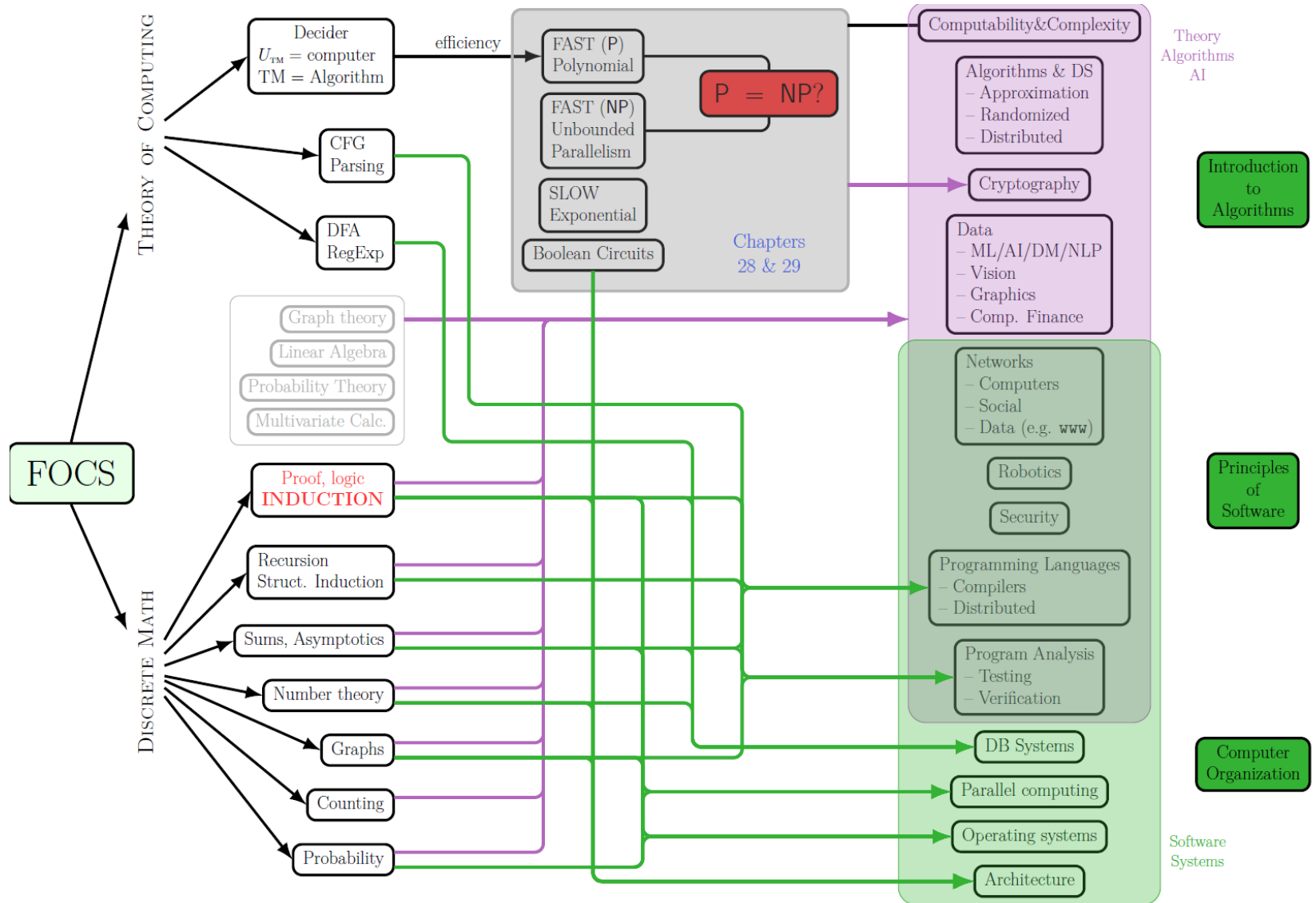


Efficiency

Reading

- Malik Magdon-Ismail. Discrete Mathematics and Computing.
 - Chapter 28

The Path Forward: Focus on Decidable Problems

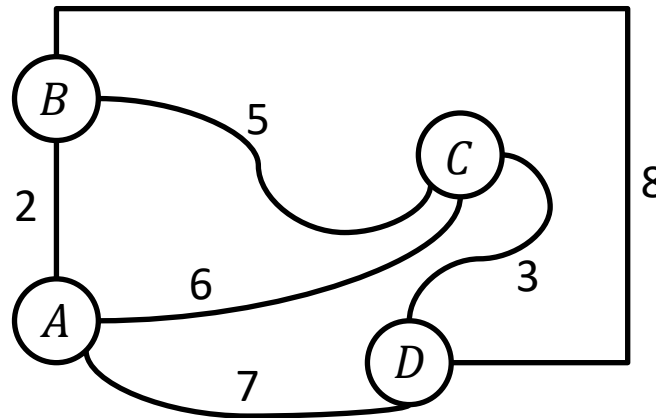


Overview

- Time complexity: Asymptotic worst-case analysis.
- The class P: Efficiently solvable problems.
- Polynomial on one architecture means polynomial on pretty much any architecture.

Running Time

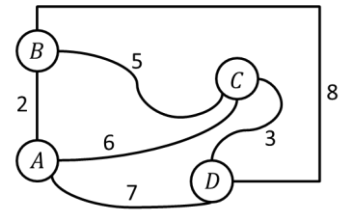
- Suppose you are a traveling salesman
 - You want to visit all cities in your state and sell your stuff
 - Suppose the road network looks like this



- The numbers give the length of each road
- What's the shortest path that starts at *A*, visits each city once, and returns to *A*?
A, B, C, D, A (cost of 17)
- How did you find it?
- Enumerated all possible paths and took the fastest

Running Time, cont'd

- What if we had 50 cities? How many paths would we have to check?
 - There are potentially 49 options for the 1st city, then 48, etc.
 - In total, there are $49!$ paths in a fully-connected graph!
- How many paths are there in a general graph with n nodes?
 - There are $n - 1$ options for the first node, then $n - 2$, etc.
 - In total there are $(n - 1)!$ paths
- Even for 50 cities, checking all paths on a 10GHz computer would take 10^{50} years!
 - The universe is 10^{10} years old...
- There's got to be a faster way to find the optimal path!



Running Time, cont'd

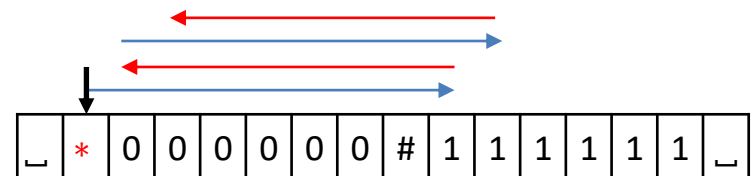
- Efficiently solving a problem, with low runtime, is as important as solving it!
 - I don't care about your algorithm if it will finish after there is no more Earth!
- How do we analyze algorithms?
- Let's look at our Turing Machine for balanced strings

