



Simple Type Inference



Announcements

- Quiz 5
- No class on April 8th
- I have graded HW4
- HW6 is a team homework
- I will work on paper list, guidelines and presentation schedule over weekend



So far

- Introduction to types and type systems
- Simply typed lambda calculus (System F_1)
 - Language syntax, type expression syntax
 - Static semantics
 - Dynamic semantics
 - Type soundness: Safety = Progress + Preservation
 - Proved for the simply typed lambda calculus



Outline

- Simple type inference
 - Equality constraints
 - Unification
 - Substitution
 - Strategy 1: Constraint-based typing
 - Strategy 2: On-the-fly typing: Algorithm W, almost
- Parametric polymorphism (next time...)
- Hindley Milner type inference. Algorithm W



Reading

- “Types and Programming Languages”, by Benjamin Pierce, Chapter 22, 23
- Lecture notes based partially on MIT 2015 Program Analysis OCW

Core Typing Rules

$$\frac{}{\Gamma \vdash c : \text{int}}$$

[x: int, y: int → int]

Type expressions:
 $\tau ::= \text{int} \mid \tau \rightarrow \tau$

$$\frac{x:\tau \in \Gamma}{\Gamma \vdash x : \tau}$$

(Var)

$$\frac{\Gamma \vdash x : \tau}{\Gamma, x:\sigma \vdash E_1 : \tau}$$

Γ ⊢ x:σ

Environment:
 $\Gamma ::= \text{Nil} \mid \Gamma, x:\tau$

$$\frac{\Gamma \vdash x : \tau}{\Gamma \vdash (\lambda x:\sigma. E_1) : \sigma \rightarrow \tau}$$

(Abs)

$$\frac{\Gamma \vdash E_1 : \sigma \rightarrow \tau \quad \Gamma \vdash E_2 : \sigma}{\Gamma \vdash (E_1 E_2) : \tau}$$

(App)

$$\Gamma \vdash (E_1 E_2) : \tau$$

Extensions to Core Typing Rules

$$\Gamma \vdash c : \text{int}$$
$$\Gamma \vdash E_1 : \text{int} \quad \Gamma \vdash E_2 : \text{int}$$

$$\Gamma \vdash E_1 + E_2 : \text{int}$$
$$\Gamma \vdash E_1 : \text{int} \quad \Gamma \vdash E_2 : \text{int}$$

$$\Gamma \vdash E_1 = E_2 : \text{bool}$$

(Comparison)

$$\Gamma \vdash b : \text{bool} \quad \Gamma \vdash E_1 : \tau \quad \Gamma \vdash E_2 : \tau$$

