

Knowledge Representation

Ref: Chapter 10

Knowledge Representation

What

Physical Objects

Actions

Time

Beliefs

How

individuals

classes

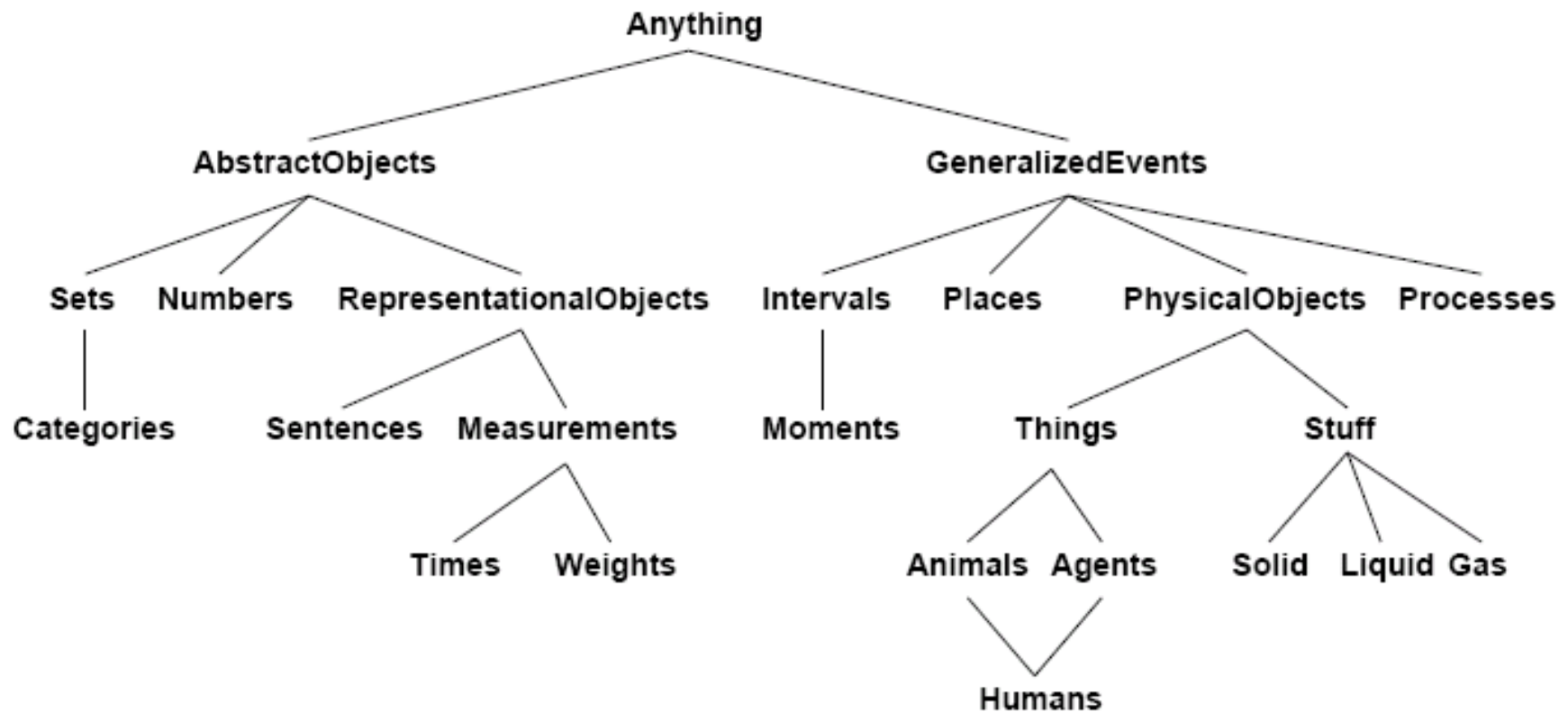
attributes

relations

Ontologies

- Organization of the *world* into hierarchy of categories.
 - a formal, consistent vocabulary.
- Not hard in toy domains
 - Wumpus World: room, wumpus, gold, pit, movement, etc.
- Upper Ontology: broad, general, framework of concepts.
 - Dublin Core, GFO, and others.

