

Volume Visualization



<http://gizmodo.com/ges-new-fast-ct-scanner-captures-insane-images-in-a-he-1482904872>
http://www3.gehealthcare.com/en/Products/Categories/Computed_Tomography/Revolution_CT

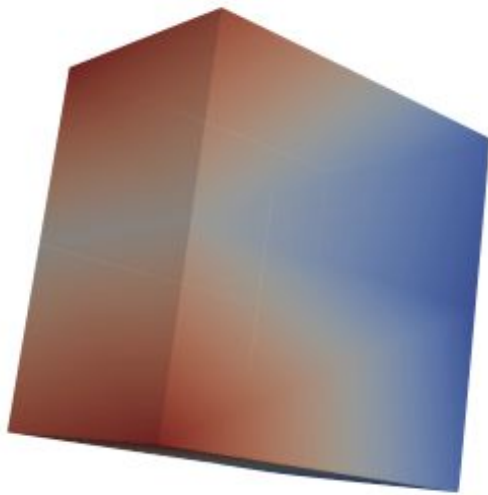


Figure 1: Frame 17 of the visualization

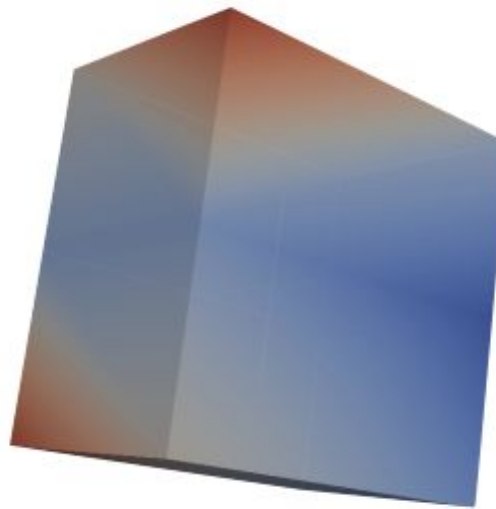


Figure 3: Frame 19 of the visualization

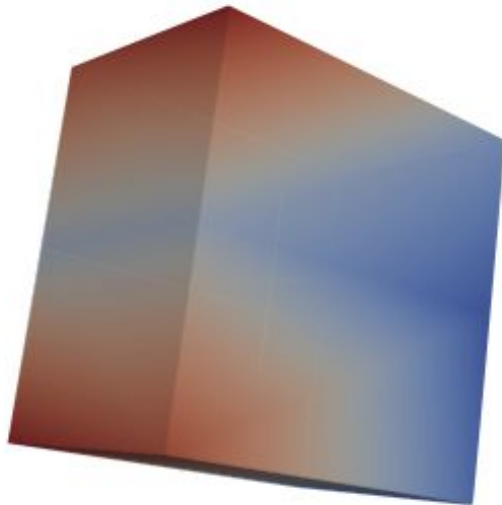


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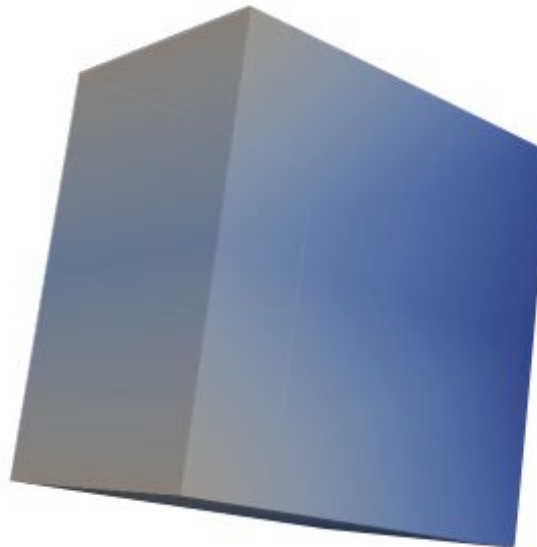
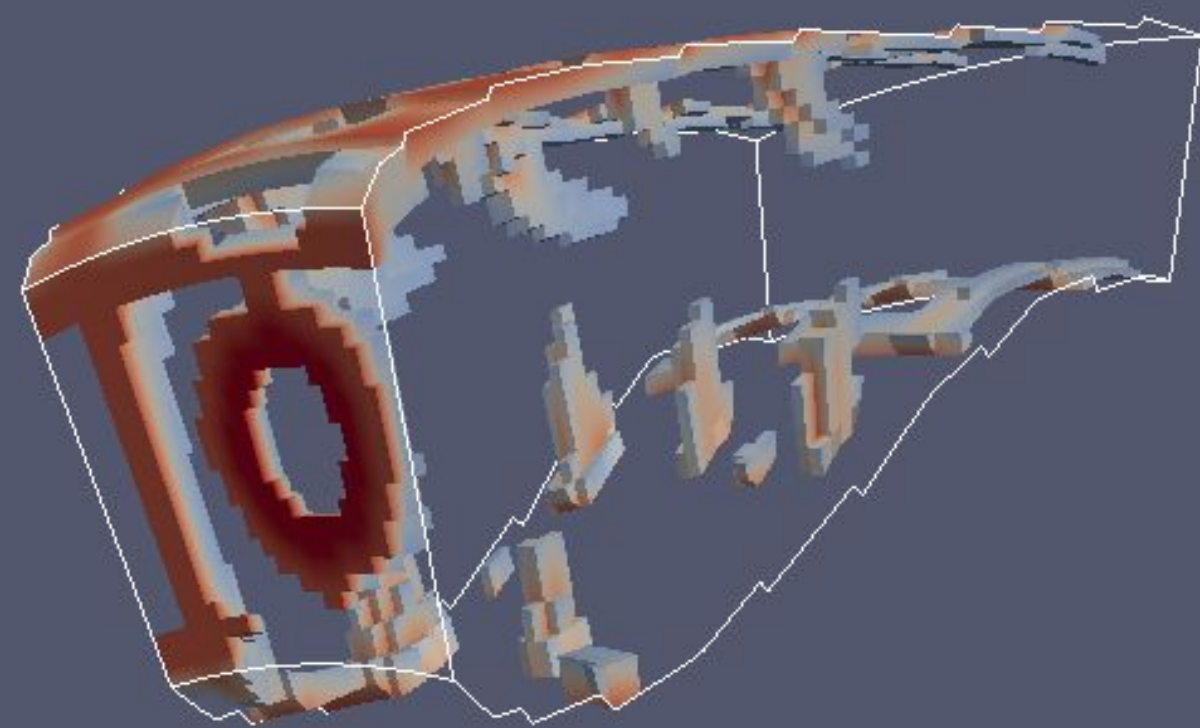