$$\Gamma \vdash \text{if } b \text{ then } E_1 \text{ else } E_2 : \tau$$

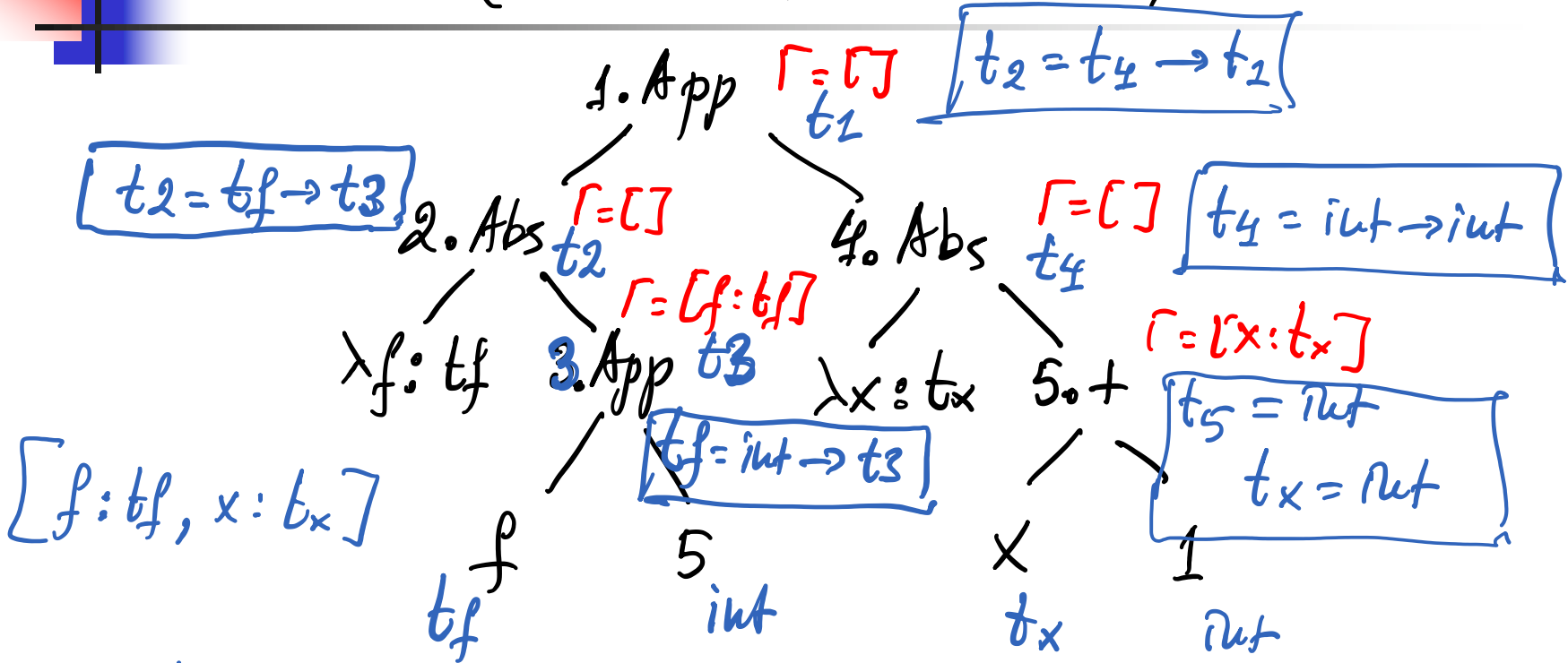


Type Inference, Strategy 1

- We can figure out all types even without explicit types for variables
 - $(\lambda \underline{f}. f \ 5) (\lambda \underline{x}. x+1) : ?$
 - Type inference

- Type inference, Strategy 1
 - Use typing rules to define type constraints
 - Solve type constraints
 - Aka constraint-based typing (e.g., Pierce)

$Nil \vdash (\lambda f. f 5) (\lambda x. x+1) : \mathbb{I}$



$[f: t_f, x: t_x]$

$t_2 = t_f \rightarrow t_3$
 $t_2 = t_4 \rightarrow t_2$
 $t_f = \text{int} \rightarrow t_3$
 $t_4 = \text{int} \rightarrow \text{int}$

$t_f = t_4$
 $t_3 = t_1$
 $t_3 = \text{int}$

$t_f = \text{int} \rightarrow \text{int}$
 $t_1 = \text{int}$

We Can Infer All Types!

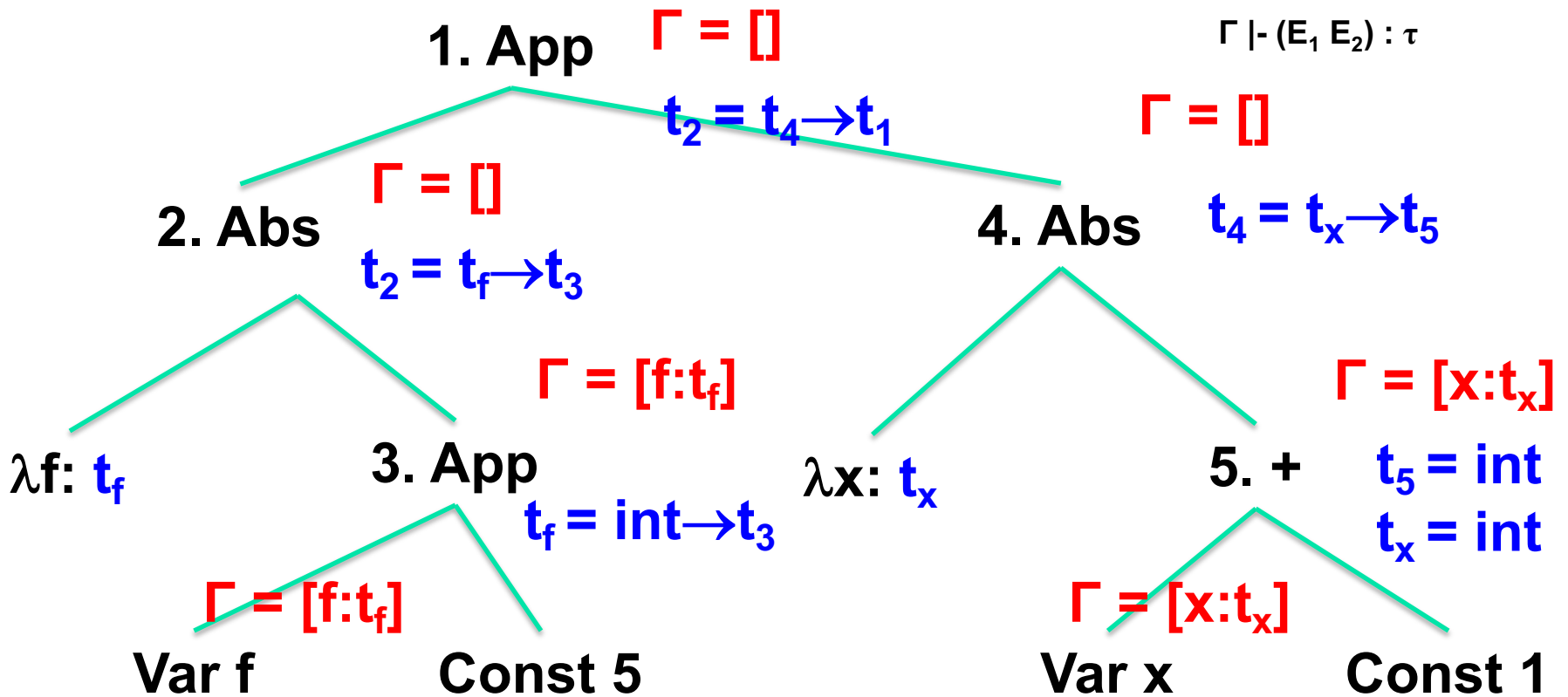
$$\frac{\Gamma \vdash E_1 : \text{int} \quad \Gamma \vdash E_2 : \text{int}}{\Gamma \vdash E_1 + E_2 : \text{int}}$$