An Upper Ontology



Ontological Engineering

- Finding a representation of *a world* so that an agent can:
 - keep track of facts and rules.
 - map sensors to facts and rules.
 - reason (make decisions).
 - reason about reasoning?

Universal Ontology?

- Is there a general ontology on which we can base any special purpose ontology?
 - probably (philosophers have studied this question for centuries).
- The idea is to use a general ontology as a starting point.
 - map domain specific concepts onto the general ontology
 - resolve overlaps/conflicts

Categories and Objects

- KR requires the organization of objects into categories
 - Interaction with the world involves objects.
 - Reasoning involves categories.
- Ex: poker agent uses sensory info to categorize an opponent as "conservative".
 - strategies for playing are governed by the category(s) of opponent.

Categories and Objects

- Categories can be represented in two ways by FOL
 - Predicates: `ConservativePlayer(x)`
 - *Reify* the category as an object:

`Member(x, ConservativePlayer)`

`Subset(ConservativePlayer, BeatablePlayer)`

Organization of Categories

- Categories are related by Inheritance
 - simplifies development and representation of rules and attributes.
 - General rules/attributes apply to broad categories
 - rules/attributes are inherited by subcategories
 - exceptions can easily be expressed as overriding rules/attributes for subcategory.
- Types of relations:
 - subclass/subset , membership, disjoint relations, compositions, etc.