Figure 4: Frame 20 of the visualization

***Visualize data
values on the
surface of a volume***

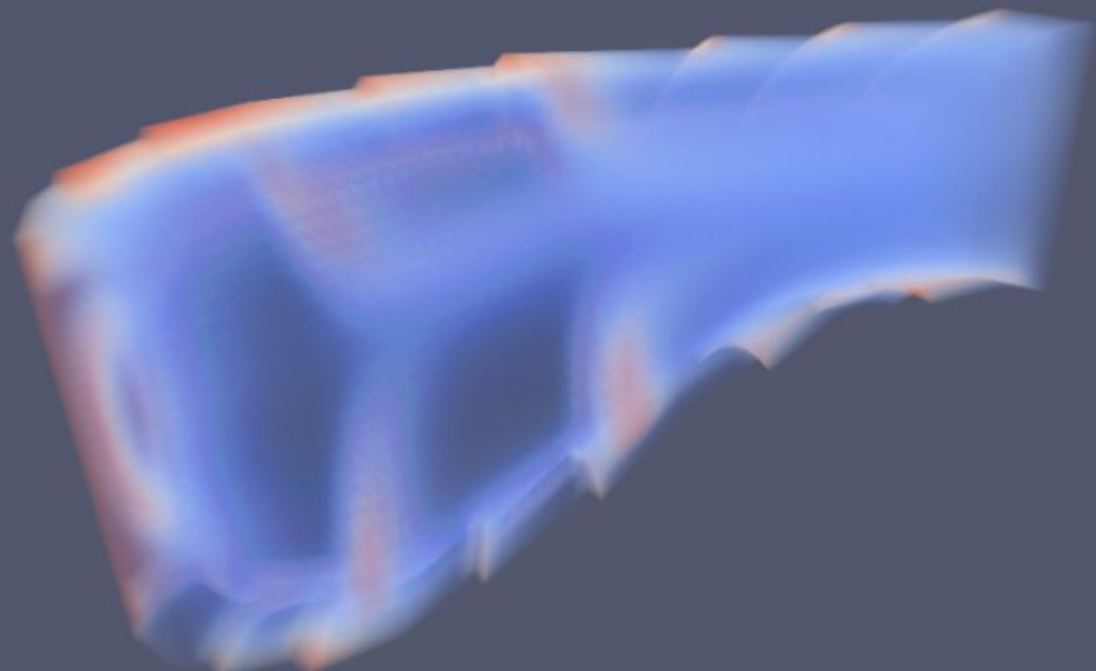
Using VTK HW - Elsa



*Threshold and
show/hide cells*

Transparency

Using VTK HW - Artem

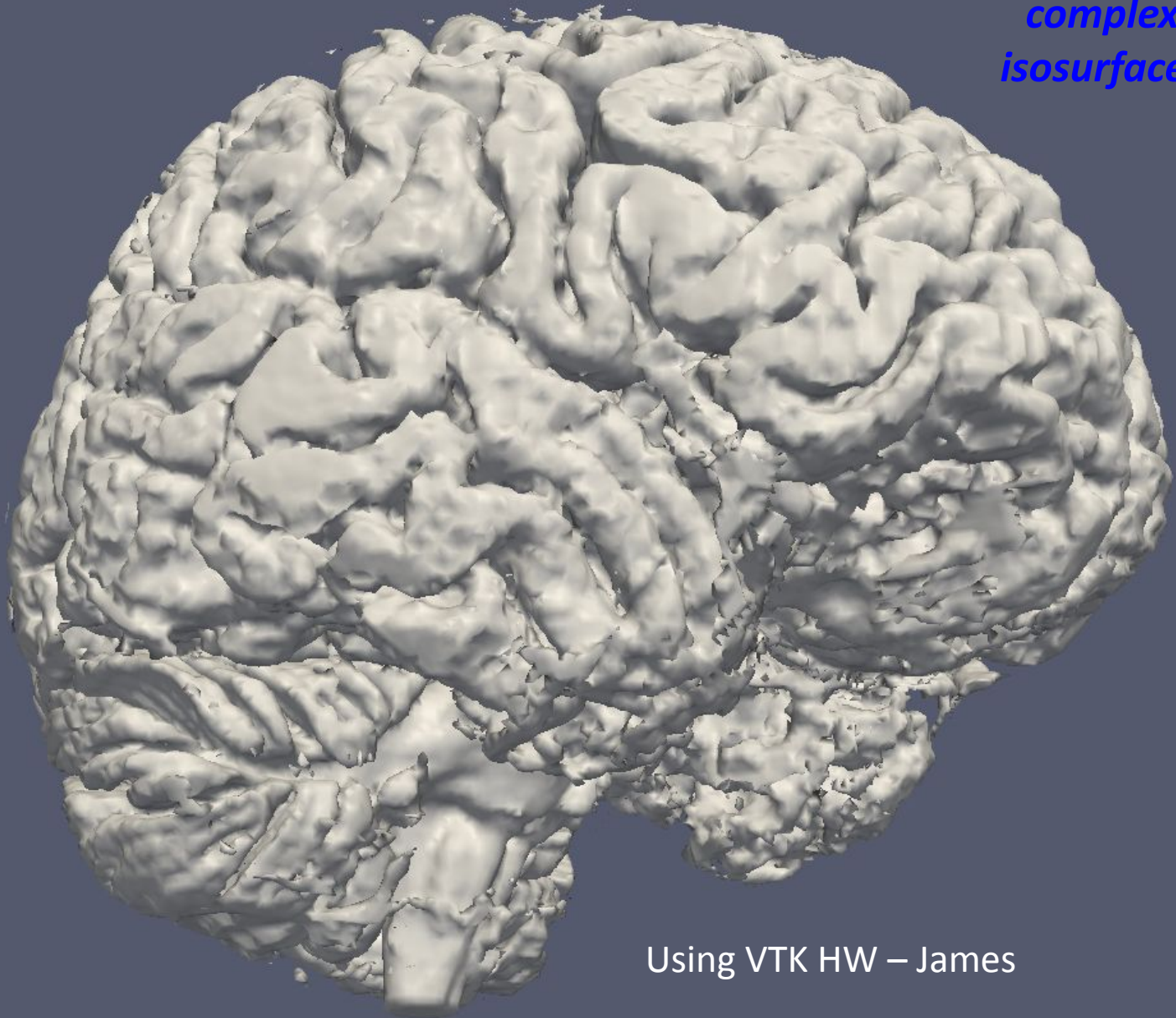




*Well-positioned
cutting planes to
reveal interior*

Using VTK HW - Cagri

*Extraction of
complex
isosurfaces*



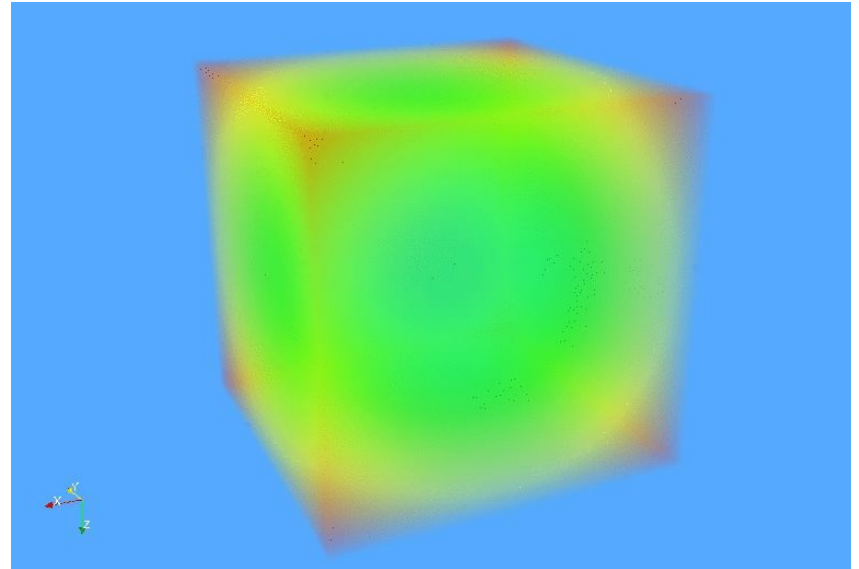
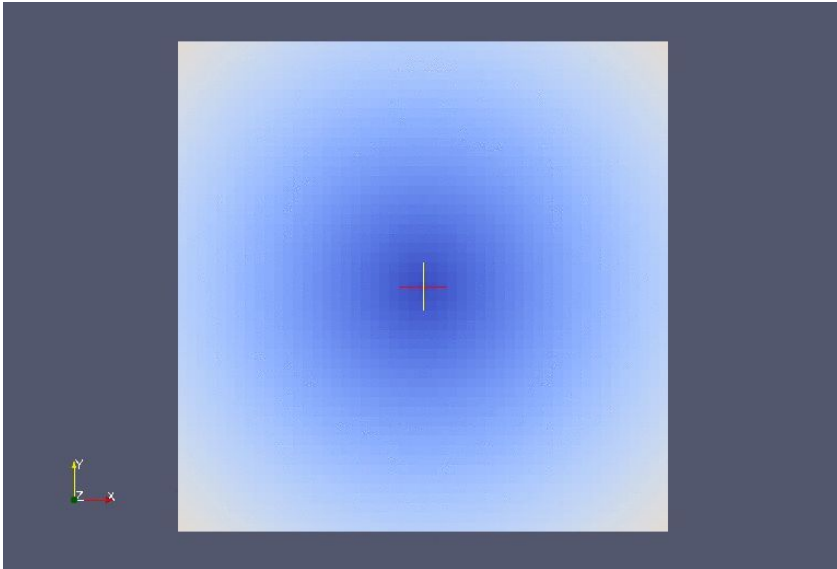
Using VTK HW – James

Today

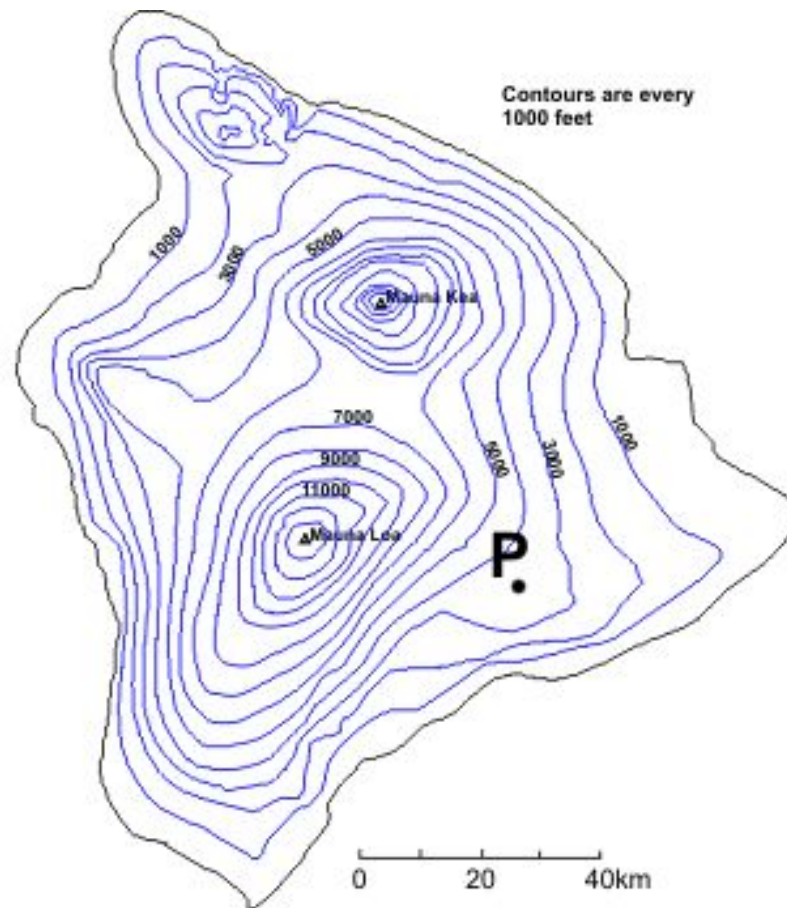
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- Readings for Friday

Isocontours / Isosurfaces

- "iso-" (from Greek word meaning 'equal')
- Determine everywhere in a data set that the data equals a specified value



Contour Map



https://www.e-education.psu.edu/meteo3/l1_p10.html

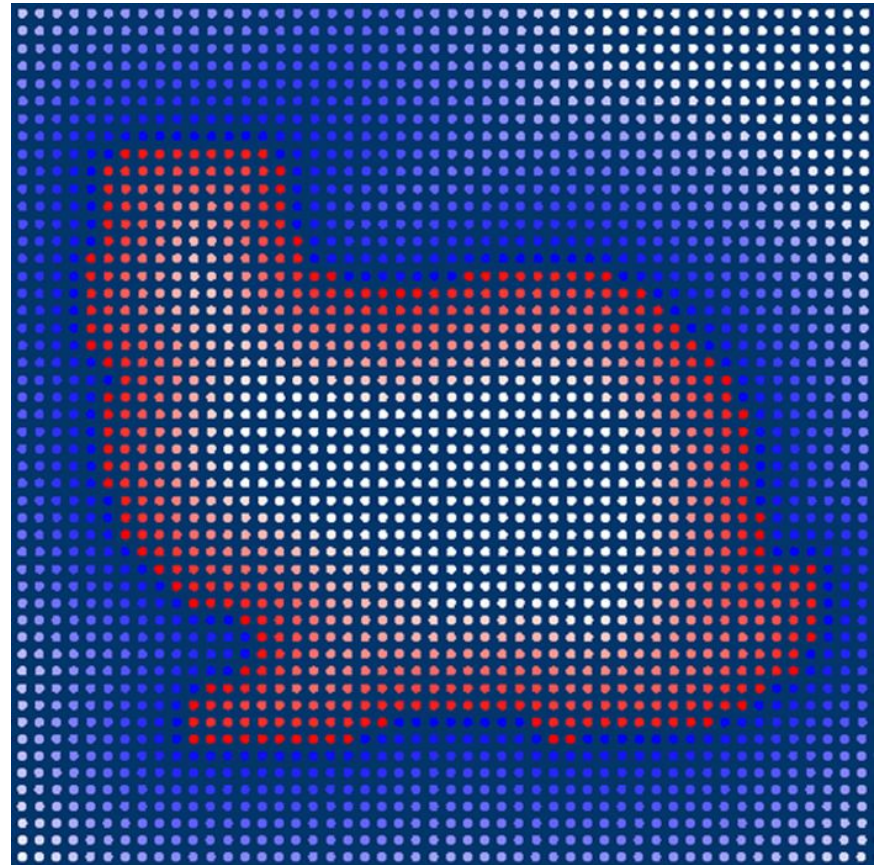
Implicit Surfaces

*Normally we focus on modeling
surfaces with triangle meshes
separating “inside” from “outside”*

- For a sphere:

$$H(x,y,z) = x^2 + y^2 + z^2 - r^2$$

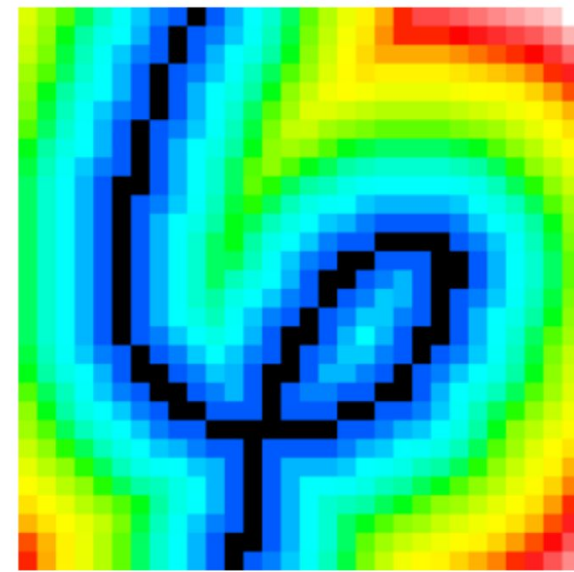
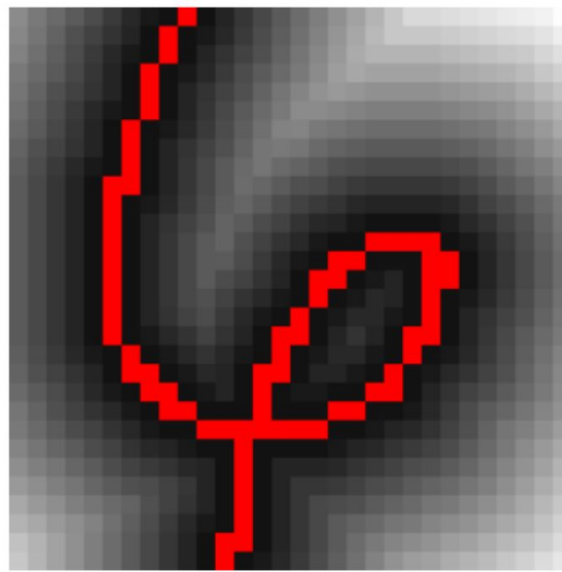
- If $H(x,y,z) = 0$,
on surface
- If $H(x,y,z) > 0$,
outside surface
- If $H(x,y,z) < 0$,
inside surface



Computing a Signed Distance Field

- Given a shape/surface
- Cost to compute shortest distance to original shape for each point (on a grid) in the volume?