$$\Gamma \vdash E_1 + E_2 : \text{int}$$

$$\frac{\Gamma \vdash E_1 : \sigma \rightarrow \tau \quad \Gamma \vdash E_2 : \sigma}{\Gamma \vdash (E_1 E_2) : \tau}$$

$$\Gamma \vdash (E_1 E_2) : \tau$$

- $(\lambda f. f \ 5) (\lambda x. x+1) : ?$



Type Constraints

- We constructed a system of type constraints
- Let's solve the system of constraints

$$t_2 = t_4 \rightarrow t_1$$
$$t_2 = t_f \rightarrow t_3$$

$$t_f = \text{int} \rightarrow t_3 = t_4 = \text{int} \rightarrow \text{int}$$

$$t_3 = \text{int} \quad t_1 = t_3 = \text{int}$$

$$t_4 = t_x \rightarrow t_5$$

$$t_4 = \text{int} \rightarrow \text{int}$$

$$t_f = \text{int} \rightarrow t_3$$

$$t_5 = \text{int}, t_x = \text{int}$$

We inferred all t 's!

$$t_1 = \text{int}$$

$$t_2 = (\text{int} \rightarrow \text{int}) \rightarrow \text{int}$$

$$t_3 = \text{int}$$

$$t_4 = \text{int} \rightarrow \text{int}$$

$$t_f = \text{int} \rightarrow \text{int}$$

- $(\lambda f:\text{int} \rightarrow \text{int}. f \ 5) (\lambda x:\text{int}. x+1) : \text{int} (t_1)$

$$\text{twice} = \lambda f. \lambda x. f (f x)$$

Another Example

- $\text{twice } f \ x = f (f \ x)$

- What is the type of **twice**?

$$(\tau \rightarrow \tau) \rightarrow (\tau \rightarrow \tau)$$

$$t_f = t_x \rightarrow t_2 \quad t_x \rightarrow t_x = t_f$$

$$t_f = t_2 \rightarrow t_1 \quad t_x \rightarrow t_x = t_f$$

$$\text{twice} : (t_x \rightarrow t_x) \rightarrow t_x \rightarrow t_x$$

Another Example

- **twice f x = f (f x)**
- What is the type of **twice**?
 - It is $\mathbf{t_f \rightarrow t_x \rightarrow t_1}$ ($\mathbf{t_1}$ is the type of $\mathbf{f (f x)}$)
- Based on the syntax tree of $\mathbf{f (f x)}$ we have:

$$\mathbf{t_f = t_2 \rightarrow t_1}$$
$$\mathbf{t_f = t_x \rightarrow t_2}$$

Thus, $\mathbf{t_x = t_1 = t_2}$, $\mathbf{t_f = t_x \rightarrow t_x}$ and

type of **twice** is $\mathbf{(t_x \rightarrow t_x) \rightarrow t_x \rightarrow t_x}$

Note: $\mathbf{t_x}$ is a free type variable! **Polymorphism!** 13

Type Constraints from Typing Rules, as Attribute Grammar

- Syntax: $E ::= x \mid c \mid \lambda x.E \mid E_1 E_2 \mid E_1 + E_2$

Grammar rule:

Attribute rule:

$E ::= x$

$C_E = \{ t_E = \Gamma_E(x) \}$

$E ::= c$

$C_E = \{ t_E = \text{int} \}$

$E ::= \lambda x.E_1$

$\Gamma_{E_1} = \Gamma_E; x:t_x$

$C_E = C_{E_1} \cup \{ t_E = t_x \rightarrow t_{E_1} \}$

$E ::= E_1 E_2$

$\Gamma_{E_1} = \Gamma_E \quad \Gamma_{E_2} = \Gamma_E$

$C_E = C_{E_1} \cup C_{E_2} \cup \{ t_{E_1} = t_{E_2} \rightarrow t_E \}$

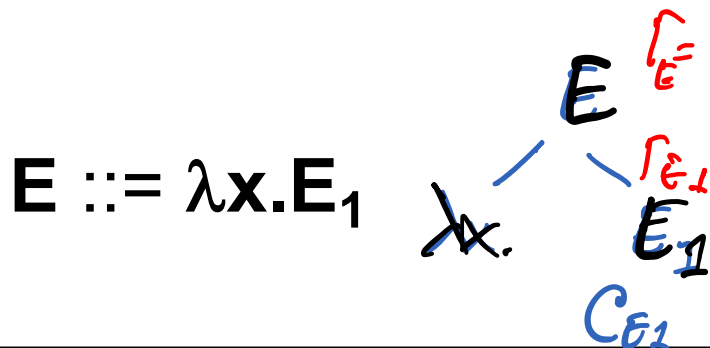
$E ::= E_1 + E_2$

$\Gamma_{E_1} = \Gamma_E \quad \Gamma_{E_2} = \Gamma_E$

$C_E = C_{E_1} \cup C_{E_2} \cup \{ t_{E_1} = \text{int}, t_{E_2} = \text{int}, t_E = \text{int} \}$

Type Constraints from Typing Rules, as Attribute Grammar

...