$M = \text{Turing Machine that solves } \{0^k \# 1^k\}$

Input: Binary string w

1. Check that input has the correct format and return to *
2. Match each 0 left of # with a 1 right of #
3. If a match fails or there are more 1s, REJECT. Otherwise ACCEPT

- How fast is that algorithm?
 - Hard to tell from this high-level sketch
 - Machine is in reality doing a zig-zag



Running Time, cont'd

- Let's be more specific with our step 2:

$M = \text{Turing Machine that solves } \{0^{\bullet k} \# 1^{\bullet k}\}$

Input: Binary string w

1. Check that input has the correct format and return to *
 2. Match each 0 left of # with a 1 right of #
 - Move right and mark the first unmarked 0 (if none, GOTO step 3)
 - Move right and mark the first unmarked 1 (if none, REJECT)
 - Move left until you come to a marked 0.
 3. If a match fails or there are more 1s, REJECT. Otherwise ACCEPT
- Now we can at least count how many operations each step takes depending on string size

Time Complexity

- To analyze the runtime of M , we must specify the input

$M =$ Turing Machine that solves $\{0^k \# 1^k\}$

Input: Binary string w

1. Check that input has the correct format and return to *
2. Match each 0 left of # with a 1 right of #
 - Move right and mark the first unmarked 0 (if none, GOTO step 3)
 - Move right and mark the first unmarked 1 (if none, REJECT)
 - Move left until you come to a marked 0.
3. If a match fails or there are more 1s, REJECT. Otherwise ACCEPT

- Runtime increase with the input size. What size input shall we take?
- Runtime can vary within inputs of the same size. What do we do about this?
- **Worst case analysis!**
 - This is the norm in computer science
 - How does our algorithm perform over the worst possible input

