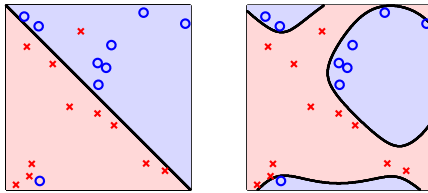


Learning From Data

Lecture 11

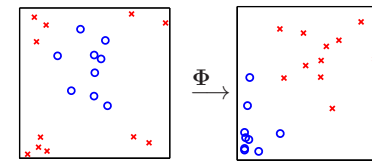
Overfitting

What is Overfitting
When does Overfitting Occur
Stochastic and Deterministic Noise



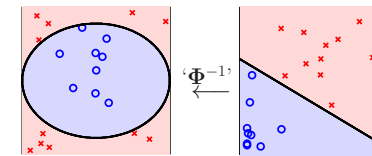
M. Magdon-Ismail
CSCI 4100/6100

RECAP: Nonlinear Transforms



1. Original data $x_n \in \mathcal{X}$

2. Transform the data $z_n = \Phi(x_n) \in \mathcal{Z}$



4. Classify in \mathcal{X} -space $g(x) = \hat{g}(\Phi(x)) = \text{sign}(\tilde{w}^T \Phi(x))$

3. Separate data in \mathcal{Z} -space $\hat{g}(z) = \text{sign}(\tilde{w}^T z)$

\mathcal{X} -space is \mathbb{R}^d

$$x = \begin{bmatrix} 1 \\ x_1 \\ \vdots \\ x_d \end{bmatrix}$$

x_1, x_2, \dots, x_N

y_1, y_2, \dots, y_N

no weights

$d_{vc} = d + 1$

$g(x) = \text{sign}(\tilde{w}^T \Phi(x))$

\mathcal{Z} -space is \mathbb{R}^d

$$z = \Phi(x) = \begin{bmatrix} 1 \\ \Phi_1(x) \\ \vdots \\ \Phi_d(x) \end{bmatrix} = \begin{bmatrix} 1 \\ z_1 \\ \vdots \\ z_d \end{bmatrix}$$

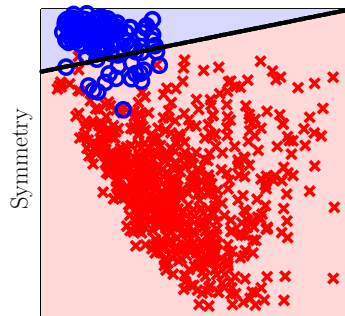
z_1, z_2, \dots, z_N

y_1, y_2, \dots, y_N

$$\tilde{w} = \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_d \end{bmatrix}$$

$d_{vc} = d + 1$

RECAP: Digits Data “1” Versus “All”

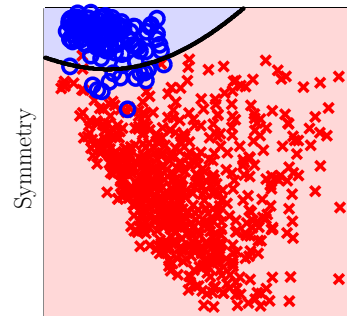


Average Intensity

Linear model

$$E_{in} = 2.13\%$$

$$E_{out} = 2.38\%$$



Average Intensity

3rd order polynomial model

$$E_{in} = 1.75\%$$

$$E_{out} = 1.87\%$$

Superstitions – Myth or Reality?

- **Paraskevedekatriaphobia** – fear of Friday the 13th.
– Are *future* Friday the 13ths really more dangerous?

- **OCD** [medical journal, citation lost, can you find it?]

the subjects performs an action which leads to a good outcome and thereby generalizes it as cause and effect: the action will always give good results. Having *overfit* the data, the subject compulsively engages in that activity.

Humans are **overfitting machines**, very good at “finding coincidences”.

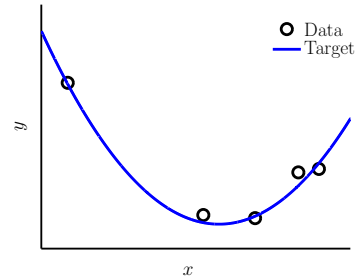
An Illustration of Overfitting on a Simple Example

Quadratic f

5 data points

A *little* noise (measurement error)

5 data points \rightarrow 4th order polynomial fit



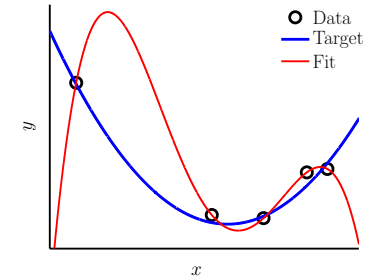
An Illustration of Overfitting on a Simple Example

Quadratic f

5 data points

A *little* noise (measurement error)

5 data points \rightarrow 4th order polynomial fit



Classic overfitting: simple target with excessively complex \mathcal{H} .