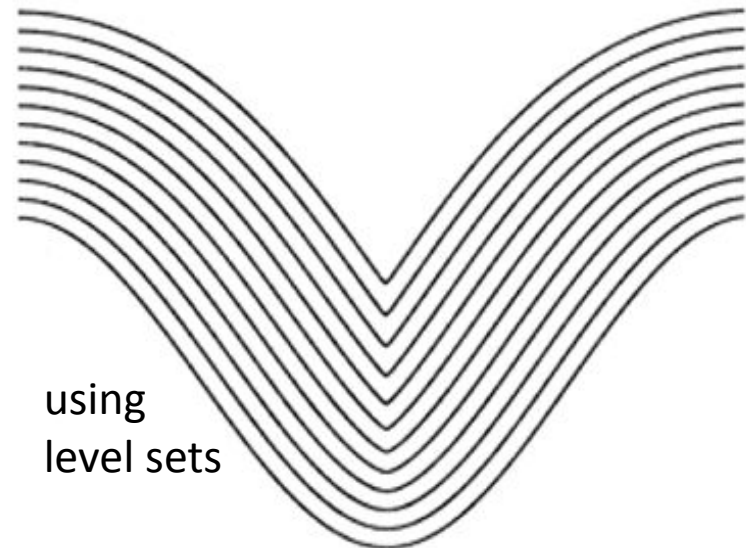
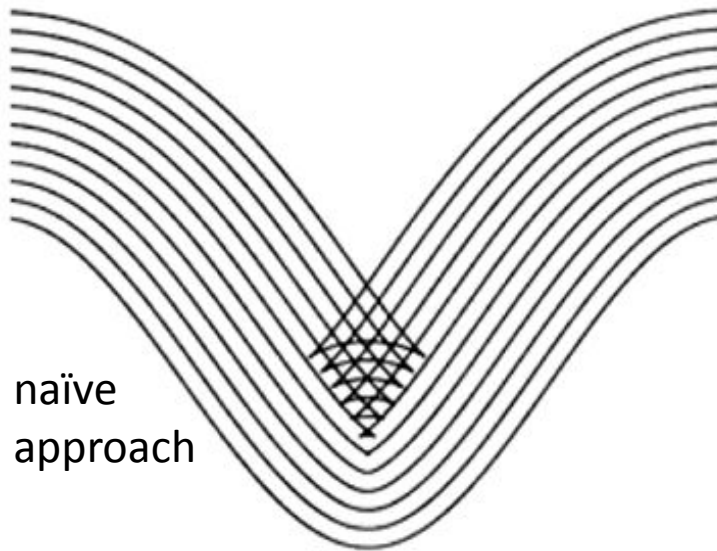
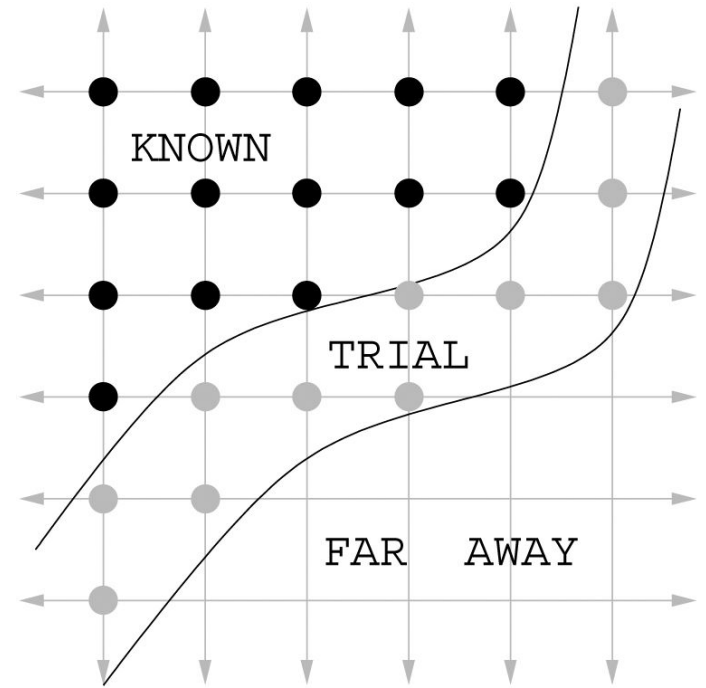
*Naive: $O(\text{\# of volume grid samples} * \text{\# of surface elements})$*



Level Sets

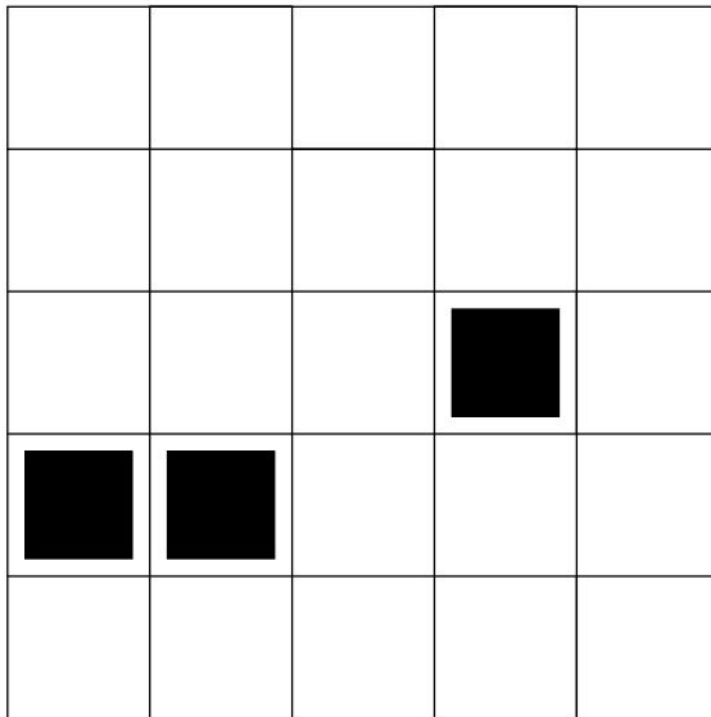
- Efficient method for computing signed distance field

*Level Set Methods and
Fast Marching Methods,*
Sethian, 1999



A Data Structures Homework

https://www.cs.rpi.edu/academics/courses/fall18/csci1200/hw/10_level_sets/hw.pdf



input image










∞ 4,0	∞ 4,1	∞ 4,2	∞ 4,3	∞ 4,4
∞ 3,0	∞ 3,1	∞ 3,2	∞ 3,3	∞ 3,4
∞ 2,0	∞ 2,1	∞ 2,2	0 2,3	∞ 2,4
0 1,0	0 1,1	∞ 1,2	∞ 1,3	∞ 1,4
∞ 0,0	∞ 0,1	∞ 0,2	∞ 0,3	∞ 0,4

initialization of the
signed distance field

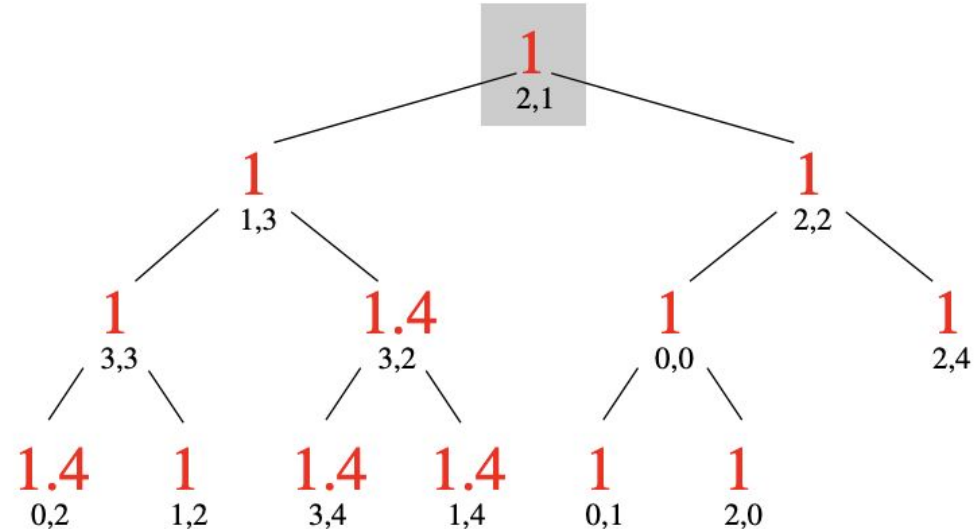
Initially, only the surface pixels are “known” to have distance = 0

A Data Structures Homework

We compute the distance of all neighbors of these “known” pixels

 4,0	 4,1	 4,2	 4,3	 4,4
 3,0	 3,1	1.4 3,2	1 3,3	1.4 3,4
1 2,0	1 2,1	1 2,2	0 2,3	1 2,4
0 1,0	0 1,1	1 1,2	1 1,3	1.4 1,4
1 0,0	1 0,1	1.4 0,2	 0,3	 0,4

propagating initial values

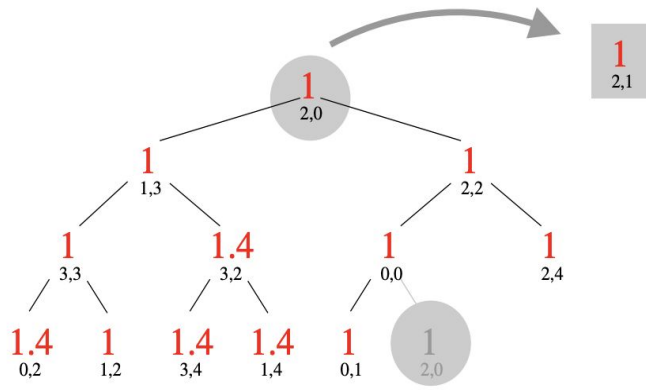


initial priority queue of pixels

Put all these new pixels in a priority queue, ordered by distance

A Data Structures Homework

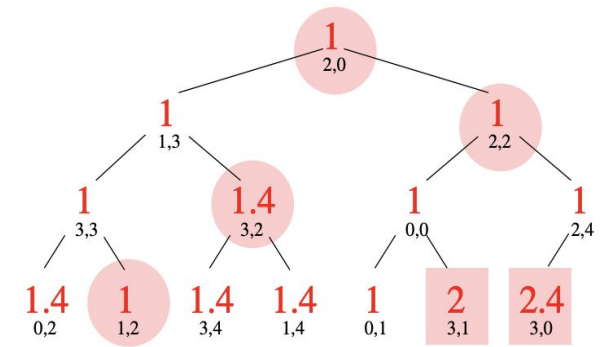
Grab the top item from the priority queue...



