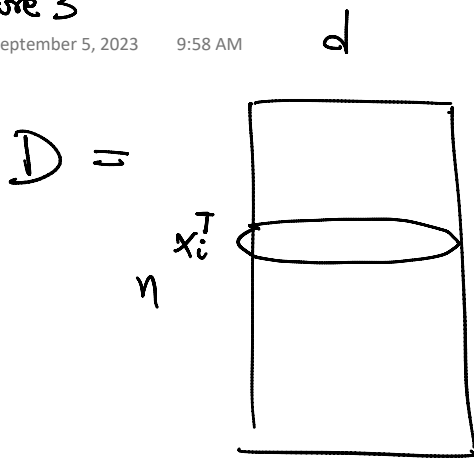
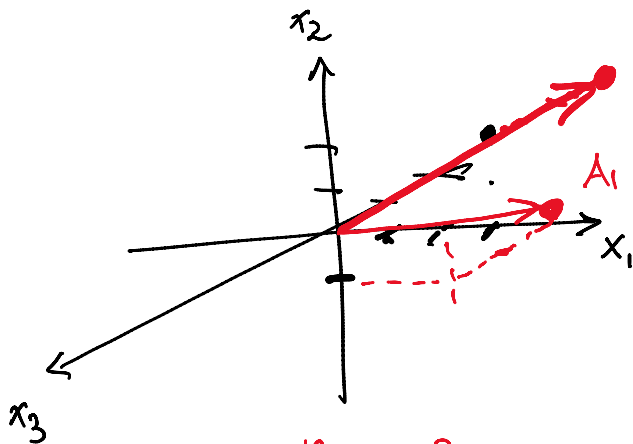


Lecture 3

Tuesday, September 5, 2023 9:58 AM



Point / row
view



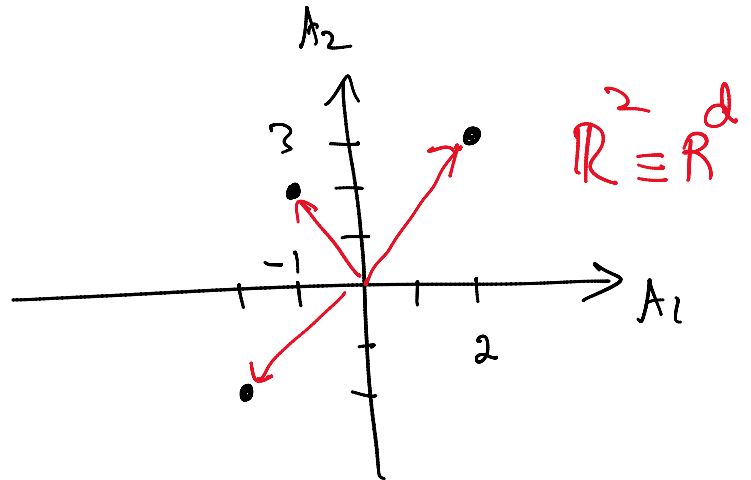
$$\mathbb{R}^n = \mathbb{R}^3$$

Sample space
Col space

$d=2$

	A_1	A_2
x_i^T	2	3
	-1	2
	-2	-2

$n=3$



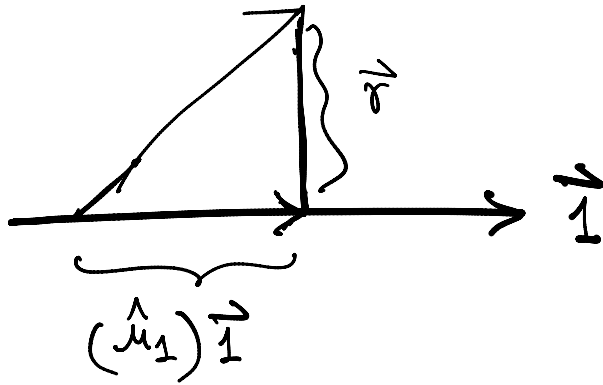
$(A_1, A_2) \equiv$ basis vectors

$\hat{\mu} \equiv$ Sample mean

orthogonal projection along $\vec{1}$
(ones vector)