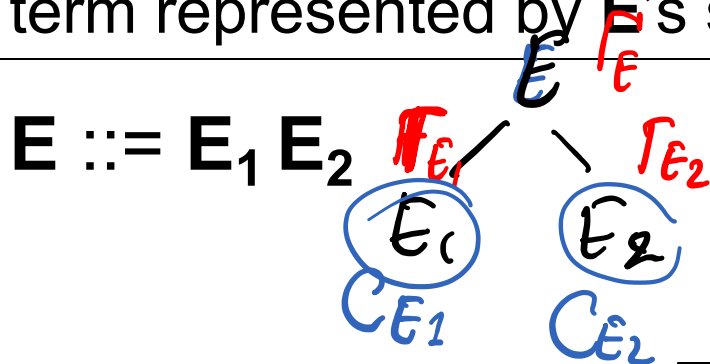


Γ is inherited. Propagates top-down the tree.

$$\Gamma_{E_1} = \Gamma_E; x:t_x$$

$$C_E = C_{E_1} \cup \{ t_E = t_x \rightarrow t_{E_1} \}$$

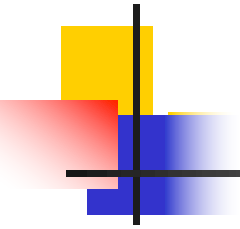
t_E is "fresh" type variable for term represented by E 's subtree.



$$\Gamma_{E_1} = \Gamma_E \quad \Gamma_{E_2} = \Gamma_E$$

$$C_E = C_{E_1} \cup C_{E_2} \cup \{ t_{E_1} = t_{E_2} \rightarrow t_E \} \dots$$

C collects constraints. It is synthesized. Propagates bottom-up the tree.





Solving Constraints

- Two key concepts
- Equality
 - What does it mean for two types to be equal?
 - Structural equality (aka structural equivalence)
- Unification
 - Can two types be made equal by choosing appropriate substitutions for their type variables?
 - Robinson's unification algorithm (which you already know from Prolog!)

Equality and Unification

- What does it mean for two types τ_a and τ_b to be equal?

- Structural equality

- Suppose $\tau_a = \mathbf{t_1} \rightarrow \mathbf{t_2}$

- $\tau_b = \mathbf{t_3} \rightarrow \mathbf{t_4}$

- Structural equality entails

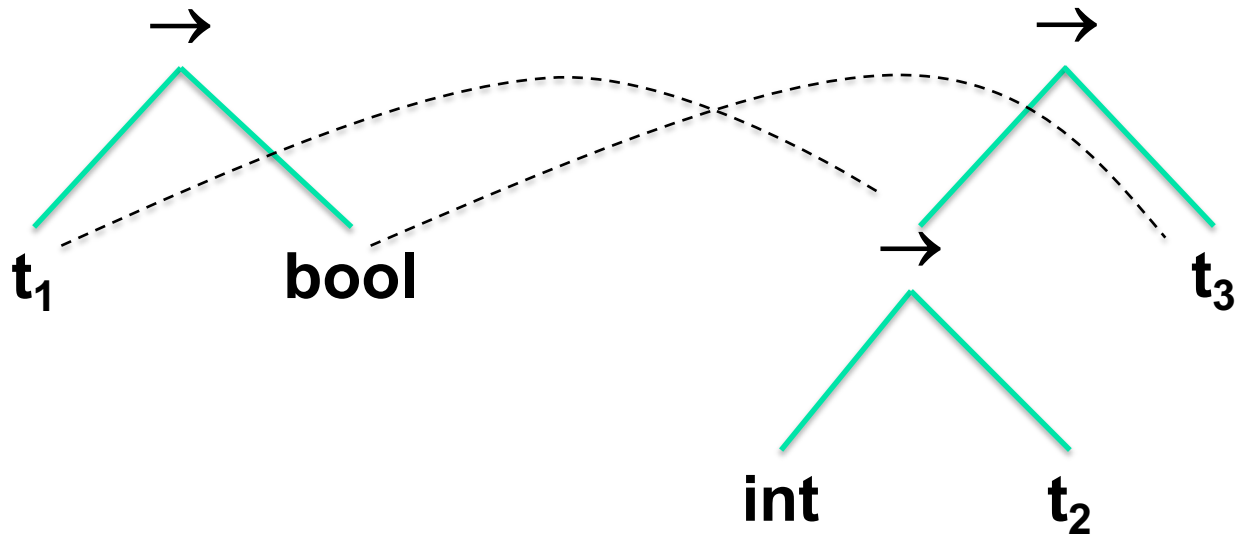
$\tau_a = \tau_b$ means $\mathbf{t_1} \rightarrow \mathbf{t_2} = \mathbf{t_3} \rightarrow \mathbf{t_4}$ iff $\mathbf{t_1} = \mathbf{t_3}$ and $\mathbf{t_2} = \mathbf{t_4}$