after popping & fixing the top value,
grab the last leaf & percolate down

∞ 4,0	∞ 4,1	∞ 4,2	∞ 4,3	∞ 4,4
2.4 3,0	2 3,1	1.4 3,2	1 3,3	1.4 3,4
1 2,0	1 2,1	1 2,2	0 2,3	1 2,4
0 1,0	0 1,1	1 1,2	1 1,3	1.4 1,4
1 0,0	1 0,1	1.4 0,2	∞ 0,3	∞ 0,4

propagate fixed value to neighbors



adjust existing values & add
new values to the priority queue

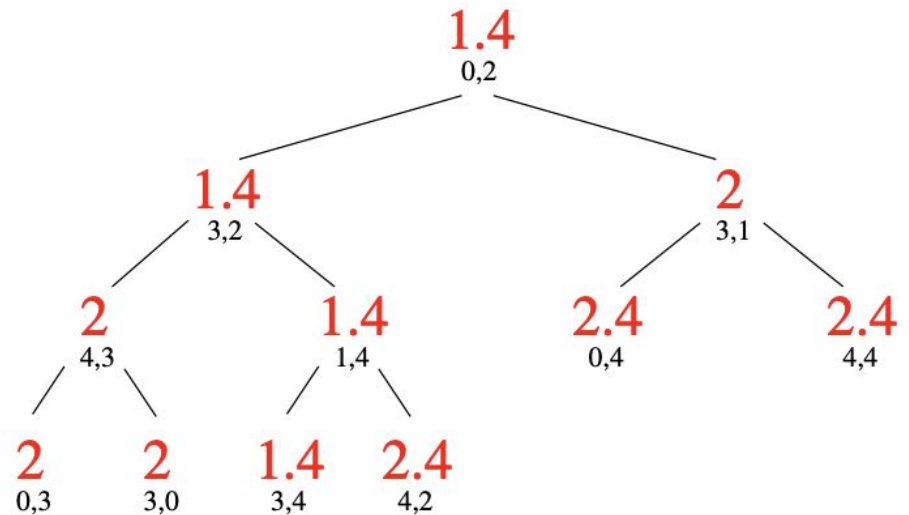
Lock its value, and update its immediate neighbors

A Data Structures Homework

Grab the next pixel in the priority queue and repeat....

∞ 4,0	∞ 4,1	2.4 4,2	2 4,3	2.4 4,4
2 3,0	2 3,1	1.4 3,2	1 3,3	1.4 3,4
1 2,0	1 2,1	1 2,2	0 2,3	1 2,4
0 1,0	0 1,1	1 1,2	1 1,3	1.4 1,4
1 0,0	1 0,1	1.4 0,2	2 0,3	2.4 0,4

after fixing all pixels ≤ 1



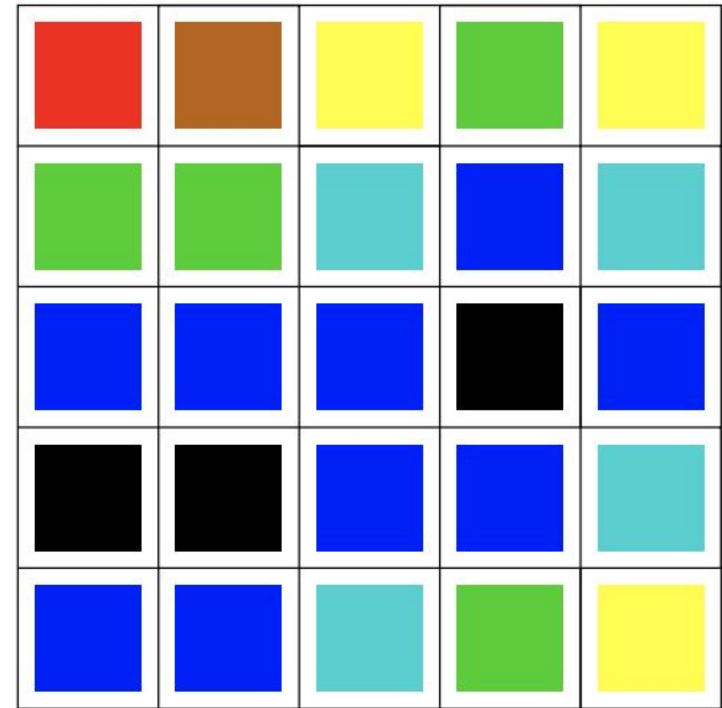
priority queue after fixing all pixels ≤ 1

A Data Structures Homework

Final result: Every pixel stores the (approximate) shortest distance to the original surface (black pixels)

3 4,0	2.8 4,1	2.4 4,2	2 4,3	2.4 4,4
2 3,0	2 3,1	1.4 3,2	1 3,3	1.4 3,4
1 2,0	1 2,1	1 2,2	0 2,3	1 2,4
0 1,0	0 1,1	1 1,2	1 1,3	1.4 1,4
1 0,0	1 0,1	1.4 0,2	2 0,3	2.4 0,4

final distance field

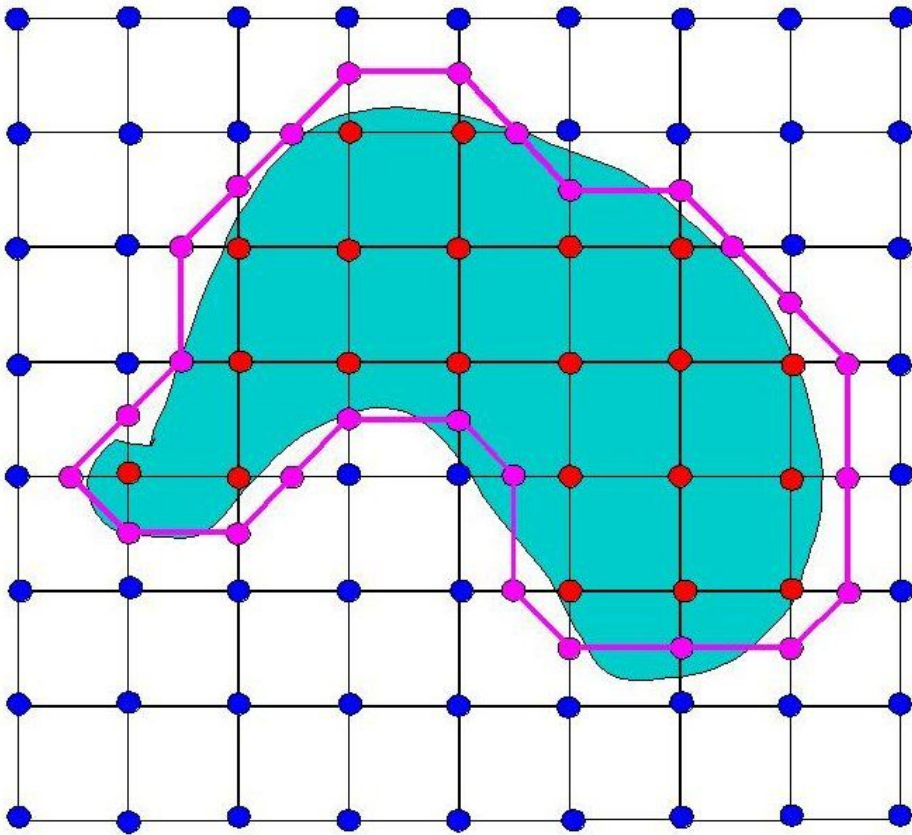


output image

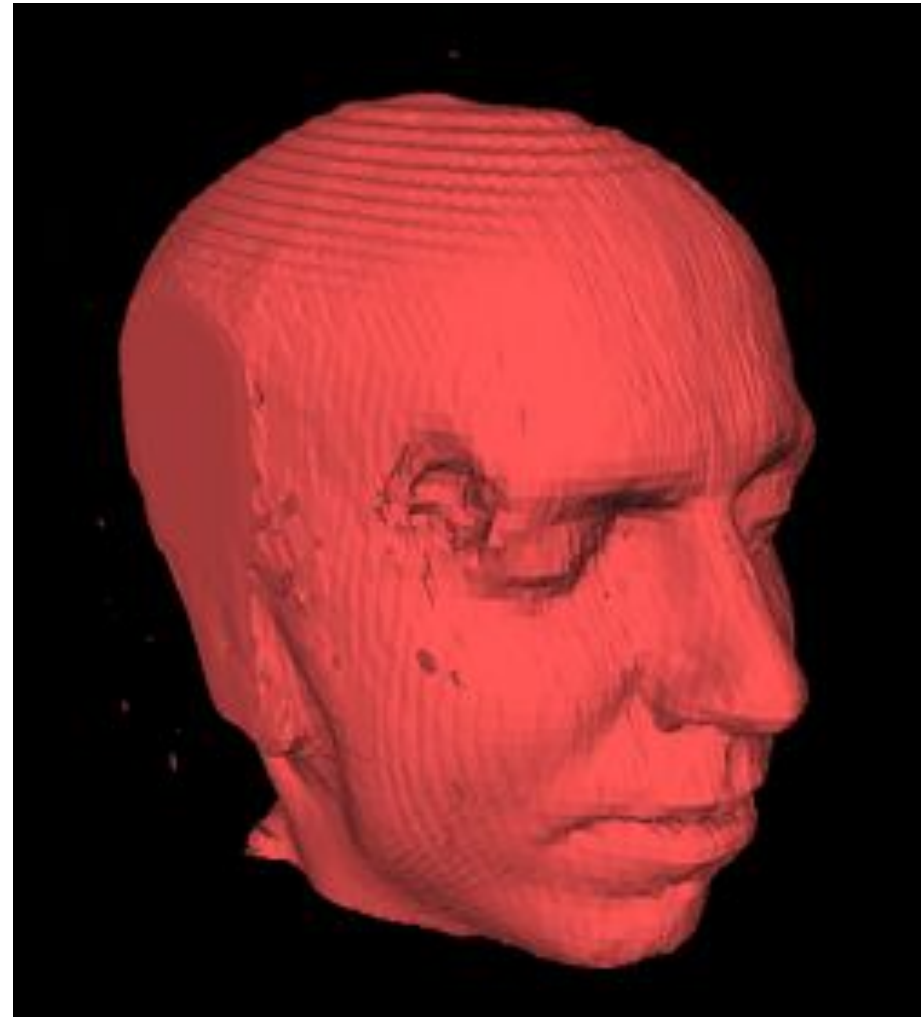
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Marching Cubes



[http://www.cs.carleton.edu/
cs_comps/0405/shape/marc
hing_cubes.html](http://www.cs.carleton.edu/cs_comps/0405/shape/marching_cubes.html)

