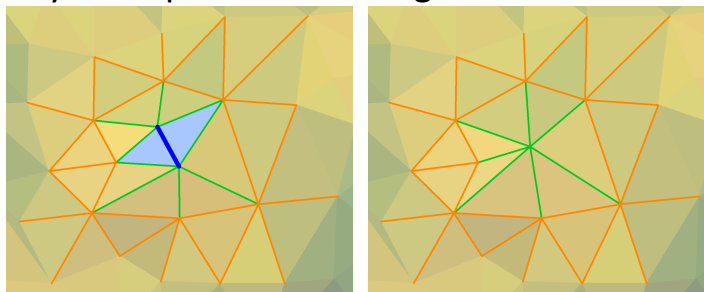


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Edge Contraction / Edge Collapse

- Goal: Reduce number of vertices/edges while minimize shape/color/attribute loss
- Possible algorithm for 3D meshes:
Always collapse shortest edge



- But what to do for data without obvious spatial coordinate system?

Reading for Friday

*Post a comment/question
on LMS by Tuesday @10am*

- “Social Network Clustering and Visualization using Hierarchical Edge Bundles”, Jia, Garland, & Hart, Computer Graphics Forum, 2011.