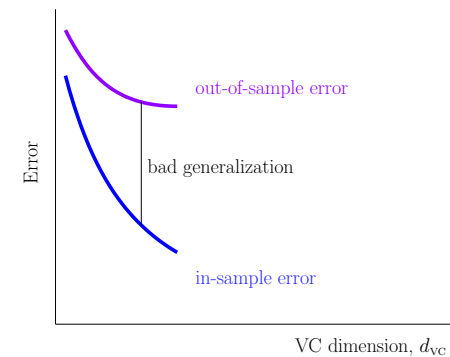
$$E_{\text{in}} \approx 0; E_{\text{out}} \gg 0$$

The **noise** did us in. (why?)

What is Overfitting?

Fitting the data **more** than is **warranted**

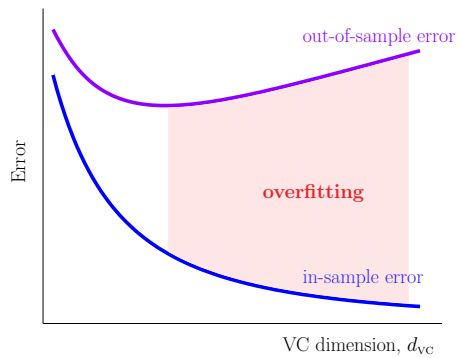
Overfitting is Not Just Bad Generalization



VC Analysis:

Covers bad generalization but with lots of slack – the VC bound is loose

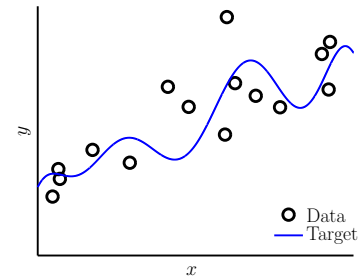
Overfitting is Not Just Bad Generalization



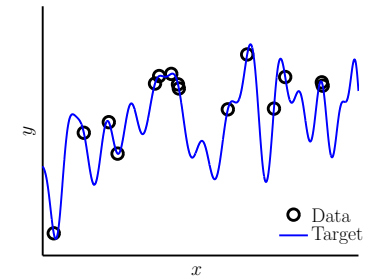
Overfitting:

Going for lower and lower E_{in} results in higher and higher E_{out}

Case Study: 2nd vs 10th Order Polynomial Fit

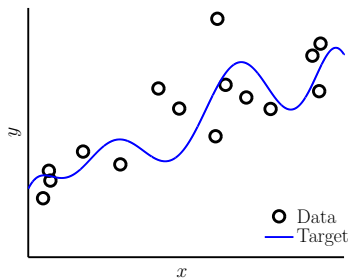


10th order f with noise.

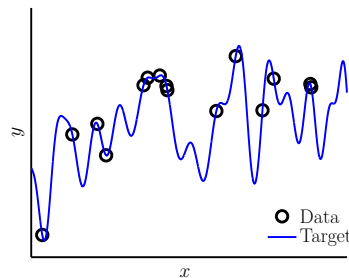


50th order f with no noise.

Case Study: 2nd vs 10th Order Polynomial Fit



10th order f with noise.



50th order f with no noise.

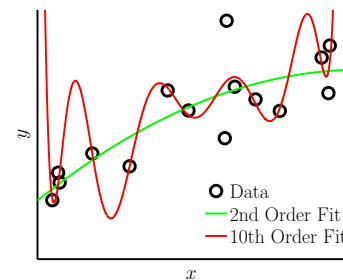
\mathcal{H}_2 : 2nd order polynomial fit

\mathcal{H}_{10} : 10th order polynomial fit

\leftarrow special case of linear models with feature transform $x \mapsto (1, x, x^2, \dots)$.

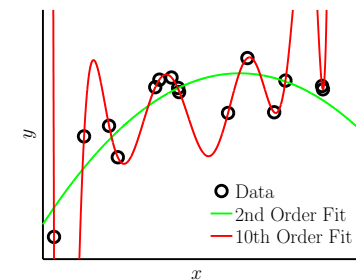
Which model do you pick for which problem and why?