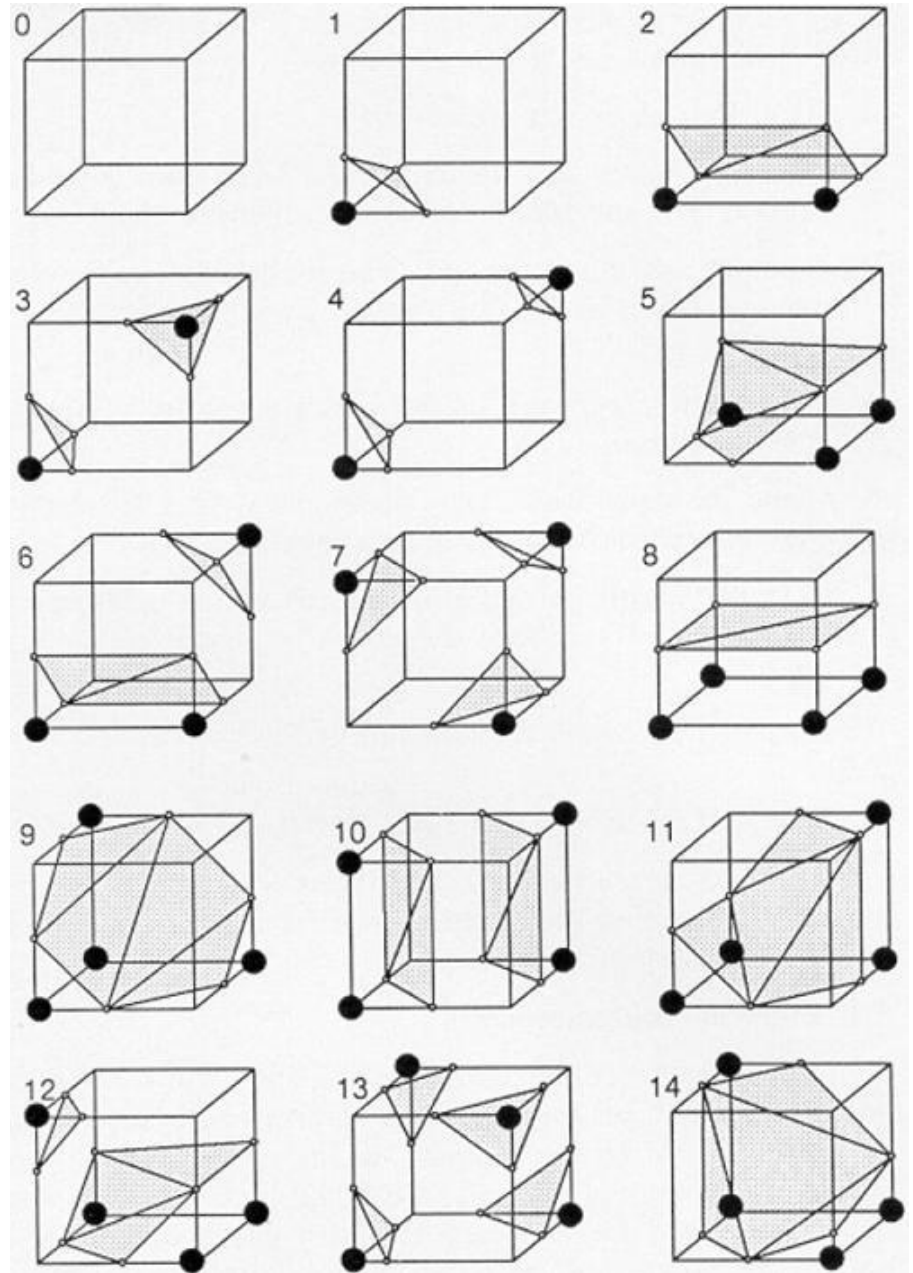


[http://en.wikipedia.org/
wiki/Marching_cubes](http://en.wikipedia.org/wiki/Marching_cubes)

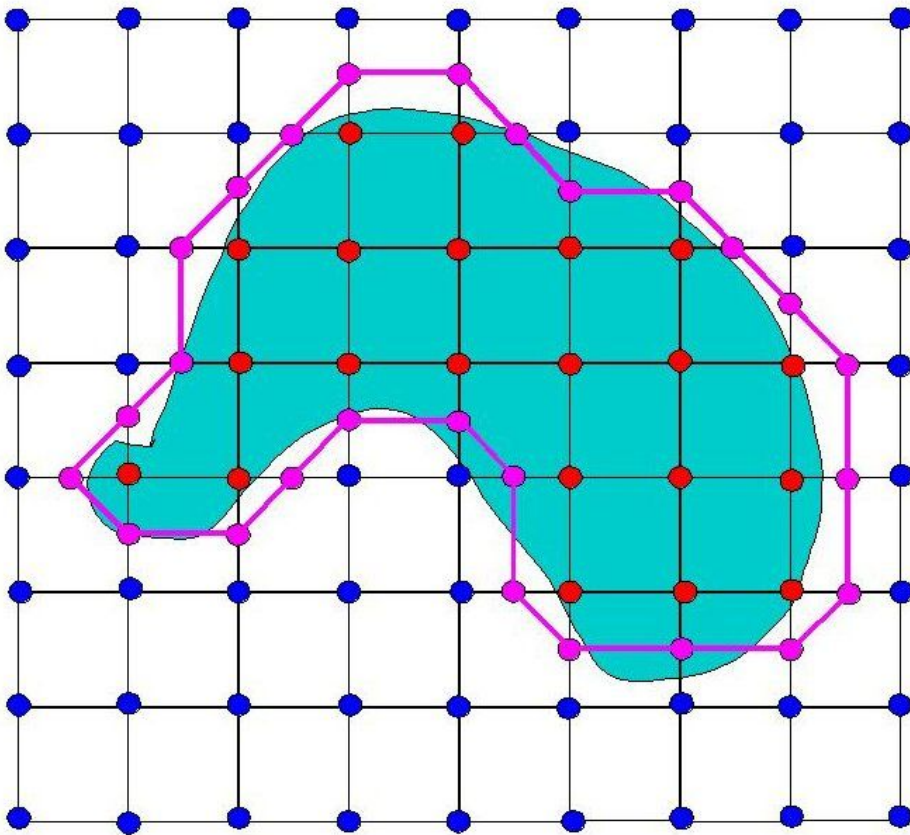
Marching Cubes

- Polygonization:
extract triangle
mesh from signed
distance field

"Marching Cubes: A High Resolution 3D
Surface Construction Algorithm",
Lorensen and Cline, SIGGRAPH '87.



Note about Marching Cubes



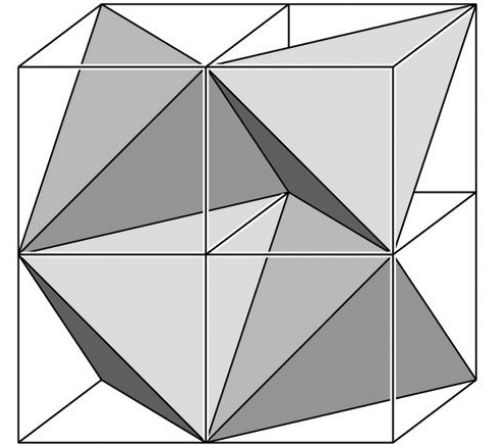
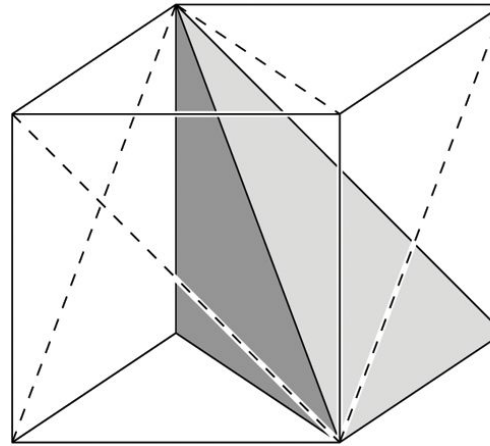
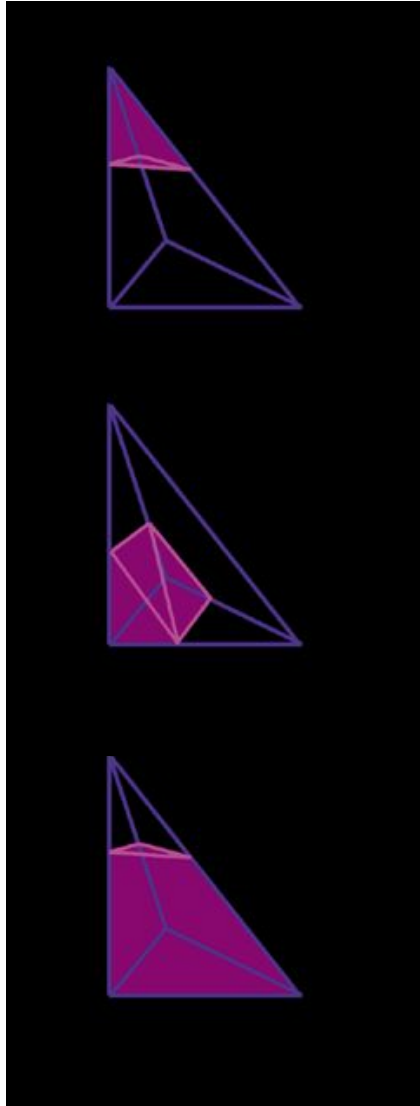
- If the grid points are only boolean data, labeling “inside” vs. “outside” the marching cubes surface will simply **bisect** each cell boundary
- If we have floating point “signed distance from surface” values, we can interpolate those values and position the iso-surface for a specific value more accurately

... Worksheet for Friday

[http://www.cs.carleton.edu/
cs_comps/0405/shape/marc
hing_cubes.html](http://www.cs.carleton.edu/cs_comps/0405/shape/marching_cubes.html)

“Marching Tetrahedra”

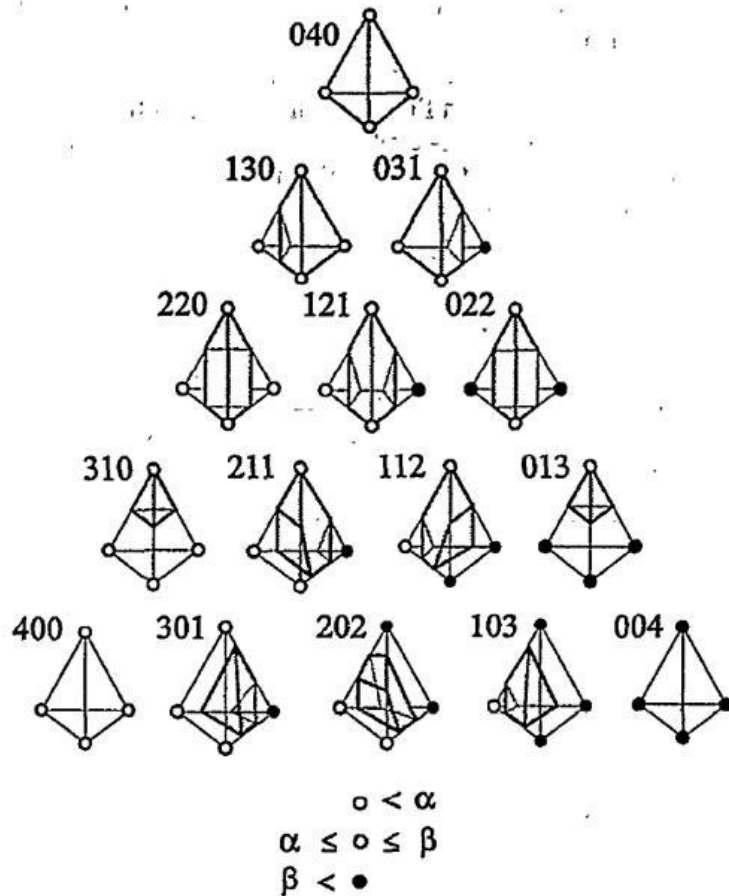
Jules Bloomenthal
“An implicit surface polygonizer”
Graphics Gems IV



“When the Blobs Go
Marching Two by Two”,
Jeff Lander, Gamasutra

“Marching Tetrahedra”