$\bar{D} \equiv$ Centered data \equiv orthogonalize wrt $\vec{1}$

$A_1 \rightarrow x_i^T - \hat{\mu}^T$



$$\hat{\mu} = (\hat{\mu}_1, \hat{\mu}_2)^T$$

$$A_1 - (\hat{\mu}_1) \mathbf{1}$$

Variance

$$\hat{\sigma}_1^2 = \frac{\|\bar{A}_1\|^2}{n}$$

Squared norm / dim

$$\hat{\sigma}_1^2 \propto \|\bar{A}_1\|^2$$

$$\hat{\sigma}_2^2 \propto \|\bar{A}_2\|^2$$

$$\hat{\sigma}_{12} = \frac{\bar{A}_1^T \bar{A}_2}{n}$$

Cov

dot product between
the centered attribute vectors

$$\hat{\rho}_{12} = \left(\frac{\bar{A}_1}{\|\bar{A}_1\|} \right)^T \left(\frac{\bar{A}_2}{\|\bar{A}_2\|} \right) = \cos \theta$$

Correlation

$$\hat{\Sigma} = \begin{bmatrix} \hat{\sigma}_1^2 & \hat{\sigma}_{12} \\ \hat{\sigma}_{12} & \hat{\sigma}_2^2 \end{bmatrix}$$

Cov matrix

A_1	A_2

$$= \begin{bmatrix} \text{Var}(A_1) & \text{Cov}(A_1, A_2) \\ \text{Cov}(A_1, A_2) & \text{Var}(A_2) \end{bmatrix}$$

$$d=2$$

Square matrix 2×2 , symmetric

$$\Sigma^T = \Sigma$$

PSD: positive semi-definite matrix

any vector $\vec{a} \in \mathbb{R}^d$

$$\vec{a}^T \Sigma \vec{a} \geq 0$$

quadratic form

$$\vec{a}^T \vec{a} = \|\vec{a}\|^2$$

$$\vec{a}^T (\mathbf{I}) \vec{a}$$

Consequences:

Σ has d non-negative eigenvalues

Σ in the full d -dim case

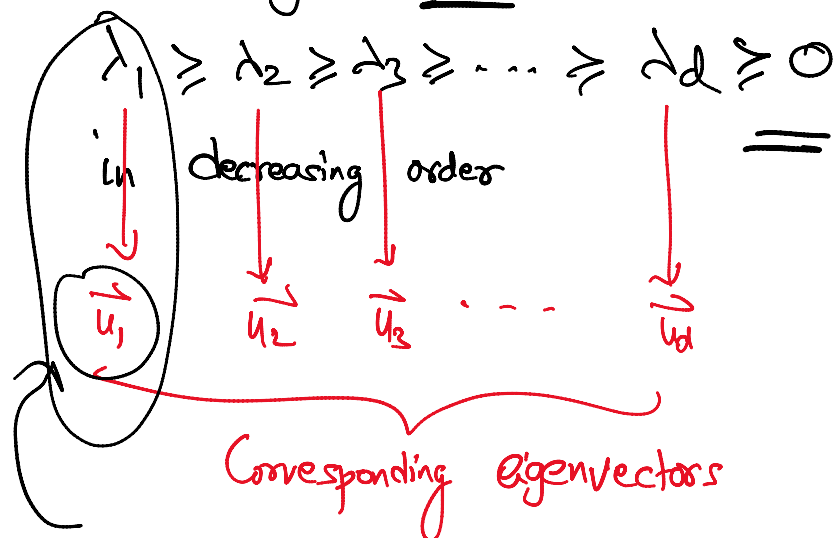
$$= \begin{bmatrix} \sigma_1^2 & \sigma_{12} & \sigma_{13} & \dots & \sigma_{1d} \\ \sigma_{12} & \sigma_2^2 & \sigma_{23} & \dots & \sigma_{2d} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \sigma_{d1} & \sigma_{d2} & \sigma_{d3} & \dots & \sigma_d^2 \end{bmatrix}$$

