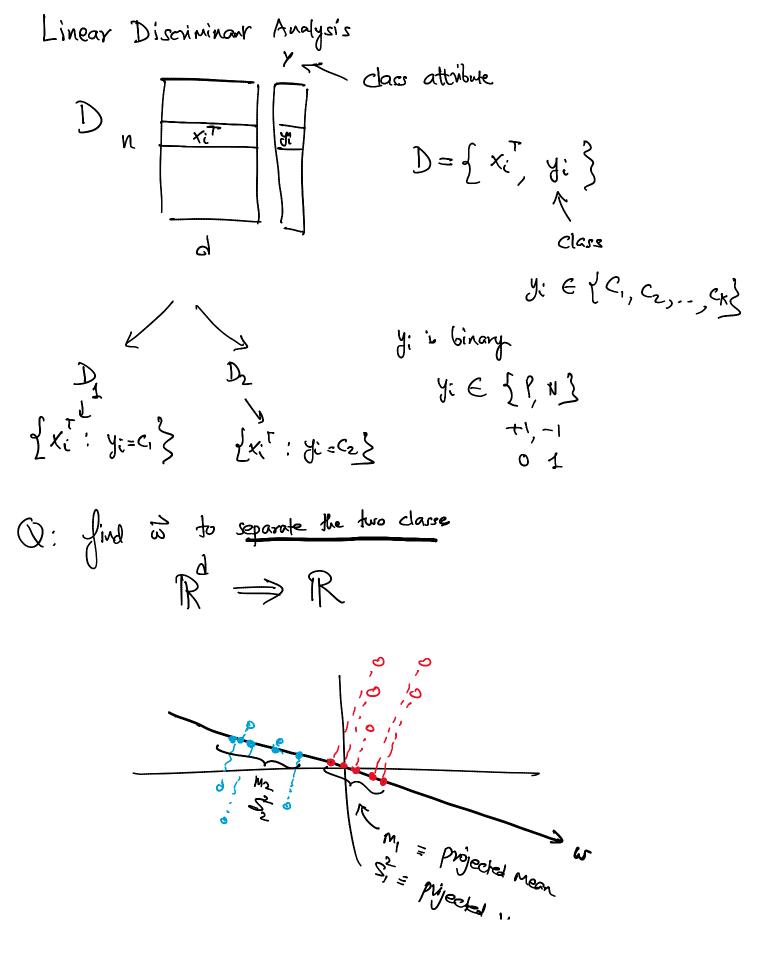
Lecture 6

Thursday, September 14, 2023 9:55 AM



$$J_{i} = N_{i}^{2} e_{i} e_{i} M_{enc}$$

$$J_{i}^{2} = Scatter total squared deviation total squared deviation for  $T = \frac{(M_{1} - M_{2})^{2}}{(M_{1} + S_{2})^{2}}$ 

$$A_{i}^{T} \in D_{i} \qquad \int_{G_{i}}^{G_{i}} e_{i} \int_{G_{i}}^{G_{i}} \int_{G_{i}}^{G_{i}} e_{i} \int_{G_{i}}^{G_{i}} e$$$$

$$= \left( \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right)^{T} \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right)^{T} \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right)^{T} \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right)^{2} \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right)^{2} \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \left( \overrightarrow{h_{1}} - \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \cancel{h_{2}} = \overrightarrow{h_{1}} \cdot \overrightarrow{h_{1}} \right) \right)^{2}$$

$$= \begin{array}{c} \widetilde{\omega}^{T} \left( \cancel{h_{2}} = \overrightarrow{h_{2}} \right) \overrightarrow{\omega}$$

$$S_{1}^{2} + S_{2}^{2} = \begin{array}{c} \widetilde{\omega}^{T} \left( \overrightarrow{h_{1}} + \overrightarrow{h_{2}} \right) \overrightarrow{\omega}$$