Worst Case Analysis

- The steps to get the worst case runtime are:
 1. Fix the size of the input to n and identify the worst input w_* of size n
 2. Determine the runtime for the input w_* . This worst case runtime will depend on n
- To determine the runtime, recall the definitions

$$T \in o(f)$$

$$"T < f"$$

$$T \in O(f)$$

$$"T \leq f"$$

$$T \in \Theta(f)$$

$$"T = f"$$

$$T \in \Omega(f)$$

$$"T \geq f"$$

$$T \in \omega(f)$$

$$"T > f"$$

- In practice, inputs are very large, i.e., $n \rightarrow \infty$
 - We care about runtimes in the asymptotic regime
- Additive and multiplicative constants are minor
 - We care about the growth rate of the runtime with n

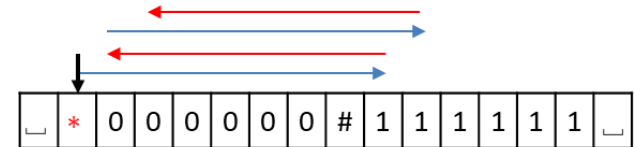
Analyzing the decider for $\{0^k \# 1^k\}$

- How many operations does this machine perform?

$M =$ Turing Machine that solves $\{0^k \# 1^k\}$

Input: Binary string w

1. Check that input has the correct format and return to $*$
2. Match each 0 left of $\#$ with a 1 right of $\#$
 - Move right and mark the first unmarked 0 (if none, GOTO step 3)
 - Move right and mark the first unmarked 1 (if none, REJECT)
 - Move left until you come to a marked 0.
3. If a match fails or there are more 1s, REJECT. Otherwise ACCEPT



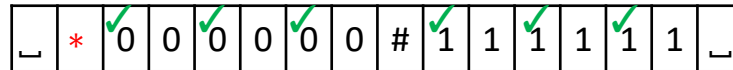
- During step 1, in the worst case, go through the entire input twice
- During step 2, machine zig-zags for each 0
 - For a well-formatted string, there are at most $\frac{n}{2}$ zig-zags and each zig-zag is at most $2n$ steps
- Finally, step 3 takes one full scan
- So in total:

$$\text{runtime} \leq 2n + \frac{n}{2} \times 2n + n$$

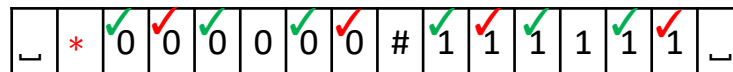
- What is $O(2n + \frac{n}{2} \times 2n + n)$ simplified to?

Can we do better than $O(n^2)$?

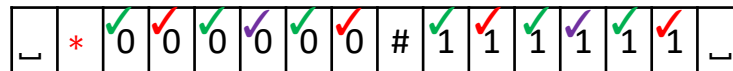
- What if we instead scan every other 0 and then every other 1?



- We cover roughly half the string in a single scan! Then the next scan is similar



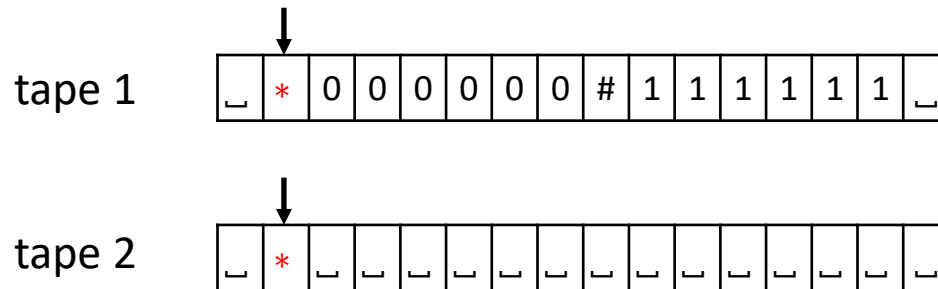
- The final scan completes the last missing 0 and 1