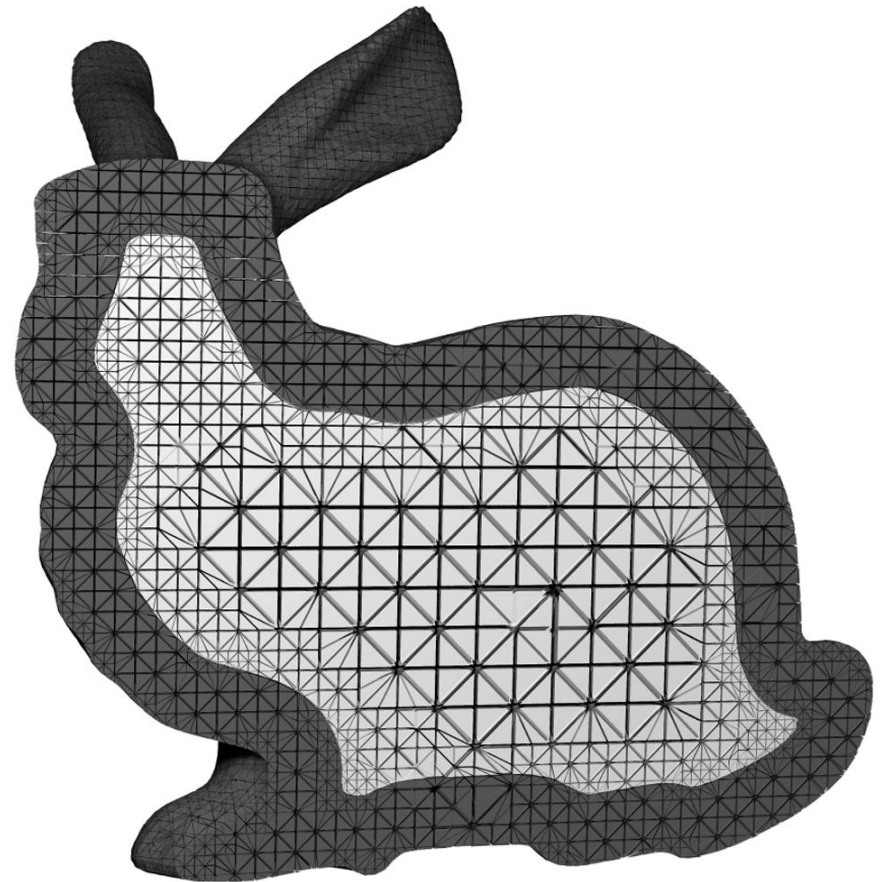
Similarly, we can create volumetric models:



“Interval volume tetrahedrization”

Visualization '97

Nielson & Sung



Today

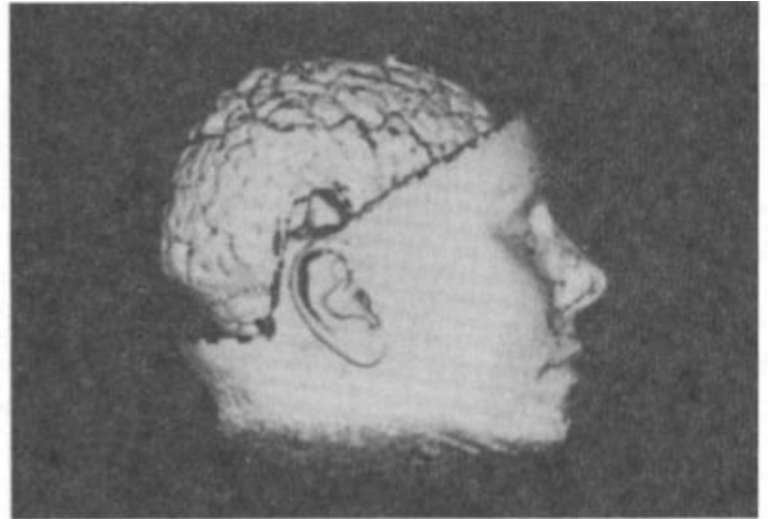
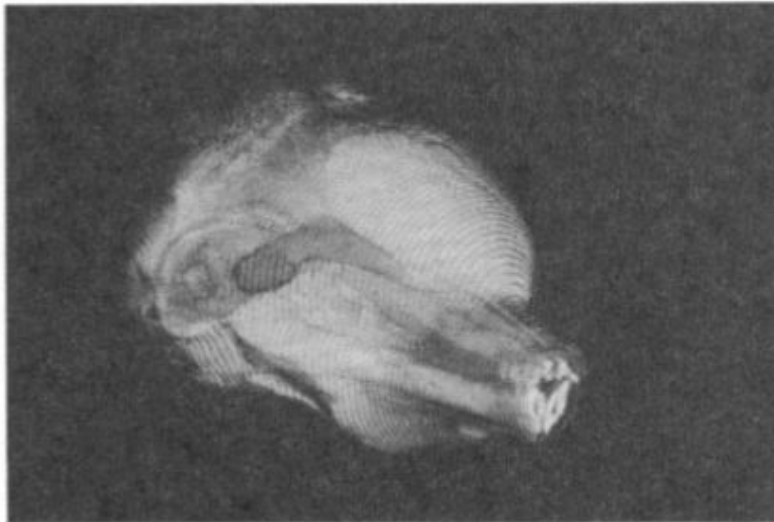
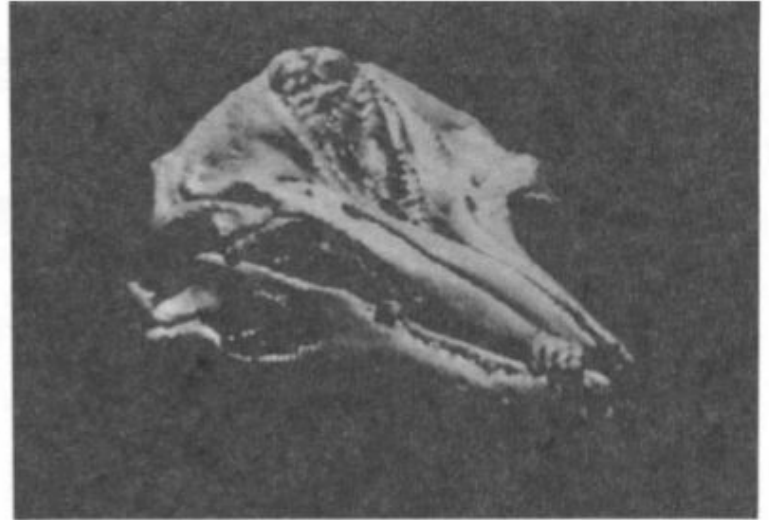
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A Reading From Past Terms...

- “A survey of algorithms for volume visualization”, T. Todd Elvins, 1992



- Applications in: Geoscience, astrophysics, chemistry, microscopy, mechanical engineering, non-destructive testing
- Types of data: Density, pressure, temperature, electrostatic charge, velocity
- Sources of data: MRI, CT, PET, Sonogram, Laser scan confocal & other microscopes, simulation, created by-hand
- Data is on a 3D lattice, with 1 or more values at each grid point
- Animation is critical: from a static 2D image, it is hard to understand 3D information
- "... in 10 years, all rendering will be volume rendering"
Jim Kajiya at SIGGRAPH '91

- Steps in all volume visualization methods
 - Data acquisition
 - Slice pre-processing (adjust contrast, etc)
 - Resample/interpolate (as needed) to proportional 3D volume/grid
 - Data classification (a.k.a. thresholding)
 - Add external elements (e.g., radiation treatment plan, etc.)
 - Mapping to geometric or display primitives
 - The key difference between volume visualization algorithms*
 - Store, manipulate, transform, shade, display to screen
- Traversal orders: image order (scanline) and object order (front-to-back or back-to-front)
- Orthographic (better for DVR) vs perspective
- Photorealism?

Challenges

- Choosing appropriate threshold values & Choosing appropriate color & opacity tables
 - Highly dependent on dataset! Examine data, chose initial values, visualize, adjust values, repeat
- Avoid rendering artifacts/errors that mislead to incorrect medical diagnoses
- Resolution vs. rendering speed vs. accuracy/errors
- Future work: parallelization, automate data classification, make real-time

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Readings for Today:

- “Interactive Dynamic Volume Illumination with Refraction and Caustics”
Magnus & Bruckner,
IEEE TVCG 2017

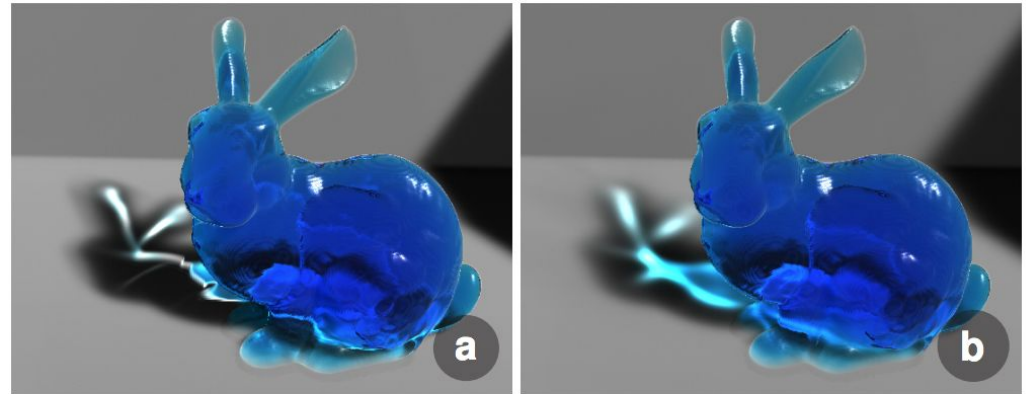


Fig. 3: Effects of light filtering. (a) No filtering. (b) Filtering of light and light direction.

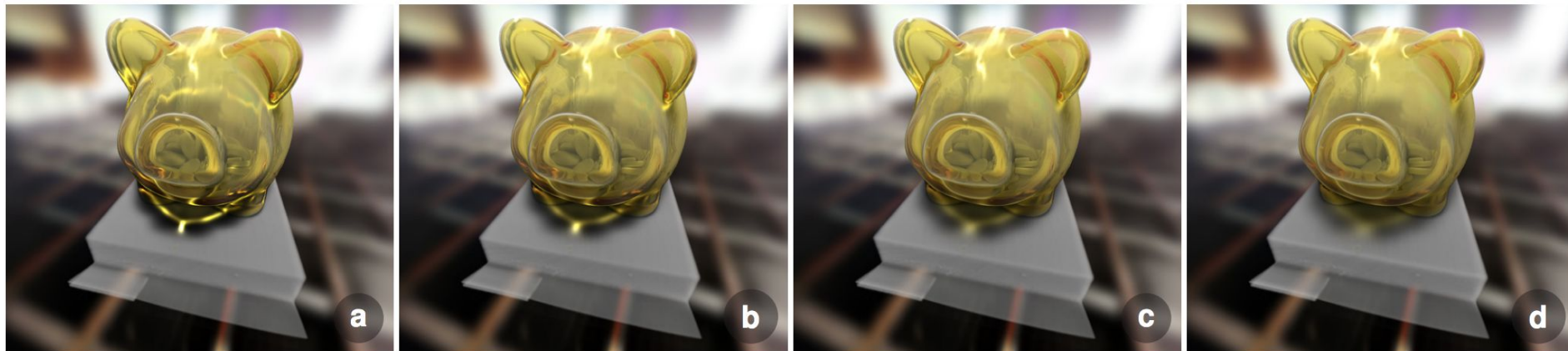


Fig. 7: CT scan of a piggy bank with refraction and combination of transmissive and reflective material properties and increasing light source softness from (a) to (d).

- Snell's law!
- The rendering equation!
- Wyman's GPU trick for approximate single object refraction...
- Parameters:
 - Medium color
 - density of reflective particles
- "... it is not our goal to accurately simulate light transport in participating media, but rather to achieve plausible results at interactive frame rates ..."