Equality and Unification

- Can two types be made equal by choosing appropriate substitutions for their type variables?
- Robinson's unification algorithm
 - Suppose $\tau_a = \mathbf{int} \rightarrow \mathbf{t}_1$
 $\tau_b = \mathbf{t}_2 \rightarrow \mathbf{bool}$
 - Can we unify τ_a and τ_b ? Yes, if $\mathbf{bool}/\mathbf{t}_1$ and $\mathbf{int}/\mathbf{t}_2$
 - Suppose $\tau_a = \mathbf{int} \rightarrow \mathbf{t}_1$
 $\tau_b = \mathbf{bool} \rightarrow \mathbf{bool}$
 - Can we unify τ_a and τ_b ? No.

Example

$$t_1 \rightarrow \text{bool} = (\text{int} \rightarrow t_2) \rightarrow t_3$$



Yes, if $\text{int} \rightarrow t_2 / t_1$ and bool / t_3

Simple Type Substitution

(essential to define unification)

- Language of types

$\tau ::= \mathbf{b}$ // primitive type, e.g., **int**, **bool**

| \mathbf{t} // type variable

| $\tau \rightarrow \tau$ // function type

- A **substitution** is a map

- $\mathbf{S} : \text{Type Variable} \rightarrow \text{Type}$

- $\mathbf{S} = [\tau_1/\mathbf{t}_1, \dots, \tau_n/\mathbf{t}_n]$ // substitute type τ_i for type var \mathbf{t}_i

- A **substitution instance** $\tau' = \mathbf{S} \tau$

- $\mathbf{S} = [\mathbf{t}_0 \rightarrow \mathbf{bool} / \mathbf{t}_1]$ $\tau = \mathbf{t}_1 \rightarrow \mathbf{t}_1$ then

- $\mathbf{S}(\tau) = \mathbf{S}(\mathbf{t}_1 \rightarrow \mathbf{t}_1) = (\mathbf{t}_0 \rightarrow \mathbf{bool}) \rightarrow (\mathbf{t}_0 \rightarrow \mathbf{bool})$

Simple Type Substitution

(essential to define unification)

- Substitutions can be composed
 - $S_1 = [t_0 \rightarrow \text{bool} / t_1]$
 - $S_2 = [\text{int} / t_0]$
 - $\tau = t_1 \rightarrow t_1$
 - $S_2 S_1 (\tau) = S_2 (S_1 (t_1 \rightarrow t_1)) =$



Examples

- Substitutions can be composed
 - $S_1 = [t_x / t_1]$
 - $S_2 = [t_x / t_2]$

 - $\tau = t_2 \rightarrow t_1$
 - $S_2 S_1 (\tau) = ?$



Examples

- Substitutions can be composed
 - $S_1 = [t_1 / t_2]$
 - $S_2 = [t_3 / t_1]$
 - $S_3 = [t_4 \rightarrow \text{int} / t_3]$

 - $\tau = t_1 \rightarrow t_2$
 - $S_3 S_2 S_1 (\tau) = ?$



Some Terminology...

- A substitution \mathbf{S}_1 is **less specific (i.e., more general)** than substitution \mathbf{S}_2 if $\mathbf{S}_2 = \mathbf{S} \mathbf{S}_1$ for some substitution \mathbf{S}
 - E.g., $\mathbf{S}_1 = [t_1 \rightarrow t_1 / t_2]$ is more general than $\mathbf{S}_2 = [\text{int} \rightarrow \text{int} / t_2]$ because $\mathbf{S}_2 = \mathbf{S} \mathbf{S}_1$ for $\mathbf{S} = [\text{int} / t_1]$
- A **principal unifier** of a constraint set \mathbf{C} is a substitution \mathbf{S}_1 that satisfies \mathbf{C} , and \mathbf{S}_1 is more general than any \mathbf{S}_2 that satisfies \mathbf{C}



Examples

- Find principal unifiers (when they exist) for
 - $\{ \text{int} \rightarrow \text{int} = \mathbf{t_1} \rightarrow \mathbf{t_2} \}$
 - $\{ \text{int} = \text{int} \rightarrow \mathbf{t_2} \}$
 - $\{ \mathbf{t_1} = \text{int} \rightarrow \mathbf{t_2} \}$

 - $\{ \mathbf{t_1} = \text{int}, \mathbf{t_2} = \mathbf{t_1} \rightarrow \mathbf{t_1} \}$
 - $\{ \mathbf{t_1} \rightarrow \mathbf{t_2} = \mathbf{t_2} \rightarrow \mathbf{t_3}, \mathbf{t_3} = \mathbf{t_4} \rightarrow \mathbf{t_5} \}$

Unification

(essential for type inference!)