Case Study: 2nd vs 10th Order Polynomial Fit



simple noisy target

	2nd Order	10th Order
E_{in}	0.050	0.034
E_{out}	0.127	9.00



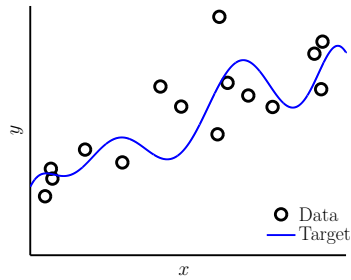
complex noiseless target

	2nd Order	10th Order
E_{in}	0.029	10^{-5}
E_{out}	0.120	7680

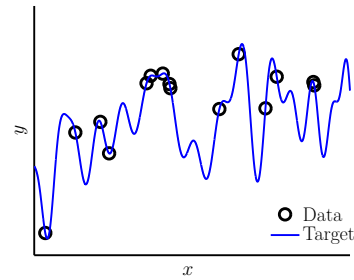
Go figure:

Simpler \mathcal{H} is better even for the more complex target with no noise.

Is there Really “No Noise” with the Complex f ?

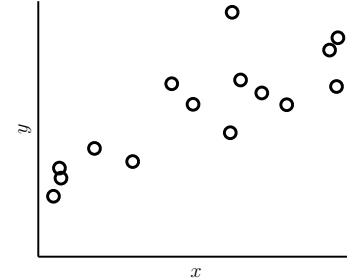


Simple f with noise.

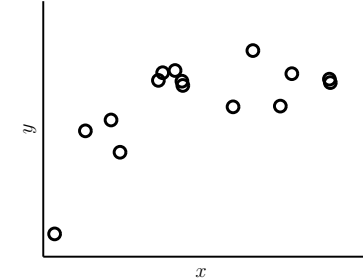


Complex f with no noise.

Is there Really “No Noise” with the Complex f ?



Simple f with noise.

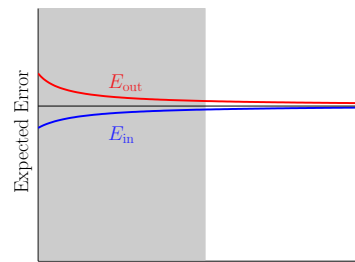


Complex f with no noise.

\mathcal{H} should match *quantity and quality of data*, not f

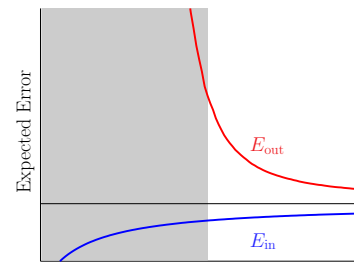
When is \mathcal{H}_2 Better than \mathcal{H}_{10} ?

Learning curves for \mathcal{H}_2



Number of Data Points, N

Learning curves for \mathcal{H}_{10}

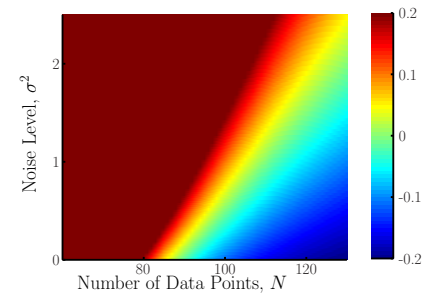


Number of Data Points, N

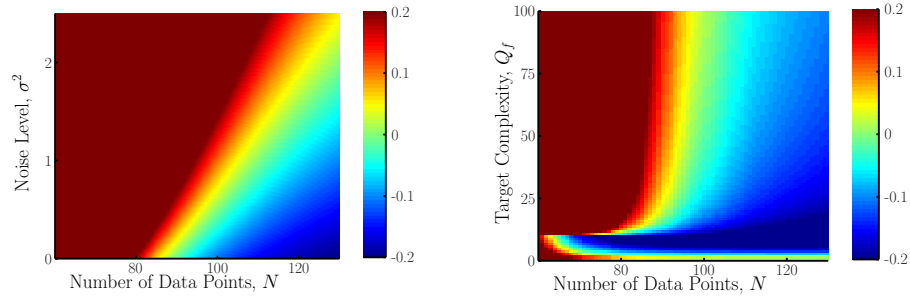
Overfitting:

$$E_{out}(\mathcal{H}_{10}) > E_{out}(\mathcal{H}_2)$$

Overfit Measure: $E_{out}(\mathcal{H}_{10}) - E_{out}(\mathcal{H}_2)$



Overfit Measure: $E_{\text{out}}(\mathcal{H}_{10}) - E_{\text{out}}(\mathcal{H}_2)$



Number of data points \uparrow	Overfitting \downarrow
Noise \uparrow	Overfitting \uparrow
Target complexity \uparrow	Overfitting \uparrow

Noise

That part of y we *cannot* model

it has two sources ...