$d \times d$, symmetric, PSD matrix

$$\begin{matrix} A_1 & A_2 & \dots & A_d \\ \hline & & & \end{matrix}$$

\sim

d non-negative eigenvalues



$$\vec{u}_i^T \vec{u}_j = 0 \quad \forall i, j = 1, \dots, d$$

\vec{u}_i is orthogonal to \vec{u}_j

$$\vec{u}_i^T \vec{u}_i = 1, \quad \|\vec{u}_i\| = 1$$

unit vectors

$$D = \begin{matrix} & d \\ n & \boxed{} \end{matrix}$$

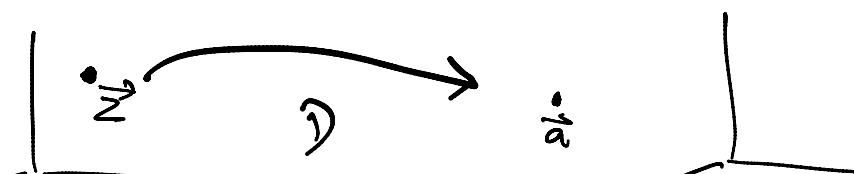
$$\vec{z} \in \mathbb{R}^d$$

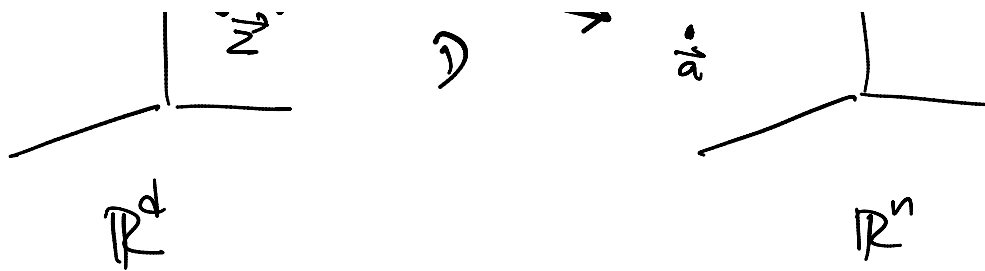
$$\vec{a}_{n \times 1} = D \vec{z}_{(d \times 1)}$$

$(n \times d)$ $(d \times 1)$

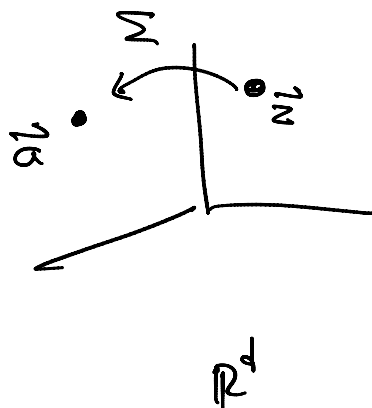
D acts like a function

$$\mathbb{R}^d \rightarrow \mathbb{R}^n$$





$$\Sigma \in \mathbb{R}^{d \times d} : \mathbb{R}^d \rightarrow \mathbb{R}^d$$



$$\vec{a} = \Sigma \vec{z}$$

$$\Sigma = \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix}$$

$$\vec{z} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\vec{a} = \Sigma \vec{z} = \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 7 \\ 3 \end{pmatrix}$$