Provides more choices/tools for the visualization designer: opacity vs. medium color

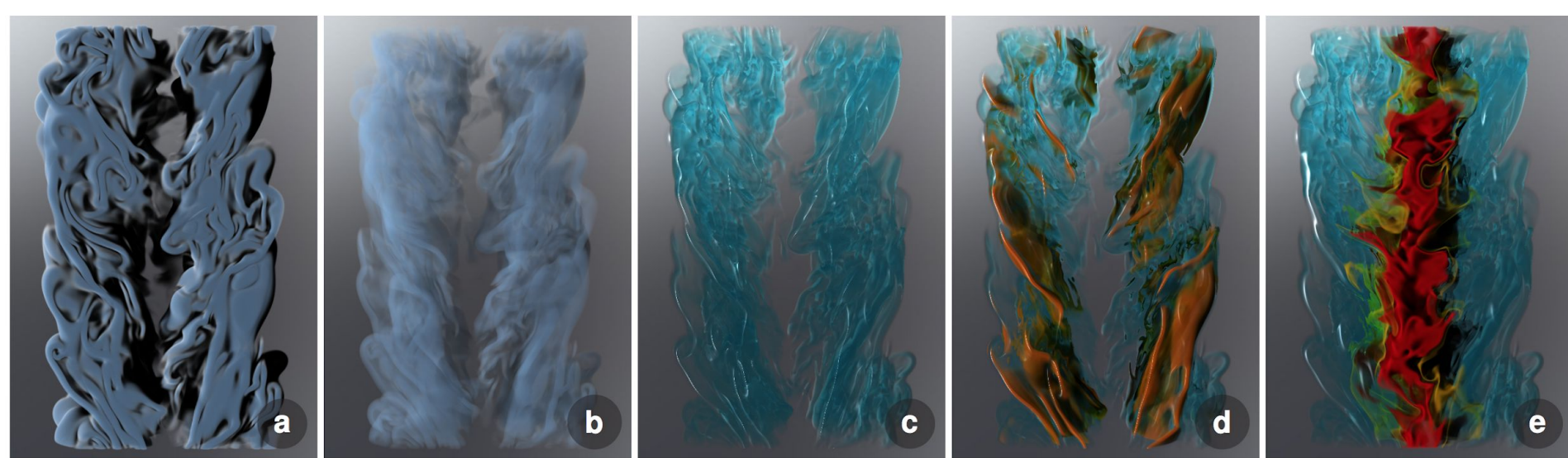
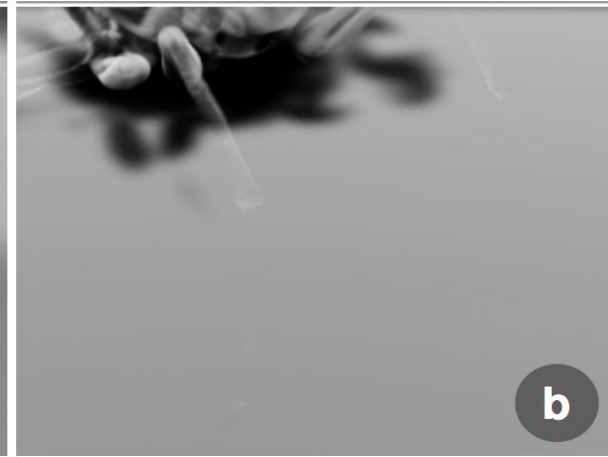
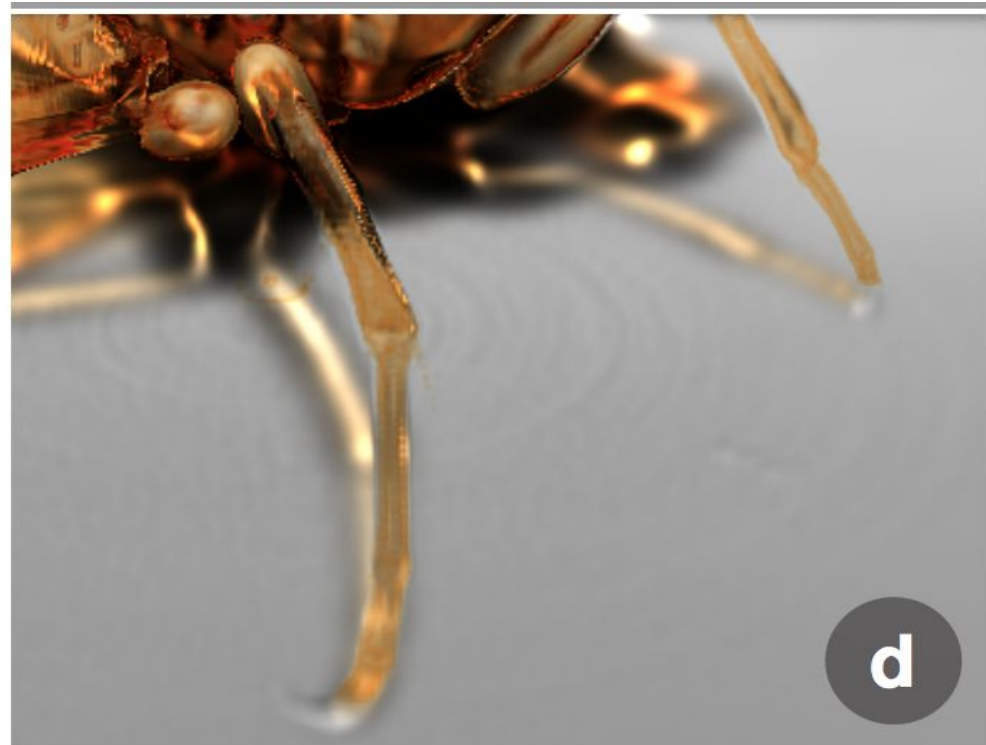


Fig. 12: A timestep of a combustion simulation. In (a) and (b), the chi variable is mapped to opacity, while in (c) the index of refraction is used instead, providing an overview visualization without introducing occlusion. (d) Reflective and refractive properties are combined to selectively highlight higher values. (e) Reflective properties are used to show the mixture fraction variable instead.

“For some visualization applications, the effects of refraction may be undesirable.”



“perception literature show that refractive effects can improve the perception of transparent structures”



Harvard's Glass Flowers



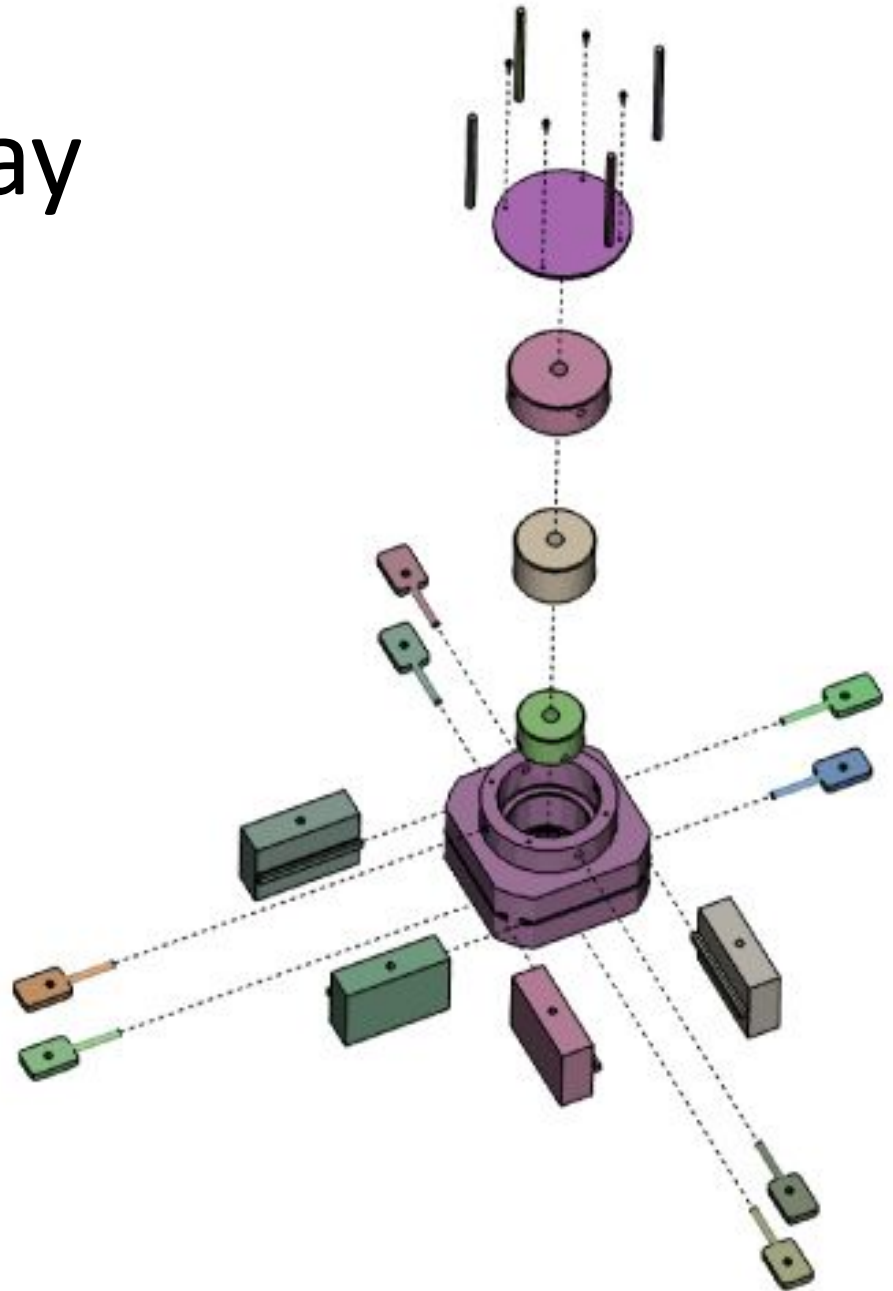
<https://gardeninggonewild.com/glass-flowers-of-harvard/>
<https://hmn.harvard.edu/glass-flowers>

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Reading for Tuesday

- “Designing Effective Step-by-step Assembly Instructions”
Agrawala, Phan,
Heiser, Haymaker,
Klingner,
Hanrahan, & Tversky,
SIGGRAPH 2003



Homework Assignment 8:

Volume Visualization Using Paraview

- *The last non-final project assignment*
- Download and experiment with Paraview...
- which is based on VTK: The Visualization Toolkit...
- from Kitware, and open-source software company *in Clifton Park, NY -- just north of RPI!*
- Start with the Paraview Tutorial & sample datasets
- Experiment with settings, take screenshots
- Try your hand at creating your own input dataset
 - generated input is probably easiest
 - or construct a real-world dataset!
- Write a short review of the tool

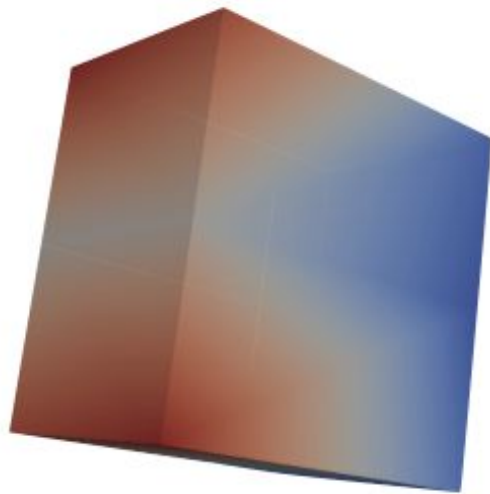


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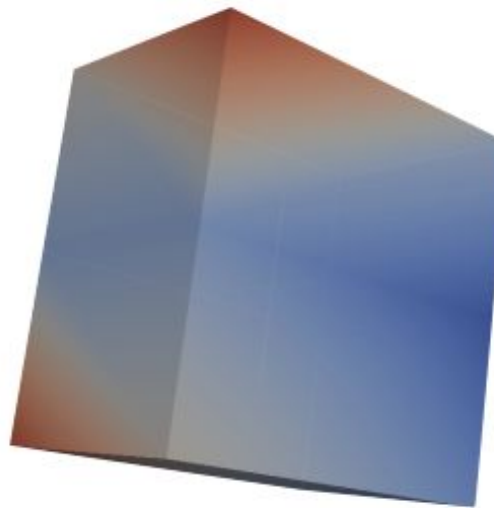