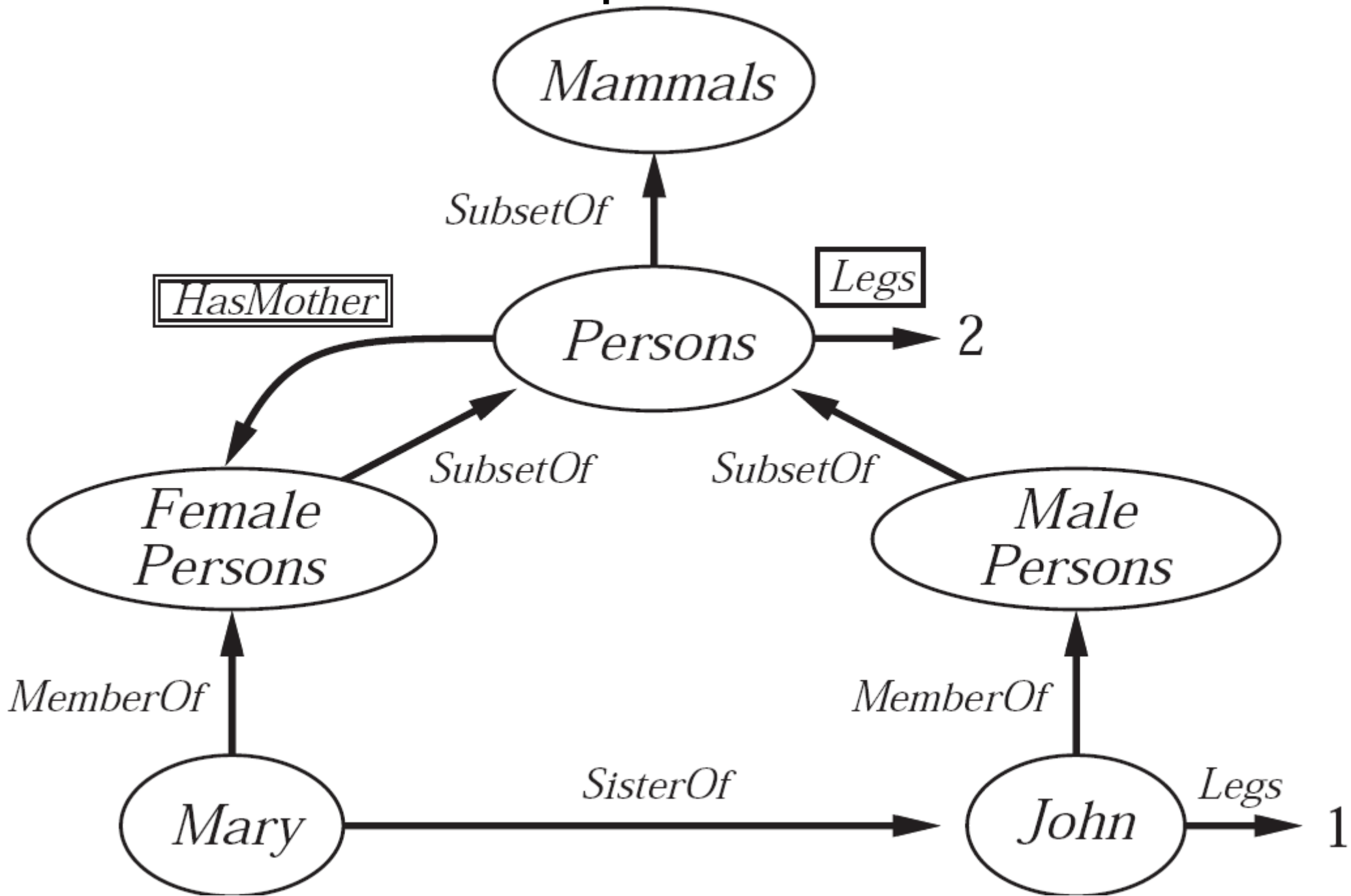
Reasoning System for Categories

- How to organize and reason with categories?
 - Semantic networks
 - Visualize knowledge-base
 - Efficient algorithms for category membership inference
 - Description logics
 - Formal language for constructing and combining category definitions
 - Efficient algorithms to decide subset and superset relationships between categories.

Semantic Networks

- Many variations
 - All represent individual objects, categories of objects and relationships among objects.
- Allows for inheritance reasoning
 - Female persons inherit all properties from person.
- Inference of inverse links
 - SisterOf vs. HasSister

Inheritance Graph/Semantic Network



FOL and Categories

- An object is a member of a category

`MemberOf (BB12 , Basketballs)`

- A category is a subclass of another category

`SubsetOf (Basketballs , Balls)`

- All members of a category have some properties

$\forall x \text{ (MemberOf (} x \text{ , Basketballs) } \Rightarrow \text{ Round (} x \text{))}$

Logic and Categories (cont.)

- All members of a category can be recognized by some properties

$$\begin{aligned} &\forall x (\text{Orange}(x) \wedge \\ &\quad \text{Round}(x) \wedge \\ &\quad \text{Diameter}(x) = 9.5 \text{in} \wedge \\ &\quad \text{MemberOf}(x, \text{Balls}) \Rightarrow \\ &\quad \text{MemberOf}(x, \text{BasketBalls})) \end{aligned}$$

- A category as a whole has some properties

$$\text{MemberOf}(\text{Dogs}, \text{DomesticatedSpecies})$$

Category Relations

Two or more categories are ***disjoint*** if they have no members in common:

Disjoint(s) \Leftrightarrow

$(\forall c_1, c_2 (c_1 \in s) \wedge (c_2 \in s) \wedge (c_1 \neq c_2) \Rightarrow$

Intersection(c_1, c_2) = $\{\}$)

Example: Disjoint({animals, vegetables})

Category Relations (cont.)

A set of categories s constitutes an ***exhaustive decomposition*** of a category c if all members of c are covered by categories in s :

$$\text{E.D.}(s,c) \Leftrightarrow (\forall i \ i \in c \Rightarrow \exists c_2 \ c_2 \in s \wedge i \in c_2)$$

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ExhaustiveDecomposition({Americans,  
Canadian, Mexicans},NorthAmericans)
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Category Relations (cont.)

A **partition** is a disjoint exhaustive decomposition:

$$\text{Partition}(s, c) \Leftrightarrow \text{Disjoint}(s) \wedge \text{E.D.}(s, c)$$

$\text{Partition}(\{\text{Males}, \text{Females}\}, \text{Persons})$.