Σ as a transformation

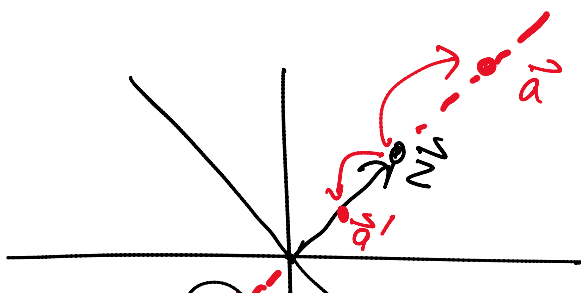
Q: $\exists \vec{u}$, such that $\lambda \vec{u} = \Sigma \vec{u}$

unit
vector

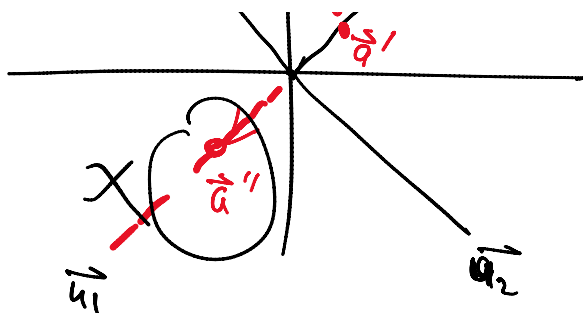
eigen
value

eigenvector

invariant direction



for Σ symmetric



for Σ symmetric

$$\Sigma \in \mathbb{R}^{2 \times 2}$$

An eigenvector is a non-zero ^{unit} vector $\vec{u} \in \mathbb{R}^d$

that satisfies the equation

$$\Sigma \vec{u} = \lambda \vec{u}$$

Eigen
value

$$\lambda \in \mathbb{R}$$

(Scalar)

$$\Sigma \vec{u}_1 = \lambda_1 \vec{u}_1$$

$$\Sigma \vec{u}_2 = \lambda_2 \vec{u}_2$$

\vdots

$$\Sigma \vec{u}_d = \lambda_d \vec{u}_d$$

d equations

Power-Iteration to find the dominant eigenvector/eigenvalue

$$\Sigma = \begin{pmatrix} 5 & 2 \\ 2 & 1 \end{pmatrix}$$

$$\hat{\lambda}_1 = 7$$

$$\vec{x}_0 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Sigma \vec{x}_0 = \begin{pmatrix} 7 \\ 3 \end{pmatrix} = \vec{x}_1'$$

$$\hat{\lambda}_1 = 5.86$$

$$\vec{x}_1' \xrightarrow{\text{scale by } 1/3} \begin{pmatrix} 1 \\ 3/3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0.43 \end{pmatrix} = \vec{x}_0$$

$$= \begin{pmatrix} 5.86 \\ 2.43 \end{pmatrix} = \vec{x}_2'$$

$$\xrightarrow{\text{scale}} \begin{pmatrix} 1 \\ 2.43/5.86 \end{pmatrix} = \begin{pmatrix} 1 \\ 0.41 \end{pmatrix}$$

\vec{x}_2

$$\vec{x}_2 = \begin{pmatrix} 1 \\ 0.42 \end{pmatrix} \rightarrow \Sigma \vec{x}_2 = \begin{pmatrix} 5.84 \\ 2.42 \end{pmatrix} \xrightarrow{\text{scale}} \begin{pmatrix} 1 \\ 2.42/5.84 \end{pmatrix} = \begin{pmatrix} 1 \\ 0.42 \end{pmatrix}$$

$$\vec{u}_1 = \begin{pmatrix} 1 \\ 0.42 \end{pmatrix} \xrightarrow{\text{unit vector}} \frac{1}{\sqrt{1^2 + 0.42^2}} \begin{pmatrix} 1 \\ 0.42 \end{pmatrix} = \frac{1}{\sqrt{1.18}} \begin{pmatrix} 1 \\ 0.42 \end{pmatrix} = \frac{1}{1.07} \begin{pmatrix} 1 \\ 0.42 \end{pmatrix}$$

$$\text{dominant eigenvector} \rightarrow \vec{u}_1 = \begin{pmatrix} 0.93 \\ 0.39 \end{pmatrix} \quad \lambda_1 = 5.84$$

do one more matrix multiplication and find λ

$$\Sigma u_i = (\lambda_i) u_i$$

Dominant \rightarrow Power Iteration $\rightarrow \lambda_1, \vec{u}_1$

Q: how to find λ_2, \vec{u}_2 , and the rest?

$$D = \mathbb{R}^{n \times d}$$

$$\lambda_1 \lambda_2 \dots \lambda_d$$

Approximation

$$\begin{matrix} & A_1 A_2 \dots A_d \\ \begin{matrix} x_1^T \\ x_2^T \\ \vdots \\ x_n^T \end{matrix} & \left| \begin{matrix} \\ \\ \\ \end{matrix} \right. \end{matrix}$$

Q: what single point
best approximates D ?