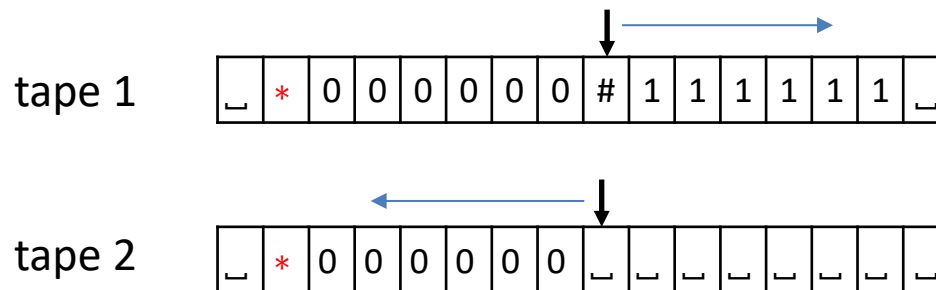
- **Exercise.** Finish the details of this algorithm and prove it is correct
- How many passes does the above algorithm make?
 - Input is halved after each pass, so at most $\log_2 n$
- How long is each pass at most?
 - Can't go further than full input, so n (rough analysis gets you far in algorithm analysis!)
- Total runtime is $O(n \log_2(n))$

Can we do better than $O(n \log_2(n))$? Two Tapes

- Suppose we had a Turing Machine with two tapes
 - Computer scientists like convoluted devices!



- How can we use the second tape?
 - Copy the 0s from tape 1 and then match 1s on tape 1 with 0s on tape 2



- Only need 2 passes now!
 - Runtime is $O(n)$, but we require better hardware

Efficiently Solvable Problems: The Class P

- So far, we've seen three algorithms to decide $\{0^k \# 1^k\}$
 - Brute-force, $O(n^2)$
 - Smart halving algorithm, $O(n \log_2 n)$
 - Fast algorithm using a better architecture, $O(n)$
- Efficiency is all about faster algorithms!
- Contrast with computability
 - There EXISTS NO algorithm for the halting problem!
 - I don't care how many Turing Machines with how many tapes you throw at it
- So when we talk about efficiency, we're talking about decidable problems
- But then you might ask, "Fine, $O(n)$ is faster but is $O(n^2)$ really so bad?"
 - Obviously, it depends on what input sizes you're dealing with
 - If input sizes are in the 1000s, you won't notice a big difference
 - If input sizes are in the 1000000s, you might have to wait a while in one case!

The Class P, cont'd

- Typically, we measure “fastness” with respect to a target function f that we deem to be sufficiently fast
- What choices of f are there?
 - Linear, quadratic, polynomial, exponential
 - Turns out polynomial is a good compromise
- A Turing Machine is **fast** if the worst case runtime is bounded by a function $f(n)$ which increases by at most a constant factor when you double the size of the input from n to $2n$

$$\text{worst-case runtime} \leq f(n) \quad \text{AND} \quad f(2n) \leq \lambda f(n)$$

The Class P, cont'd

- *Theorem [Fast means polynomial]*. A Turing Machine M is fast if and only if its worst-case runtime on an input of size n is in $O(n^k)$, for a constant k .
 - See book for proof.
- *Definition [The Class P]*. A problem \mathcal{L} is in P if there exists a fast, polynomial-time, Turing machine that decides \mathcal{L} . The class P is a set of computing problems, i.e., languages.
- The class P is one of the most important classes in computer science
 - Generally, these are the problems that can be solved for very large inputs
 - Examples include sorting, shortest path, hashing, search...
 - Problems not in P are HARD!!
 - For example, factorization is not known to be in P
 - The main encryption algorithms only work because we don't know how to quickly factorize very large numbers

How About Turing Machines with Two Tapes?

- Already saw that a Turing Machine with two tapes gets us from $O(n \log_2 n)$ to $O(n)$
- So you should be asking yourselves: what if we define P in terms of two-tape Turing Machines?
 - How about 2^{1000} tapes?
- Well, both $O(n \log_2 n)$ and $O(n)$ are polynomial, so they're still in P
 - Adding more tapes didn't bring a "qualitative" change
- *Extended Church-Turing Thesis*. Any efficiently solvable problem can be decided by a fast Turing Machine with a single tape. The class P is independent of Turing Machine architecture.
 - (Within limits – if I can choose number of tapes depending on the input size, then the above doesn't hold)
 - Turns out a single-tape Turing Machine can simulate multi-tape machines in polynomial time (see book)
- The class P is robust. Also, Turing Machines are a very general computing framework

A Decidable Non-Polynomial Problem

- We know that there exists no Turing Machine that can tell us whether a given other Turing Machine will halt
- How about whether another Turing Machine will terminate “fast”?
- Consider the language:

$$\mathcal{L}_{EXP} = \{ \langle M \rangle \# w \mid M \text{ accepts } w \text{ within at most } 2^{|w|} \text{ steps} \}$$

- What is this language?
 - All Turing Machines that run within at most exponential time
- Is this language decidable?
 - Yes, use our simulator Turing Machine U_{TM}
 - Simulate M on each input w for exactly $2^{|w|}$ steps
 - If M terminates and accepts, output YES; otherwise output NO
- Is this language in P?
 - Ah, trickyyy
 - How can you tell if M will terminate if you don't run it for all $2^{|w|}$ steps??