Stochastic Noise — Data Error

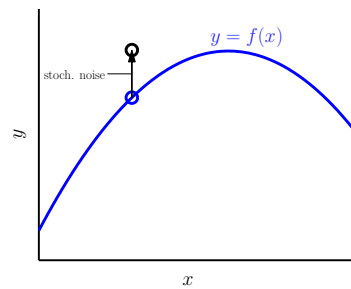
We would like to learn from \circ :

$$y_n = f(x_n)$$

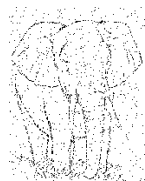
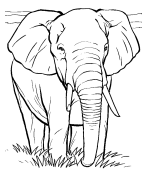
Unfortunately, we only observe \circ :

$$y_n = f(x_n) + \text{'stochastic noise'}$$

\uparrow
no one can model this



Stochastic Noise: fluctuations/measurement errors we cannot model.



Deterministic Noise — Model Error

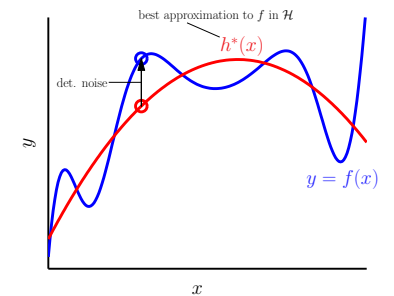
We would like to learn from \circ :

$$y_n = h^*(x_n)$$

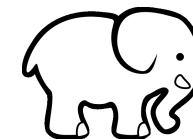
Unfortunately, we only observe \circ :

$$y_n = f(x_n) = h^*(x_n) + \text{'deterministic noise'}$$

\uparrow
 \mathcal{H} cannot model this

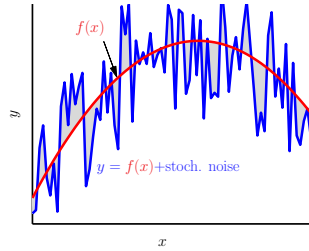


Deterministic Noise: the part of f we cannot model.



Stochastic & Deterministic Noise Hurt Learning

Stochastic Noise

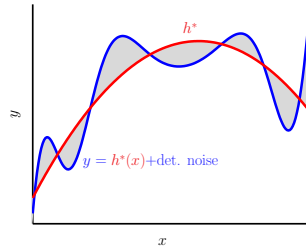


source: random measurement errors

re-measure y_n
stochastic noise changes.

change \mathcal{H}
stochastic noise the same.

Deterministic Noise



source: learner's \mathcal{H} cannot model f

re-measure y_n
deterministic noise the same.

change \mathcal{H}
deterministic noise changes.

We have single \mathcal{D} and fixed \mathcal{H} so we cannot distinguish

Noise and the Bias-Variance Decomposition

$$y = f(\mathbf{x}) + \epsilon$$

↑
measurement error

$$\begin{aligned} \mathbb{E}[E_{\text{out}}(\mathbf{x})] &= \mathbb{E}_{\mathcal{D}, \epsilon}[(g(\mathbf{x}) - f(\mathbf{x}) - \epsilon)^2] \\ &= \mathbb{E}_{\mathcal{D}, \epsilon}[(g(\mathbf{x}) - f(\mathbf{x}))^2 + 2(g(\mathbf{x}) - f(\mathbf{x}))\epsilon + \epsilon^2] \end{aligned}$$

↓ bias + var
 ↓ 0
 ↓ σ^2

Noise and the Bias-Variance Decomposition

$$y = f(\mathbf{x}) + \epsilon$$

↑
measurement error

$$\mathbb{E}[E_{\text{out}}(\mathbf{x})] = \sigma^2 + \text{bias} + \text{var}$$

↑ stochastic noise
 ↑ deterministic noise
 ↑ indirect impact of noise

Noise is the Culprit

Overfitting is the disease

Noise is the cause

Learning is led astray by fitting the noise more than the signal

Cures

Regularization: Putting on the brakes.

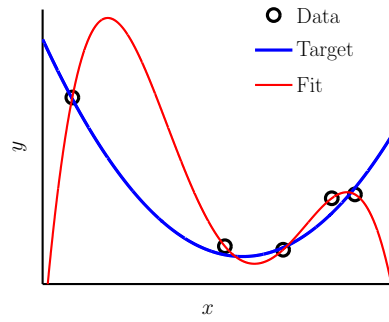


Validation: A reality check from peeking at E_{out} (the bottom line).

Regularization

no regularization

regularization!



Regularization

no regularization

regularization!