Figure 3: Frame 19 of the visualization

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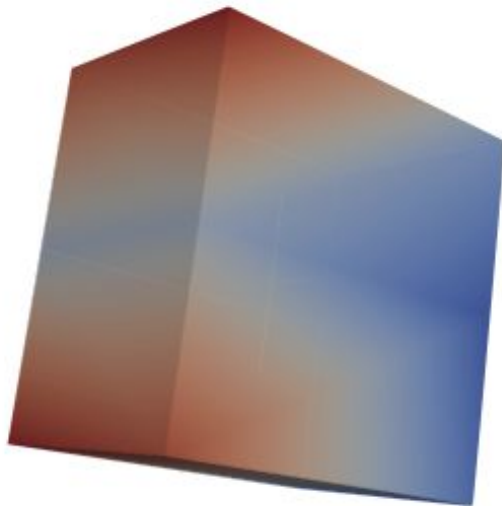


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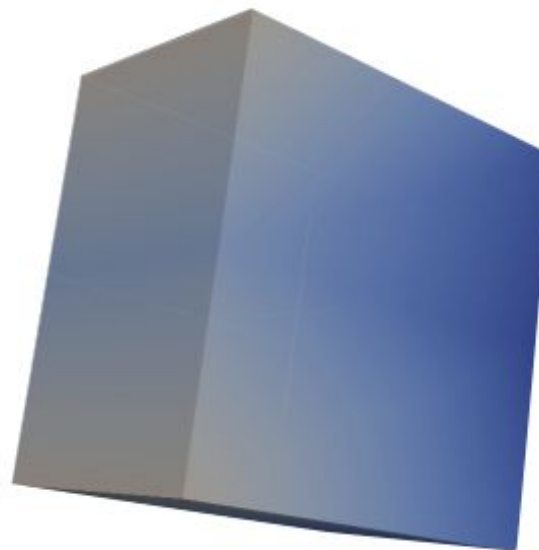
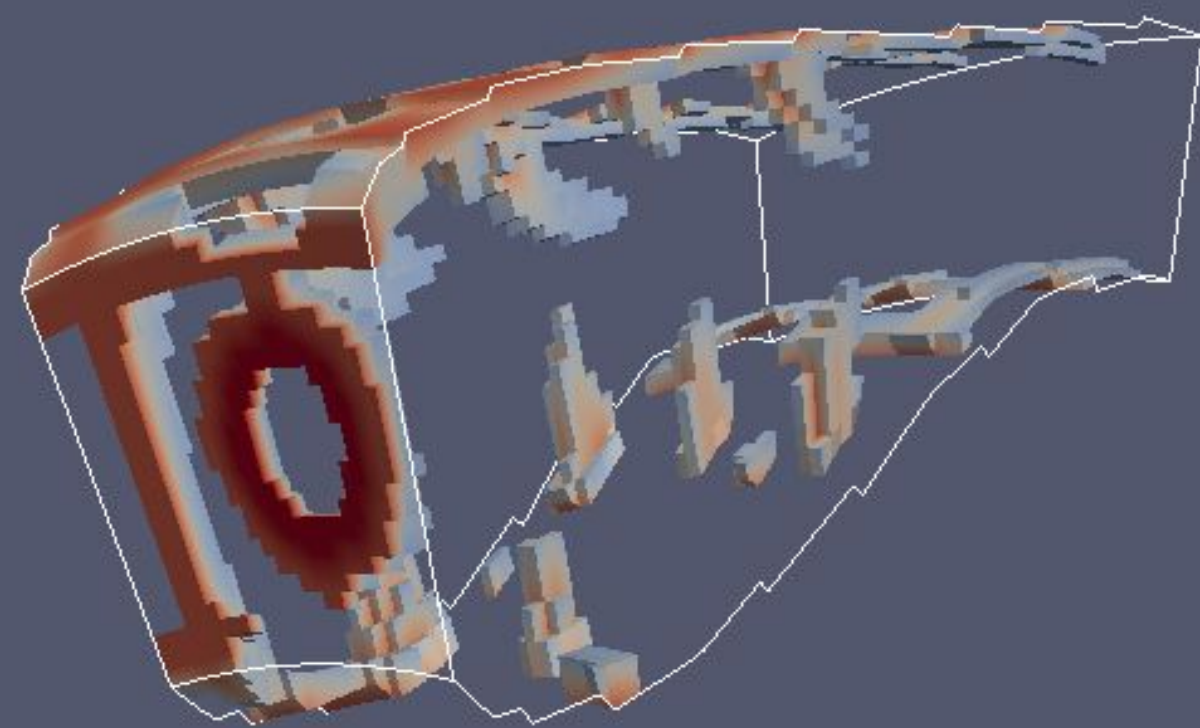


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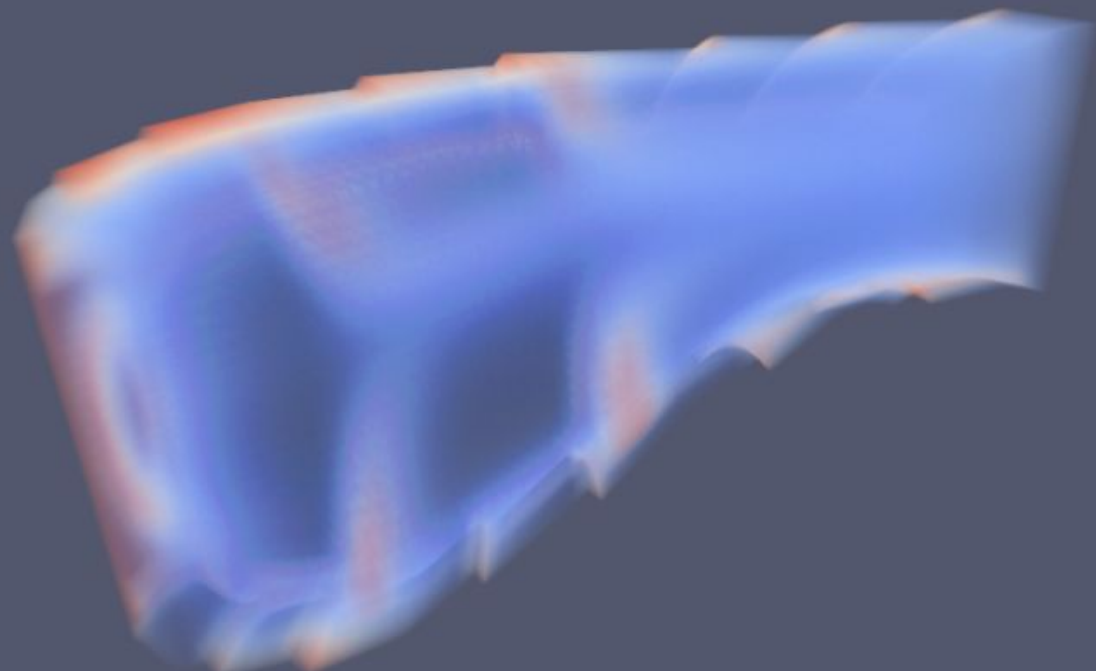
Using VTK HW - Elsa



*Threshold and
show/hide cells*

Transparency

Using VTK HW - Artem

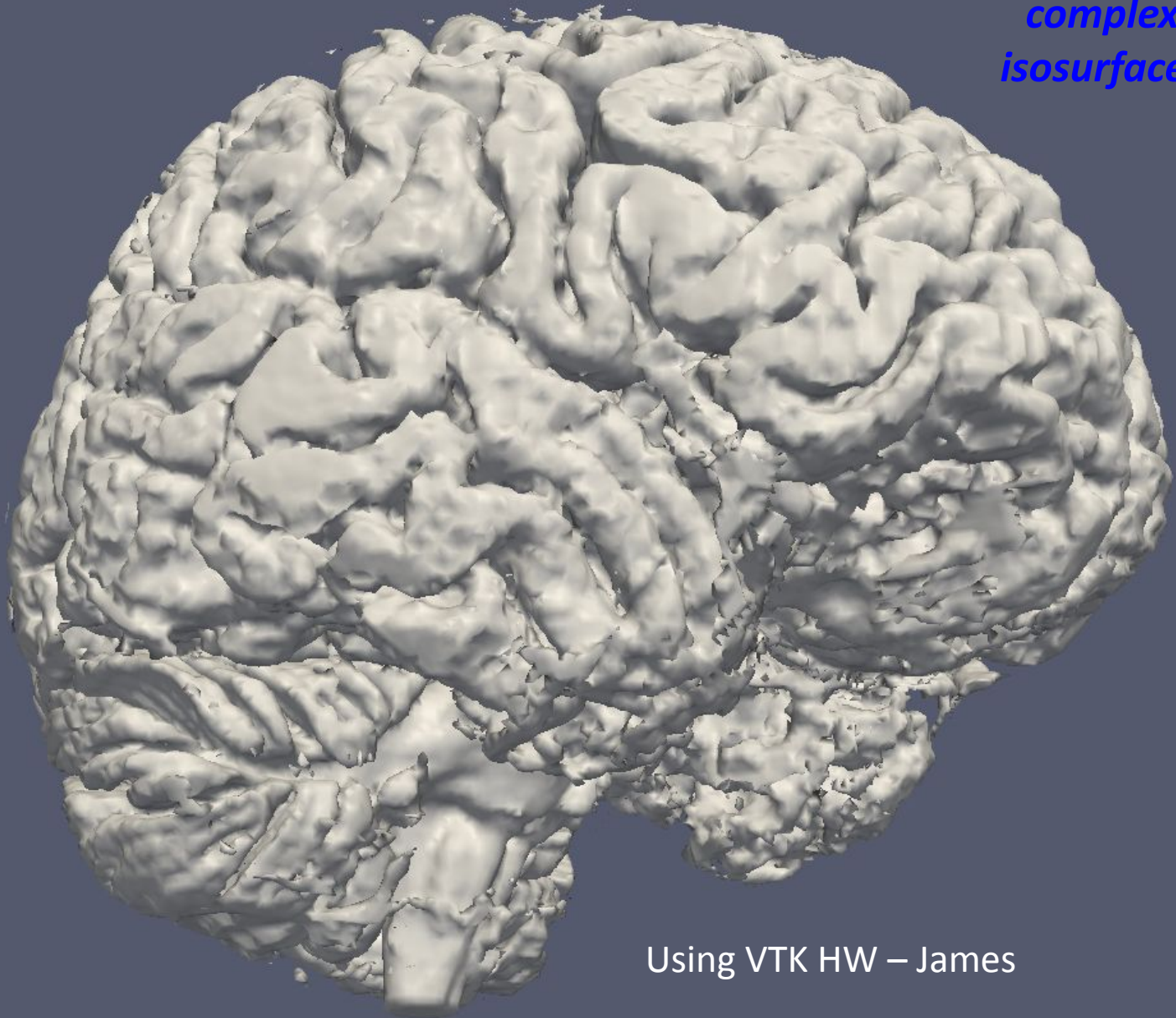




*Well-positioned
cutting planes to
reveal interior*

Using VTK HW - Cagri

*Extraction of
complex
isosurfaces*



Using VTK HW – James