\vec{z} should be close to
all other points

$$\vec{z} \in \mathbb{R}^d$$

$$\text{square dist}(\vec{z}, \vec{x}_i) = \|\vec{z} - \vec{x}_i\|^2$$

$$\vec{x}_i \in D$$

$$\vec{z}?$$

$$\min_{\vec{z}} J = \sum_{i=1}^n \|\vec{z} - \vec{x}_i\|^2$$

$$\frac{\partial J}{\partial \vec{z}} = \vec{0}$$

partial derivative, set to zero, solve (if possible)

$$\begin{aligned} \sum \|\vec{z} - \vec{x}_i\|^2 &= \sum_{i=1}^n (\vec{z} - \vec{x}_i)^T (\vec{z} - \vec{x}_i) \\ &= \sum_{i=1}^n \left(\underbrace{\vec{z}^T \vec{z}} + \underbrace{\vec{x}_i^T \vec{x}_i} - 2 \underbrace{\vec{z}^T \vec{x}_i} \right) \end{aligned}$$

$$\frac{\partial J}{\partial \vec{z}} = \sum_{i=1}^n 2\vec{z} - 2\vec{x}_i = \vec{0}$$

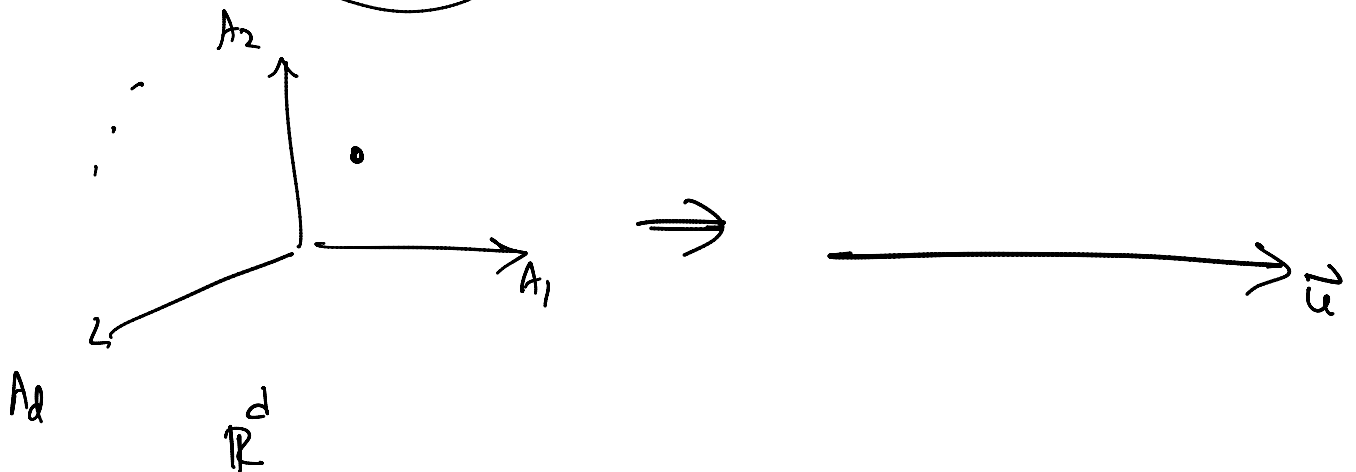
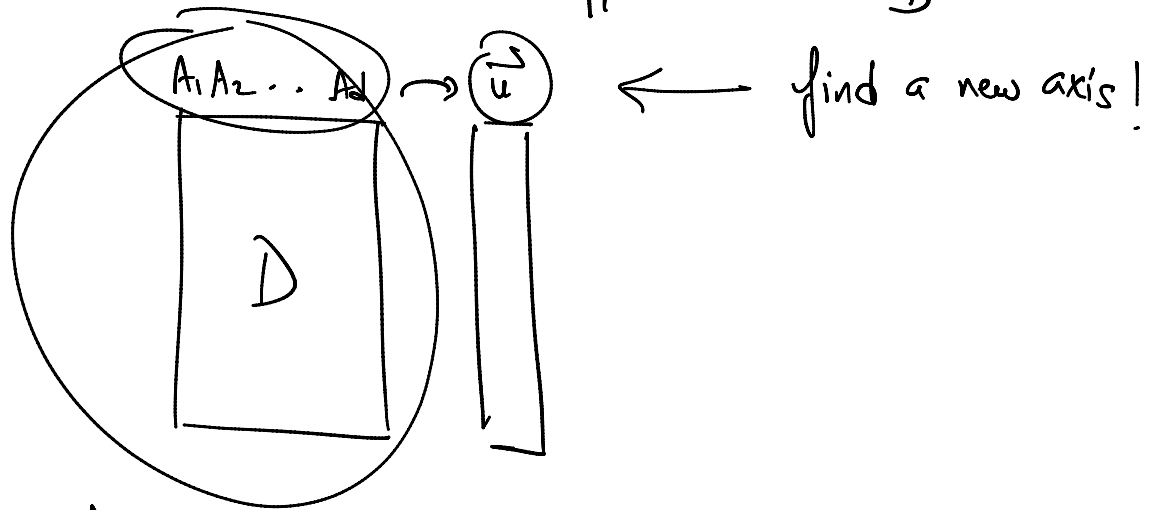
$$= \sum_{i=1}^n \vec{z} = \sum_{i=1}^n \vec{x}_i$$