A Decidable Non-Polynomial Problem, cont'd

- Consider the language:

$$\mathcal{L}_{EXP} = \{ \langle M \rangle \# w \mid M \text{ accepts } w \text{ within at most } 2^{|w|} \text{ steps} \}$$

- *Theorem.* \mathcal{L}_{EXP} is not in P.
- *Proof.* By contradiction. Suppose there exists a decider E_{TM} with polynomial worst-case runtime, i.e.,

$$E_{TM} = \begin{cases} \text{ACCEPT} & \text{if } M \text{ accepts } w \text{ within at most } 2^{|w|} \text{ steps} \\ \text{REJECT} & \text{otherwise} \end{cases}$$

- Let's build our diabolical diagonal Turing Machine D again:

D : “Diagonal” Turing Machine derived from E_{TM}

input: $\langle M \rangle$ where M is a Turing Machine

1. Run E_{TM} with input $\langle M \rangle \# \langle M \rangle$
2. If E_{TM} accepts then REJECT; otherwise (E_{TM} rejects) ACCEPT

A Decidable Non-Polynomial Problem, cont'd

- *Proof.* By contradiction. Suppose there exists a decider E_{TM} with polynomial worst-case runtime, i.e.,

$$E_{TM} = \begin{cases} \text{ACCEPT} & \text{if } M \text{ accepts } w \text{ within at most } 2^{|w|} \text{ steps} \\ \text{REJECT} & \text{otherwise} \end{cases}$$

- E_{TM} implies D exists, hence it will appear on the list of all Turing Machines:
 $\langle M_1 \rangle, \langle M_2 \rangle, \langle M_3 \rangle, \langle M_4 \rangle, \langle D \rangle, \dots$

$E_{TM}(\langle M_i \rangle \# \langle M_j \rangle)$	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$	$\langle M_4 \rangle$	$\langle D \rangle$
$\langle M_1 \rangle$	<u>ACCEPT</u>	ACCEPT	REJECT	ACCEPT	ACCEPT
$\langle M_2 \rangle$	ACCEPT	<u>REJECT</u>	REJECT	ACCEPT	REJECT
$\langle M_3 \rangle$	REJECT	ACCEPT	<u>REJECT</u>	REJECT	ACCEPT
$\langle M_4 \rangle$	REJECT	ACCEPT	REJECT	<u>ACCEPT</u>	REJECT
$\langle D \rangle$					

A Decidable Non-Polynomial Problem, cont'd

- *Proof.* By contradiction. Suppose there exists a decider E_{TM} with polynomial worst-case runtime, i.e.,

$$E_{TM} = \begin{cases} \text{ACCEPT} & \text{if } M \text{ accepts } w \text{ within at most } 2^{|w|} \text{ steps} \\ \text{REJECT} & \text{otherwise} \end{cases}$$

- E_{TM} implies D exists, hence it will appear on the list of all Turing Machines:
 $\langle M_1 \rangle, \langle M_2 \rangle, \langle M_3 \rangle, \langle M_4 \rangle, \langle D \rangle, \dots$

$E_{TM}(\langle M_i \rangle \# \langle M_j \rangle)$	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$	$\langle M_4 \rangle$	$\langle D \rangle$
$\langle M_1 \rangle$	<u>ACCEPT</u>	ACCEPT	REJECT	ACCEPT	ACCEPT
$\langle M_2 \rangle$	ACCEPT	<u>REJECT</u>	REJECT	ACCEPT	REJECT
$\langle M_3 \rangle$	REJECT	ACCEPT	<u>REJECT</u>	REJECT	ACCEPT
$\langle M_4 \rangle$	REJECT	ACCEPT	REJECT	<u>ACCEPT</u>	REJECT
$\langle D \rangle$	REJECT	ACCEPT	ACCEPT	REJECT	???

