

Learning From Data

Lecture 5

Training Versus Testing

The Two Questions of Learning
 Theory of Generalization ($E_{in} \approx E_{out}$)
 An Effective Number of Hypotheses
 A Combinatorial Puzzle

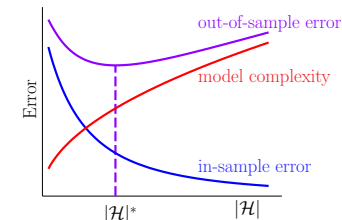
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 CSCI 4100/6100

RECAP: The Two Questions of Learning

1. Can we make sure that $E_{out}(g)$ is close enough to $E_{in}(g)$?
2. Can we make $E_{in}(g)$ small enough?

The Hoeffding *generalization bound*:

$$E_{out}(g) \leq E_{in}(g) + \underbrace{\sqrt{\frac{1}{2N} \ln \frac{2|\mathcal{H}|}{\delta}}}_{\text{generalization error bar}}$$



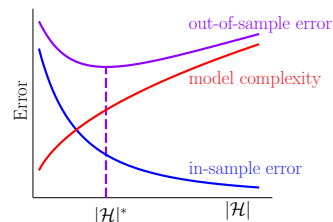
E_{in} : training (eg. the practice exam)

E_{out} : testing (eg. the real exam)

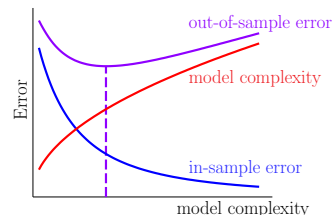
There is a tradeoff when picking $|\mathcal{H}|$.

What Will The Theory of *Generalization* Achieve?

$$E_{out}(g) \leq E_{in}(g) + \sqrt{\frac{1}{2N} \ln \frac{2|\mathcal{H}|}{\delta}}$$



$$E_{out}(g) \leq E_{in}(g) + \sqrt{\frac{8}{N} \ln \frac{4m\mathcal{H}}{\delta}}$$



The new bound will be applicable to *infinite* \mathcal{H} .

Why is $|\mathcal{H}|$ an Overkill

How did $|\mathcal{H}|$ come in?

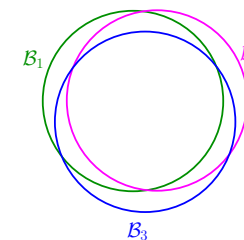
Bad events

$$\mathcal{B}_g = \{|E_{out}(g) - E_{in}(g)| > \epsilon\}$$

$$\mathcal{B}_m = \{|E_{out}(h_m) - E_{in}(h_m)| > \epsilon\}$$

We do not know which g , so use a worst case union bound.

$$\mathbb{P}[\mathcal{B}_g] \leq \mathbb{P}[\text{any } \mathcal{B}_m] \leq \sum_{m=1}^{|\mathcal{H}|} \mathbb{P}[\mathcal{B}_m].$$



- \mathcal{B}_m are events (sets of outcomes); they can overlap.
- If the \mathcal{B}_m overlap, the union bound is loose.
- If many h_m are similar, the \mathcal{B}_m overlap.
- There are “effectively” fewer than $|\mathcal{H}|$ hypotheses.
- We can replace $|\mathcal{H}|$ by something smaller.

$|\mathcal{H}|$ fails to account for similarity between hypotheses.

Measuring the Diversity (Size) of \mathcal{H}

We need a way to measure the *diversity* of \mathcal{H} .

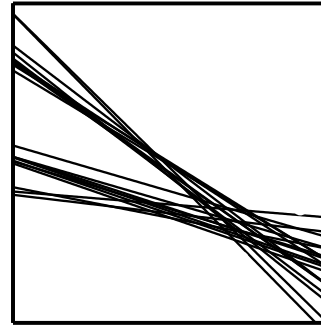
A simple idea:

Fix *any* set of N data points.

If \mathcal{H} is diverse it should be able to implement all functions

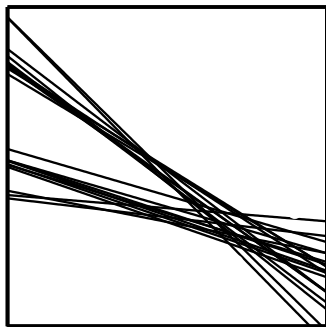
... on these N points.

A Data Set Reveals the True Colors of an \mathcal{H}

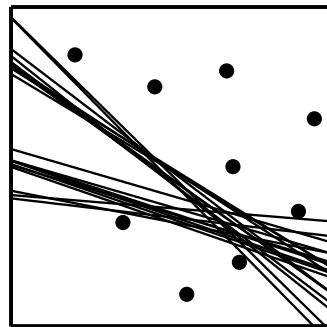


\mathcal{H}

A Data Set Reveals the True Colors of an \mathcal{H}

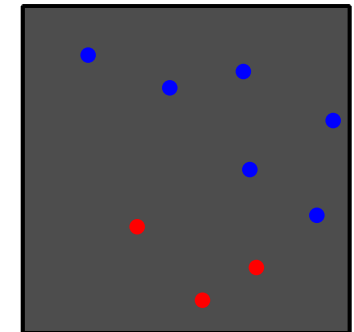
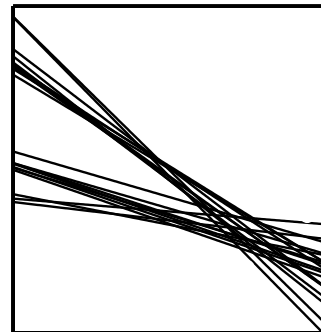


\mathcal{H}



\mathcal{H} through the eyes of the \mathcal{D}

A Data Set Reveals the True Colors of an \mathcal{H}



From the point of view of \mathcal{D} , the entire \mathcal{H} is just one *dichotomy*.