- **Unify**: tries to unify τ_1 and τ_2 and returns a **principal unifier for $\tau_1 = \tau_2$** if unification is successful

def **Unify**(τ_1, τ_2) =

This is the **occurs check!**

case (τ_1, τ_2)

(τ_1, \mathbf{t}_2) = [τ_1/\mathbf{t}_2] provided \mathbf{t}_2 does not **occur** in τ_1

(\mathbf{t}_1, τ_2) = [τ_2/\mathbf{t}_1] provided \mathbf{t}_1 does not **occur** in τ_2

($\mathbf{b}_1, \mathbf{b}_2$) = if (eq? \mathbf{b}_1 \mathbf{b}_2) then [] else **fail**

($\tau_{11} \rightarrow \tau_{12}, \tau_{21} \rightarrow \tau_{22}$) = let **S**₁ = **Unify**(τ_{11}, τ_{21})

S₂ = **Unify**(**S**₁(τ_{12}), **S**₁(τ_{22}))

in **S**₂ **S**₁ // compose substitutions

otherwise = **fail**



Examples

- **Unify** ($\text{int} \rightarrow \text{int}$, $t_1 \rightarrow t_2$) yields ?

- **Unify** (int , $\text{int} \rightarrow t_2$) yields ?

- **Unify** (t_1 , $\text{int} \rightarrow t_2$) yields ?



Unify Set of Constraints C

- **UnifySet**: tries to unify **C** and returns a **principal unifier for C** if unification is successful

def **UnifySet** (**C**) =

if **C** is Empty Set then []

else let

C = { $\tau_1 = \tau_2$ } U **C'**

S = **Unify** (τ_1, τ_2) // **Unify** returns a substitution **S**

in

UnifySet (**S**(**C'**)) **S**

// Compose the substitutions



Examples

- $\{ t_1 = \text{int}, t_2 = t_1 \rightarrow t_1 \}$
- $\{ t_1 \rightarrow t_2 = t_2 \rightarrow t_3, t_3 = t_4 \rightarrow t_5 \}$
- $\{ t_f = t_2 \rightarrow t_1, t_f = t_x \rightarrow t_2 \}$
- $\{ t_2 = t_4 \rightarrow t_1, t_2 = t_f \rightarrow t_3, t_4 = t_x \rightarrow t_5, t_f = \text{int} \rightarrow t_3, t_5 = \text{int}, t_x = \text{int} \}$



Type Inference, Strategy 1

- Aka constraint-based typing (e.g., Pierce)
- Traverse parse tree to derive a set of type constraints **C**
 - These are equality constraints
 - (Pseudo code in earlier slides)
- Solve type constraints offline
 - Use unification algorithm
 - (Pseudo code in earlier slide)



Outline

- Simple type inference
 - Equality constraints
 - Unification
 - Substitution
 - Strategy 1: Constraint-based typing
 - Strategy 2: On-the-fly typing: Algorithm W, almost
- Parametric polymorphism (next time...)
- Hindley Milner type inference. Algorithm W



Type Inference, Strategy 2

- Strategy 1 collects all constraints, then solves them offline
- Strategy 2 solves constraints on the fly
 - Builds the substitution map incrementally

Add a New Attribute, Substitution

Map S

T_E is the inferred type of E .
 S_E is the substitution map
resulting from inferring T_E .
 t_x, t_E are fresh type variables.

Grammar rule:

Attribute rule:

$E ::= x$

$T_E = \Gamma_E(x) \quad S_E = []$

$E ::= c$

$T_E = \text{int} \quad S_E = []$

$E ::= \lambda x. E_1$

$\Gamma_{E_1} = \Gamma_E; x:t_x$

$T_E = S_{E_1}(t_x) \rightarrow T_{E_1} \quad S_E = S_{E_1}$

$E ::= E_1 E_2$

$\Gamma_{E_1} = \Gamma_E \quad \Gamma_{E_2} = S_{E_1}(\Gamma_E)$

$S = \text{Unify}(S_{E_2}(T_{E_1}), T_{E_2} \rightarrow t_E)$

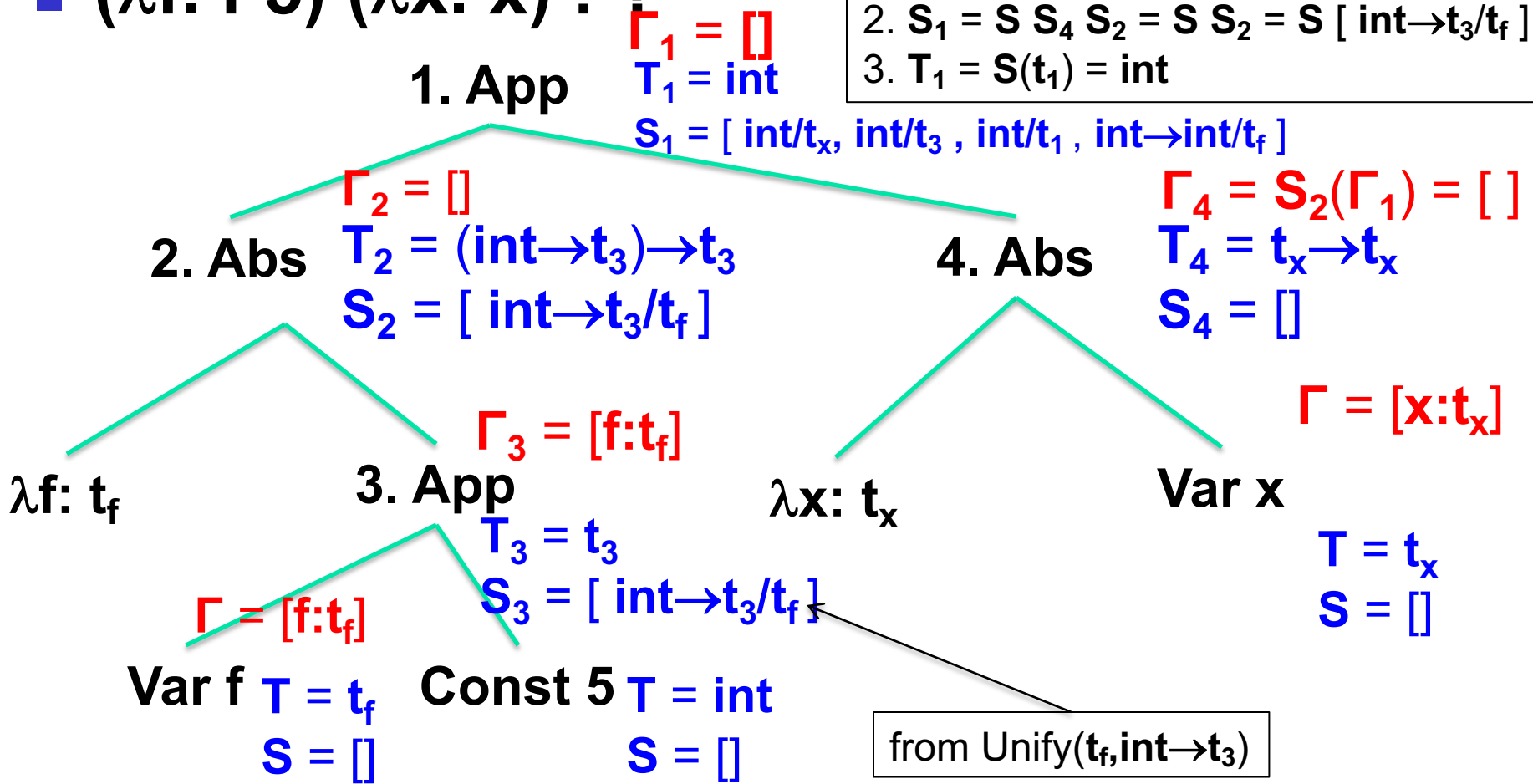
$T_E = S(t_E) \quad S_E = S S_{E_2} S_{E_1}$

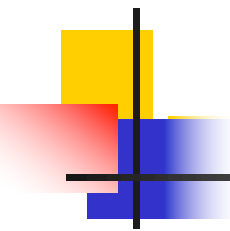
Example: $(\lambda f. f\ 5)\ (\lambda x. x)$

Steps at 1, finally:

1. unify($(\text{int} \rightarrow t_3) \rightarrow t_3, (t_x \rightarrow t_x) \rightarrow t_1$)
returns $S = [\text{int}/t_x, \text{int}/t_3, \text{int}/t_1]$
2. $S_1 = S\ S_4\ S_2 = S\ S_2 = S [\text{int} \rightarrow t_3/t_f]$
3. $T_1 = S(t_1) = \text{int}$

■ $(\lambda f. f\ 5)\ (\lambda x. x) : ?$





Example: $\lambda f. \lambda x. (f (f x))$

The Let Construct

- In dynamic semantics, **let $x = E_1$ in E_2** is equivalent to **$(\lambda x.E_2) E_1$**

- Typing rule

$$\frac{\Gamma \vdash E_1 : \sigma \quad \Gamma; x:\sigma \vdash E_2 : \tau}{\Gamma \vdash \text{let } x = E_1 \text{ in } E_2 : \tau}$$

- In static semantics **let $x = E_1$ in E_2** is not equivalent to **$(\lambda x.E_2) E_1$**
 - In **let**, the type of “argument” **E_1** is inferred/checked **before** the type of function body **E_2**
 - **let** construct enables Hindley Milner style polymorphism!