A Decidable Non-Polynomial Problem, cont'd

- $D(\langle M_i \rangle)$ does the opposite of $E_{TM}(\langle M_i \rangle \# \langle M_i \rangle)$
- Suppose $E_{TM}(\langle D \rangle \# \langle D \rangle)$ accepts
 - That means that D accepts (fast) on input $\langle D \rangle$
 - But D should reject because $E_{TM}(\langle D \rangle \# \langle D \rangle)$ accepted
 - **FISHY!**
- Suppose $E_{TM}(\langle D \rangle \# \langle D \rangle)$ rejects
 - That means that D either rejects or is slow to accept input $\langle D \rangle$
 - May or may not accept (no contradiction so far)
 - We know D should accept because $E_{TM}(\langle D \rangle \# \langle D \rangle)$ rejected
 - But E_{TM} is fast (runs in polynomial time in $\langle D \rangle$)
 - Note that D runs by simulating E_{TM} on $\langle D \rangle \# \langle D \rangle$
 - So the runtime of D is bounded by the runtime of E_{TM} , plus the overhead of preparing the input to E_{TM} (polynomial time to copy $\langle D \rangle$, etc.)
 - The runtime of E_{TM} is at most polynomial
 - Finally, I can bloat D arbitrarily to ensure runtime of $D \leq 2^{|\langle D \rangle|}$
 - **FISHY!**

Boundary Between Efficient and Inefficient

- Turing Machines are the gold standard for defining solvable and efficiently solvable
 - We have a robust notion of an efficiently solvable problem, the class P
 - There are many interesting problems in P
 - There are problems that are not in P (\mathcal{L}_{EXP})
 - There are problems that we believe are not in P
 - Traveling salesman, factorization, CLIQUE, etc.
 - Instant fame if you can prove this (P vs NP)!
- In practice, efficiency has many dimensions
 - When a problem has no fast solution but still needs to be solved, we use servers, clusters, etc. (salesmen need to travel!)
 - Mobile platforms optimize for battery consumption, at the expense of runtime
 - Distributed platforms spread data across and must solve problems with limited communication
 - Streaming platforms may pre-load data
 - Machine learning applications may need to preserve privacy, fairness, etc.

Computers are now used everywhere, including in safety-critical systems!

- **Mariner rocket explodes (1962).** Formula into code bug resulted in no smoothing of deviations.
- **WWIII (1983)?** Soviet EWS detects 5 US-missiles (bug detected sunlight reflections).
 - **Luckily Stanislav “funny feeling in my gut” Petrov** thought: “surely they’d use more missiles?”
- **Therac 25 (1985).** Concurrent programming bug killed patients through massive 100 × radiation overdose.
- **AT&T Lines Go Dead (1990).** 75 million calls dropped (one line of buggy code in software upgrade).
- **Patriot missile defense fails (1991). 28 soldiers dead, 100 injured** (rounding error in scud-detection).
- **Pentium floating point long-division bug (1993).** Cost: \$475 million – flawed division table.
- **Ariane rocket explosion (1996).** Cost: \$500 million – overflow in 64-bit to 16-bit conversion.
- **Y2K (1999).** Cost: \$500 billion spent because year was stored as 2 digits to save space.
- **Mars Climate Orbiter Crash (1998).** Cost: \$125 million lost due to metric to imperial units bug.
- **Tesla Self-Driving Car (2016). 1 dead.** Auto-pilot didn’t “see” tractor-trailer. (many more since then)
- **Financial Disasters:** London Stock Exchange down due to single server bug (**2009**; billions of pounds of trading); Knight Capital computer glitch triggers stock sale (**2012**; 500 million lost and Knight’s value drops by 75%).
- **Airline Disasters:**
 - AirFrance 447 2009, **228 dead**: pitot-tube failure feeds inconsistent data to programs which then panic pilot.
 - Spanair 5022, 2008, **154 dead**: malware virus.
 - AdamAir 574, 2007, **102 dead**: navigation system errors (and pilot errors).
 - KoreanAir 801, 1997, **228 dead**: ground proximity warning system bug.
 - AeroPerú 603, 1996, **70 dead**: altimeter failures.
 - Scottish RAF Chinook, 1994, **29 dead**: faulty test program
 - AirFrance 296, 1988, **3 dead**: altimeter bug.
 - IranAir 655, 1988, **290 dead**: shot down by US Aegis combat system (misidentified as attacking military plane).
 - KoreanAir 007, 1983, **269 dead**: autopilot took plane into Soviet airspace where it got shot down.
 - Boeing 737 Max, 2018,2019, **346 dead**: attack sensor + algorithm errors.