Is $(\{\text{Americans}, \text{Canadian}, \text{Mexicans}\}, \text{NorthAmericans})$
a partition?

no – some people have dual citizenship

Category Relations (cont.)

Categories can be defined by providing necessary and sufficient conditions for membership

$$\forall x \text{ Bachelor}(x) \Leftrightarrow \text{Male}(x) \wedge \text{Adult}(x) \wedge \text{Unmarried}(x)$$

Physical Composition

One object is a part of another object.

PartOf (Bucharest, Romania)

PartOf (Romania, EasternEurope)

PartOf (EasternEurope, Europe)

PartOf is transitive and reflective:

$$\forall x, y, z \text{ PartOf}(x, y) \wedge \text{PartOf}(y, z) \Rightarrow \text{PartOf}(x, z)$$
$$\forall x \text{ PartOf}(x, x)$$

We can infer PartOf (Bucharest, Europe)

Physical Composition (cont.)

Often characterized by structural relations among parts.

Example: $Biped(a) \Rightarrow$

$$\begin{aligned} & (\exists l_1, l_2, b)(Leg(l_1) \wedge Leg(l_2) \wedge Body(b) \wedge \\ & PartOf(l_1, a) \wedge PartOf(l_2, a) \wedge PartOf(b, a) \wedge \\ & Attached(l_1, b) \wedge Attached(l_2, b) \wedge \\ & l_1 \neq l_2 \wedge (\forall l_3)(Leg(l_3) \Rightarrow (l_3 = l_1 \vee l_3 = l_2))) \end{aligned}$$

Measurements

- Objects have height, mass, cost,
 - Values that we assign to these are **measures**
- Combine Unit functions with a number:

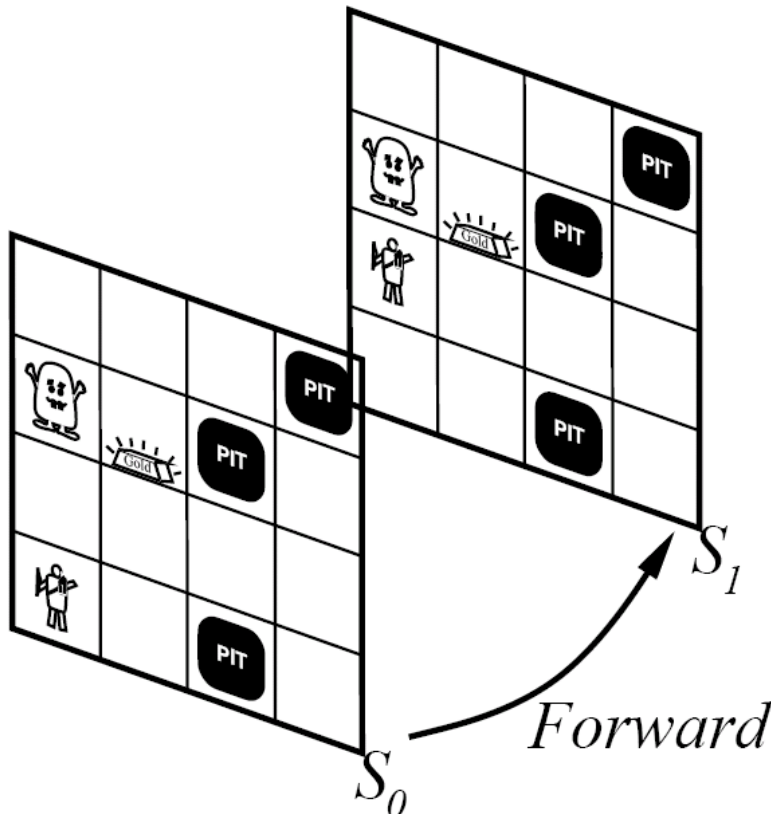
$$\text{Length}(L_1) = \text{Inches}(1.5) = \text{Centimeters}(3.81)$$

- Conversion between units:

$$\forall i \text{ Centimeters}(2.54 \times i) = \text{Inches}(i)$$

- Some measures have no scale: Beauty, Difficulty, etc.
 - Most important aspect of measures: that they are orderable.