The Let Construct

- Typing rule

$$\frac{\Gamma \vdash E_1 : \sigma \quad \Gamma; x:\sigma \vdash E_2 : \tau}{\Gamma \vdash \text{let } x = E_1 \text{ in } E_2 : \tau}$$

- Attribute grammar rule

$E ::= \text{let } x = E_1 \text{ in } E_2$

$$\Gamma_{E_1} = \Gamma_E$$

$$\Gamma_{E_2} = \mathbf{S}_{E_1}(\Gamma_E) + \{x:T_{E_1}\}$$

$$T_E = T_{E_2} \quad \mathbf{S}_E = \mathbf{S}_{E_2} \mathbf{S}_{E_1}$$



The Letrec Construct

- **letrec** $x = E_1$ in E_2
 - x can be referenced from within E_1
 - Extends calculus with general recursion
 - No need to type **fix** (we can't!) but we can still type recursive functions like **plus**, **times**, etc.
 - Haskell's **let** is a **letrec** actually...
- E.g.,
letrec plus = $\lambda x.\lambda y.$ if ($x=0$) then y else $((\mathbf{plus} \ x-1) \ y+1)$
written as
letrec plus $x \ y =$ if ($x=0$) then y else **plus** $(x-1) \ (y+1)$

The Letrec Construct

- **letrec $x = E_1$ in E_2**

Extensions over let rule

1. T_{E_1} is inferred in augmented environment $\Gamma_E + \{x:t_x\}$
 2. Must unify $S_{E_1}(t_x)$ and T_{E_1}
 3. Apply substitution S on top of S_{E_1}
- Note: Can merge **let** and **letrec**, in **let Unify** and S have no impact

- Attribute grammar rule

$E ::= \text{letrec } x = E_1 \text{ in } E_2$

$$\Gamma_{E_1} = \Gamma_E + \{x:t_x\}$$

$$S = \text{Unify}(S_{E_1}(t_x), T_{E_1})$$

$$\Gamma_{E_2} = S S_{E_1}(\Gamma_E) + \{x:T_{E_1}\}$$

$$T_E = T_{E_2} \quad S_E = S_{E_2} S S_{E_1}$$



let/letrec Examples

letrec **plus** x y = if (x=0) then y else **plus** (x-1) (y+1)

- Typing **plus** using Strategy 1...

$$t_{\text{plus}} = t_x \rightarrow t_y \rightarrow t_1$$

$t_x = \text{int}$ // because of **x=0** and **x-1**

$t_y = \text{int}$ // because of **y+1**

Unify(t_{plus} , $\text{int} \rightarrow \text{int} \rightarrow \text{int}$) yields $t_1 = \text{int}$

- Haskell

plus :: int -> int -> int

plus x y = if (x=0) then y else **plus** (x-1) (y+1)

Algorithm W, Almost There!

def $W(\Gamma, E) = \text{case } E \text{ of}$

$c \rightarrow ([], \text{TypeOf}(c))$

$x \rightarrow \text{if } (x \text{ NOT in Dom}(\Gamma)) \text{ then } \textit{fail}$
else let $T_E = \Gamma(x);$
in $([], T_E)$

$\lambda x. E_1 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma + \{x: t_x\}, E_1)$
in $(S_{E_1}, S_{E_1}(t_x) \rightarrow T_{E_1})$

$E_1 E_2 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma, E_1)$
 $(S_{E_2}, T_{E_2}) = W(S_{E_1}(\Gamma), E_2)$
 $S = \text{Unify}(S_{E_2}(T_{E_1}), T_{E_2} \rightarrow t)$
in $(S S_{E_2} S_{E_1}, S(t))$ // $S S_{E_2} S_{E_1}$ composes substitutions

let $x = E_1$ in $E_2 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma, E_1)$
 $(S_{E_2}, T_{E_2}) = W(S_{E_1}(\Gamma) + \{x: T_{E_1}\}, E_2)$
in $(S_{E_2} S_{E_1}, T_{E_2})$

Algorithm W, Almost There!

(merges **let** and **letrec**)

def $W(\Gamma, E) = \text{case } E \text{ of}$

$c \rightarrow ([], \text{TypeOf}(c))$

$x \rightarrow \text{if } (x \text{ NOT in Dom}(\Gamma)) \text{ then } \textit{fail}$
 $\text{else let } T_E = \Gamma(x);$
 $\text{in } ([], T_E)$

$\lambda x.E_1 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma + \{x:t_x\}, E_1)$
 $\text{in } (S_{E_1}, S_{E_1}(t_x) \rightarrow T_{E_1})$

$E_1 E_2 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma, E_1)$
 $(S_{E_2}, T_{E_2}) = W(S_{E_1}(\Gamma), E_2)$
 $S = \text{Unify}(S_{E_2}(T_{E_1}), T_{E_2} \rightarrow t)$
 $\text{in } (S S_{E_2} S_{E_1}, S(t)) \text{ // } S S_{E_2} S_{E_1} \text{ composes substitutions}$

$\text{let } x = E_1 \text{ in } E_2 \rightarrow \text{let } (S_{E_1}, T_{E_1}) = W(\Gamma + \{x:t_x\}, E_1)$

$S = \text{Unify}(S_{E_1}(t_x), T_{E_1})$

$(S_{E_2}, T_{E_2}) = W(S S_{E_1}(\Gamma) + \{x:T_{E_1}\}, E_2)$

$\text{in } (S_{E_2} S S_{E_1}, T_{E_2})$



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- **Parametric polymorphism**
- Hindley Milner type inference. Algorithm W