An Effective Number of Hypotheses

If \mathcal{H} is diverse it should be able to implement many dichotomys.

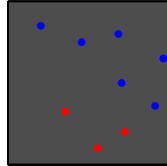
$|\mathcal{H}|$ only captures the maximum possible diversity of \mathcal{H} .

Consider an $h \in \mathcal{H}$, and a data set $\mathbf{x}_1, \dots, \mathbf{x}_N$.

h gives us an N -tuple of ± 1 's:

$$(h(\mathbf{x}_1), \dots, h(\mathbf{x}_N)).$$

A dichotomy of the inputs.



dichotomy

If \mathcal{H} is diverse, we get many different dichotomys.

If \mathcal{H} contains similar functions, we only get a few dichotomys.

The growth function quantifies this.

The Growth Function $m_{\mathcal{H}}(N)$

Define the the restriction of \mathcal{H} to the inputs $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_N$:

$$\mathcal{H}(\mathbf{x}_1, \dots, \mathbf{x}_N) = \{(h(\mathbf{x}_1), \dots, h(\mathbf{x}_N)) \mid h \in \mathcal{H}\}$$

(set of dichotomys induced by \mathcal{H})

The Growth Function $m_{\mathcal{H}}(N)$

The largest set of dichotomys induced by \mathcal{H} :

$$m_{\mathcal{H}}(N) = \max_{\mathbf{x}_1, \dots, \mathbf{x}_N} |\mathcal{H}(\mathbf{x}_1, \dots, \mathbf{x}_N)|.$$

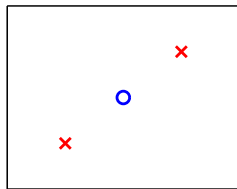
$$m_{\mathcal{H}}(N) \leq 2^N.$$

Can we replace $|\mathcal{H}|$ by $m_{\mathcal{H}}$, an effective number of hypotheses?

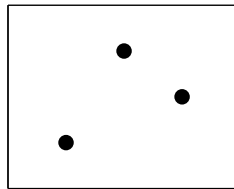
- Replacing $|\mathcal{H}|$ with 2^N is no help in the bound. (why?)
- We want $m_{\mathcal{H}}(N) \leq \text{poly}(N)$ to get a useful error bar.

(the error bar is $\sqrt{\frac{1}{2N} \ln \frac{2|\mathcal{H}|}{\delta}}$)

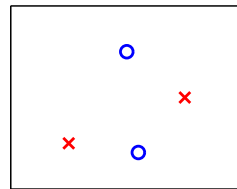
Example: 2-D Perceptron Model



Cannot implement



Can implement all 8



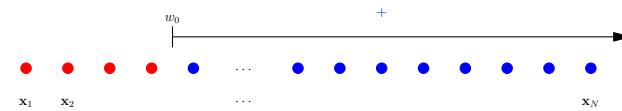
Can implement at most 14

$$m_{\mathcal{H}}(3) = 8 = 2^3.$$

$$m_{\mathcal{H}}(4) = 14 < 2^4.$$

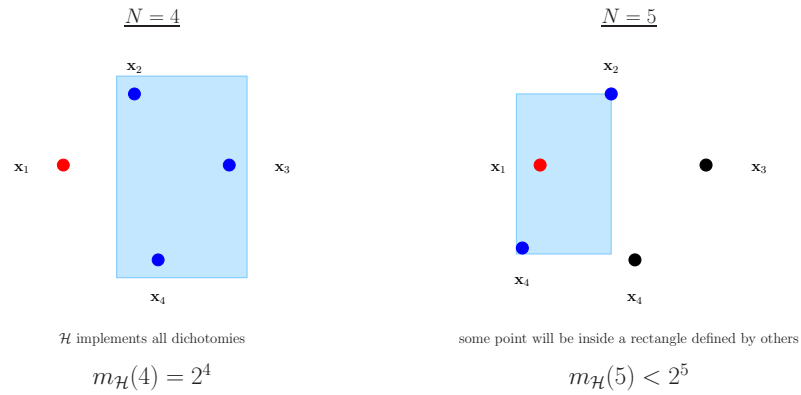
What is $m_{\mathcal{H}}(5)$?

Example: 1-D Positive Ray Model



- $h(x) = \text{sign}(x - w_0)$
- Consider N points.
- There are $N + 1$ dichotomys depending on where you put w_0 .
- $m_{\mathcal{H}}(N) = N + 1$.

Example: Positive Rectangles in 2-D



We have not computed $m_{\mathcal{H}}(5)$ – not impossible, but tricky.

Example Growth Functions

	1	2	3	N 4	5	...
2-D perceptron	2	4	8	14	...	
1-D pos. ray	2	3	4	5	...	
2-D pos. rectangles	2	4	8	16	$< 2^5$...

- $m_{\mathcal{H}}(N)$ drops below 2^N – there is hope for the generalization bound.
- A **break point** is any n for which $m_{\mathcal{H}}(n) < 2^n$.

A Combinatorial Puzzle

X_1	X_2	X_3
○	○	○
○	○	●
○	●	○
○	●	●

A set of dichotomys

A Combinatorial Puzzle

X_1	X_2	X_3
○	○	○
○	○	●
○	●	○
○	●	●

Two points are *shattered*

A Combinatorial Puzzle

X_1	X_2	X_3
○	○	○
○	○	●
○	●	○
●	○	○

No pair of points is shattered

A Combinatorial Puzzle

X_1	X_2	X_3	X_4
○	○	○	○
○	○	●	○
○	●	○	○
●	○	○	○
		⋮	

4 dichotomies is max.

If $N = 4$ how many possible dichotomys with no 2 points shattered?