$$= \frac{1}{\omega}^{T} S \frac{1}{\omega}$$

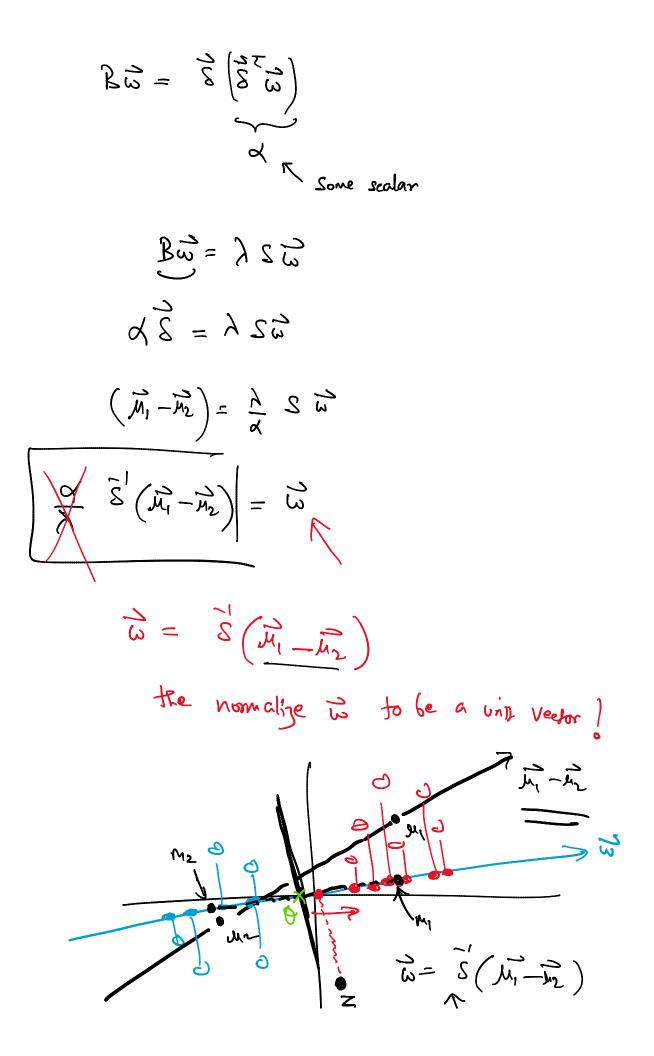
$$= \frac{1}{\omega}^{T} S \frac{1}{\omega}$$

$$poll (i)(i)(i)(-class state)$$

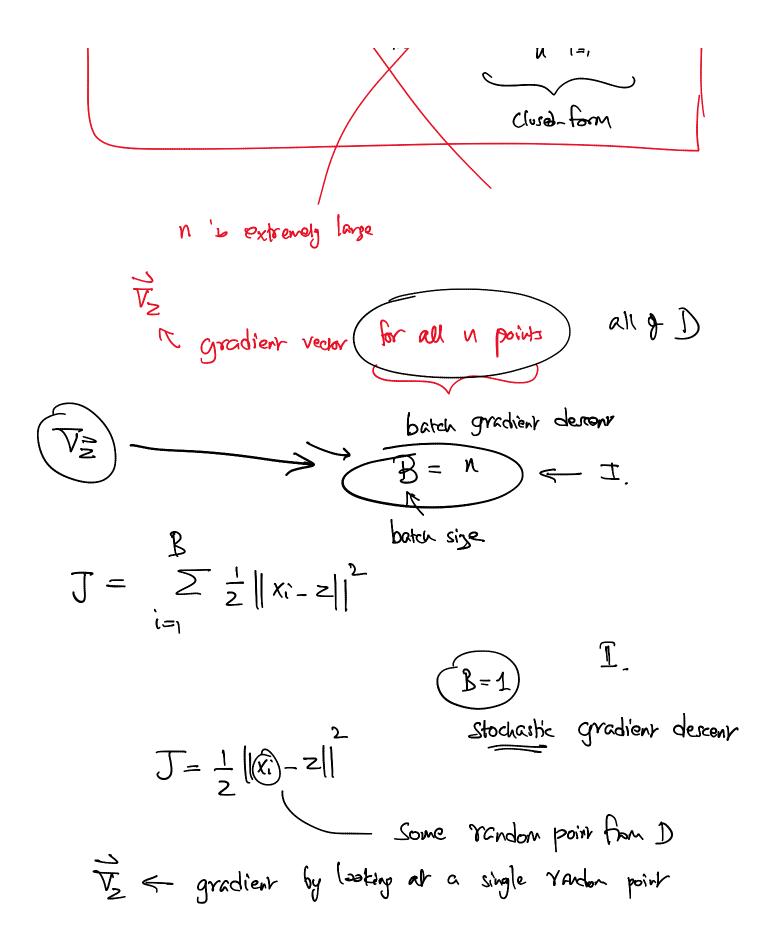
$$poll (i)(i)(i)(-class state)$$

$$= \frac{1}{\omega} = \frac{1}{\omega}$$

$$\frac{3}{3} = \frac{1}{3} \frac{$$



Solution: 
$$\vec{w} = \frac{1}{2} \begin{bmatrix} \vec{w} = S(\vec{w}_1 - \vec{w}_2) \\ \gamma = \frac{1}{2} \begin{bmatrix} \vec{w} = S(\vec{w}_1 - \vec{w}_2) \\ \gamma = \frac{1}{2} \begin{bmatrix} \vec{w} = \frac{1}{$$



$$\vec{z}_{t} = \vec{z}_{t-1} - \eta \cdot \vec{y}_{z}$$

$$(vhen n is very have the gradient in the gradient is the gradient is$$