Actions and Situations

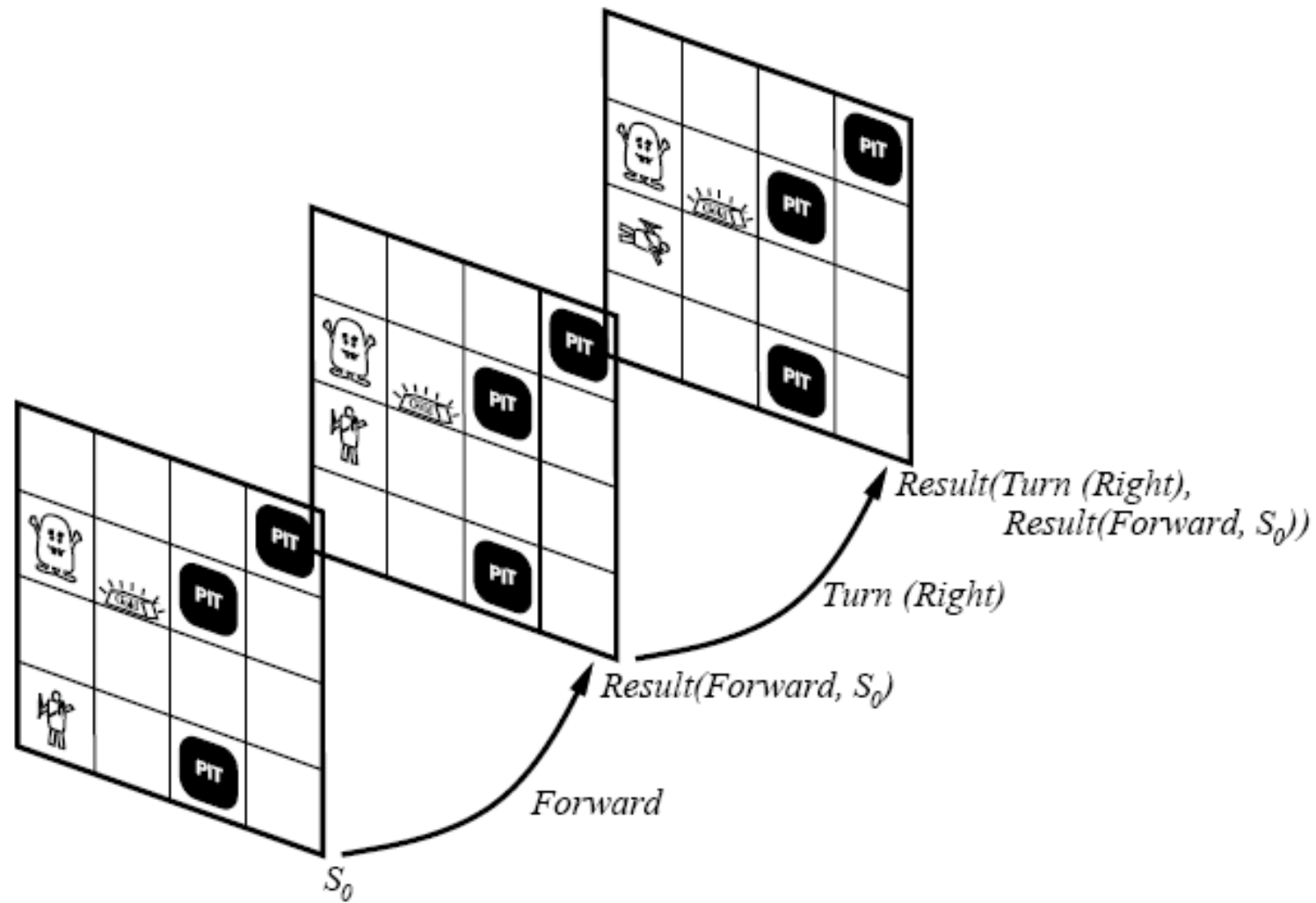


- Reasoning about actions is why we need a KB!
- We need rules that deal with time (for example, the next time step).
- In FOL, it is actually simpler to deal with *situations*
 - states that result from actions

Situation Calculus

- Ontology:
 - situations: logical terms including an initial situation S_0 and all situations that can be generated by applying an action to a situation.
 - $Result(a,s)$ is the situation resulting from action a in situation s
 - $Result(a,s)$ is a function.