$$\Rightarrow n \cdot \vec{z} = \sum_{i=1}^n \vec{x}_i$$

$$\Rightarrow \vec{z} = \frac{1}{n} \sum_{i=1}^n \vec{x}_i = \vec{\mu}$$

↑
mean value!

Q. what's the best 1d approximation to D



Project all points onto the \vec{u} direction \vec{x}_i should be a

Project all points onto the \vec{u} direction, \vec{u} should be a unit vector

$$x_i \in \mathbb{R}^d$$

$$\vec{u} \in \mathbb{R}^d$$

$$\vec{u}^T \vec{u} = 1$$

$$\|\vec{u}\| = 1$$

$$\left(\frac{\vec{x}_i^T \vec{u}}{\vec{u}^T \vec{u}} \right) \vec{u}$$

Scalar projection

$$a_i = \vec{x}_i^T \vec{u}$$

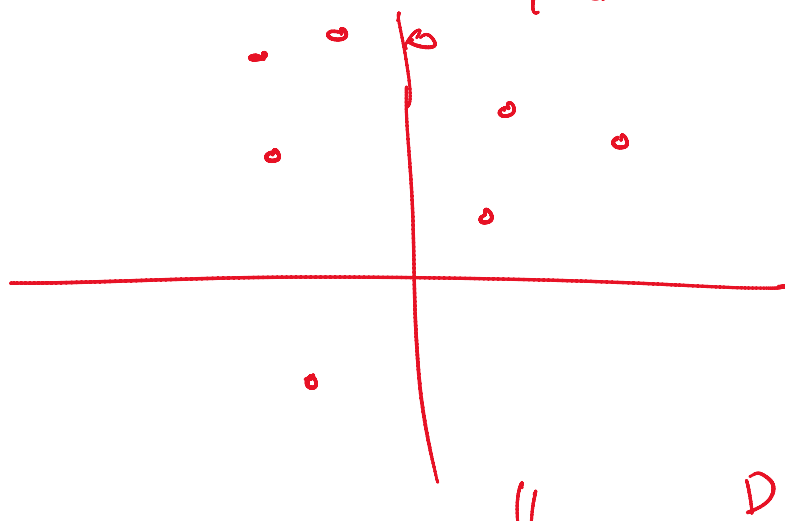
Projected
scalar
value
along \vec{u}