Wumpus Situations



Fluents

- A *fluent* is a function or predicate that varies from one situation to the next.
 - Wumpus World Examples:
 - Location
 - $\neg \text{Holding}(G_1, S_0)$
 - *gold G_1 is not held in the initial situation*

Atemporal/ Eternal

- Predicates/functions that always hold (regardless of the situation).
- Many facts are atemporal.
- Wumpus Examples:

Gold(G_1)

LeftLegOf(Wumpus)

Situation Calculus Tasks

- *Projection task*: an Situation Calculus agent should be able to deduce the outcome of a sequence of actions.
- *Planning task*: find a sequence that achieves a desirable effect.

Describing Change

- Situation calculus requires two axioms to describe change:
 - Possibility axiom: when is it possible to do the action

$$At(Agent, x, s) \wedge Adjacent(x, y) \Rightarrow Poss(Go(x, y), s)$$

- Effect axiom: describe changes due to action

$$Poss(Go(x, y), s) \Rightarrow At(Agent, y, Result(Go(x, y), s))$$

Describing what doesn't change

- This is called the *frame problem*
- Typically most things don't change when an action takes place.
 - need a way to explicitly represent which things don't change.
- Frame Axioms:
 - describe non-changes due to actions
 - Example: what moves with the wumpus:
$$At(o, x, s) \wedge (o \neq Agent) \wedge \neg Holding(o, s) \Rightarrow At(o, x, Result(Go(y, z), s))$$

Representation Frame Problem

- If there are F fluents and A actions then we need AF frame axioms to describe objects that are stationary unless they are held.
 - We write down the effect of each actions
- Solution; describe how each fluent changes over time
 - Successor-state axiom:

$$Pos(a, s) \Rightarrow$$

$$(At(Agent, y, Result(a, s)) \Leftrightarrow$$

$$(a = Go(x, y)) \vee (At(Agent, y, s) \wedge a \neq Go(y, z))$$

- Note that next state is completely specified by current state.
- Each action effect is mentioned only once.

Other Problems

- How to deal with secondary (implicit) effects?
 - If the agent is carrying the gold and the agent moves then the gold moves too.
 - Ramification problem
- How to decide EFFICIENTLY whether fluents hold in the future?
 - Inferential frame problem.
- Extensions:
 - Event calculus (when actions have a duration)
 - Process categories

Mental Events and Objects

- So far, KB agents can have beliefs and deduce new beliefs
- What about knowledge about beliefs? What about knowledge about the inference process?
 - Requires a model of the mental objects in someone's head and the processes that manipulate these objects.
- Relationships between agents and mental objects: believes, knows, wants, ...
 - Believes(Lois,Flies(Superman)) with Flies(Superman) being a function ... a candidate for a mental object (reification).
 - Agent can now reason about the beliefs of agents.

Internet Shopping Agent

- A Knowledge Engineering example
- An agent that helps a buyer to find product offers on the WWW.
 - IN = product description (precise or not)
 - OUT = list of webpages that offer the product for sale.
- Environment = WWW
- Percepts = web pages (character strings)
 - Extracting useful information required.

Shopping Agent

- Find relevant product offers

$RelevantOffer(page, url, query) \Leftrightarrow$

$Relevant(page, url, query) \wedge Offer(page)$

- Write axioms to define Offer(x)
- Find relevant pages: Relevant(x,y,z) ?
 - Start from an initial set of stores.
 - What is a relevant category?
 - What are relevant connected pages?
- Compare offers (information extraction)
- See the text for more details...