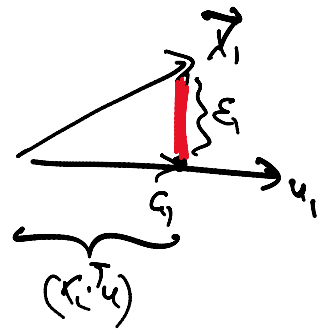
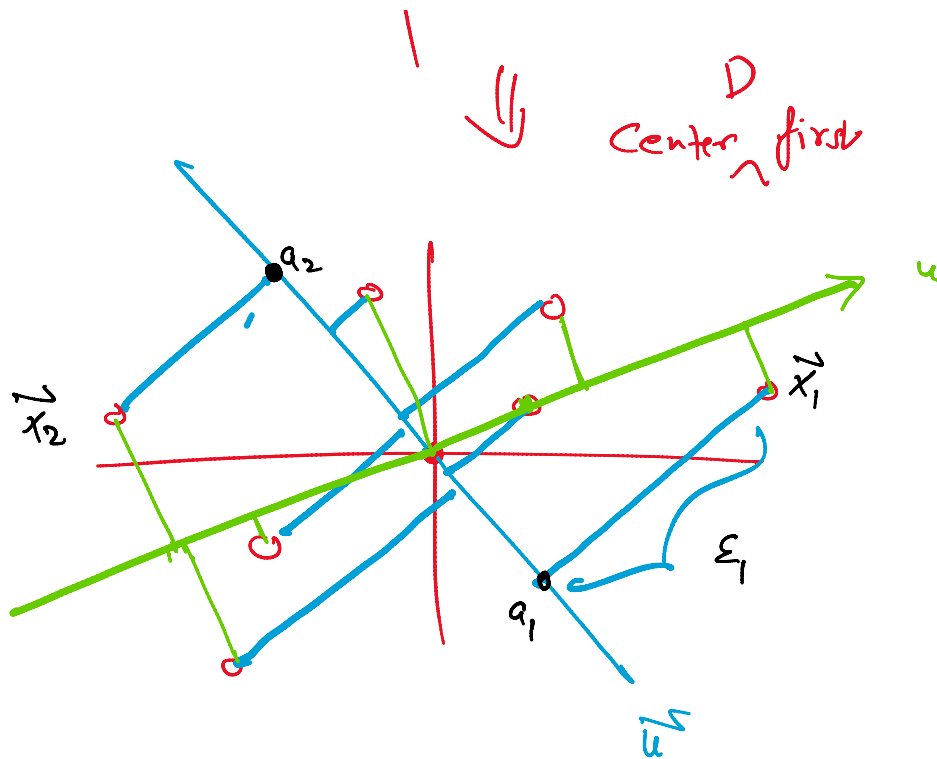


I Objective: maximize the ^{Projected} variance

$$\frac{1}{n} \sum_{i=1}^n (a_i - \mu_a)^2$$

II: Minimize error (distance squared)





$$\min_{\vec{u}} \underbrace{\frac{1}{n} \sum_{i=1}^n \|\epsilon_i\|^2}_{\text{MSE}} = \left(\frac{1}{n}\right) \sum_{i=1}^n \left\| \vec{x}_i - (\vec{x}_i^T \vec{u}) \vec{u} \right\|^2$$

mean squared error

Maximization of projected variance \equiv minimization of MSE

\vec{u} is in fact the dominant eigenvector of Σ
(cov matrix!)

$$\vec{u} = \vec{u}_1$$

λ_1 \leftarrow variance along the new axis
Eigenvalue \nwarrow